# 1.8V 256M-BIT SERIAL FLASH MEMORY WITH DUAL/QUAD SPI

*For Industrial & Industrial Plus Grade*

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## 1. GENERAL DESCRIPTIONS

The W25Q256JW (256M-bit) Serial Flash memory provides a storage solution for systems with limited space, pins and power. The 25Q series offers flexibility and performance well beyond ordinary Serial Flash devices. They are ideal for code shadowing to RAM, executing code directly from Dual/Quad SPI (XIP) and storing voice, text and data. The device operates on a single 1.7V to 1.95V power supply with current consumption as low as 1µA for power-down. All devices are offered in space-saving packages.

The W25Q256JW array is organized into 131,072 programmable pages of 256-bytes each. Up to 256 bytes can be programmed at a time. Pages can be erased in groups of 16 (4KB sector erase), groups of 128 (32KB block erase), groups of 256 (64KB block erase) or the entire chip (chip erase). The W25Q256JW has 8,192 erasable sectors and 512 erasable blocks respectively. The small 4KB sectors allow for greater flexibility in applications that require data and parameter storage.

The W25Q256JW supports the standard Serial Peripheral Interface (SPI), and a high performance Dual/Quad output as well as Dual/Quad I/O SPI: Serial Clock, Chip Select, Serial Data I/O0 (DI), I/O1 (DO), I/O2, and I/O3. SPI clock frequencies of up to 133MHz are supported allowing equivalent clock rates of 532MHz (133MHz x 4) for Quad I/O when using the SPI Fast Read Quad I/O instructions. These transfer rates can outperform standard Asynchronous 8 and 16-bit Parallel Flash memories.

Additionally, the device supports JEDEC standard manufacturer and device ID and SFDP Register, a 64-bit Unique Serial Number and three 256-bytes Security Registers.

## 2. FEATURES

- **New Family of SpiFlash Memories**
  - W25Q256JW: 256M-bit / 32M-byte
  - Standard SPI: CLK, /CS, DI, DO
  - Dual SPI: CLK, /CS, $IO_0$, $IO_1$
  - Quad SPI: CLK, /CS, $IO_0$, $IO_1$, $IO_2$, $IO_3$
  - 3 or 4-Byte Addressing Mode
  - Software & Hardware Reset
- **Highest Performance Serial Flash**
  - 133MHz Quad I/O SPI clocks
  - 532MHz equivalent Quad I/O SPI
  - 66MB/S continuous data transfer rate
  - Min. 100K Program-Erase cycles
  - More than 20-year data retention
- **Low Power, Wide Temperature Range**
  - Single 1.7V to 1.95V supply
  - <1µA Power-down (typ.)
  - -40°C to +85°C operating range
  - -40°C to +105°C operating range(2)
- **Flexible Architecture with 4KB sectors**
  - Uniform Sector/Block Erase (4K/32K/64K-Byte)
  - Program 1 to 256 byte per programmable page
  - Erase/Program Suspend & Resume
- **Advanced Security Features**
  - Software and Hardware Write-Protect
  - Power Supply Lock-Down
  - Special OTP protection
  - Top/Bottom, Complement array protection
  - Individual Block/Sector array protection
  - 64-Bit Unique ID for each device
  - Discoverable Parameters (SFDP) Register
  - 3X256-Bytes Security Registers with OTP locks
  - Volatile & Non-volatile Status Register Bits
- **Space Efficient Packaging**
  - 8-pad WSON 6x5-mm / 8x6-mm
  - 16-pin SOIC 300-mil (additional /RESET pin)
  - 24-ball TFBGA 8x6-mm
  - 32-ball WLCSP
  - Contact Winbond for KGD and other options

**Note:**

1. Hardware /RESET pin is available on SOIC-16 or TFBGA; please contact Winbond for this package.
2. Please contact Winbond for further information.



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# 3. PACKAGE TYPES AND PIN CONFIGURATIONS

## 3.1 Pad Configuration 6x5-mm/ 8x6-mm

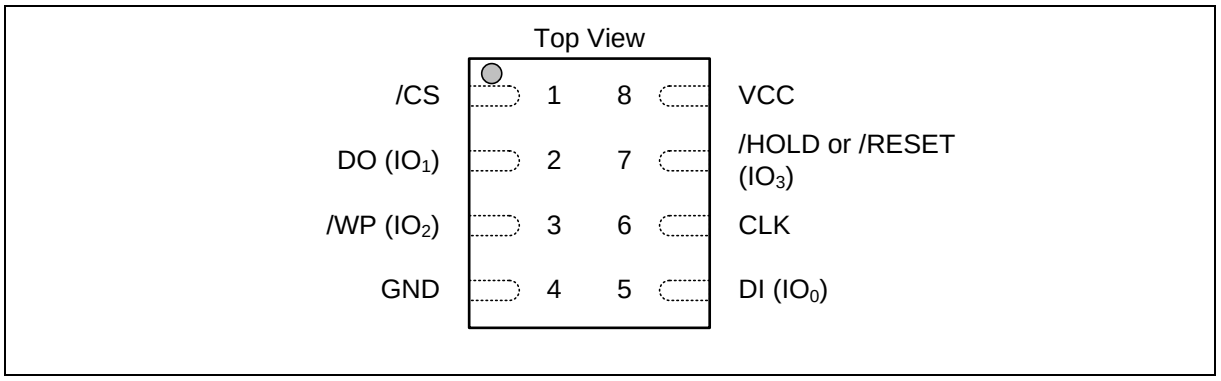



Figure 1a. W25Q256JW Pad Assignments, 8-pad WSON 6x5 & 8x6-mm (Package Code P & E)

## 3.2 Pad Description WSON 6x5-mm/ 8x6-mm

| PAD NO. | PAD NAME | I/O | FUNCTION |
|---|---|---|---|
| 1 | /CS | I | Chip Select Input |
| 2 | DO (IO1) | I/O | Data Output (Data Input Output 1)(1) |
| 3 | /WP (IO2) | I/O | Write Protect Input ( Data Input Output 2)(2) |
| 4 | GND | | Ground |
| 5 | DI (IO0) | I/O | Data Input (Data Input Output 0)(1) |
| 6 | CLK | I | Serial Clock Input |
| 7 | /HOLD or /RESET (IO3) | I/O | Hold or Reset Input (Data Input Output 3)(2) |
| 8 | VCC | | Power Supply |

**Notes:**

1. IO0 and IO1 are used for Standard and Dual SPI instructions
2. IO0 – IO3 are used for Quad SPI instructions, /HOLD (or /RESET) function is only available for Standard/Dual SPI (part numbers with ordering options “IM”).



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## 3.3 Pin Configuration SOIC 300-mil

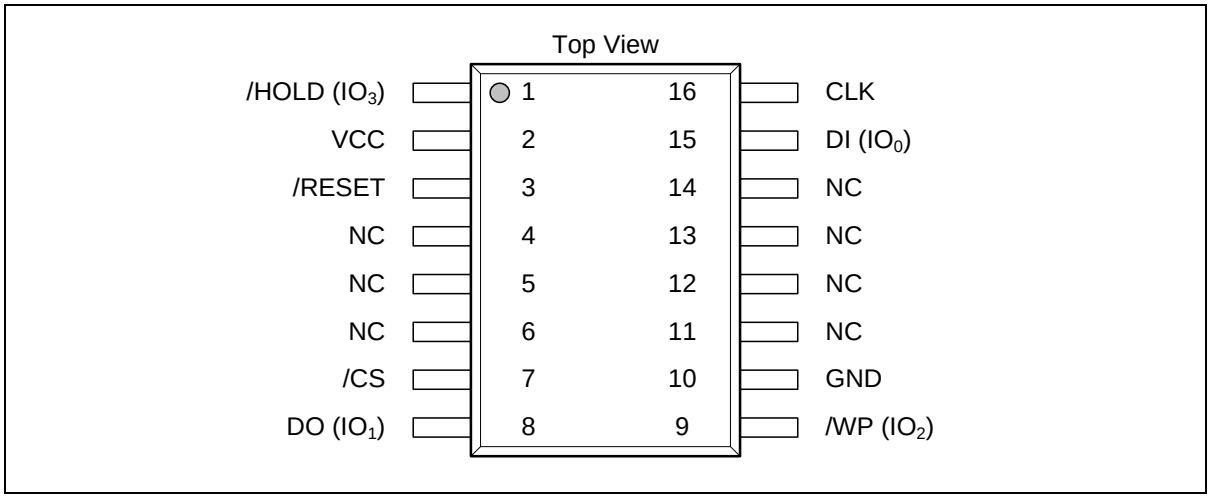



Figure 1b. W25Q256JW Pin Assignments, 16-pin SOIC 300-mil (Package Code F)

## 3.4 Pin Description SOIC 300-mil

| PIN NO. | PIN NAME | I/O | FUNCTION |
|---|---|---|---|
| 1 | /HOLD or /RESET (IO3) | I/O | Hold or Reset Input (Data Input Output 3)(2) |
| 2 | VCC | | Power Supply |
| 3 | /RESET | I | Reset Input(3) |
| 4 | N/C | | No Connect |
| 5 | N/C | | No Connect |
| 6 | N/C | | No Connect |
| 7 | /CS | I | Chip Select Input |
| 8 | DO (IO1) | I/O | Data Output (Data Input Output 1)(1) |
| 9 | /WP (IO2) | I/O | Write Protect Input (Data Input Output 2)(2) |
| 10 | GND | | Ground |
| 11 | N/C | | No Connect |
| 12 | N/C | | No Connect |
| 13 | N/C | | No Connect |
| 14 | N/C | | No Connect |
| 15 | DI (IO0) | I/O | Data Input (Data Input Output 0)(1) |
| 16 | CLK | I | Serial Clock Input |

**Notes:**

1. IO0 and IO1 are used for Standard and Dual SPI instructions.
2. IO0 – IO3 are used for Quad SPI instructions, /HOLD (or /RESET) function is only available for Standard/Dual SPI(part numbers with ordering options “IM”).
3. The /RESET pin is a dedicated hardware reset pin regardless of device settings or operation states. If the hardware reset function is not used, this pin can be left floating or connected to VCC in the system.



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## 3.5 Ball Configuration TFBGA 8x6-mm (5x5 or 6x4 Ball Array)

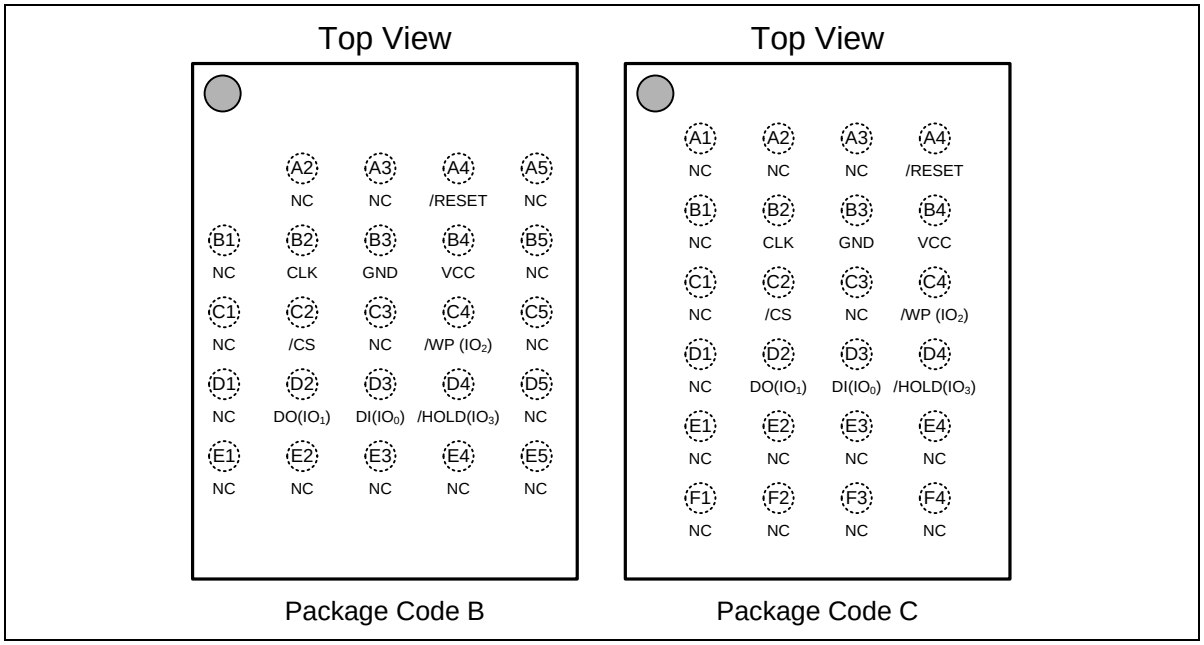



Figure 1c. W25Q256JW Ball Assignments, 24-ball TFBGA 6x8-mm (Package Code B & C)

## 3.6 Ball Description TFBGA 8x6-mm

| BALL NO. | PIN NAME | I/O | FUNCTION |
|---|---|---|---|
| A4 | /RESET | I | Reset Input(3) |
| B2 | CLK | I | Serial Clock Input |
| B3 | GND | | Ground |
| B4 | VCC | | Power Supply |
| C2 | /CS | I | Chip Select Input |
| C4 | /WP (IO2) | I/O | Write Protect Input (Data Input Output 2)(2) |
| D2 | DO (IO1) | I/O | Data Output (Data Input Output 1)(1) |
| D3 | DI (IO0) | I/O | Data Input (Data Input Output 0)(1) |
| D4 | /HOLD or /RESET (IO3) | I/O | Hold or Reset Input (Data Input Output 3)(2) |
| Multiple | NC | | No Connect |

**Notes:**

1. IO0 and IO1 are used for Standard and Dual SPI instructions
2. IO0 – IO3 are used for Quad SPI instructions, /HOLD (or /RESET) function is only available for Standard/Dual SPI(part numbers with ordering options “IM”).
3. The /RESET pin is a dedicated hardware reset pin regardless of device settings or operation states. If the hardware reset function is not used, this pin can be left floating or connected to VCC in the system



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## 3.7 Ball Configuration WLCSP

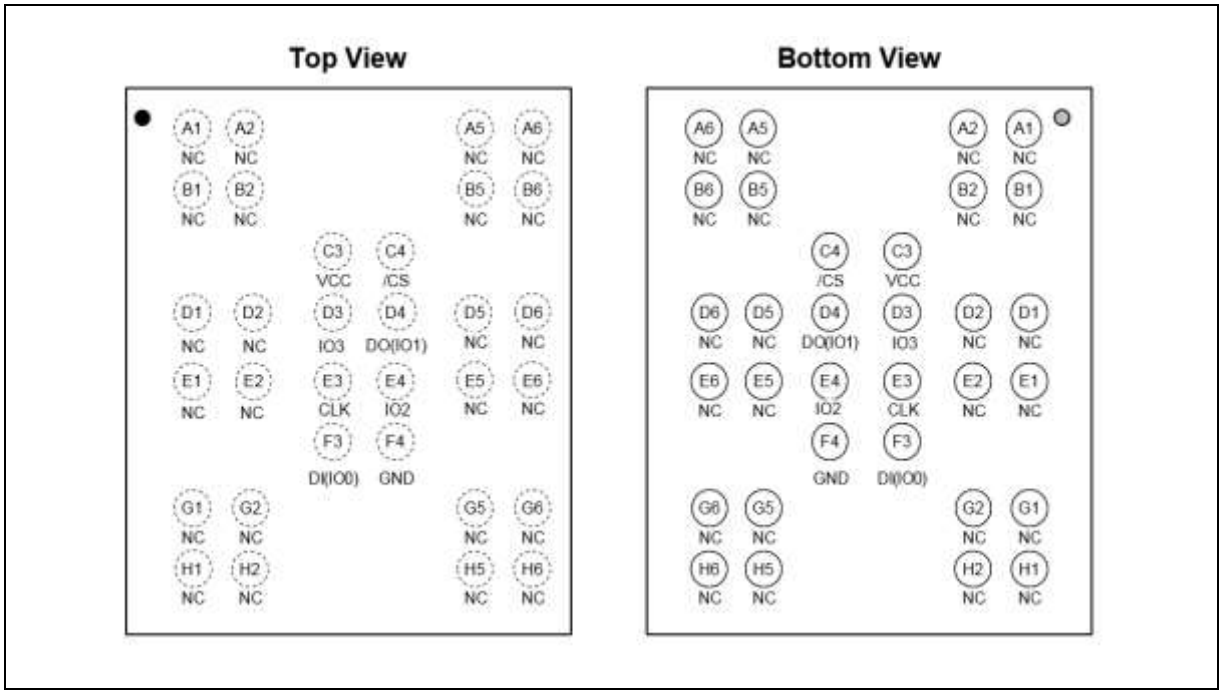



Figure 1d. W25Q256JW Ball Assignments, 32-ball WLCSP (Package Code Y)

## 3.8 Ball Description WLCSP

| BALL NO. | PIN NAME | I/O | FUNCTION |
|---|---|---|---|
| C3 | VCC | | Power Supply |
| D3 | IO3 | I/O | Data Input Output 3(2) |
| E3 | CLK | I | Serial Clock Input |
| F3 | DI (IO0) | I/O | Data Input (Data Input Output 0)(1) |
| C4 | /CS | I | Chip Select Input |
| D4 | DO (IO1) | I/O | Data Output (Data Input Output 1)(1) |
| E4 | IO2 | I/O | Data Input Output 2(2) |
| F4 | GND | | Ground |
| Multiple | NC | | No Connect |

**Notes:**

1. IO0 and IO1 are used for Standard and Dual SPI instructions
2. IO0 – IO3 are used for Quad SPI instructions, /HOLD (or /RESET) function is only available for Standard/Dual SPI(part numbers with ordering options “IM”).
3. The /RESET pin is a dedicated hardware reset pin regardless of device settings or operation states.
   If the hardware reset function is not used, this pin can be left floating or connected to VCC in the system



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# 4. PIN DESCRIPTIONS

## 4.1 Chip Select (/CS)

The SPI Chip Select (/CS) pin enables and disables device operation. When /CS is high the device is deselected and the Serial Data Output (DO, or IO0, IO1, IO2, IO3) pins are at high impedance. When deselected, the devices power consumption will be at standby levels unless an internal erase, program or write status register cycle is in progress. When /CS is brought low the device will be selected, power consumption will increase to active levels and instructions can be written to and data read from the device. After power-up, /CS must transition from high to low before a new instruction will be accepted. The /CS input must track the VCC supply level at power-up and power-down (see “Write Protection” and Figure 58). If needed a pull-up resistor on the /CS pin can be used to accomplish this.

## 4.2 Serial Data Input, Output and IOs (DI, DO and IO0, IO1, IO2, IO3)

The W25Q256JW supports standard SPI, Dual SPI and Quad SPI operation. Standard SPI instructions use the unidirectional DI (input) pin to serially write instructions, addresses or data to the device on the rising edge of the Serial Clock (CLK) input pin. Standard SPI also uses the unidirectional DO (output) to read data or status from the device on the falling edge of CLK.

Dual and Quad SPI instructions use the bidirectional IO pins to serially write instructions, addresses or data to the device on the rising edge of CLK and read data or status from the device on the falling edge of CLK. Quad SPI instructions require the non-volatile Quad Enable bit (QE) in Status Register-2 to be set. When QE=1, the /WP pin becomes IO2 and the /HOLD pin becomes IO3.

## 4.3 Write Protect (/WP)

The Write Protect (/WP) pin can be used to prevent the Status Register from being written. Used in conjunction with the Status Register’s Block Protect (CMP, SEC, TB, BP2, BP1 and BP0) bits and Status Register Protect (SRP) bits, a portion as small as a 4KB sector or the entire memory array can be hardware protected. The /WP pin is active low.

## 4.4 HOLD (/HOLD)

The /HOLD pin allows the device to be paused while it is actively selected. When /HOLD is brought low, while /CS is low, the DO pin will be at high impedance and signals on the DI and CLK pins will be ignored (don’t care). When /HOLD is brought high, device operation can resume. The /HOLD function can be useful when multiple devices are sharing the same SPI signals. The /HOLD pin is active low. When the QE bit of Status Register-2 is set for Quad I/O, the /HOLD pin function is not available since this pin is used for IO3. See Figure 1a-c for the pin configuration of Quad I/O operation.

## 4.5 Serial Clock (CLK)

The SPI Serial Clock Input (CLK) pin provides the timing for serial input and output operations. ("See SPI Operations")

## 4.6 Reset (/RESET)

A dedicated hardware /RESET pin is available on SOIC-16 and TFBGA packages. When it’s driven low for a minimum period of ~1µS, this device will terminate any external or internal operations and return to its power-on state.

**Note:** Hardware /RESET pin is available on SOIC-16 or TFBGA; please contact Winbond for this package.



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## 5. BLOCK DIAGRAM

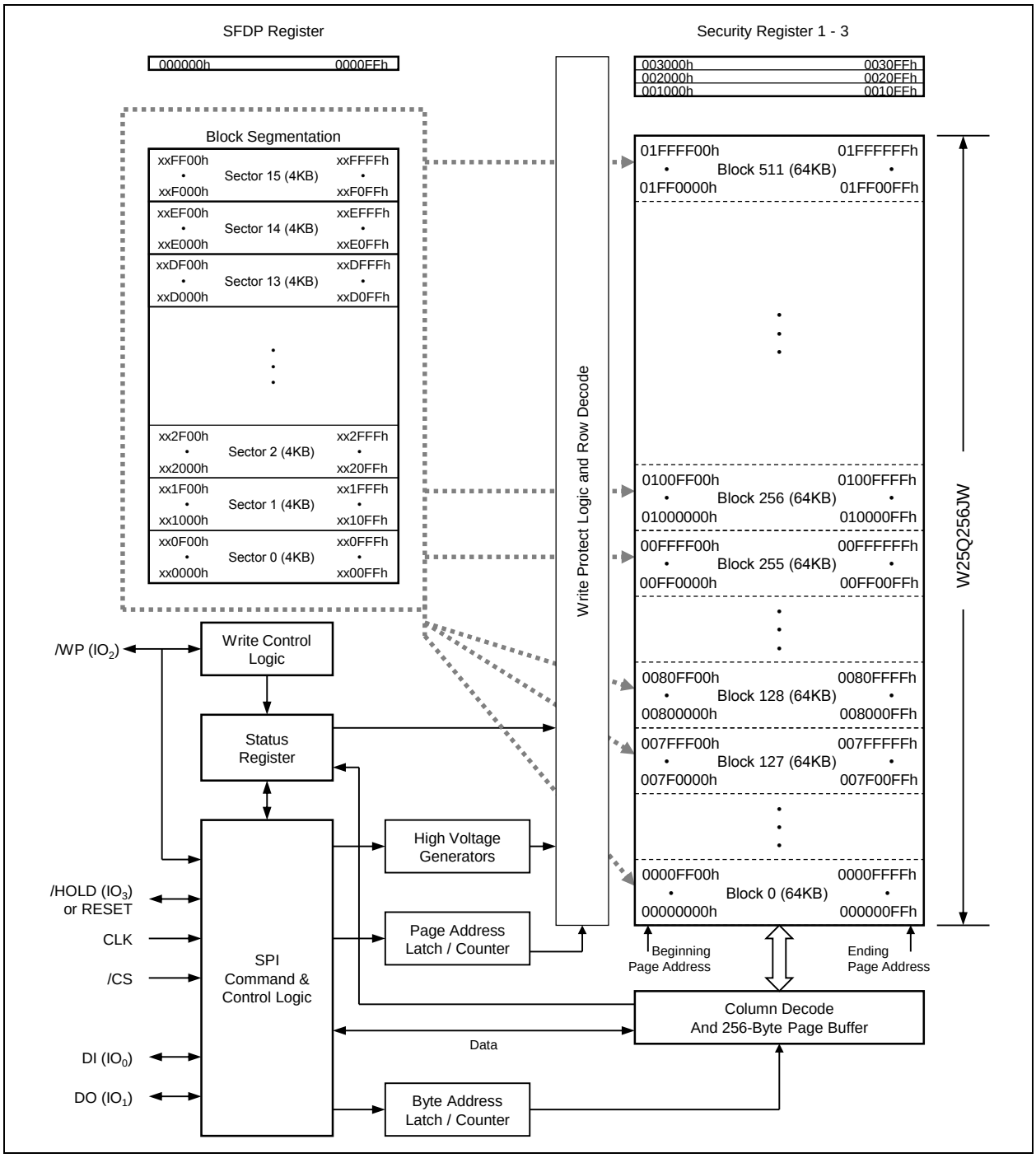



Figure 2. W25Q256JW Serial Flash Memory Block Diagram



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# 6. FUNCTIONAL DESCRIPTIONS

## 6.1 SPI Operations

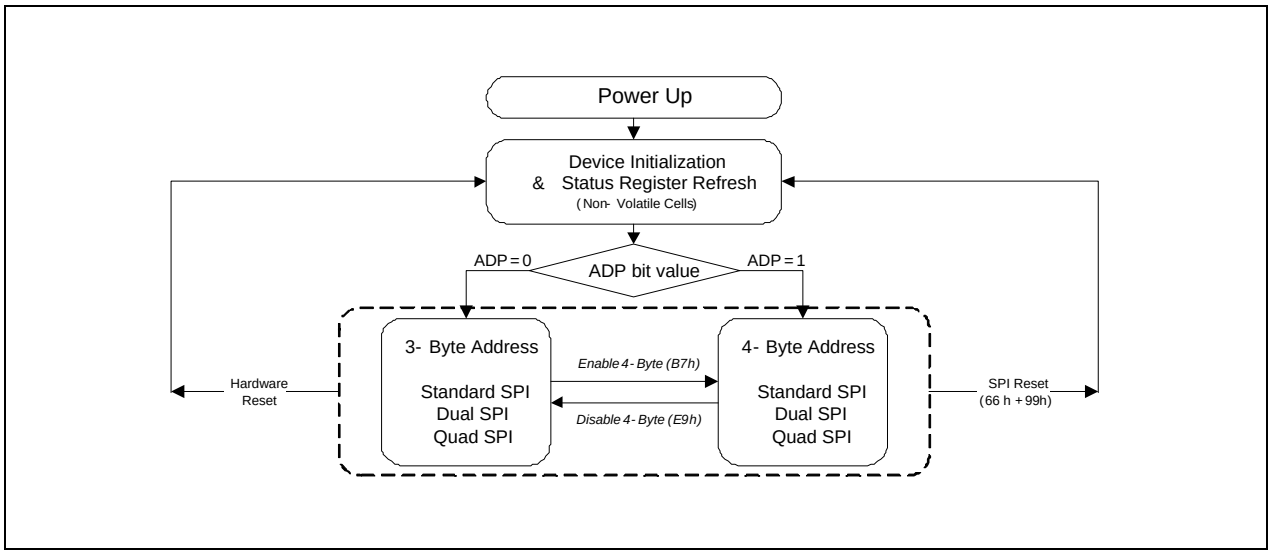



Figure 3. W25Q256JW Serial Flash Memory Operation Diagram

### 6.1.1 Standard SPI Instructions

The W25Q256JW is accessed through an SPI compatible bus consisting of four signals: Serial Clock (CLK), Chip Select (/CS), Serial Data Input (DI) and Serial Data Output (DO). Standard SPI instructions use the DI input pin to serially write instructions, addresses or data to the device on the rising edge of CLK. The DO output pin is used to read data or status from the device on the falling edge of CLK.

SPI bus operation Mode 0 (0,0) and 3 (1,1) are supported. The primary difference between Mode 0 and Mode 3 concerns the normal state of the CLK signal when the SPI bus master is in standby and data is not being transferred to the Serial Flash. For Mode 0, the CLK signal is normally low on the falling and rising edges of /CS. For Mode 3, the CLK signal is normally high on the falling and rising edges of /CS.

### 6.1.2 Dual SPI Instructions

The W25Q256JW supports Dual SPI operation when using instructions such as “Fast Read Dual Output (3Bh)” and “Fast Read Dual I/O (BBh)”. These instructions allow data to be transferred to or from the device at two to three times the rate of ordinary Serial Flash devices. The Dual SPI Read instructions are ideal for quickly downloading code to RAM upon power-up (code-shadowing) or for executing non-speed-critical code directly from the SPI bus (XIP). When using Dual SPI instructions, the DI and DO pins become bidirectional I/O pins: IO0 and IO1.

### 6.1.3 Quad SPI Instructions

The W25Q256JW supports Quad SPI operation when using instructions such as “Fast Read Quad Output (6Bh)”, “Fast Read Quad I/O (EBh)”. These instructions allow data to be transferred to or from the device four to six times the rate of ordinary Serial Flash. The Quad Read instructions offer a significant improvement in continuous and random access transfer rates allowing fast code-shadowing to RAM or execution directly from the SPI bus (XIP).

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### 6.1.4 3-Byte / 4-Byte Address Modes

The W25Q256JW provides two Address Modes that can be used to specify any byte of data in the memory array. The 3-Byte Address Mode is backward compatible to older generations of serial flash memory that only support up to 128M-bit data. To address the 256M-bit or more data in 3-Byte Address Mode, Extended Address Register must be used in addition to the 3-Byte addresses.

4-Byte Address Mode is designed to support Serial Flash Memory devices from 256M-bit to 32G-bit. The extended Address Register is not necessary when the 4-Byte Address Mode is enabled.

Upon power up, the W25Q256JW can operate in either 3-Byte Address Mode or 4-Byte Address Mode, depending on the Non-Volatile Status Register Bit ADP (S17) setting. If ADP=0, the device will operate in 3-Byte Address Mode; if ADP=1, the device will operate in 4-Byte Address Mode. The factory default value for ADP is 0.

To switch between the 3-Byte or 4-Byte Address Modes, “Enter 4-Byte Mode (B7h)” or “Exit 4-Byte Mode (E9h)” instructions must be used. The current address mode is indicated by the Status Register Bit ADS (S16).

W25Q256JW also supports a set of basic SPI instructions which requires dedicated 4-Byte address regardless the device Address Mode setting. Please refer to Instruction Set Table 2 for details.

### 6.1.5 Software Reset & Hardware /RESET pin

The W25Q256JW can be reset to the initial power-on state by a software Reset sequence in SPI mode. This sequence must include two consecutive commands: Enable Reset (66h) & Reset (99h). If the command sequence is successfully accepted, the device will take approximately 30uS ($t_{RST}$) to reset. No command will be accepted during the reset period.

For the SOIC-16 and TFBGA package, W25Q256JW provides a dedicated /RESET pin. Drive the /RESET pin low for a minimum period of ~1us (tRESET*) will reset the device to its initial power-on state.

Hardware /RESET pin has the highest priority among all the input signals. Drive /RESET low for a minimum period of ~1us (tRESET*) will interrupt any on-going external/internal operations, regardless the status of other SPI signals (/CS, CLK, IOs).

**Note:**

1. While a faster /RESET pulse (as short as a few hundred nanoseconds) will often reset the device, a 1us minimum pulse is recommended to ensure reliable operation.
2. There is an internal pull-up resistor for the dedicated /RESET pin on the SOIC-16 & TFBGA package. If the reset function is not used, this pin can be left floating in the system.



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## 6.2 Write Protection

Applications that use non-volatile memory must take into consideration the possibility of noise and other adverse system conditions that may compromise data integrity. To address this concern, the W25Q256JW provides several means to protect the data from inadvertent writes.

- Device resets when VCC is below threshold
- Time delay write disable after Power-up
- Write enable/disable instructions and automatic write disable after erase or program
- Software and Hardware (/WP pin) write protection using Status Registers
- Additional Individual Block/Sector Locks for array protection
- Write Protection using Power-down instruction
- Lock Down write protection for Status Register until the next power-up
- One Time Program (OTP) write protection for array and Security Registers using Status Register*

  * Note: This feature is available upon special flow. Please contact Winbond for details.

Upon power-up or at power-down, the W25Q256JW will maintain a reset condition while VCC is below the threshold value of $V_{WI}$, (See Power-up Timing and Voltage Levels and Figure 43). While reset, all operations are disabled and no instructions are recognized. During power-up and after the VCC voltage exceeds $V_{WI}$, all program and erase related instructions are further disabled for a time delay of $t_{PUW}$. This includes the Write Enable, Page Program, Sector Erase, Block Erase, Chip Erase and the Write Status Register instructions. Note that the chip select pin (/CS) must track the VCC supply level at power-up until the VCC-min level and $t_{VSL}$ time delay is reached, and it must also track the VCC supply level at power-down to prevent adverse command sequence. If needed, a pull-up resistor on /CS pin can be used to accomplish this.

After power-up the device is automatically placed in a write-disabled state with the Status Register Write Enable Latch (WEL) set to a 0. A Write Enable instruction must be issued before a Page Program, Sector Erase, Block Erase, Chip Erase or Write Status Register instruction will be accepted. After completing a program, erase or write instruction the Write Enable Latch (WEL) is automatically cleared to a write-disabled state of 0.

Software controlled write protection is facilitated using the Write Status Register instruction and setting the Status Register Protect (SRP, SRL) and Block Protect (CMP, TB, BP[3:0]) bits. These settings allow a portion or the entire memory array to be configured as read only. Used in conjunction with the Write Protect (/WP) pin, changes to the Status Register can be enabled or disabled under hardware control. See Status Register section for further information. Additionally, the Power-down instruction offers an extra level of write protection as all instructions are ignored except for the Release Power-down instruction.

The W25Q256JW also provides another Write Protect method using the Individual Block Locks. Each 64KB block (except the top and bottom blocks, total of 510 blocks) and each 4KB sector within the top/bottom blocks (total of 32 sectors) are equipped with an Individual Block Lock bit. When the lock bit is 0, the corresponding sector or block can be erased or programmed; when the lock bit is set to 1, Erase or Program commands issued to the corresponding sector or block will be ignored. When the device is powered on, all Individual Block Lock bits will be 1, so the entire memory array is protected from Erase/Program. An “Individual Block Unlock (39h)” instruction must be issued to unlock any specific sector or block.

The WPS bit in Status Register-3 is used to decide which Write Protect scheme should be used. When WPS=0 (factory default), the device will only utilize CMP, TB, BP[3:0] bits to protect specific areas of the array; when WPS=1, the device will utilize the Individual Block Locks for write protection.



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# 7. STATUS AND CONFIGURATION REGISTERS

Three Status and Configuration Registers are provided for W25Q256JW. The Read Status Register-1/2/3 instructions can be used to provide status on the availability of the flash memory array, whether the device is write enabled or disabled, the state of write protection, Quad SPI setting, Security Register lock status, Erase/Program Suspend status, output driver strength, power-up and current Address Mode. The Write Status Register instruction can be used to configure the device write protection features, Quad SPI setting, Security Register OTP locks functions, output driver strength and power-up Address Mode. Write access to the Status Register is controlled by the state of the non-volatile Status Register Lock bits (SRL), the Write Enable instruction, and during Standard/Dual SPI operations.

## 7.1 Status Registers

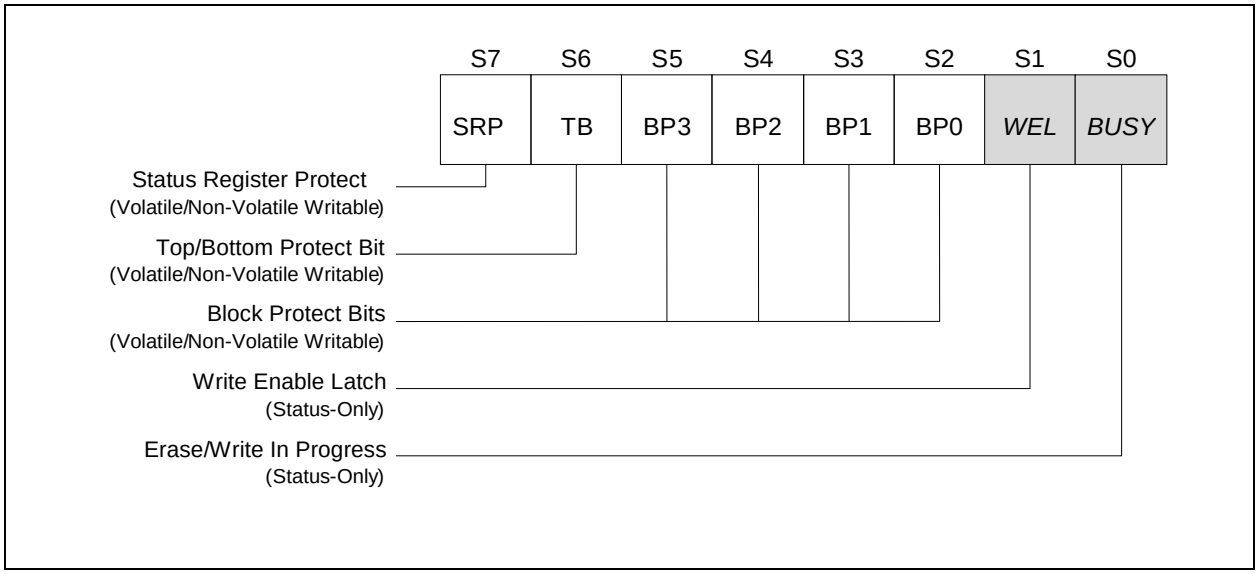



Figure 4a. Status Register-1

### 7.1.1 Erase/Write In Progress (BUSY) – *Status Only*

BUSY is a read only bit in the status register (S0) that is set to a 1 state when the device is executing a Page Program, Quad Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register or Erase/Program Security Register instruction. During this time the device will ignore further instructions except for the Read Status Register and Erase/Program Suspend instruction (see tW, tPP, tSE, tBE, and tCE in AC Characteristics). When the program, erase or write status/security register instruction has completed, the BUSY bit will be cleared to a 0 state indicating the device is ready for further instructions.

### 7.1.2 Write Enable Latch (WEL) – *Status Only*

Write Enable Latch (WEL) is a read only bit in the status register (S1) that is set to 1 after executing a Write Enable Instruction. The WEL status bit is cleared to 0 when the device is write disabled. A write disable state occurs upon power-up or after any of the following instructions: Write Disable, Page Program, Quad Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register, Erase Security Register and Program Security Register.



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### 7.1.3 Block Protect Bits (BP3, BP2, BP1, BP0) – *Volatile/Non-Volatile Writable*

The Block Protect Bits (BP3, BP2, BP1, BP0) are non-volatile read/write bits in the status register (S5, S4, S3, and S2) that provide Write Protection control and status. Block Protect bits can be set using the Write Status Register Instruction (see tw in AC characteristics). All, none or a portion of the memory array can be protected from Program and Erase instructions (see Status Register Memory Protection table). The factory default setting for the Block Protection Bits is 0, none of the array protected.

### 7.1.4 Top/Bottom Block Protect (TB) – *Volatile/Non-Volatile Writable*

The non-volatile Top/Bottom bit (TB) controls if the Block Protect Bits (BP3, BP2, BP1, BP0) protect from the Top (TB=0) or the Bottom (TB=1) of the array as shown in the Status Register Memory Protection table. The factory default setting is TB=0. The TB bit can be set with the Write Status Register Instruction depending on the state of the SRP and WEL bits.

### 7.1.5 Complement Protect (CMP) – *Volatile/Non-Volatile Writable*

The Complement Protect bit (CMP) is a non-volatile read/write bit in the status register (S14). It is used in conjunction with TB, BP3, BP2, BP1 and BP0 bits to provide more flexibility for the array protection. Once CMP is set to 1, previous array protection set by TB, BP3, BP2, BP1 and BP0 will be reversed. For instance, when CMP=0, a top 64KB block can be protected while the rest of the array is not; when CMP=1, the top 64KB block will become unprotected while the rest of the array become read-only. Please refer to the Status Register Memory Protection table for details. The default setting is CMP=0.



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### 7.1.1 Status Register Protect (SRP, SRL) – *Volatile/Non-Volatile Writable*

Three Status and Configuration Registers are provided for W25Q256JW. The Read Status Register-1/2/3 instructions can be used to provide status on the availability of the flash memory array, whether the device is write enabled or disabled, the state of write protection, Quad SPI setting, Security Register lock status, Erase/Program Suspend status, and output driver strength, The Write Status Register instruction can be used to configure the device write protection features, Quad SPI setting, Security Register OTP locks, output driver. Write access to the Status Register is controlled by the state of the non-volatile Status Register Protect bits (SRP, SRL), the Write Enable instruction, and during Standard/Dual SPI operations, the /WP pin.

| SRL | SRP | /WP | Status Register | Description |
|---|---|---|---|---|
| 0 | 0 | X | Software Protection | /WP pin has no control. The Status register can be written to after a Write Enable instruction, WEL=1. [Factory Default] |
| 0 | 1 | 0 | Hardware Protected | When /WP pin is low the Status Register locked and cannot be written to. |
| 0 | 1 | 1 | Hardware Unprotected | When /WP pin is high the Status register is unlocked and can be written to after a Write Enable instruction, WEL=1. |
| 1 | X | X | Power Supply Lock-Down | Status Register is protected and cannot be written to again until the next power-down, power-up cycle.(1) |
| 1 | X | X | One Time Program(2) | Status Register is permanently protected and cannot be written to. (**enabled by adding prefix command AAh, 55h)** |

1. When SRL =1, a power-down, power-up cycle will change SRL =0 state.
2. Please contact Winbond for details regarding the special instruction sequence.



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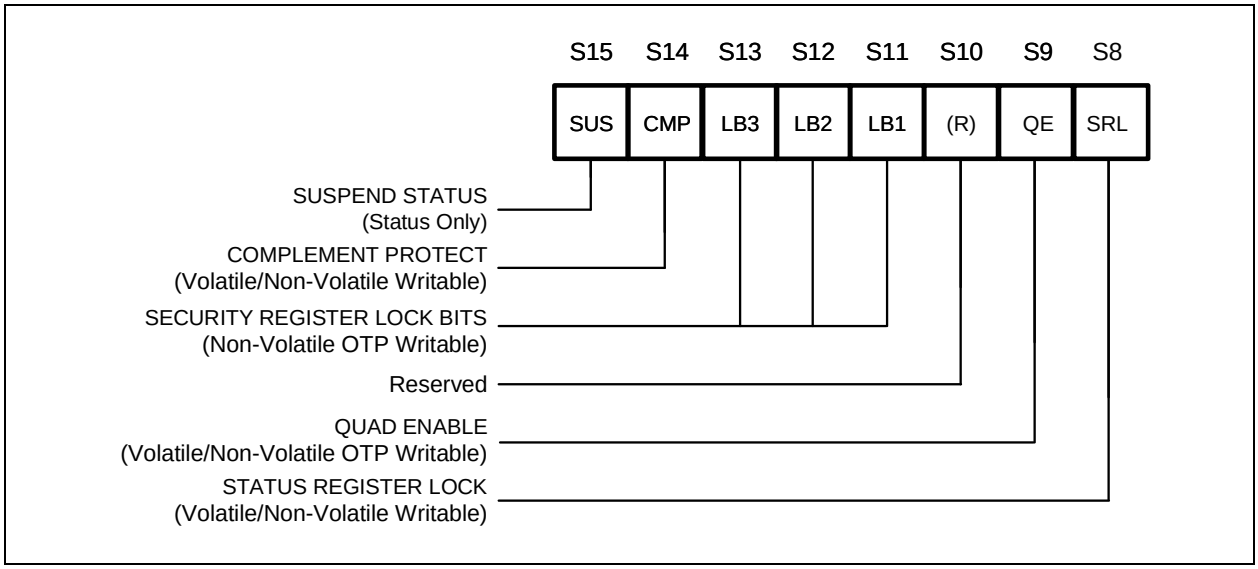



Figure 4b. Status Register-2

### 7.1.2 Erase/Program Suspend Status (SUS) – *Status Only*

The Suspend Status bit is a read only bit in the status register (S15) that is set to 1 after executing a Erase/Program Suspend (75h) instruction. The SUS status bit is cleared to 0 by Erase/Program Resume (7Ah) instruction as well as a power-down, power-up cycle.

### 7.1.3 Security Register Lock Bits (LB3, LB2, LB1) – *Non-Volatile OTP Writable*

The Security Register Lock Bits (LB3, LB2, LB1) are non-volatile One Time Program (OTP) bits in Status Register (S13, S12, S11) that provide the write protect control and status to the Security Registers. The default state of LB3-1 is 0, Security Registers are unlocked. LB3-1 can be set to 1 individually using the Write Status Register instruction. LB3-1 are One Time Programmable (OTP), once it's set to 1, the corresponding 256-Byte Security Register will become read-only permanently.

### 7.1.4 Quad Enable (QE) – *Volatile/Non-Volatile Writable*

The Quad Enable (QE) bit is a non-volatile read/write bit in the status register (S9) that enables Quad SPI operation. When the QE bit is set to a 0 state (factory default for part numbers with ordering options "IM/JM"), the /HOLD are enabled, the device operates in Standard/Dual SPI modes. When the QE bit is set to a 1 (factory fixed default for part numbers with ordering options "IQ/IN/JQ"), the Quad IO2 and IO3 pins are enabled, and /HOLD function is disabled, the device operates in Standard/Dual/Quad SPI modes.



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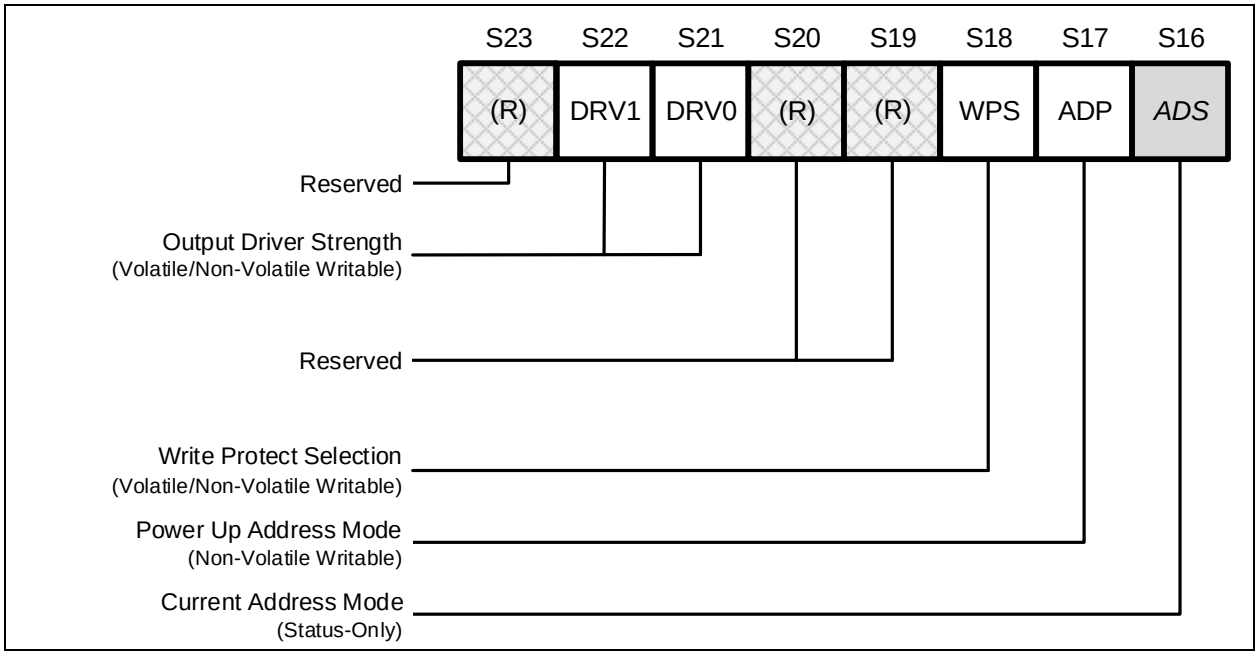



Figure 4c. Status Register-3

### 7.1.5 Current Address Mode (ADS) – *Status Only*

The Current Address Mode bit is a read only bit in the Status Register-3 that indicates which address mode the device is currently operating in. When ADS=0, the device is in the 3-Byte Address Mode, when ADS=1, the device is in the 4-Byte Address Mode.

### 7.1.6 Power-Up Address Mode (ADP) – *Non-Volatile Writable*

The ADP bit is a non-volatile bit that determines the initial address mode when the device is powered on or reset. This bit is only used during the power on or device reset initialization period, and it is only writable by the non-volatile Write Status sequence (06h + 11h). When ADP=0 (factory default), the device will power up into 3-Byte Address Mode, the Extended Address Register must be used to access memory regions beyond 128Mb. When ADP=1, the device will power up into 4-Byte Address Mode directly.

### 7.1.7 Write Protect Selection (WPS) – *Volatile/Non-Volatile Writable*

The WPS bit is used to select which Write Protect scheme should be used. When WPS=0, the device will use the combination of CMP, TB, BP[3:0] bits to protect a specific area of the memory array. When WPS=1, the device will utilize the Individual Block Locks to protect any individual sector or blocks. The default value for all Individual Block Lock bits is 1 upon device power on or after reset.



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### 7.1.8 Output Driver Strength (DRV1, DRV0) – *Volatile/Non-Volatile Writable*

The DRV1 & DRV0 bits are used to determine the output driver strength for the Read operations.

| DRV1, DRV0 | Driver Strength |
|---|---|
| 0, 0 | 100% |
| 0, 1 | 75%(1) |
| 1, 0 | 50% |
| 1, 1 | 25%(2) |

**Notes:**

1. Factory default for part numbers with ordering options “IN”
2. Factory default for part numbers with ordering options “IQ”.

### 7.1.9 Reserved Bits – *Non Functional*

There are a few reserved Status Register bits that may be read out as a “0” or “1”. It is recommended to ignore the values of those bits. During a “Write Status Register” instruction, the Reserved Bits can be written as “0”, but there will not be any effects.



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### 7.1.10 W25Q256JW Status Register Memory Protection (WPS = 0, CMP = 0)

| STATUS REGISTER(1) | | | | | W25Q256JW (256M-BIT / 32M-BYTE) MEMORY PROTECTION(2) | | | |
|---|---|---|---|---|---|---|---|---|
| TB | BP3 | BP2 | BP1 | BP0 | PROTECTED BLOCK(S) | PROTECTED ADDRESSES | PROTECTED DENSITY | PROTECTED PORTION |
| X | 0 | 0 | 0 | 0 | NONE | NONE | NONE | NONE |
| 0 | 0 | 0 | 0 | 1 | 511 | 01FF0000h - 01FFFFFFh | 64KB | Upper 1/512 |
| 0 | 0 | 0 | 1 | 0 | 510 thru 511 | 01FE0000h - 01FFFFFFh | 128KB | Upper 1/256 |
| 0 | 0 | 0 | 1 | 1 | 508 thru 511 | 01FC0000h - 01FFFFFFh | 256KB | Upper 1/128 |
| 0 | 0 | 1 | 0 | 0 | 504 thru 511 | 01F80000h - 01FFFFFFh | 512KB | Upper 1/64 |
| 0 | 0 | 1 | 0 | 1 | 496 thru 511 | 01F00000h - 01FFFFFFh | 1MB | Upper 1/32 |
| 0 | 0 | 1 | 1 | 0 | 480 thru 511 | 01E00000h - 01FFFFFFh | 2MB | Upper 1/16 |
| 0 | 0 | 1 | 1 | 1 | 448 thru 511 | 01C00000h - 01FFFFFFh | 4MB | Upper 1/8 |
| 0 | 1 | 0 | 0 | 0 | 384 thru 511 | 01800000h - 01FFFFFFh | 8MB | Upper 1/4 |
| 0 | 1 | 0 | 0 | 1 | 256 thru 511 | 01000000h - 01FFFFFFh | 16MB | Upper 1/2 |
| 1 | 0 | 0 | 0 | 1 | 0 | 00000000h - 0000FFFFh | 64KB | Lower 1/512 |
| 1 | 0 | 0 | 1 | 0 | 0 thru 1 | 00000000h - 0001FFFFh | 128KB | Lower 1/256 |
| 1 | 0 | 0 | 1 | 1 | 0 thru 3 | 00000000h - 0003FFFFh | 256KB | Lower 1/128 |
| 1 | 0 | 1 | 0 | 0 | 0 thru 7 | 00000000h - 0007FFFFh | 512KB | Lower 1/64 |
| 1 | 0 | 1 | 0 | 1 | 0 thru 15 | 00000000h - 000FFFFFh | 1MB | Lower 1/32 |
| 1 | 0 | 1 | 1 | 0 | 0 thru 31 | 00000000h - 001FFFFFh | 2MB | Lower 1/16 |
| 1 | 0 | 1 | 1 | 1 | 0 thru 63 | 00000000h - 003FFFFFh | 4MB | Lower 1/8 |
| 1 | 1 | 0 | 0 | 0 | 0 thru 127 | 00000000h - 007FFFFFh | 8MB | Lower 1/4 |
| 1 | 1 | 0 | 0 | 1 | 0 thru 255 | 00000000h - 00FFFFFFh | 16MB | Lower 1/2 |
| X | 1 | 1 | 0 | X | 0 thru 511 | 00000000h - 01FFFFFFh | 32MB | ALL |
| X | 1 | X | 1 | X | 0 thru 511 | 00000000h - 01FFFFFFh | 32MB | ALL |

**Notes:**

3. X = don't care
4. If any Erase or Program command specifies a memory region that contains protected data portion, this command will be ignored.



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### 7.1.11 W25Q256JW Status Register Memory Protection (WPS = 0, CMP = 1)

| STATUS REGISTER(1) | | | | | W25Q256JW (256M-BIT / 32M-BYTE) MEMORY PROTECTION(2) | | | |
|---|---|---|---|---|---|---|---|---|
| TB | BP3 | BP2 | BP1 | BP0 | PROTECTED BLOCK(S) | PROTECTED ADDRESSES | PROTECTED DENSITY | PROTECTED PORTION |
| X | 0 | 0 | 0 | 0 | ALL | 00000000h - 01FFFFFFh | ALL | ALL |
| 0 | 0 | 0 | 0 | 1 | 0 thru 510 | 00000000h - 01FEFFFFh | 32,704KB | Lower 511/512 |
| 0 | 0 | 0 | 1 | 0 | 0 thru 509 | 00000000h - 01FDFFFFh | 32,640KB | Lower 255/256 |
| 0 | 0 | 0 | 1 | 1 | 0 thru 507 | 00000000h - 01FBFFFFh | 32,512KB | Lower 127/128 |
| 0 | 0 | 1 | 0 | 0 | 0 thru 503 | 00000000h - 01F7FFFFh | 32,256KB | Lower 63/64 |
| 0 | 0 | 1 | 0 | 1 | 0 thru 495 | 00000000h - 01EFFFFFh | 31MB | Lower 31/32 |
| 0 | 0 | 1 | 1 | 0 | 0 thru 479 | 00000000h - 01DFFFFFh | 30MB | Lower 15/16 |
| 0 | 0 | 1 | 1 | 1 | 0 thru 447 | 00000000h - 01BFFFFFh | 28MB | Lower 7/8 |
| 0 | 1 | 0 | 0 | 0 | 0 thru 383 | 00000000h - 017FFFFFh | 24MB | Lower 3/4 |
| 0 | 1 | 0 | 0 | 1 | 0 thru 255 | 00000000h - 00FFFFFFh | 16MB | Lower 1/2 |
| 1 | 0 | 0 | 0 | 1 | 1 thru 511 | 00010000h - 01FFFFFFh | 32,704KB | Upper 511/512 |
| 1 | 0 | 0 | 1 | 0 | 2 thru 511 | 00020000h - 01FFFFFFh | 32,640KB | Upper 255/256 |
| 1 | 0 | 0 | 1 | 1 | 4 thru 511 | 00040000h - 01FFFFFFh | 32,512KB | Upper 127/128 |
| 1 | 0 | 1 | 0 | 0 | 8 thru 511 | 00080000h - 01FFFFFFh | 32,256KB | Upper 63/64 |
| 1 | 0 | 1 | 0 | 1 | 16 thru 511 | 00100000h - 01FFFFFFh | 31MB | Upper 31/32 |
| 1 | 0 | 1 | 1 | 0 | 32 thru 511 | 00200000h - 01FFFFFFh | 30MB | Upper 15/16 |
| 1 | 0 | 1 | 1 | 1 | 64 thru 511 | 00400000h - 01FFFFFFh | 28MB | Upper 7/8 |
| 1 | 1 | 0 | 0 | 0 | 128 thru 511 | 00800000h - 01FFFFFFh | 24MB | Upper 3/4 |
| 1 | 1 | 0 | 0 | 1 | 256 thru 511 | 01000000h - 01FFFFFFh | 16MB | Upper 1/2 |
| X | 1 | 1 | 0 | X | NONE | NONE | NONE | NONE |
| X | 1 | X | 1 | X | NONE | NONE | NONE | NONE |

**Notes:**

1. X = don't care
2. If any Erase or Program command specifies a memory region that contains protected data portion, this command will be ignored.



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### 7.1.12 W25Q256JW Individual Block Memory Protection (WPS=1)

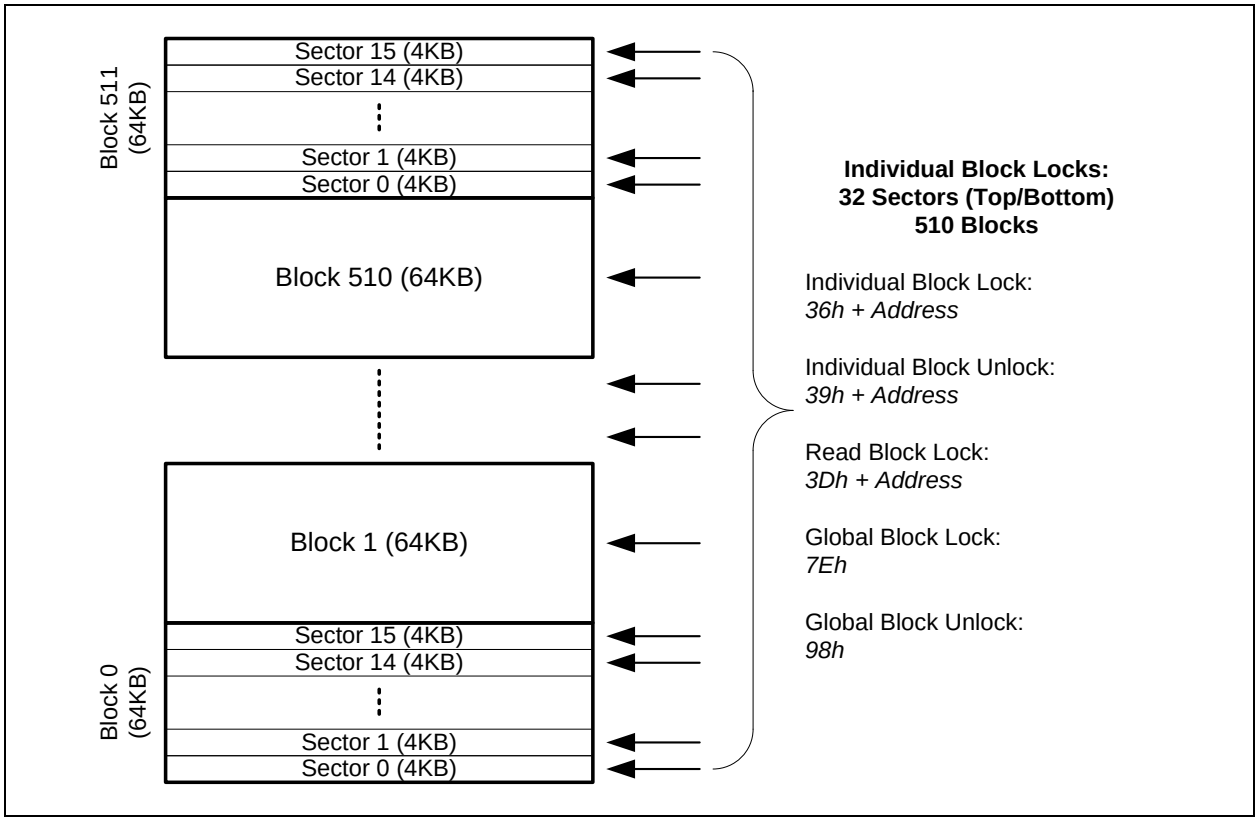



Figure 4d. Individual Block/Sector Locks

**Notes:**

1. Individual Block/Sector protection is only valid when WPS=1.
2. All individual block/sector lock bits are set to 1 by default after power up, all memory array is protected.



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## 7.2 Extended Address Register – *Volatile Writable Only*

In addition to the Status Registers, W25Q256JW provides a volatile Extended Address Register which consists of the 4th byte of memory address. The Extended Address Register is used only when the device is operating in the 3-Byte Address Mode (ADS=0). The lower 128Mb memory array (00000000h – 00FFFFFFh) is selected when A24=0, all instructions with 3-Byte addresses will be executed within that region. When A24=1, the upper 128Mb memory array (01000000h – 01FFFFFFh) will be selected.

If the device powers up with ADP bit set to 1, or an "Enter 4-Byte Address Mode (B7h)" instruction is issued, the device will require 4-Byte address input for all address related instructions, and the Extended Address Register setting will be ignored. However, any command with 4-byte address input will replace the Extended Address Register Bits (A31-A24) with new settings.

Upon power up or after the execution of a Software/Hardware Reset, the Extended Address Register values will be cleared to 0.

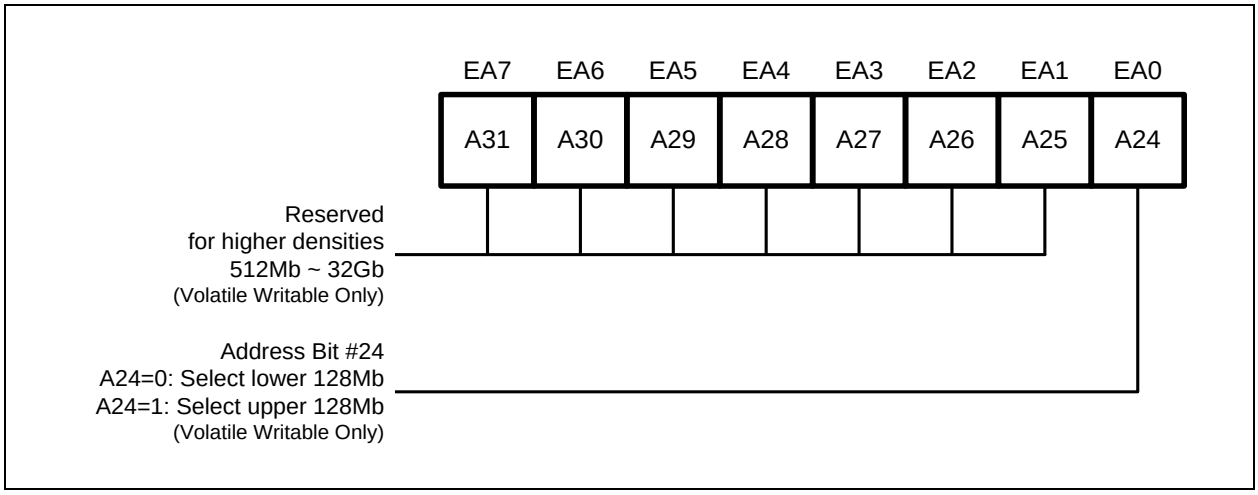



Figure 4e. Extended Address Register



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# 8. INSTRUCTIONS

The Standard/Dual/Quad SPI instruction set of the W25Q256JW consists of 48 basic instructions that are fully controlled through the SPI bus (see Instruction Set Table1-4). Instructions are initiated with the falling edge of Chip Select (/CS). The first byte of data clocked into the DI input provides the instruction code. Data on the DI input is sampled on the rising edge of clock with most significant bit (MSB) first.

Instructions vary in length from a single byte to several bytes and may be followed by address bytes, data bytes, dummy bytes (don't care), and in some cases, a combination. Instructions are completed with the rising edge of edge /CS. Clock relative timing diagrams for each instruction are included in Figures 5 through 57. All read instructions can be completed after any clocked bit. However, all instructions that Write, Program or Erase must complete on a byte boundary (/CS driven high after a full 8-bits have been clocked) otherwise the instruction will be ignored. This feature further protects the device from inadvertent writes. Additionally, while the memory is being programmed or erased, or when the Status Register is being written, all instructions except for Read Status Register will be ignored until the program or erase cycle has completed.

## 8.1 Device ID and Instruction Set Tables

### 8.1.1 Manufacturer and Device Identification

| **MANUFACTURER ID** | **(MF7 - MF0)** | |
|---|---|---|
| Winbond Serial Flash | EFh | |
| | | |
| **Device ID** | **(ID7 - ID0)** | **(ID15 - ID0)** |
| **Instruction** | **ABh, 90h, 92h, 94h** | **9Fh** |
| W25Q256JW | 18h | 6019h |
| W25Q256JW-IM* | 18h | 8019h |

Note: For DTR, QPI supporting, please refer to W25Q256JW-M DTR data sheet.



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### 8.1.2 Instruction Set Table 1 (Standard/Dual/Quad SPI, 3-Byte Address Mode)(1)

| Data Input Output | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|---|---|---|---|---|---|---|---|
| **Number of Clock(1-1-1)** | **8** | **8** | **8** | **8** | **8** | **8** | **8** |
| Write Enable | **06h** | | | | | | |
| Volatile SR Write Enable | **50h** | | | | | | |
| Write Disable | **04h** | | | | | | |
| Release Power-down | **ABh** | | | | | | |
| Device ID | **ABh** | Dummy | Dummy | Dummy | (ID7-ID0)(2) | | |
| Manufacturer/Device ID | **90h** | Dummy | Dummy | 00h | (MF7-MF0) | (ID7-ID0) | |
| JEDEC ID | **9Fh** | (MF7-MF0) | (ID15-ID8) | (ID7-ID0) | | | |
| Read Unique ID | **4Bh** | Dummy | Dummy | Dummy | Dummy | (UID63-0) | |
| Read Data | **03h** | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | | |
| Read Data with 4-Byte Address | **13h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | |
| Fast Read | **0Bh** | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) | |
| Fast Read with 4-Byte Address | **0Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) |
| Page Program | **02h** | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) | |
| Page Program with 4-Byte Address | **12h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) |
| Sector Erase (4KB) | **20h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Sector Erase (4KB) with 4-Byte Address | **21h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Block Erase (32KB) | **52h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Block Erase (64KB) | **D8h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Block Erase (64KB) with 4-Byte Address | **DCh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Chip Erase | **C7h/60h** | | | | | | |
| Read Status Register-1 | **05h** | (S7-S0)(2) | | | | | |
| Write Status Register-1(4) | **01h** | (S7-S0)(4) | | | | | |
| Read Status Register-2 | **35h** | (S15-S8)(2) | | | | | |
| Write Status Register-2 | **31h** | (S15-S8) | | | | | |
| Read Status Register-3 | **15h** | (S23-S16)(2) | | | | | |
| Write Status Register-3 | **11h** | (S23-S16) | | | | | |
| Read Extended Addr. Reg. | **C8h** | (EA7-EA0)(2) | | | | | |
| Write Extended Addr. Reg. | **C5h** | (EA7-EA0) | | | | | |
| Read SFDP Register | **5Ah** | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) | |
| Erase Security Register(5) | **44h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Program Security Register(5) | **42h** | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) | |
| Read Security Register(5) | **48h** | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) | |
| Global Block Lock | **7Eh** | | | | | | |
| Global Block Unlock | **98h** | | | | | | |
| Read Block Lock | **3Dh** | A23-A16 | A15-A8 | A7-A0 | (L7-L0) | | |
| Individual Block Lock | **36h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Individual Block Unlock | **39h** | A23-A16 | A15-A8 | A7-A0 | | | |
| Erase / Program Suspend | **75h** | | | | | | |
| Erase / Program Resume | **7Ah** | | | | | | |
| Power-down | **B9h** | | | | | | |
| Enter 4-Byte Address Mode | **B7h** | | | | | | |
| Exit 4-Byte Address Mode | **E9h** | | | | | | |
| Enable Reset | **66h** | | | | | | |
| Reset Device | **99h** | | | | | | |



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### 8.1.3 Instruction Set Table 2 (Dual/Quad SPI Instructions,3-Byte Address Mode)

| Data Input Output | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 | Byte 8 | Byte 9 | Byte 10 |
|---|---|---|---|---|---|---|---|---|---|---|
| **Number of Clock**(1-1-2) | **8** | **8** | **8** | **8** | **8** | **4** | **4** | **4** | **4** | **4** |
| Fast Read Dual Output | **3Bh** | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0)(7) | … | … | | |
| Fast Read Dual Output with 4-Byte Address | **3Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | Dummy | (D7-D0)(7) | … | |
| **Number of Clock**(1-2-2) | **8** | **4** | **4** | **4** | **4** | **4** | **4** | **4** | **4** | **4** |
| Mftr./Device ID Dual I/O | **92h** | A23-A16 | A15-A8 | 00 | Dummy(11) | (MF7-MF0) | (ID7-ID0) | | | |
| Fast Read Dual I/O | **BBh** | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | (D7-D0) | … | | | |
| Fast Read Dual I/O with 4-Byte Address | **BCh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | (D7-D0) | … | | |
| **Number of Clock**(1-1-4) | **8** | **8** | **8** | **8** | **2** | **2** | **2** | **2** | **2** | **2** |
| Quad Input Page Program | **32h** | A23-A16 | A15-A8 | A7-A0 | (D7-D0)(9) | (D7-D0)(3) | … | | | |
| Quad Page Program with 4-Byte Address | **34h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | … | … | | |
| Fast Read Quad Output | **6Bh** | A23-A16 | A15-A8 | A7-A0 | Dummy | Dummy | Dummy | Dummy | (D7-D0)(9) | … |
| Fast Read Quad Output with 4-Byte Address | **6Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | Dummy | Dummy | Dummy | (D7-D0)(9) |
| **Number of Clock**(1-4-4) | **8** | **2** | **2** | **2** | **2** | **2** | **2** | **2** | **2** | **2** |
| Mftr./Device ID Quad I/O | **94h** | A23-A16 | A15-A8 | 00 | Dummy(11) | Dummy | Dummy | (MF7-MF0) | (ID7-ID0) | |
| Fast Read Quad I/O | **EBh** | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | Dummy | Dummy | (D7-D0) | … | |
| Fast Read Quad I/O with 4-Byte Address | **ECh** | A31-A24 | A23-A16 | A15-A8 | A7-A0f | Dummy(11) | Dummy | Dummy | (D7-D0) | … |



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### 8.1.4 Instruction Set Table 3 (Standard SPI, 4-Byte Address Mode)(1)

| Data Input Output | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|---|---|---|---|---|---|---|---|
| **Number of Clock**(1-1-1) | **8** | **8** | **8** | **8** | **8** | **8** | **8** |
| Write Enable | **06h** | | | | | | |
| Volatile SR Write Enable | **50h** | | | | | | |
| Write Disable | **04h** | | | | | | |
| Release Power-down | **ABh** | | | | | | |
| Device ID | **ABh** | Dummy | Dummy | Dummy | (ID7-ID0)(2) | | |
| Manufacturer/Device ID | **90h** | Dummy | Dummy | 00h | (MF7-MF0) | (ID7-ID0) | |
| JEDEC ID | **9Fh** | (MF7-MF0) | (ID15-ID8) | (ID7-ID0) | | | |
| Read Unique ID | **4Bh** | Dummy | Dummy | Dummy | Dummy | Dummy | (UID63-0) |
| Read Data | **03h** | **A31-A24** | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | |
| Read Data with 4-Byte Address | **13h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | (D7-D0) | |
| Fast Read | **0Bh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) |
| Fast Read with 4-Byte Address | **0Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) |
| Page Program | **02h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) |
| Page Program with 4-Byte Address | **12h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) |
| Sector Erase (4KB) | **20h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Sector Erase (4KB) with 4-Byte Address | **21h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Block Erase (32KB) | **52h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Block Erase (64KB) | **D8h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Block Erase (64KB) with 4-Byte Address | **DCh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Chip Erase | **C7h/60h** | | | | | | |
| Read Status Register-1 | **05h** | (S7-S0)(2) | | | | | |
| Write Status Register-1(4) | **01h** | (S7-S0)(4) | | | | | |
| Read Status Register-2 | **35h** | (S15-S8)(2) | | | | | |
| Write Status Register-2 | **31h** | (S15-S8) | | | | | |
| Read Status Register-3 | **15h** | (S23-S16)(2) | | | | | |
| Write Status Register-3 | **11h** | (S23-S16) | | | | | |
| Read Extended Addr. Reg. | **C8h** | (EA7-EA0)(2) | | | | | |
| Write Extended Addr. Reg. | **C5h** | (EA7-EA0) | | | | | |
| Read SFDP Register | **5Ah** | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) | |
| Erase Security Register(5) | **44h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Program Security Register(5) | **42h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0(3) |
| Read Security Register(5) | **48h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0) |
| Global Block Lock | **7Eh** | | | | | | |
| Global Block Unlock | **98h** | | | | | | |
| Read Block Lock | **3Dh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | (L7-L0) | |
| Individual Block Lock | **36h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Individual Block Unlock | **39h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | | |
| Erase / Program Suspend | **75h** | | | | | | |
| Erase / Program Resume | **7Ah** | | | | | | |
| Power-down | **B9h** | | | | | | |
| Enter 4-Byte Address Mode | **B7h** | | | | | | |
| Exit 4-Byte Address Mode | **E9h** | | | | | | |
| Enable Reset | **66h** | | | | | | |
| Reset Device | **99h** | | | | | | |



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### 8.1.5 Instruction Set Table 4 (Dual/Quad SPI Instructions, 4-Byte Address Mode)

| Data Input Output | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 | Byte 8 | Byte9 |
|---|---|---|---|---|---|---|---|---|---|
| **Number of Clock(1-1-2)** | **8** | **8** | **8** | **8** | **8** | **8** | **4** | **4** | |
| Fast Read Dual Output | **3Bh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0,…)(7) | | |
| Fast Read Dual Output with 4-Byte Address | **3Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | (D7-D0,…)(7) | | |
| **Number of Clock**(1-2-2) | **8** | **4** | **4** | **4** | **4** | **4** | **4** | **4** | |
| Mftr./Device ID Dual I/O | **92h** | A31-A24 | A23-A16 | A15-A8 | 00 | Dummy(11) | (MF7-MF0) | (ID7-ID0) | |
| Fast Read Dual I/O | **BBh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | (D7-D0) | | |
| Fast Read Dual I/O with 4-Byte Address | **BCh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | (D7-D0) | | |
| **Number of Clock**(1-1-4) | **8** | **8** | **8** | **8** | **8** | **4** | **4** | **4** | |
| Quad Input Page Program | **32h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | (D7-D0)(9) | (D7-D0)(3).. | | |
| Quad Page Program with 4-Byte Address | **34h** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | D7-D0 | D7-D0 | D7-D0 | D7-D0 |
| Fast Read Quad Output | **6Bh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | Dummy | (D7-D0)(9) | |
| Fast Read Quad Output with 4-Byte Address | **6Ch** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy | Dummy | (D7-D0)(9) | |
| **Number of Clock**(1-4-4) | **8** | **2** | **2** | **2** | **2** | **2** | **4** | **2** | **2** |
| Mftr./Device ID Quad I/O | **94h** | A31-A24 | A23-A16 | A15-A8 | 00 | Dummy(11) | Dummy | (MF7-MF0) | (ID7-ID0) |
| Fast Read Quad I/O | **EBh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | Dummy | (D7-D0) | |
| Fast Read Quad I/O with 4-Byte Address | **ECh** | A31-A24 | A23-A16 | A15-A8 | A7-A0 | Dummy(11) | Dummy | (D7-D0) | |



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**Notes:**

1. Data bytes are shifted with Most Significant Bit first. Byte fields with data in parenthesis “( )” indicate data output from the device on either 1, 2 or 4 IO pins.
2. The Status Register contents and Device ID will repeat continuously until /CS terminates the instruction.
3. At least one byte of data input is required for Page Program, Quad Page Program and Program Security Registers, up to 256 bytes of data input. If more than 256 bytes of data are sent to the device, the addressing will wrap to the beginning of the page and overwrite previously sent data.
4. Write Status Register-1 (01h) can also be used to program Status Register-1&2, see section 8.2.5.
5. Security Register Address:
   Security Register 1: A23-16 = 00h; A15-8 = 10h; A7-0 = byte address
   Security Register 2: A23-16 = 00h; A15-8 = 20h; A7-0 = byte address
   Security Register 3: A23-16 = 00h; A15-8 = 30h; A7-0 = byte address
6. Dual SPI address input format:
   IO0 = A22, A20, A18, A16, A14, A12, A10, A8 A6, A4, A2, A0, M6, M4, M2, M0
   IO1 = A23, A21, A19, A17, A15, A13, A11, A9 A7, A5, A3, A1, M7, M5, M3, M1
7. Dual SPI data output format:
   IO0 = (D6, D4, D2, D0)
   IO1 = (D7, D5, D3, D1)
8. Quad SPI address input format:
   IO0 = A20, A16, A12, A8, A4, A0, M4, M0
   IO1 = A21, A17, A13, A9, A5, A1, M5, M1
   IO2 = A22, A18, A14, A10, A6, A2, M6, M2
   IO3 = A23, A19, A15, A11, A7, A3, M7, M3
9. Quad SPI data input/output format:
   IO0 = (D4, D0, …..)
   IO1 = (D5, D1, …..)
   IO2 = (D6, D2, …..)
   IO3 = (D7, D3, …..)
10. Fast Read Quad I/O data output format:
    IO0 = (x, x, x, x, D4, D0, D4, D0)
    IO1 = (x, x, x, x, D5, D1, D5, D1)
    IO2 = (x, x, x, x, D6, D2, D6, D2)
    IO3 = (x, x, x, x, D7, D3, D7, D3)
11. The first dummy is M7-M0 should be set to Fxh or FFh.



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## 8.2 Instruction Descriptions

### 8.2.1 Write Enable (06h)

The Write Enable instruction (Figure 5) sets the Write Enable Latch (WEL) bit in the Status Register to a 1. The WEL bit must be set prior to every Page Program, Quad Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register and Erase/Program Security Registers instruction. The Write Enable instruction is entered by driving /CS low, shifting the instruction code “06h” into the Data Input (DI) pin on the rising edge of CLK, and then driving /CS high.

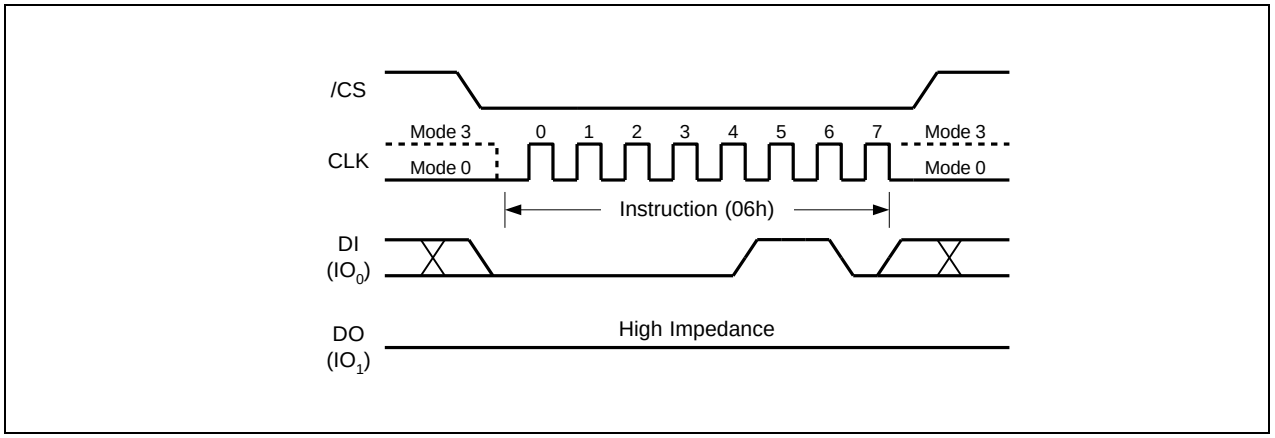



Figure 5. Write Enable Instruction

### 8.2.2 Write Enable for Volatile Status Register (50h)

The non-volatile Status Register bits described in section 7.1 can also be written to as volatile bits. This gives more flexibility to change the system configuration and memory protection schemes quickly without waiting for the typical non-volatile bit write cycles or affecting the endurance of the Status Register non-volatile bits. To write the volatile values into the Status Register bits, the Write Enable for Volatile Status Register (50h) instruction must be issued prior to a Write Status Register (01h) instruction. Write Enable for Volatile Status Register instruction (Figure 6) will not set the Write Enable Latch (WEL) bit, it is only valid for the Write Status Register instruction to change the volatile Status Register bit values.

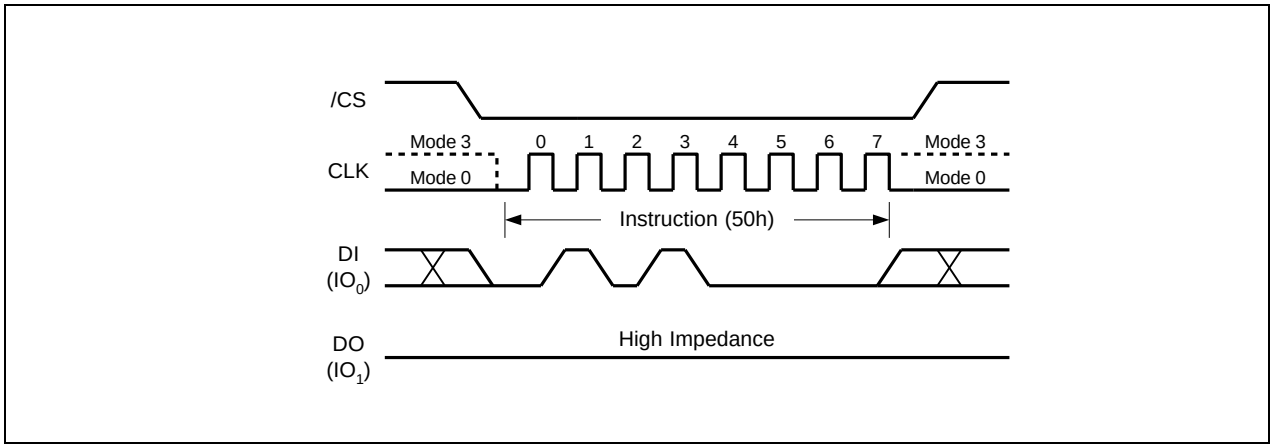



Figure 6. Write Enable for Volatile Status Register Instruction



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### 8.2.3 Write Disable (04h)

The Write Disable instruction (Figure 7) resets the Write Enable Latch (WEL) bit in the Status Register to a 0. The Write Disable instruction is entered by driving /CS low, shifting the instruction code “04h” into the DI pin and then driving /CS high. Note that the WEL bit is automatically reset after Power-up and upon completion of the Write Status Register, Erase/Program Security Registers, Page Program, Quad Page Program, Sector Erase, Block Erase, Chip Erase and Reset instructions.

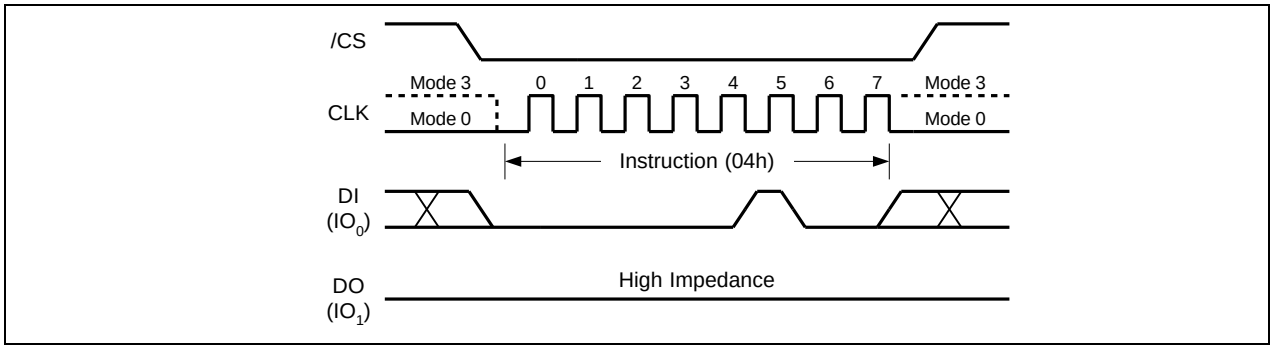



Figure 7. Write Disable Instruction for SPI Mode

### 8.2.4 Read Status Register-1 (05h), Status Register-2 (35h) & Status Register-3 (15h)

The Read Status Register instructions allow the 8-bit Status Registers to be read. The instruction is entered by driving /CS low and shifting the instruction code “05h” for Status Register-1, “35h” for Status Register-2 or “15h” for Status Register-3 into the DI pin on the rising edge of CLK. The status register bits are then shifted out on the DO pin at the falling edge of CLK with most significant bit (MSB) first as shown in Figure 8. Refer to section 7.1 for Status Register descriptions.

The Read Status Register instruction may be used at any time, even while a Program, Erase or Write Status Register cycle is in progress. This allows the BUSY status bit to be checked to determine when the cycle is complete and if the device can accept another instruction. The Status Register can be read continuously, as shown in Figure 8. The instruction is completed by driving /CS high.

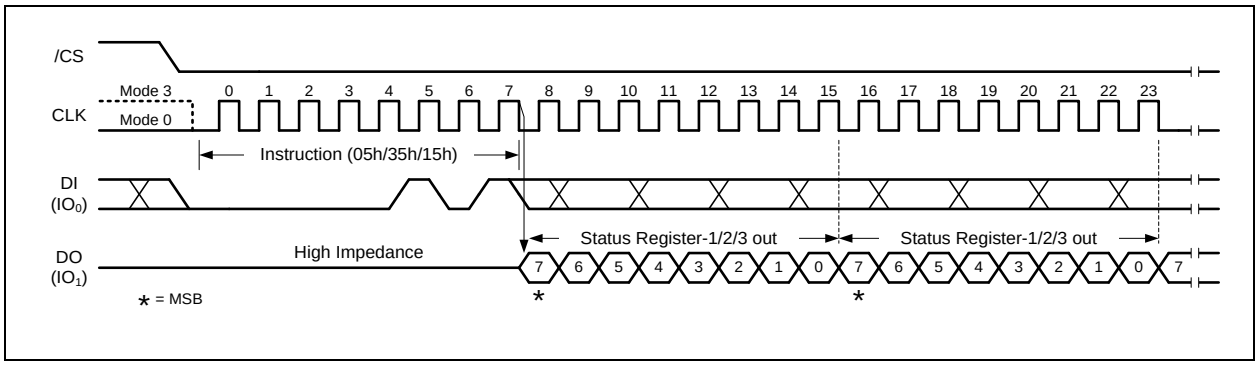



Figure 8. Read Status Register Instruction



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### 8.2.5 Write Status Register-1 (01h), Status Register-2 (31h) & Status Register-3 (11h)

The Write Status Register instruction allows the Status Registers to be written. The writable Status Register bits include: SRP, TB, BP[3:0] in Status Register-1; CMP, LB[3:1], QE, SRL in Status Register-2;, DRV1, DRV0, WPS & ADP in Status Register-3. All other Status Register bit locations are read-only and will not be affected by the Write Status Register instruction. LB[3:1] are non-volatile OTP bits, once it is set to 1, it cannot be cleared to 0.

To write non-volatile Status Register bits, a standard Write Enable (06h) instruction must previously have been executed for the device to accept the Write Status Register instruction (Status Register bit WEL must equal 1). Once write enabled, the instruction is entered by driving /CS low, sending the instruction code “01h/31h/11h”, and then writing the status register data byte as illustrated in Figure 9a & 9b.

To write volatile Status Register bits, a Write Enable for Volatile Status Register (50h) instruction must have been executed prior to the Write Status Register instruction (Status Register bit WEL remains 0). However, SRL and LB[3:1] cannot be changed from “1” to “0” because of the OTP protection for these bits. Upon power off or the execution of a Software/Hardware Reset or Power-down instruction, the volatile Status Register bit values will be lost, and the non-volatile Status Register bit values will be restored.

During non-volatile Status Register write operation (06h combined with 01h/31h/11h), after /CS is driven high, the self-timed Write Status Register cycle will commence for a time duration of $t_W$ (See AC Characteristics). While the Write Status Register cycle is in progress, the Read Status Register instruction may still be accessed to check the status of the BUSY bit. The BUSY bit is a 1 during the Write Status Register cycle and a 0 when the cycle is finished and ready to accept other instructions again. After the Write Status Register cycle has finished, the Write Enable Latch (WEL) bit in the Status Register will be cleared to 0.

During volatile Status Register write operation (50h combined with 01h/31h/11h), after /CS is driven high, the Status Register bits will be refreshed to the new values within the time period of $t_{SHSL2}$ (See AC Characteristics). BUSY bit will remain 0 during the Status Register bit refresh period.

Refer to section 7.1 for Status Register descriptions.

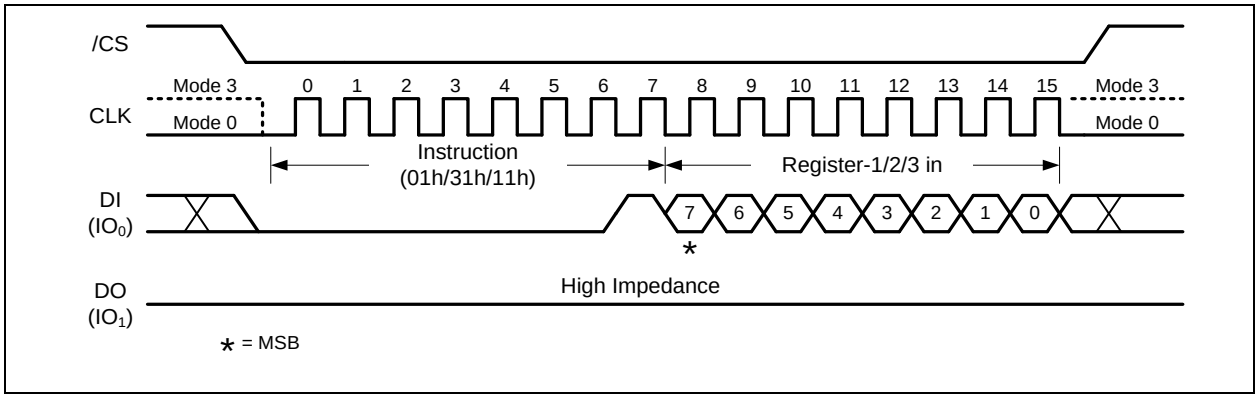



Figure 9a. Write Status Register-1/2/3 Instruction



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The W25Q256JW is also backward compatible to Winbond's previous generations of serial flash memories, in which the Status Register-1&2 can be written using a single "Write Status Register-1 (01h)" command. To complete the Write Status Register-1&2 instruction, the /CS pin must be driven high after the sixteenth bit of data that is clocked in as shown in Figure 9c & 9d. If /CS is driven high after the eighth clock, the Write Status Register-1 (01h) instruction will only program the Status Register-1, the Status Register-2 will not be affected (Previous generations will clear CMP and QE bits).

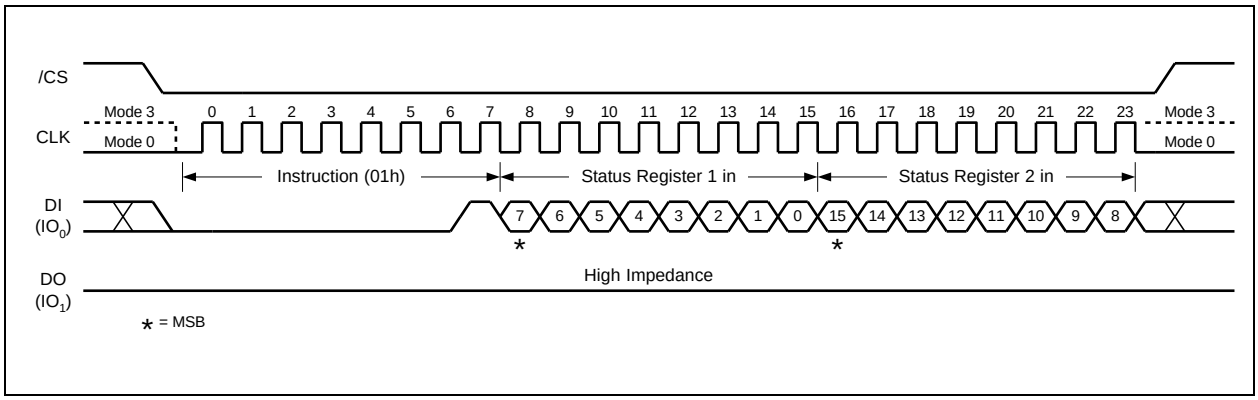



Figure 9c. Write Status Register-1/2 Instruction



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### 8.2.6 Read Extended Address Register (C8h)

When the device is in the 3-Byte Address Mode, the Extended Address Register is used as the 4th address byte A[31:24] to access memory regions beyond 128Mb. The Read Extended Address Register instruction is entered by driving /CS low and shifting the instruction code "C8h" into the DI pin on the rising edge of CLK. The Extended Address Register bits are then shifted out on the DO pin at the falling edge of CLK with most significant bit (MSB) first as shown in Figure 10.

When the device is in the 4-Byte Address Mode, the Extended Address Register is not used.

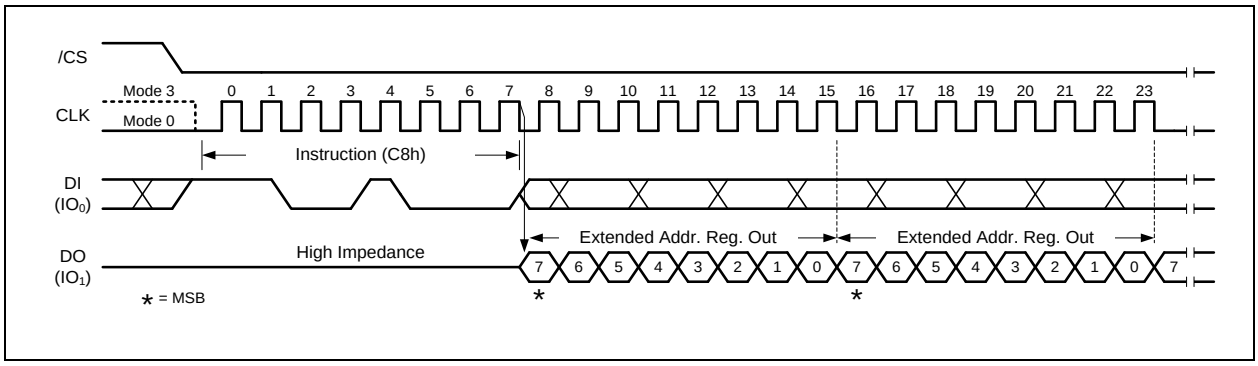



Figure 10a. Read Extended Address Register Instruction



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### 8.2.7 Write Extended Address Register (C5h)

The Extended Address Register is a volatile register that stores the 4th byte address (A31-A24) when the device is operating in the 3-Byte Address Mode (ADS=0). To write the Extended Address Register bits, a Write Enable (06h) instruction must previously have been executed for the device to accept the Write Extended Address Register instruction (Status Register bit WEL must equal 1). Once write enabled, the instruction is entered by driving /CS low, sending the instruction code “C5h”, and then writing the Extended Address Register data byte as illustrated in Figure 11.

Upon power up or the execution of a Software/Hardware Reset, the Extended Address Register bit values will be cleared to 0.

The Extended Address Register is only effective when the device is in the 3-Byte Address Mode. When the device operates in the 4-Byte Address Mode (ADS=1), any command with address input of A31-A24 will replace the Extended Address Register values. It is recommended to check and update the Extended Address Register if necessary when the device is switched from 4-Byte to 3-Byte Address Mode.

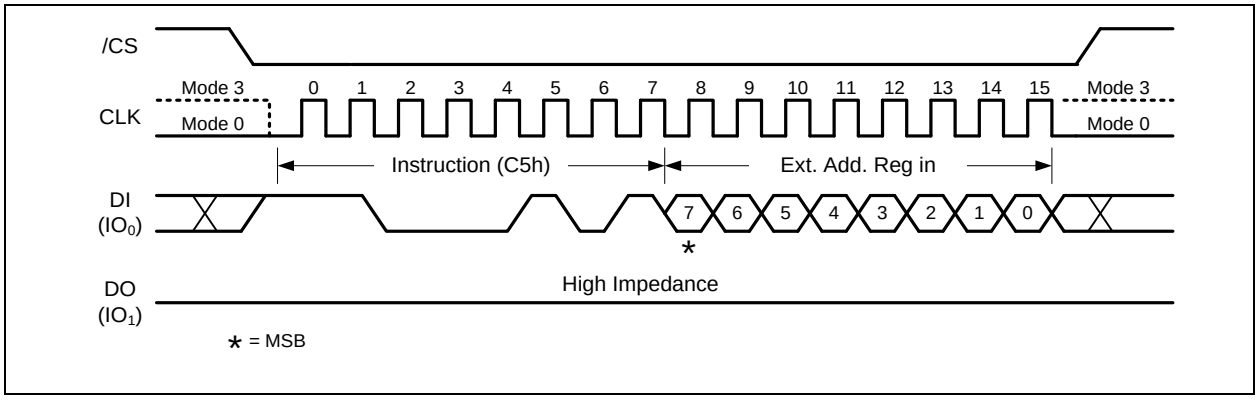



Figure 11. Write Extended Address Register Instruction



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### 8.2.8 Enter 4-Byte Address Mode (B7h)

The Enter 4-Byte Address Mode instruction (Figure 12) will allow 32-bit address (A31-A0) to be used to access the memory array beyond 128Mb. The Enter 4-Byte Address Mode instruction is entered by driving /CS low, shifting the instruction code “B7h” into the DI pin and then driving /CS high.

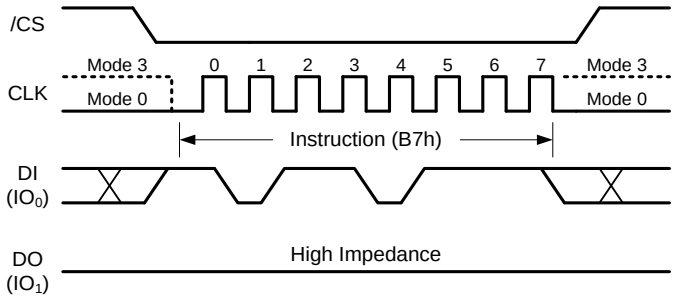



Figure 12. Enter 4-Byte Address Mode instruction

### 8.2.9 Exit 4-Byte Address Mode (E9h)

In order to be backward compatible, the Exit 4-Byte Address Mode instruction (Figure 13) will only allow 24-bit address (A23-A0) to be used to access the memory array up to 128Mb. The Extended Address Register must be used to access the memory array beyond 128Mb. The Exit 4-Byte Address Mode instruction is entered by driving /CS low, shifting the instruction code “E9h” into the DI pin and then driving /CS high.

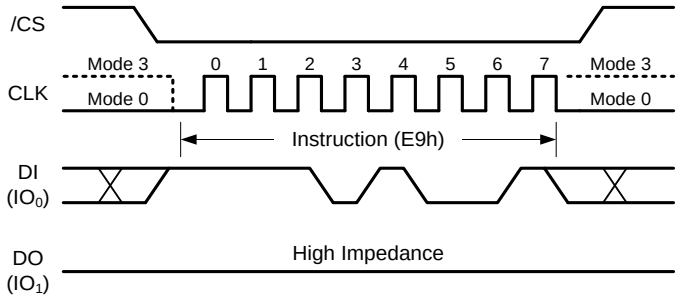



Figure 13. Exit 4-Byte Address Mode instruction



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### 8.2.10 Read Data (03h)

The Read Data instruction allows one or more data bytes to be sequentially read from the memory. The instruction is initiated by driving the /CS pin low and then shifting the instruction code “03h” followed by a 32/24-bit address (A31/A23-A0) into the DI pin, no matter in 3-byte address mode or 4-byte address mode. The code and address bits are latched on the rising edge of the CLK pin. After the address is received, the data byte of the addressed memory location will be shifted out on the DO pin at the falling edge of CLK with most significant bit (MSB) first. The address is automatically incremented to the next higher address after each byte of data is shifted out allowing for a continuous stream of data. This means that the entire memory can be accessed with a single instruction as long as the clock continues. The instruction is completed by driving /CS high.

The Read Data instruction sequence is shown in Figure 14. If a Read Data instruction is issued while an Erase, Program or Write cycle is in process (BUSY=1) the instruction is ignored and will not have any effects on the current cycle. The Read Data instruction allows clock rates from D.C. to a maximum of $f_R$ (see AC Electrical Characteristics).

The Read Data (03h) instruction is only supported in Standard SPI mode.

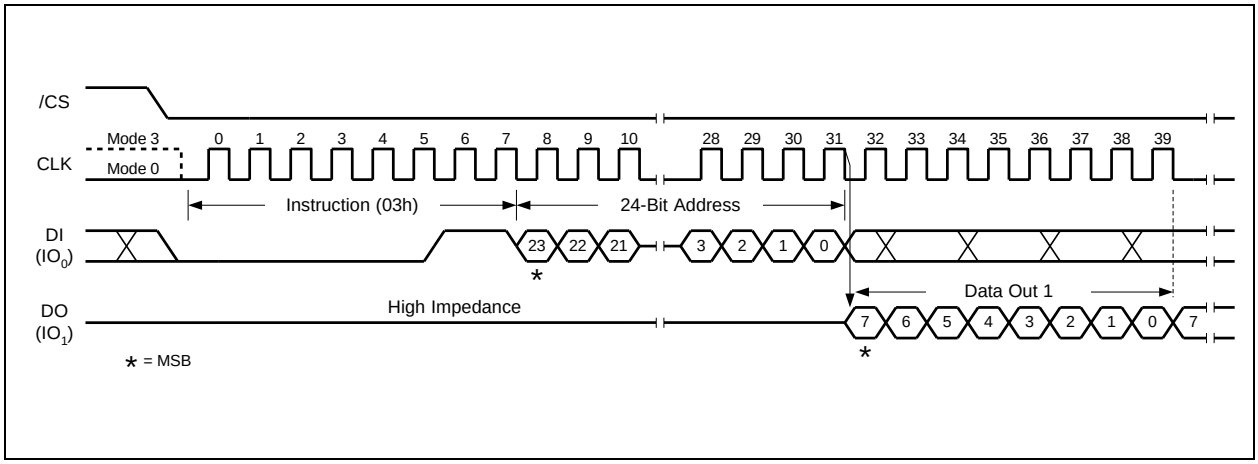



Figure 14. Read Data Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.11 Read Data with 4-Byte Address (13h)

The Read Data with 4-Byte Address instruction is similar to the Read Data (03h) instruction. Instead of 24-bit address, 32-bit address is needed following the instruction code 13h. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Read Data with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Read Data with 4-Byte Address instruction sequence is shown in Figure 15. If this instruction is issued while an Erase, Program or Write cycle is in process (BUSY=1) the instruction is ignored and will not have any effects on the current cycle. The Read Data with 4-Byte Address instruction allows clock rates from D.C. to a maximum of $f_R$ (see AC Electrical Characteristics).

The Read Data with 4-Byte Address (13h) instruction is only supported in Standard SPI mode.

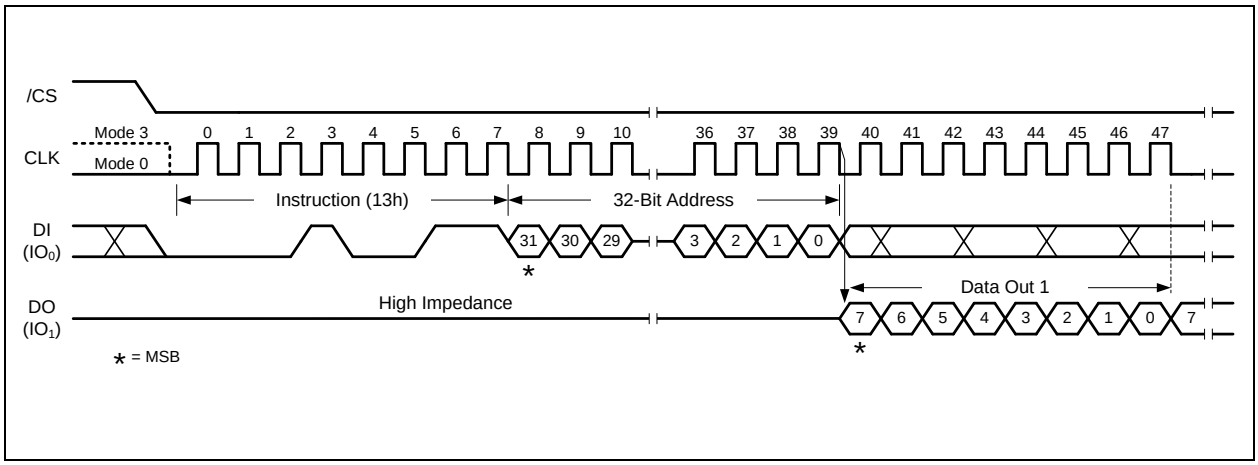



Figure 15. Read Data with 4-Byte Address Instruction



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### 8.2.12 Fast Read (0Bh)

The Fast Read instruction is similar to the Read Data instruction except that it can operate at the highest possible frequency of FR (see AC Electrical Characteristics). This is accomplished by adding eight "dummy" clocks after the 24/32-bit address as shown in Figure 16. The dummy clocks allow the devices internal circuits additional time for setting up the initial address. During the dummy clocks the data value on the DO pin is a "don't care".

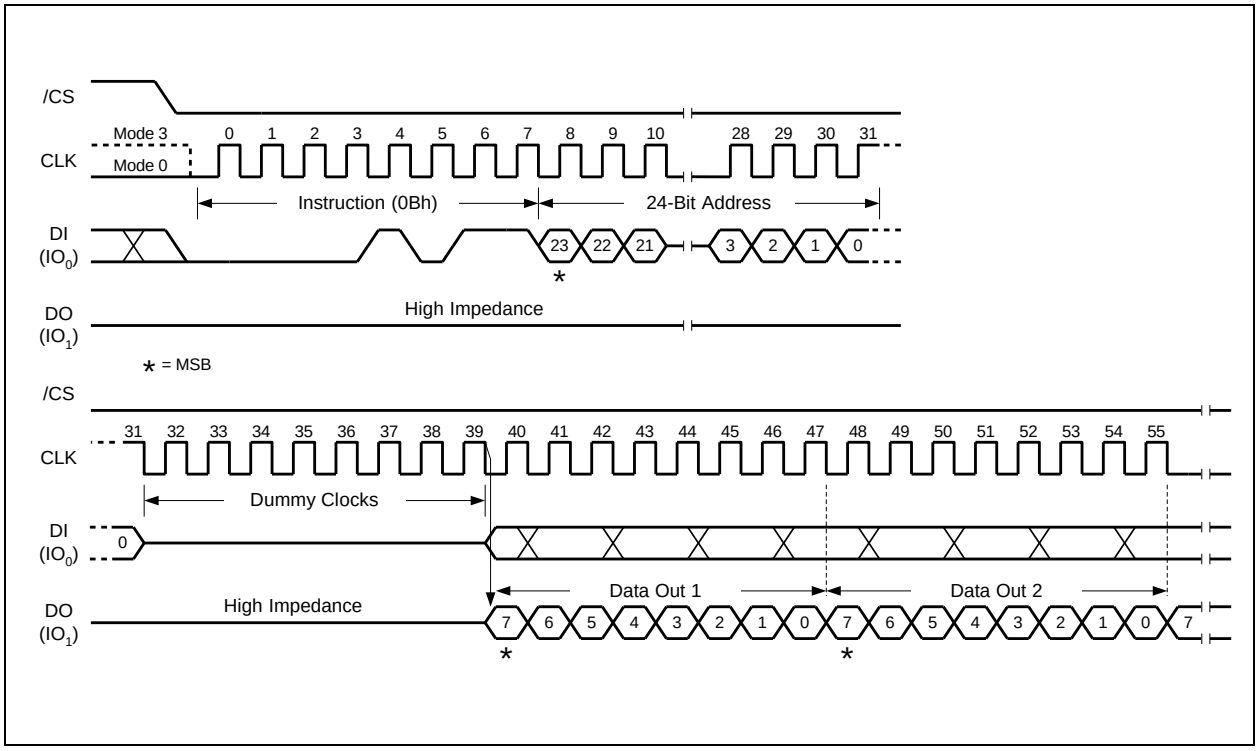



Figure 16. Fast Read Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.13 Fast Read with 4-Byte Address (0Ch)

The Fast Read with 4-Byte Address instruction is similar to the Fast Read instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Read Data with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Fast Read with 4-Byte Address (0Ch) instruction is only supported in Standard SPI mode.

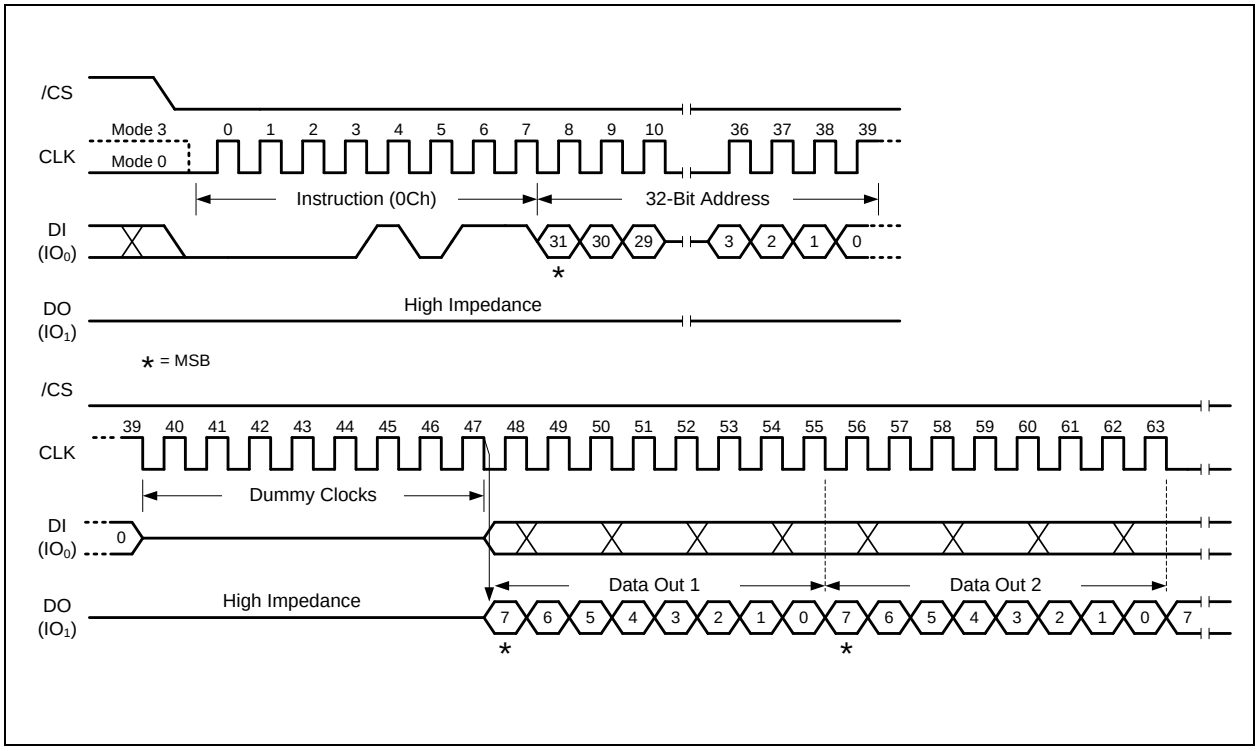



Figure 18. Fast Read with 4-Byte Address Instruction



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### 8.2.14 Fast Read Dual Output (3Bh)

The Fast Read Dual Output (3Bh) instruction is similar to the standard Fast Read (0Bh) instruction except that data is output on two pins; $IO_0$ and $IO_1$. This allows data to be transferred at twice the rate of standard SPI devices. The Fast Read Dual Output instruction is ideal for quickly downloading code from Flash to RAM upon power-up or for applications that cache code-segments to RAM for execution.

Similar to the Fast Read instruction, the Fast Read Dual Output instruction can operate at the highest possible frequency of $F_R$ (see AC Electrical Characteristics). This is accomplished by adding eight "dummy" clocks after the 24/32-bit address as shown in Figure 19. The dummy clocks allow the device's internal circuits additional time for setting up the initial address. The input data during the dummy clocks is "don't care". However, the $IO_0$ pin should be high-impedance prior to the falling edge of the first data out clock.

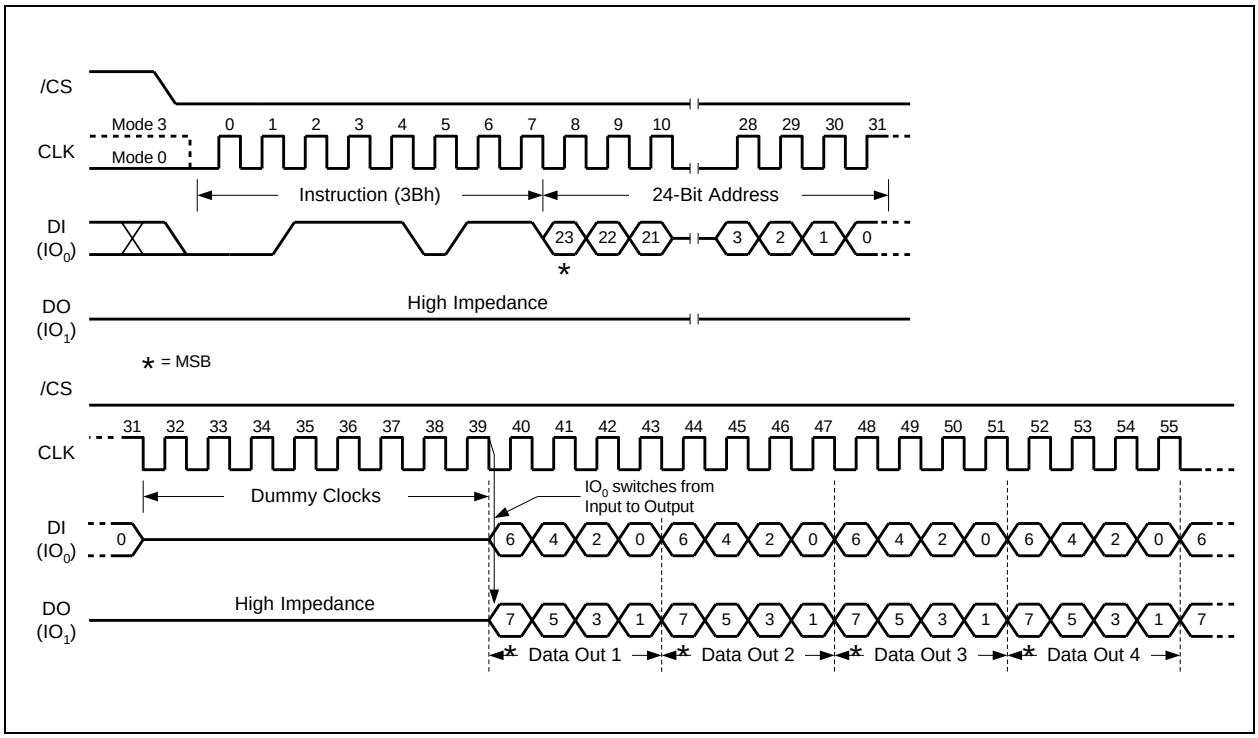



Figure 19. Fast Read Dual Output Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.15 Fast Read Dual Output with 4-Byte Address (3Ch)

The Fast Read Dual Output with 4-Byte Address instruction is similar to the Fast Read Dual Output instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Fast Read Dual Output with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Fast Read Dual Output with 4-Byte Address (3Ch) instruction is only supported in Standard SPI mode.

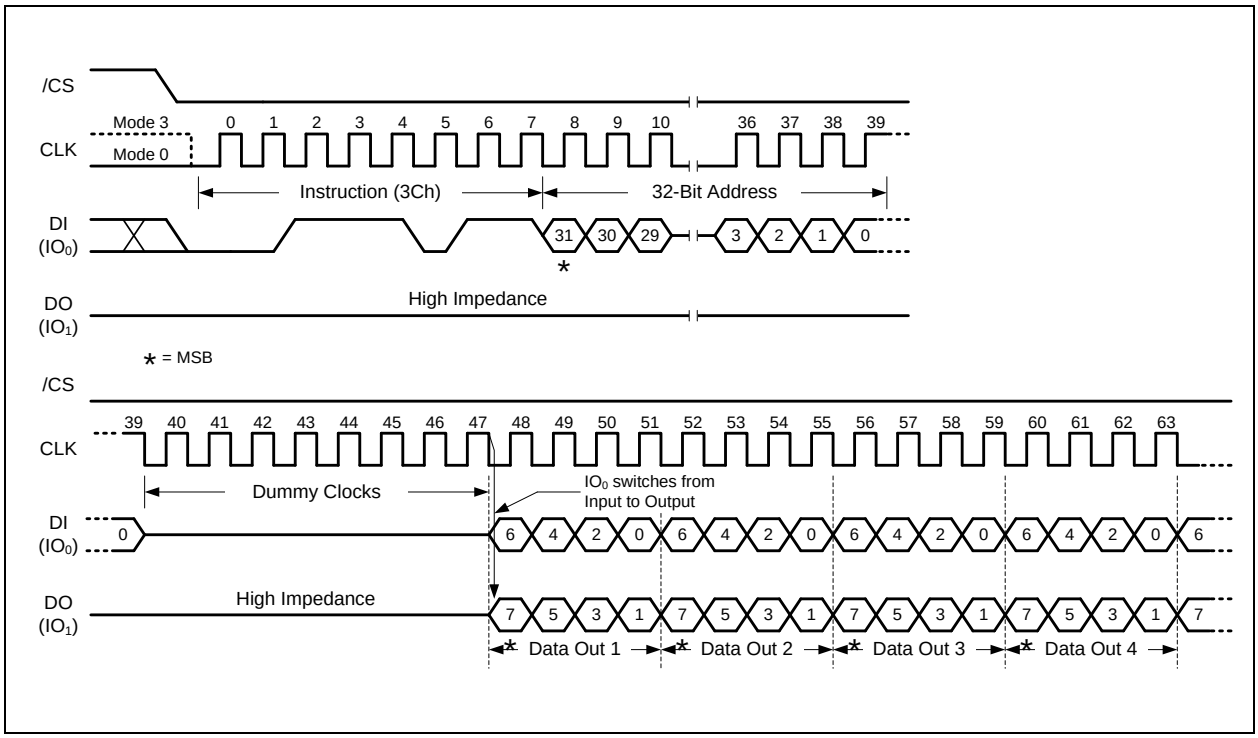



Figure 20. Fast Read Dual Output with 4-Byte Address Instruction



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### 8.2.16 Fast Read Quad Output (6Bh)

The Fast Read Quad Output (6Bh) instruction is similar to the Fast Read Dual Output (3Bh) instruction except that data is output on four pins, $IO_0$, $IO_1$, $IO_2$, and $IO_3$. The Quad Enable (QE) bit in Status Register-2 must be set to 1 before the device will accept the Fast Read Quad Output Instruction. The Fast Read Quad Output Instruction allows data to be transferred at four times the rate of standard SPI devices.

The Fast Read Quad Output instruction can operate at the highest possible frequency of FR (see AC Electrical Characteristics). This is accomplished by adding eight "dummy" clocks after the 24/32-bit address as shown in Figure 21. The dummy clocks allow the device's internal circuits additional time for setting up the initial address. The input data during the dummy clocks is "don't care". However, the IO pins should be high-impedance prior to the falling edge of the first data out clock.

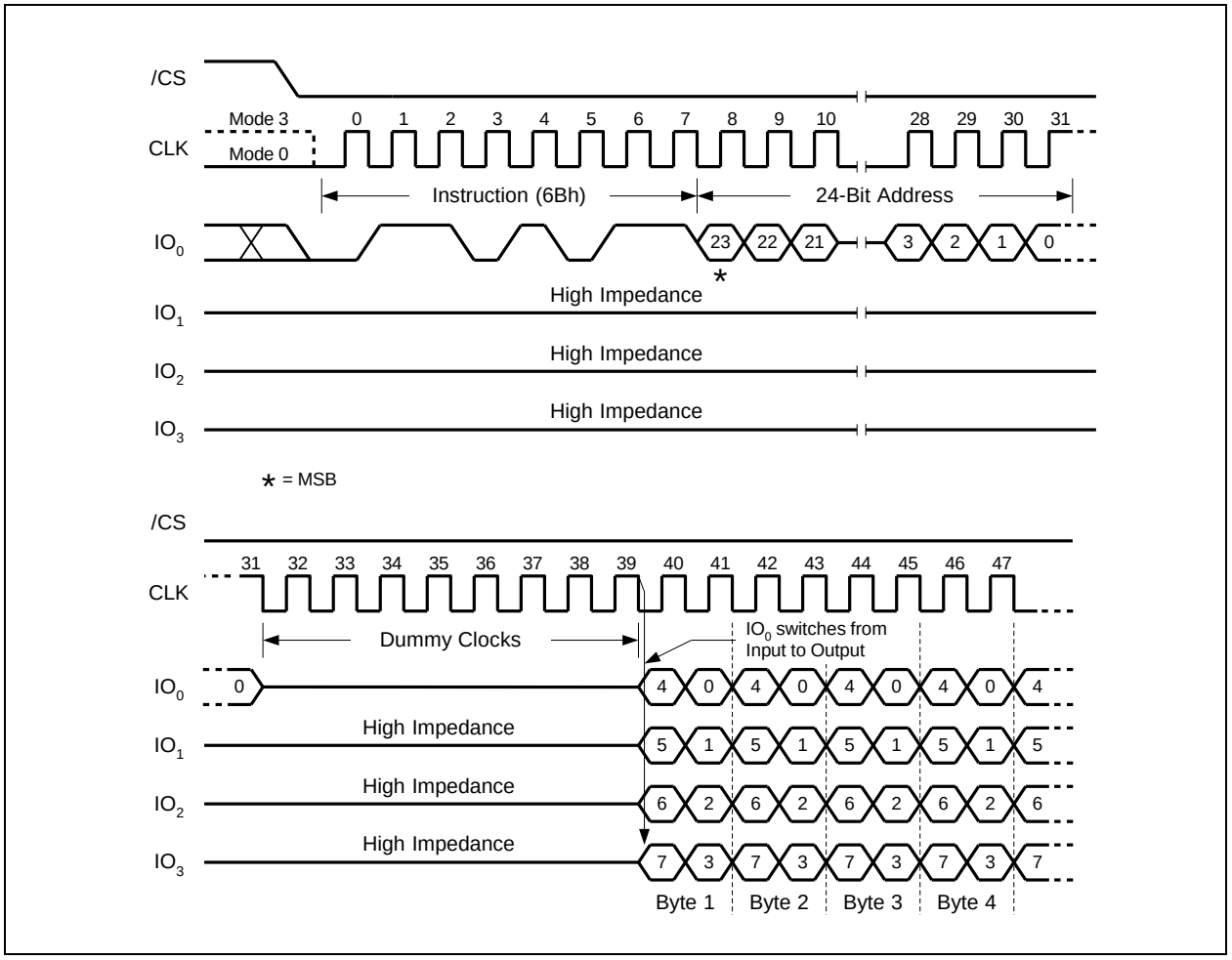



Figure 21. Fast Read Quad Output Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.17 Fast Read Quad Output with 4-Byte Address (6Ch)

The Fast Read Quad Output with 4-Byte Address instruction is similar to the Fast Read Quad Output instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Fast Read Quad Output with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Fast Read Quad Output with 4-Byte Address (6Ch) instruction is only supported in Standard SPI mode.

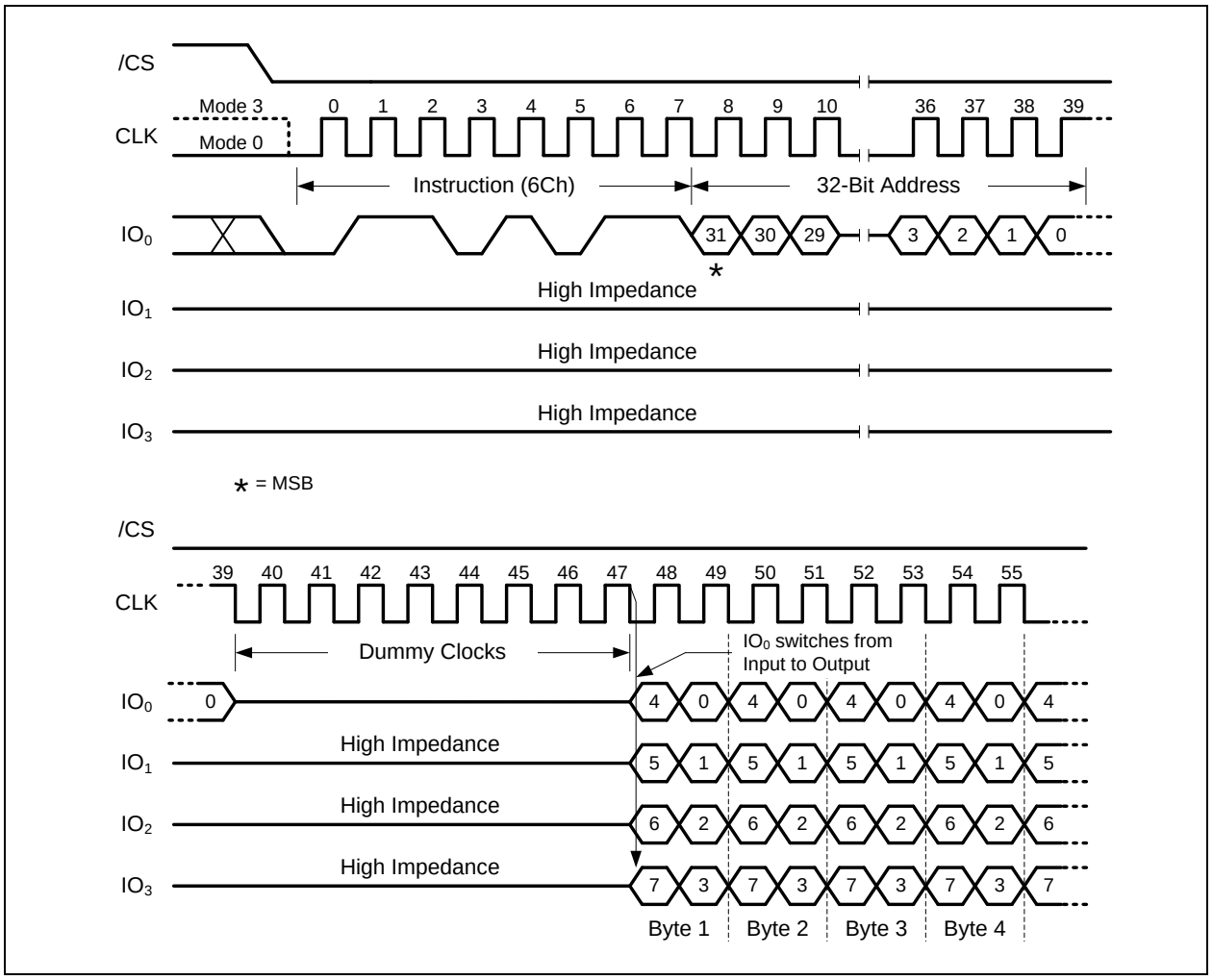



Figure 22. Fast Read Quad Output with 4-Byte Address Instruction



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### 8.2.18 Fast Read Dual I/O (BBh)

The Fast Read Dual I/O (BBh) instruction allows for improved random access while maintaining two IO pins, $IO_0$ and $IO_1$. It is similar to the Fast Read Dual Output (3Bh) instruction but with the capability to input the Address bits (A23/A31-0) two bits per clock. This reduced instruction overhead may allow for code execution (XIP) directly from the Dual SPI in some applications.

Similar to the Fast Read Dual Output (3Bh) instruction, the Fast Read Dual I/O instruction can operate at the highest possible frequency of $F_R$ (see AC Electrical Characteristics). This is accomplished by adding four “dummy” clocks after the 24/32-bit address as shown in Figure 23. The dummy clocks allow the device's internal circuits additional time for setting up the initial address. The input data during the dummy clocks is “don’t care”. However, the $IO_0$ pin should be high-impedance prior to the falling edge of the first data out clock.

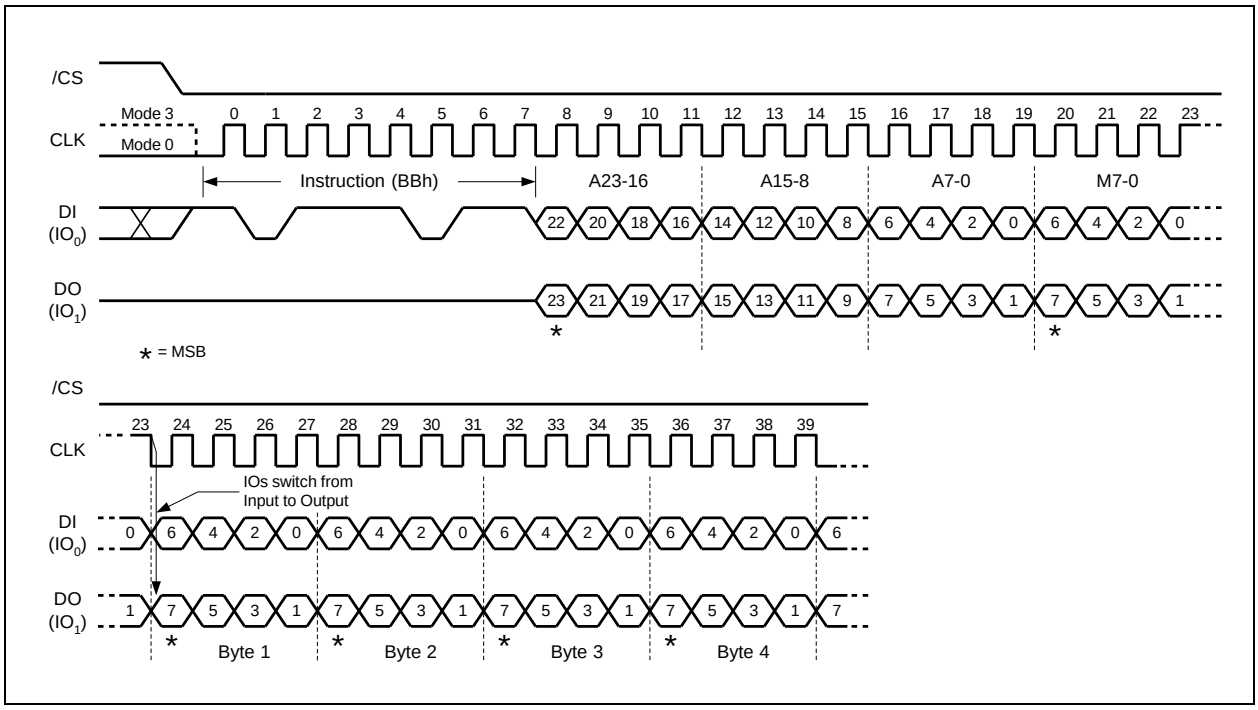



Figure 23a. Fast Read Dual I/O (M7-M0 should be set to FFh)

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.19 Fast Read Dual I/O with 4-Byte Address (BCh)

The Fast Read Dual I/O with 4-Byte Address instruction is similar to the Fast Read Dual I/O instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Fast Read Dual I/O with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Fast Read Dual I/O with 4-Byte Address (BCh) instruction is only supported in Standard SPI mode.

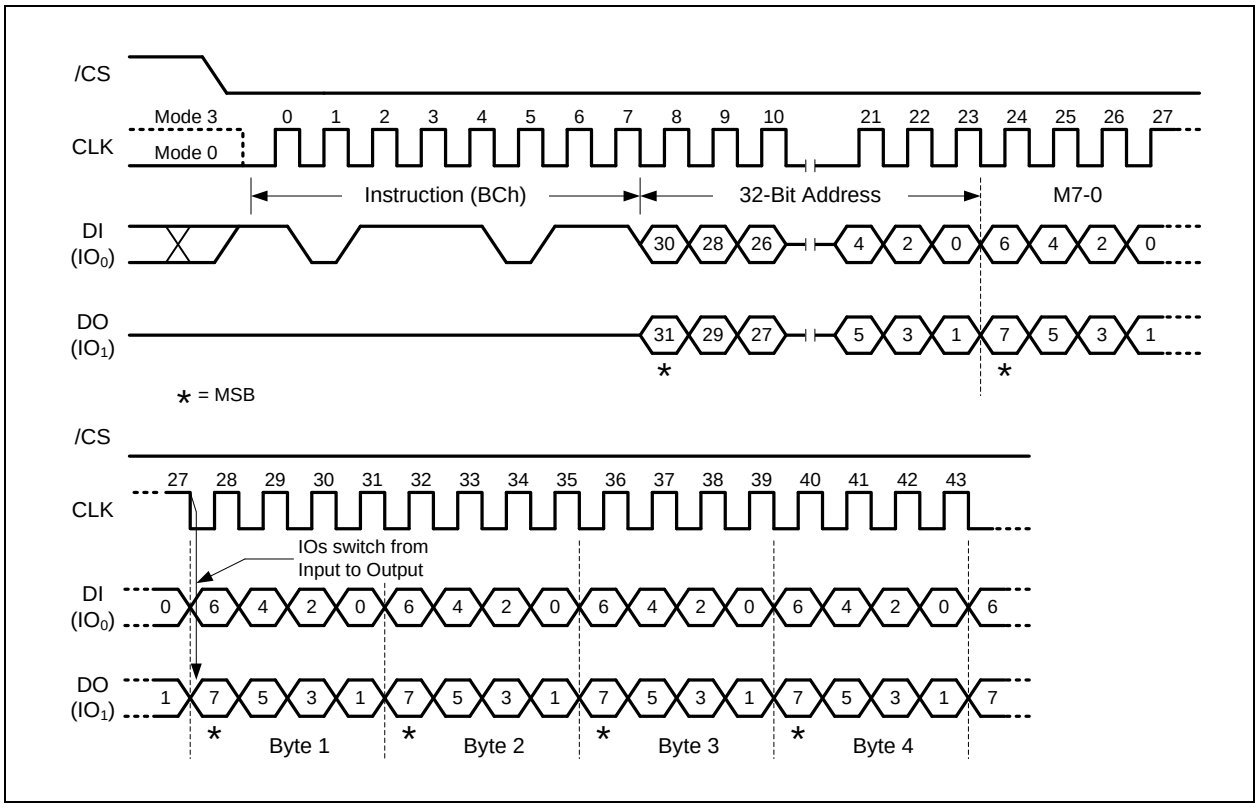



Figure 25a. Fast Read Dual I/O w/ 4-Byte Addr. (M7-M0 shuld set to FFh, SPI Mode only)



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### 8.2.20 Fast Read Quad I/O (EBh)

The Fast Read Quad I/O (EBh) instruction is similar to the Fast Read Dual I/O (BBh) instruction except that address and data bits are input and output through four pins $IO_0$, $IO_1$, $IO_2$ and $IO_3$ and four Dummy clocks are required in SPI mode prior to the data output. The Quad I/O dramatically reduces instruction overhead allowing faster random access for code execution (XIP) directly from the Quad SPI. The Quad Enable bit (QE) of Status Register-2 must be set to enable the Fast Read Quad I/O Instruction.

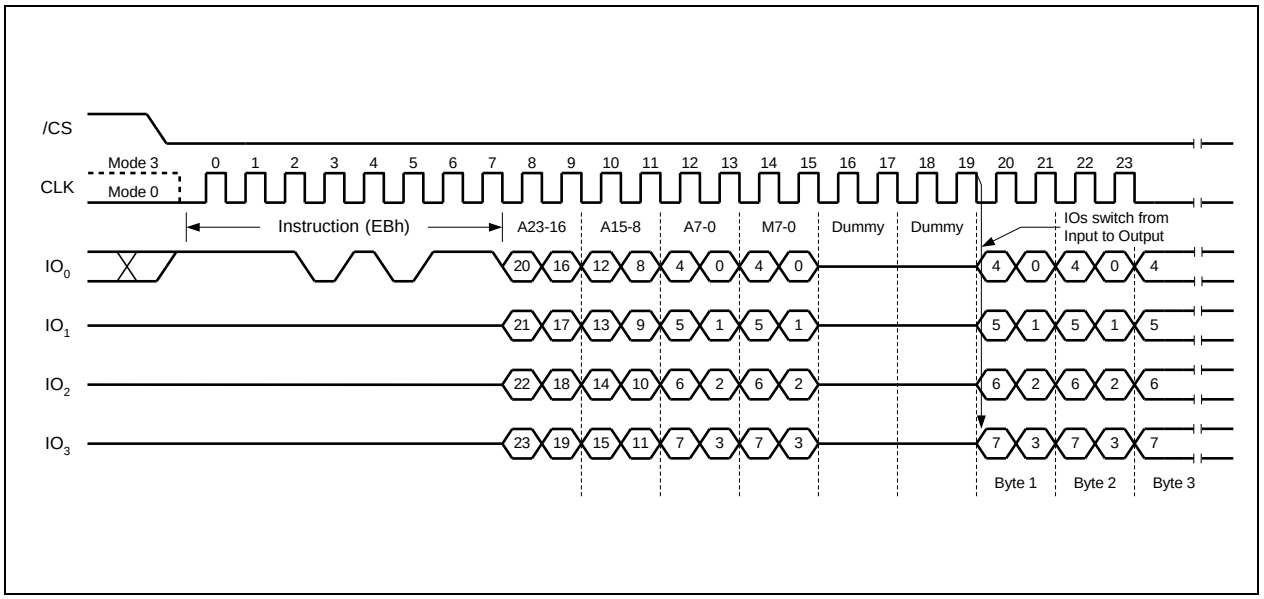



Figure 26a. Fast Read Quad I/O (M7-M0 should be set to FFh)

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.21 Fast Read Quad I/O with 4-Byte Address (ECh)

The Fast Read Quad I/O with 4-Byte Address instruction is similar to the Fast Read Dual I/O instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Fast Read Quad I/O with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

The Fast Read Quad I/O with 4-Byte Address (ECh) instruction is only supported in Standard SPI mode.

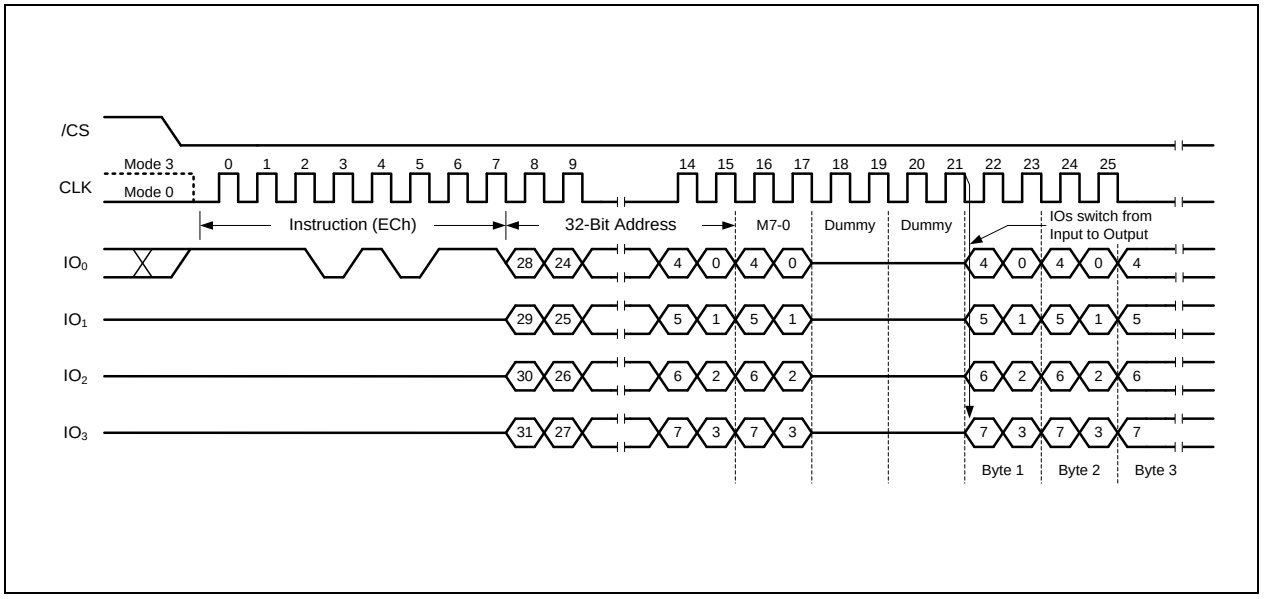



Figure 28. Fast Read Quad I/O w/ 4-Byte Addr. (M7-M0 should be set to FFh)



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### 8.2.22 Page Program (02h)

The Page Program instruction allows from one byte to 256 bytes (a page) of data to be programmed at previously erased (FFh) memory locations. A Write Enable instruction must be executed before the device will accept the Page Program Instruction (Status Register bit WEL= 1). The instruction is initiated by driving the /CS pin low then shifting the instruction code “02h” followed by a 24/32-bit address (A23/A31-A0) and at least one data byte, into the DI pin. The /CS pin must be held low for the entire length of the instruction while data is being sent to the device. The Page Program instruction sequence is shown in Figure 32.

If an entire 256 byte page is to be programmed, the last address byte (the 8 least significant address bits) should be set to 0. If the last address byte is not zero, and the number of clocks exceeds the remaining page length, the addressing will wrap to the beginning of the page. In some cases, less than 256 bytes (a partial page) can be programmed without having any effect on other bytes within the same page. One condition to perform a partial page program is that the number of clocks cannot exceed the remaining page length. If more than 256 bytes are sent to the device the addressing will wrap to the beginning of the page and overwrite previously sent data.

As with the write and erase instructions, the /CS pin must be driven high after the eighth bit of the last byte has been latched. If this is not done the Page Program instruction will not be executed. After /CS is driven high, the self-timed Page Program instruction will commence for a time duration of tpp (See AC Characteristics). While the Page Program cycle is in progress, the Read Status Register instruction may still be accessed for checking the status of the BUSY bit. The BUSY bit is a 1 during the Page Program cycle and becomes a 0 when the cycle is finished and the device is ready to accept other instructions again. After the Page Program cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Page Program instruction will not be executed if the addressed page is protected by the Block Protect (CMP, TB, BP3, BP2, BP1, and BP0) bits or the Individual Block/Sector Locks.

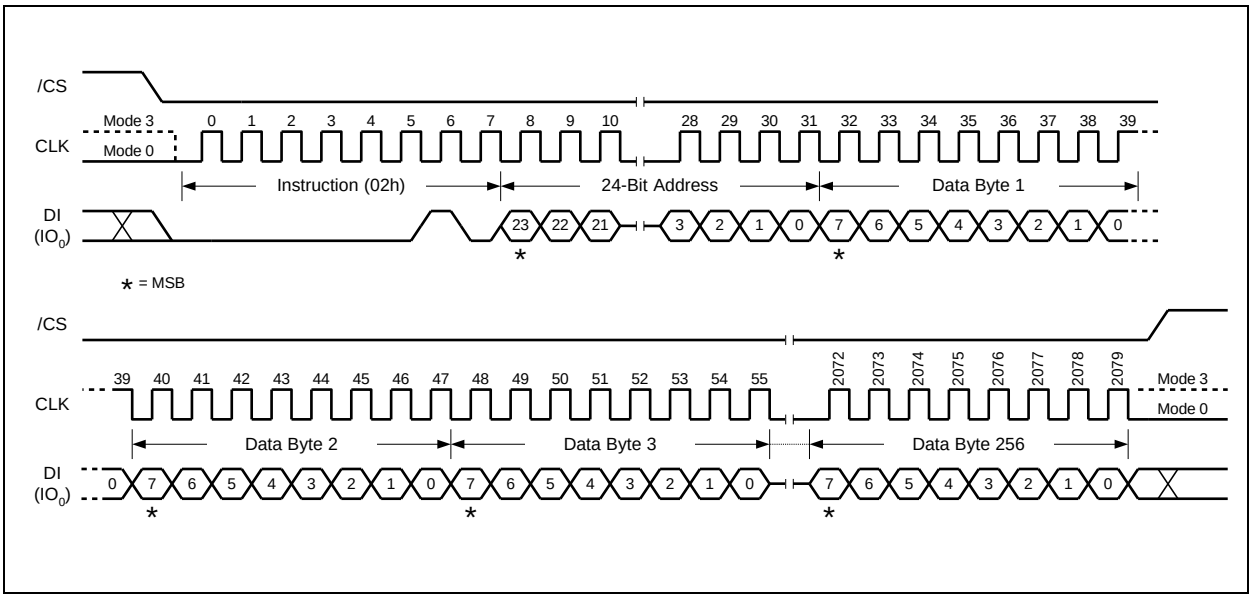



Figure 32. Page Program Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.23 Page Program with 4-Byte Address (12h)

The Page Program with 4-Byte Address instruction is similar to the Page Program instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Page Program with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

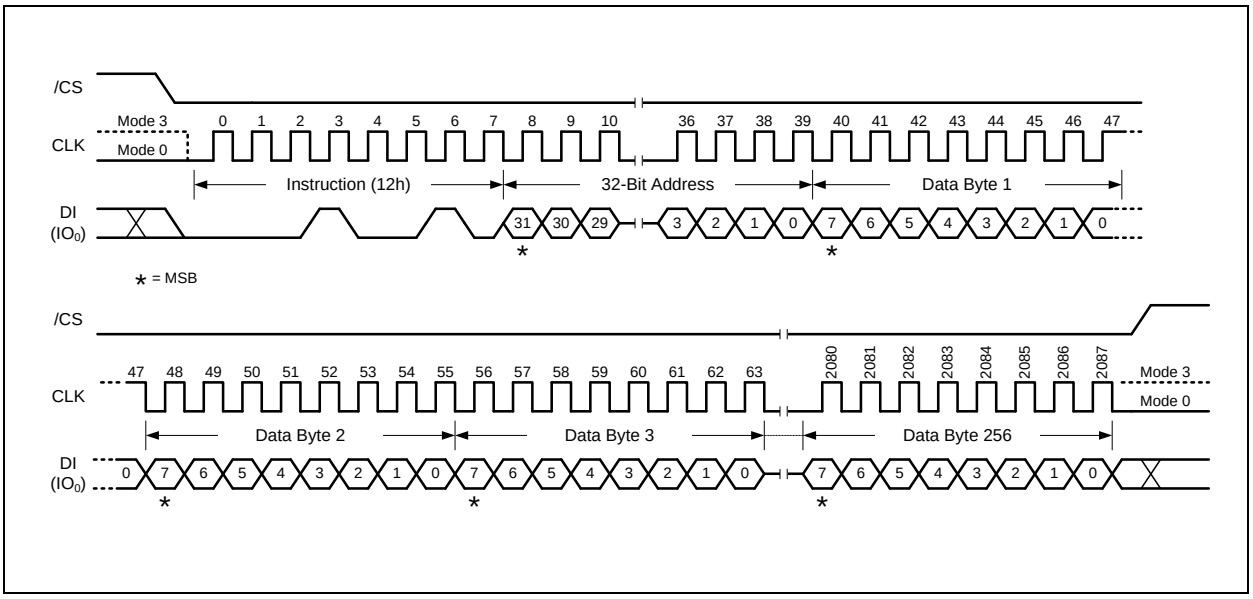



Figure 33. Page Program with 4-Byte Addr.



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### 8.2.24 Quad Input Page Program (32h)

The Quad Page Program instruction allows up to 256 bytes of data to be programmed at previously erased (FFh) memory locations using four pins: $IO_0$, $IO_1$, $IO_2$, and $IO_3$. The Quad Page Program can improve performance for PROM Programmer and applications that have slow clock speeds <5MHz. Systems with faster clock speed will not realize much benefit for the Quad Page Program instruction since the inherent page program time is much greater than the time it take to clock-in the data.

To use Quad Page Program the Quad Enable (QE) bit in Status Register-2 must be set to 1. A Write Enable instruction must be executed before the device will accept the Quad Page Program instruction (Status Register-1, WEL=1). The instruction is initiated by driving the /CS pin low then shifting the instruction code "32h" followed by a 24/32-bit address (A23/A31-A0) and at least one data byte, into the IO pins. The /CS pin must be held low for the entire length of the instruction while data is being sent to the device. All other functions of Quad Page Program are identical to standard Page Program. The Quad Page Program instruction sequence is shown in Figure 34.

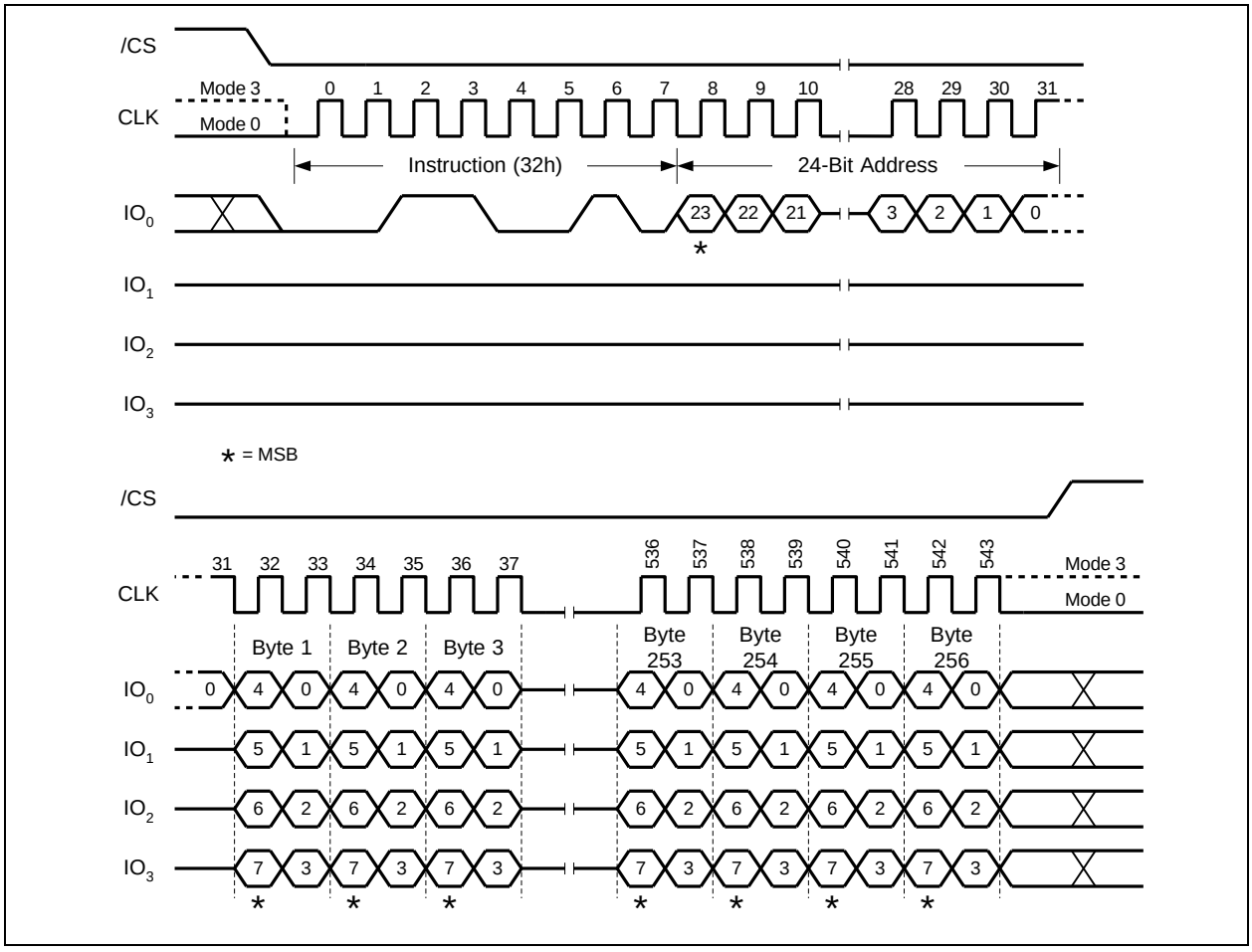



Figure 34. Quad Input Page Program Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.25 Quad Input Page Program with 4-Byte Address (34h)

The Quad Input Page Program with 4-Byte Address instruction is similar to the Quad Input Page Program instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Quad Input Page Program with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

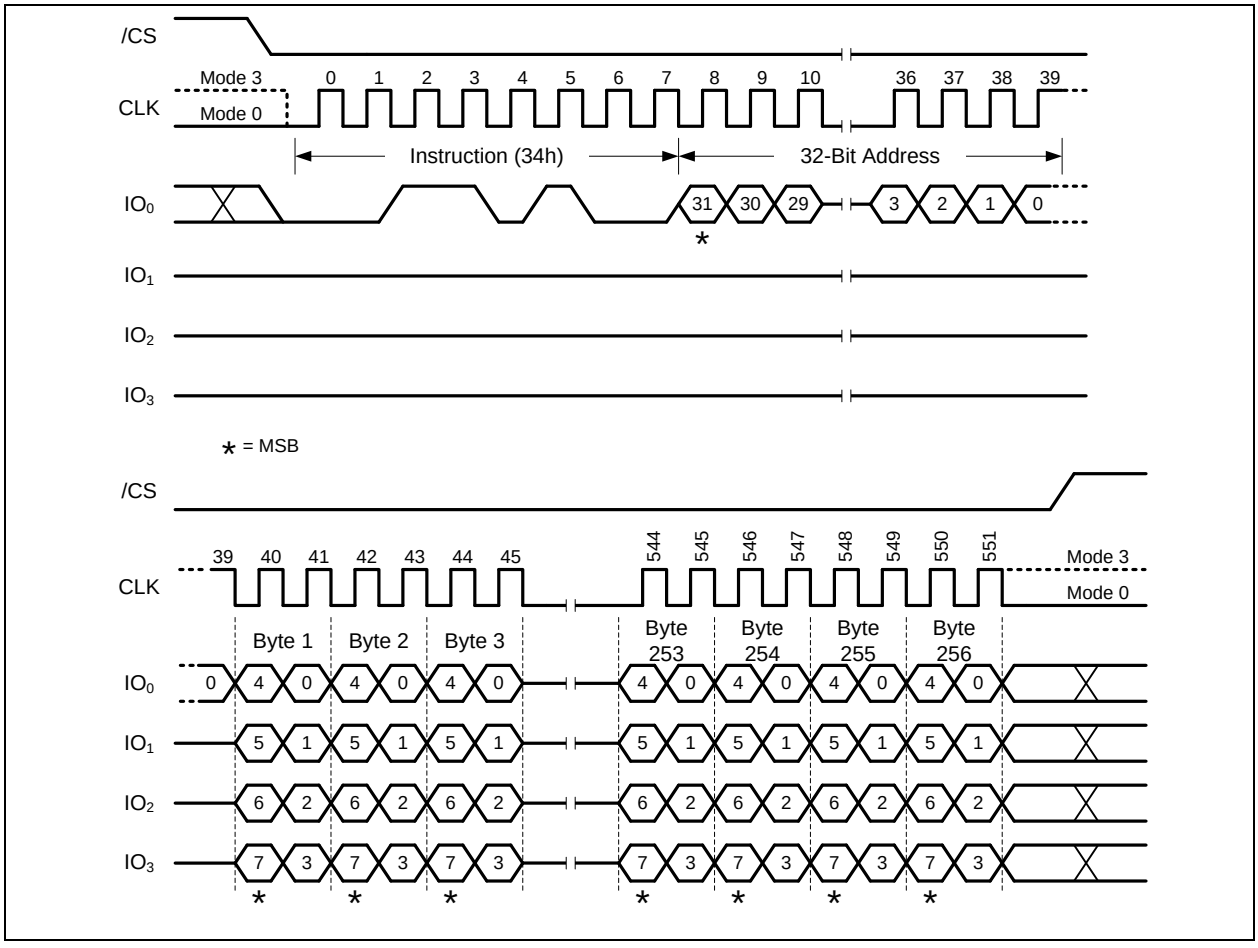



Figure 35. Quad Input Page Program with 4-Byte Addr.



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### 8.2.26 Sector Erase (20h)

The Sector Erase instruction sets all memory within a specified sector (4K-bytes) to the erased state of all 1s (FFh). A Write Enable instruction must be executed before the device will accept the Sector Erase Instruction (Status Register bit WEL must equal 1). The instruction is initiated by driving the /CS pin low and shifting the instruction code “20h” followed a 24/32-bit sector address (A23/A31-A0). The Sector Erase instruction sequence is shown in Figure 36.

The /CS pin must be driven high after the eighth bit of the last byte has been latched. If this is not done the Sector Erase instruction will not be executed. After /CS is driven high, the self-timed Sector Erase instruction will commence for a time duration of $t_{SE}$ (See AC Characteristics). While the Sector Erase cycle is in progress, the Read Status Register instruction may still be accessed for checking the status of the BUSY bit. The BUSY bit is a 1 during the Sector Erase cycle and becomes a 0 when the cycle is finished and the device is ready to accept other instructions again. After the Sector Erase cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Sector Erase instruction will not be executed if the addressed page is protected by the Block Protect (CMP, TB, BP3, BP2, BP1, and BP0) bits or the Individual Block/Sector Locks.

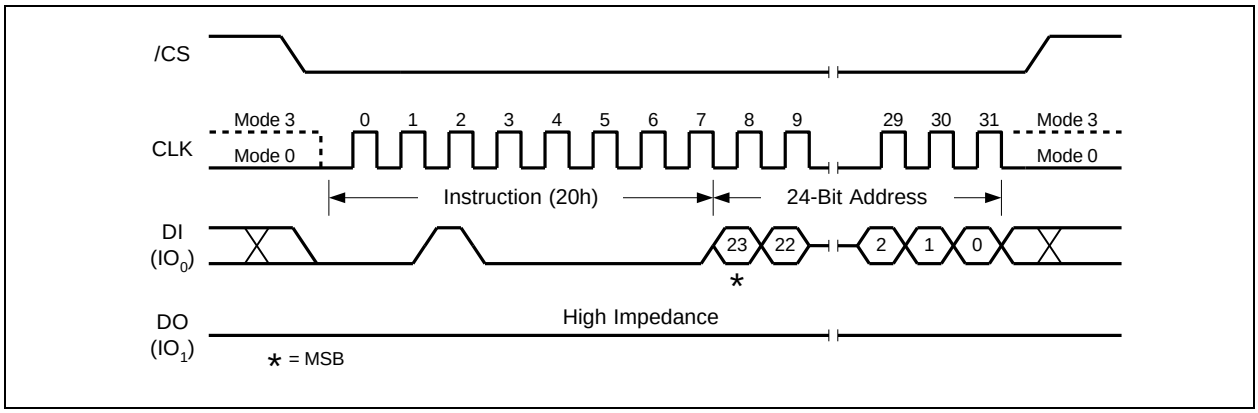



Figure 36. Sector Erase Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.27 Sector Erase with 4-Byte Address (21h)

The Sector Erase with 4-Byte Address instruction is similar to the Sector Erase instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the Sector Erase with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

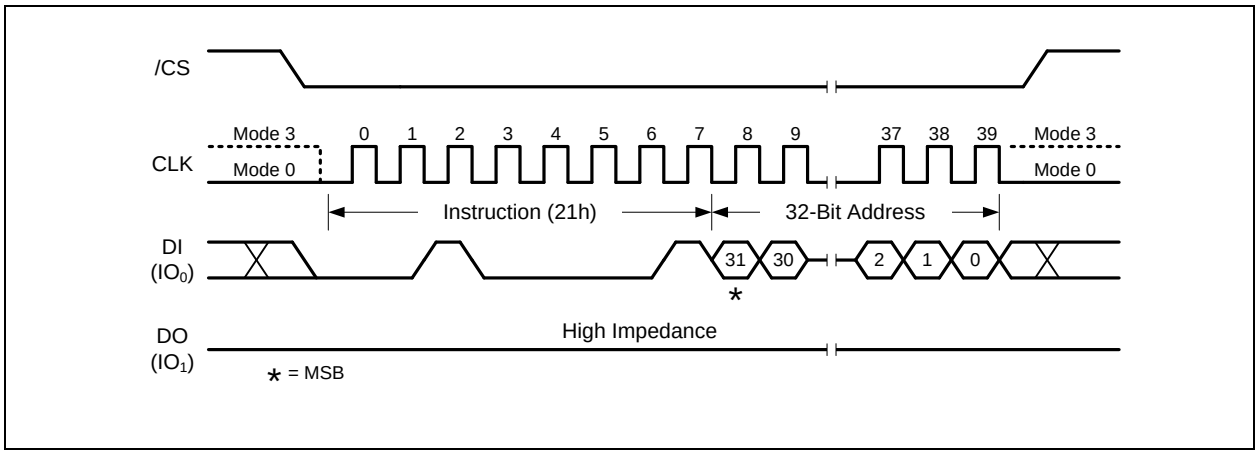



Figure 37. Sector Erase with 4-Byte Address Instruction



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### 8.2.28 32KB Block Erase (52h)

The Block Erase instruction sets all memory within a specified block (32K-bytes) to the erased state of all 1s (FFh). A Write Enable instruction must be executed before the device will accept the Block Erase Instruction (Status Register bit WEL must equal 1). The instruction is initiated by driving the /CS pin low and shifting the instruction code “52h” followed a 24/32-bit block address (A23/A31-A0). The Block Erase instruction sequence is shown in Figure 38.

The /CS pin must be driven high after the eighth bit of the last byte has been latched. If this is not done the Block Erase instruction will not be executed. After /CS is driven high, the self-timed Block Erase instruction will commence for a time duration of $t_{BE1}$ (See AC Characteristics). While the Block Erase cycle is in progress, the Read Status Register instruction may still be accessed for checking the status of the BUSY bit. The BUSY bit is a 1 during the Block Erase cycle and becomes a 0 when the cycle is finished and the device is ready to accept other instructions again. After the Block Erase cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Block Erase instruction will not be executed if the addressed page is protected by the Block Protect (CMP, TB, BP3, BP2, BP1, and BP0) bits or the Individual Block/Sector Locks.

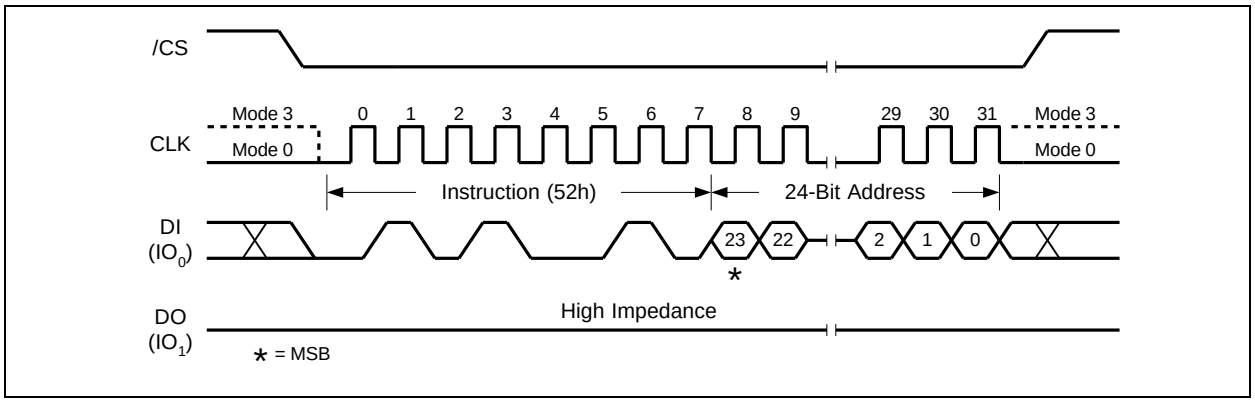



Figure 38a. 32KB Block Erase Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.29 64KB Block Erase (D8h)

The Block Erase instruction sets all memory within a specified block (64K-bytes) to the erased state of all 1s (FFh). A Write Enable instruction must be executed before the device will accept the Block Erase Instruction (Status Register bit WEL must equal 1). The instruction is initiated by driving the /CS pin low and shifting the instruction code “D8h” followed a 24/32-bit block address (A23/A31-A0). The Block Erase instruction sequence is shown in Figure 33a & 33b.

The /CS pin must be driven high after the eighth bit of the last byte has been latched. If this is not done the Block Erase instruction will not be executed. After /CS is driven high, the self-timed Block Erase instruction will commence for a time duration of $t_{BE}$ (See AC Characteristics). While the Block Erase cycle is in progress, the Read Status Register instruction may still be accessed for checking the status of the BUSY bit. The BUSY bit is a 1 during the Block Erase cycle and becomes a 0 when the cycle is finished and the device is ready to accept other instructions again. After the Block Erase cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Block Erase instruction will not be executed if the addressed page is protected by the Block Protect (CMP, TB, BP3, BP2, BP1, and BP0) bits or the Individual Block/Sector Locks.

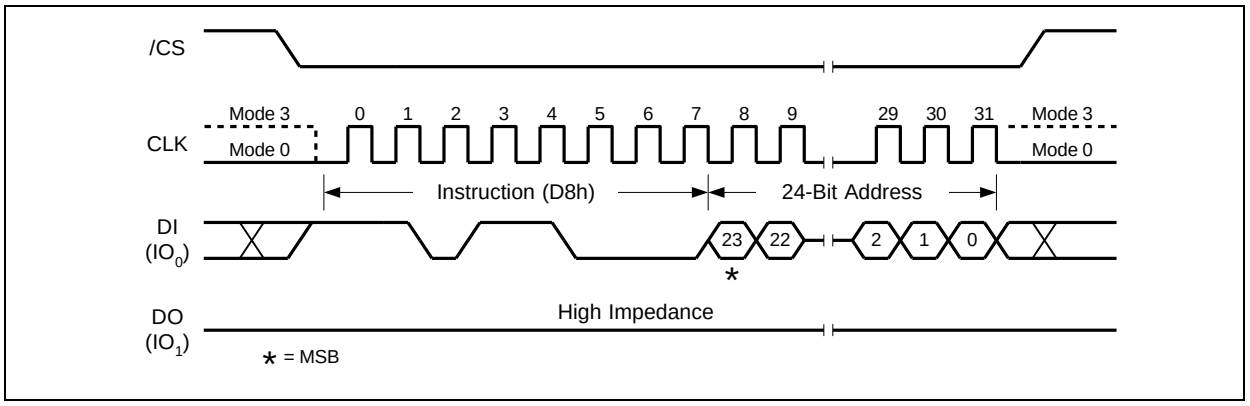



Figure 39. 64KB Block Erase Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.30 64KB Block Erase with 4-Byte Address (DCh)

The 64KB Block Erase with 4-Byte Address instruction is similar to the 64KB Block Erase instruction except that it requires 32-bit address instead of 24-bit address. No matter the device is operating in 3-Byte Address Mode or 4-byte Address Mode, the 64KB Block Erase with 4-Byte Address instruction will always require 32-bit address to access the entire 256Mb memory.

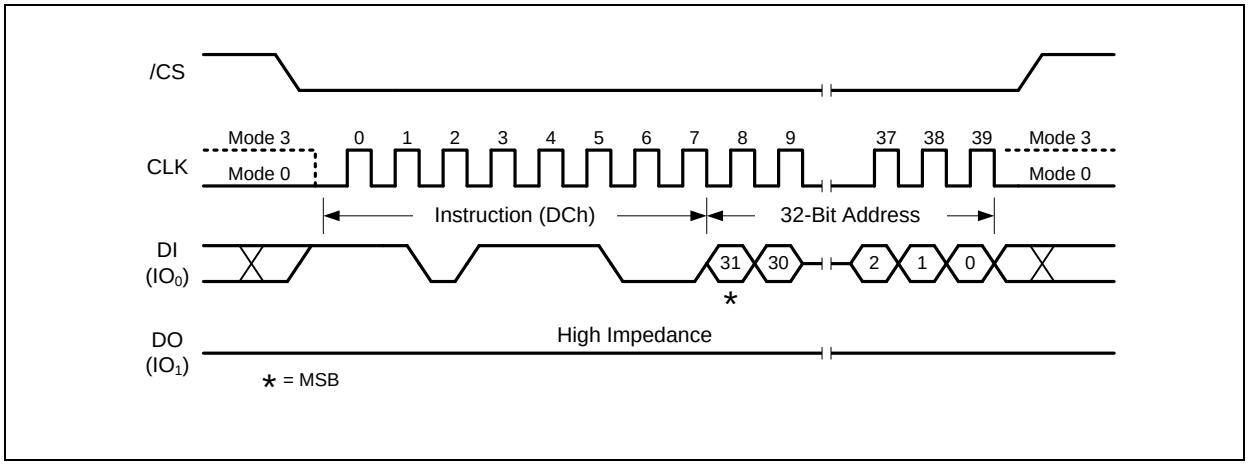



Figure 40. 64KB Block Erase with 4-Byte Address Instruction



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### 8.2.31 Chip Erase (C7h / 60h)

The Chip Erase instruction sets all memory within the device to the erased state of all 1s (FFh). A Write Enable instruction must be executed before the device will accept the Chip Erase Instruction (Status Register bit WEL must equal 1). The instruction is initiated by driving the /CS pin low and shifting the instruction code “C7h” or “60h”. The Chip Erase instruction sequence is shown in Figure 41.

The /CS pin must be driven high after the eighth bit has been latched. If this is not done the Chip Erase instruction will not be executed. After /CS is driven high, the self-timed Chip Erase instruction will commence for a time duration of $t_{CE}$ (See AC Characteristics). While the Chip Erase cycle is in progress, the Read Status Register instruction may still be accessed to check the status of the BUSY bit. The BUSY bit is a 1 during the Chip Erase cycle and becomes a 0 when finished and the device is ready to accept other instructions again. After the Chip Erase cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Chip Erase instruction will not be executed if any memory region is protected by the Block Protect (CMP, TB, BP3, BP2, BP1, and BP0) bits or the Individual Block/Sector Locks.

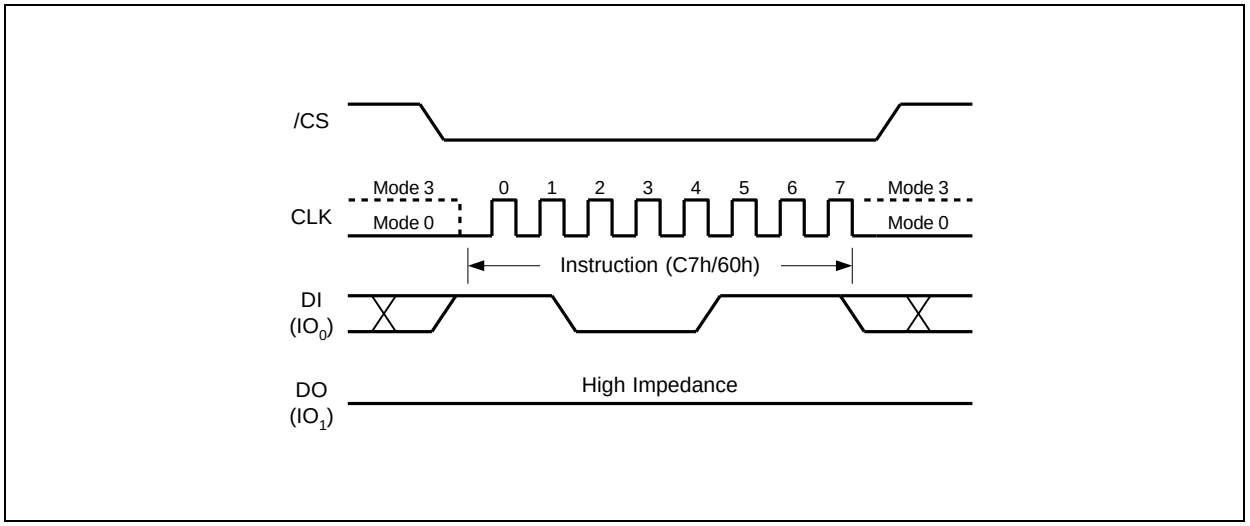



Figure 41. Chip Erase Instruction Sequence Diagram



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### 8.2.32 Erase / Program Suspend (75h)

The Erase/Program Suspend instruction “75h”, allows the system to interrupt a Sector or Block Erase operation or a Page Program operation and then read from or program/erase data to, any other sectors or blocks. The Erase/Program Suspend instruction sequence is shown in Figure 42.

The Write Status Register instruction (01h) and Erase instructions (20h, 52h, D8h, C7h, 60h, 44h) are not allowed during Erase Suspend. Erase Suspend is valid only during the Sector or Block erase operation. If written during the Chip Erase operation, the Erase Suspend instruction is ignored. The Write Status Register instruction (01h) and Program instructions (02h, 32h, 42h) are not allowed during Program Suspend. Program Suspend is valid only during the Page Program or Quad Page Program operation.

The Erase/Program Suspend instruction “75h” will be accepted by the device only if the SUS bit in the Status Register equals to 0 and the BUSY bit equals to 1 while a Sector or Block Erase or a Page Program operation is on-going. If the SUS bit equals to 1 or the BUSY bit equals to 0, the Suspend instruction will be ignored by the device. A maximum of time of “$t_{SUS}$” (See AC Characteristics) is required to suspend the erase or program operation. The BUSY bit in the Status Register will be cleared from 1 to 0 within “$t_{SUS}$” and the SUS bit in the Status Register will be set from 0 to 1 immediately after Erase/Program Suspend. For a previously resumed Erase/Program operation, it is also required that the Suspend instruction “75h” is not issued earlier than a minimum of time of “$t_{SUS}$” following the preceding Resume instruction “7Ah”.

Unexpected power off during the Erase/Program suspend state will reset the device and release the suspend state. SUS bit in the Status Register will also reset to 0. The data within the page, sector or block that was being suspended may become corrupted. It is recommended for the user to implement system design techniques against the accidental power interruption and preserve data integrity during erase/program suspend state. Note that once the Suspend instruction (75h) is accepted, the following Power-down instruction (B9h) will be ignored.

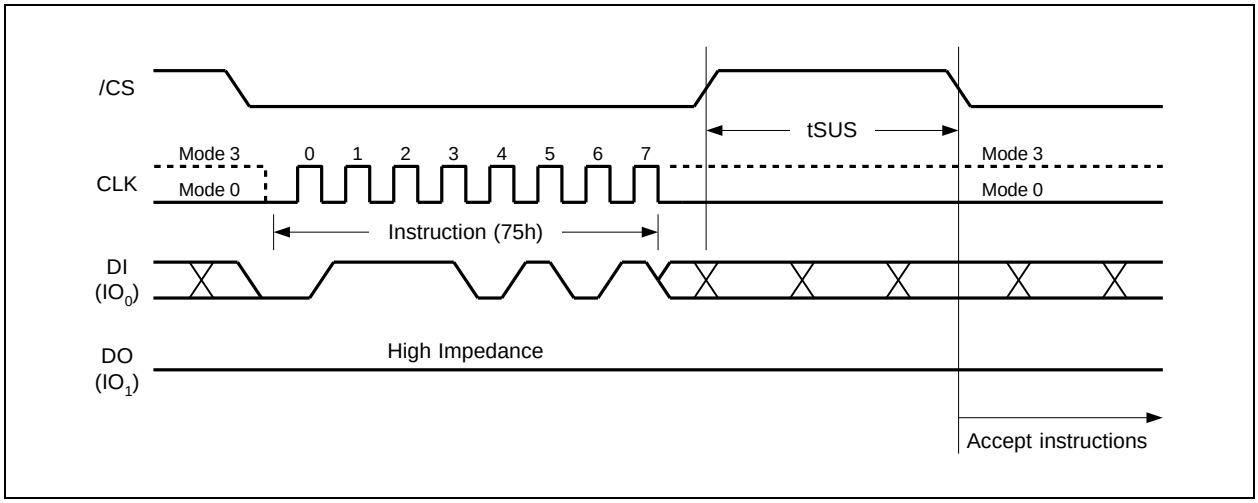



Figure 42. Erase/Program Suspend Instruction



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### 8.2.33 Erase / Program Resume (7Ah)

The Erase/Program Resume instruction “7Ah” must be written to resume the Sector or Block Erase operation or the Page Program operation after an Erase/Program Suspend. The Resume instruction “7Ah” will be accepted by the device only if the SUS bit in the Status Register equals to 1 and the BUSY bit equals to 0. After issued the SUS bit will be cleared from 1 to 0 immediately, the BUSY bit will be set from 0 to 1 within 200ns and the Sector or Block will complete the erase operation or the page will complete the program operation. If the SUS bit equals to 0 or the BUSY bit equals to 1, the Resume instruction “7Ah” will be ignored by the device. The Erase/Program Resume instruction sequence is shown in Figure 43.

Resume instruction is ignored if the previous Erase/Program Suspend operation was interrupted by unexpected power off. It is also required that a subsequent Erase/Program Suspend instruction not to be issued within a minimum of time of “$t_{SUS}$” following a previous Resume instruction.

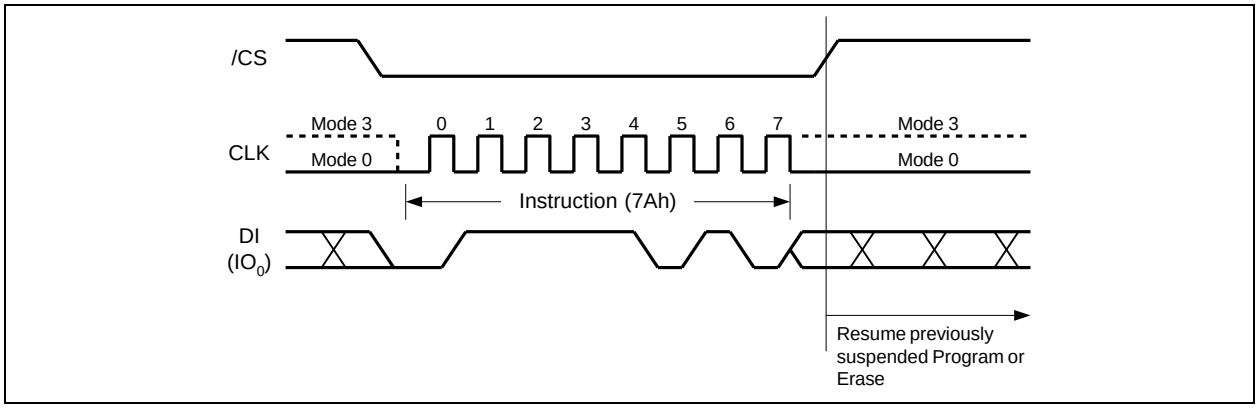



Figure 43. Erase/Program Resume Instruction



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### 8.2.34 Power-down (B9h)

Although the standby current during normal operation is relatively low, standby current can be further reduced with the Power-down instruction. The lower power consumption makes the Power-down instruction especially useful for battery powered applications (See ICC1 and ICC2 in AC Characteristics). The instruction is initiated by driving the /CS pin low and shifting the instruction code “B9h” as shown in Figure 44.

The /CS pin must be driven high after the eighth bit has been latched. If this is not done the Power-down instruction will not be executed. After /CS is driven high, the power-down state will entered within the time duration of tDP (See AC Characteristics). While in the power-down state only the Release Power-down (ABh) instruction, which restores the device to normal operation, will be recognized. All other instructions are ignored. This includes the Read Status Register instruction, which is always available during normal operation. Ignoring all but one instruction makes the Power Down state a useful condition for securing maximum write protection. The device always powers-up in the normal operation with the standby current of ICC1. After the Power-down instruction is accepted, the device will lose all the current volatile Status Register bits, please refer to section 7.1. Note that once the Suspend instruction (75h) is accepted, the following Power-down instruction (B9h) will be ignored.

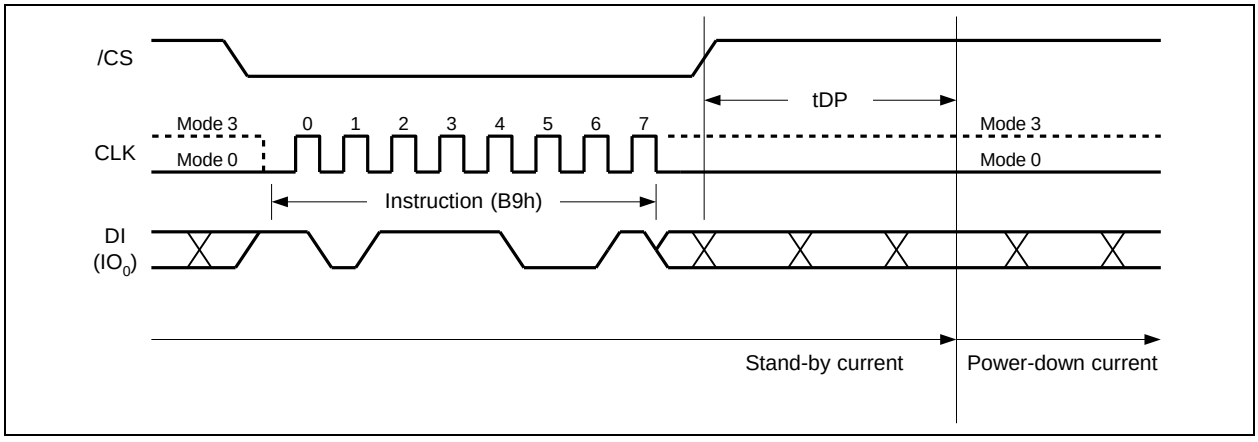



Figure 44. Deep Power-down Instruction



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### 8.2.35 Release Power-down / Device ID (ABh)

The Release from Power-down / Device ID instruction is a multi-purpose instruction. It can be used to release the device from the power-down state, or read the devices electronic identification (ID) number.

To release the device from the power-down state, the instruction is issued by driving the /CS pin low, shifting the instruction code “ABh” and driving /CS high as shown in Figure 45. Release from power-down will take the time duration of $t_{RES1}$ (See AC Characteristics) before the device will resume normal operation and other instructions are accepted. The /CS pin must remain high during the $t_{RES1}$ time duration.

When used only to obtain the Device ID while not in the power-down state, the instruction is initiated by driving the /CS pin low and shifting the instruction code “ABh” followed by 3-dummy bytes. The Device ID bits are then shifted out on the falling edge of CLK with most significant bit (MSB) first. The Device ID values for the W25Q256JW is listed in Manufacturer and Device Identification table. The Device ID can be read continuously. The instruction is completed by driving /CS high.

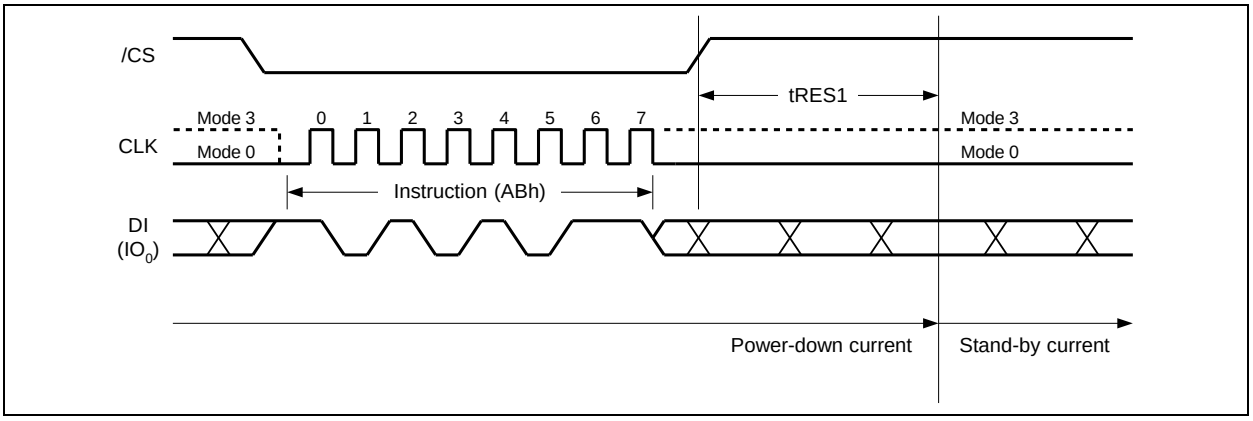



Figure 45a. Release Power-down Instruction

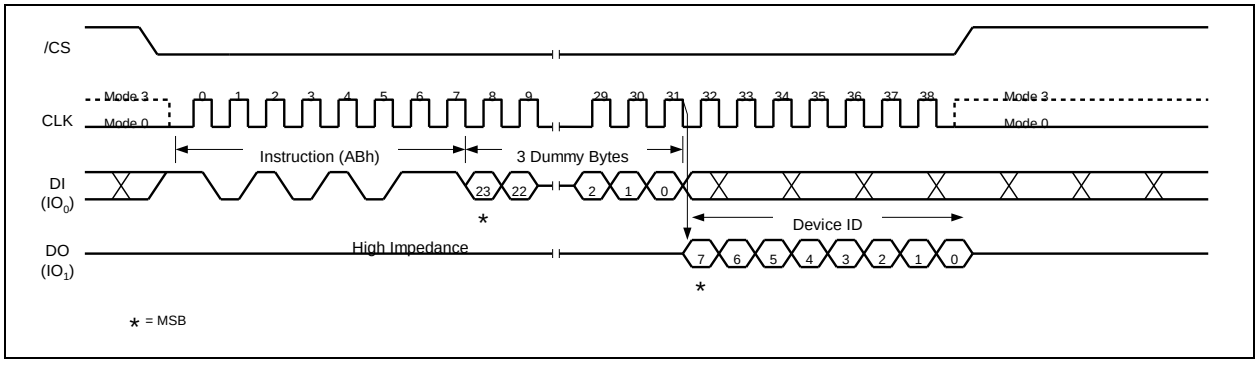



Figure 45b. Device ID Instruction



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### 8.2.36 Read Manufacturer / Device ID (90h)

The Read Manufacturer/Device ID instruction is an alternative to the Release from Power-down / Device ID instruction that provides both the JEDEC assigned manufacturer ID and the specific device ID.

The Read Manufacturer/Device ID instruction is very similar to the Release from Power-down / Device ID instruction. The instruction is initiated by driving the /CS pin low and shifting the instruction code “90h” followed by a 24-bit address (A23-A0) of 000000h. After which, the Manufacturer ID for Winbond (EFh) and the Device ID are shifted out on the falling edge of CLK with most significant bit (MSB) first as shown in Figure 46. The Device ID values for the W25Q256JW are listed in Manufacturer and Device Identification table. The instruction is completed by driving /CS high.

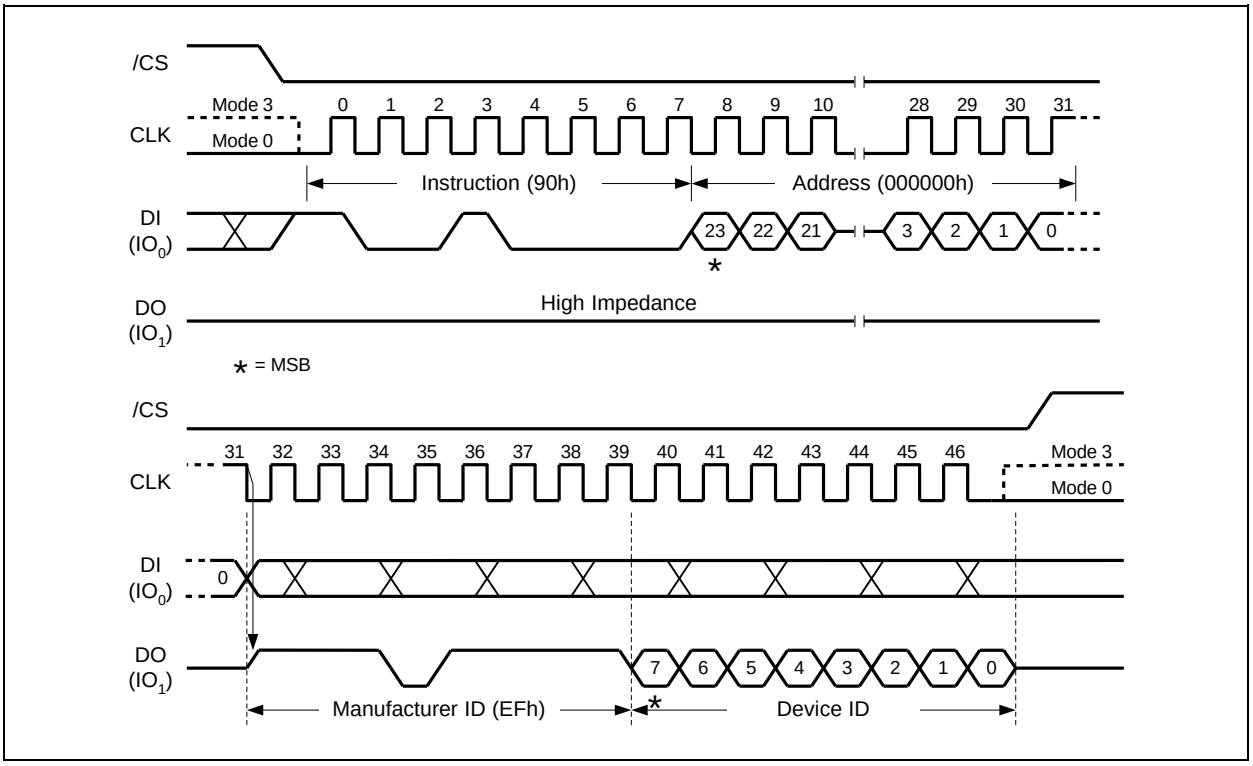



Figure 46. Read Manufacturer / Device ID Instruction



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### 8.2.37 Read Manufacturer / Device ID Dual I/O (92h)

The Read Manufacturer / Device ID Dual I/O instruction is an alternative to the Read Manufacturer / Device ID instruction that provides both the JEDEC assigned manufacturer ID and the specific device ID at 2x speed.

The Read Manufacturer / Device ID Dual I/O instruction is similar to the Fast Read Dual I/O instruction. The instruction is initiated by driving the /CS pin low and shifting the instruction code “92h” followed by a 24/32-bit address (A23/A31-A0) of 000000h, but with the capability to input the Address bits two bits per clock. After which, the Manufacturer ID for Winbond (EFh) and the Device ID are shifted out 2 bits per clock on the falling edge of CLK with most significant bits (MSB) first as shown in Figure 47. The Device ID values for the W25Q256JW are listed in Manufacturer and Device Identification table. The Manufacturer and Device IDs can be read continuously, alternating from one to the other. The instruction is completed by driving /CS high.

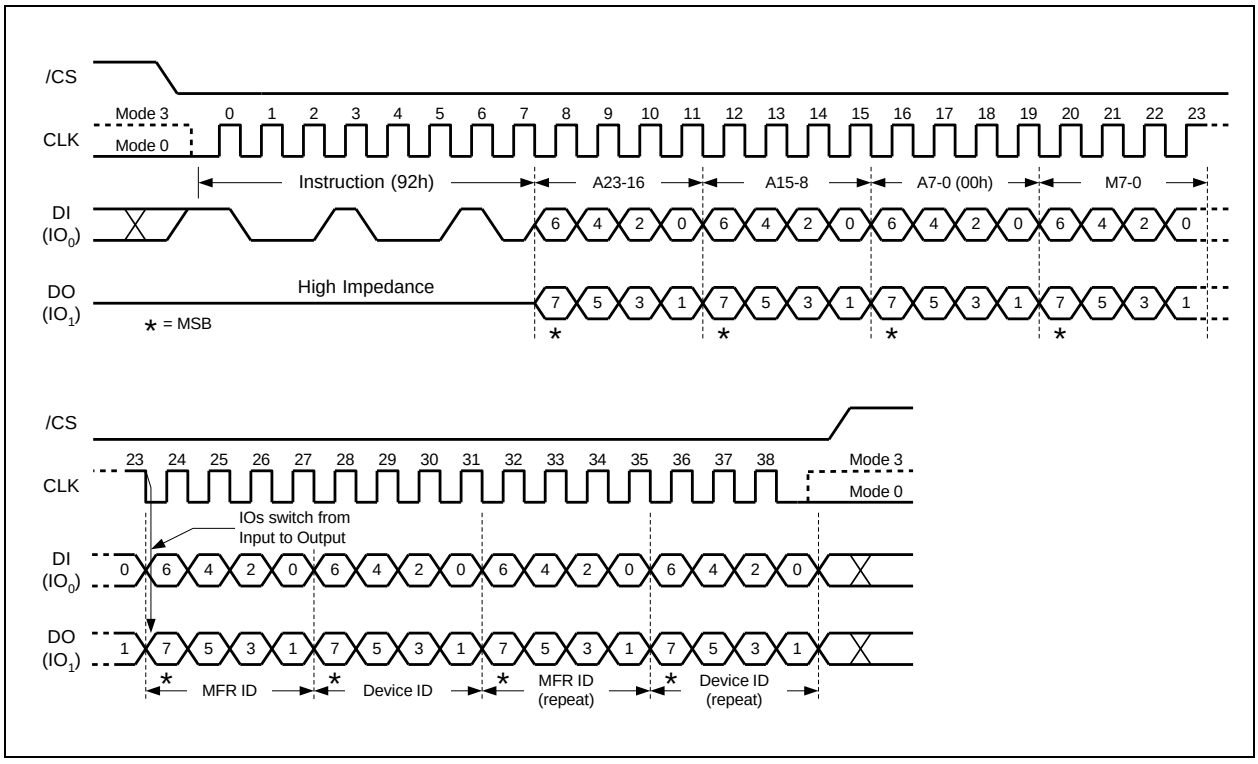



Figure 47. Read Manufacturer / Device ID Dual I/O Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*

Note:

The “Continuous Read Mode” bits M(7-0) must be set to FFh to be compatible with Fast Read Dual I/O instruction.



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### 8.2.38 Read Manufacturer / Device ID Quad I/O (94h)

The Read Manufacturer / Device ID Quad I/O instruction is an alternative to the Read Manufacturer / Device ID instruction that provides both the JEDEC assigned manufacturer ID and the specific device ID at 4x speed.

The Read Manufacturer / Device ID Quad I/O instruction is similar to the Fast Read Quad I/O instruction. The instruction is initiated by driving the /CS pin low and shifting the instruction code “94h” followed by a four clock dummy cycles and then a 24/32-bit address (A23/A31-A0) of 000000h, but with the capability to input the Address bits four bits per clock. After which, the Manufacturer ID for Winbond (EFh) and the Device ID are shifted out four bits per clock on the falling edge of CLK with most significant bit (MSB) first as shown in Figure 48. The Device ID values for the W25Q256JW are listed in Manufacturer and Device Identification table. The Manufacturer and Device IDs can be read continuously, alternating from one to the other. The instruction is completed by driving /CS high.

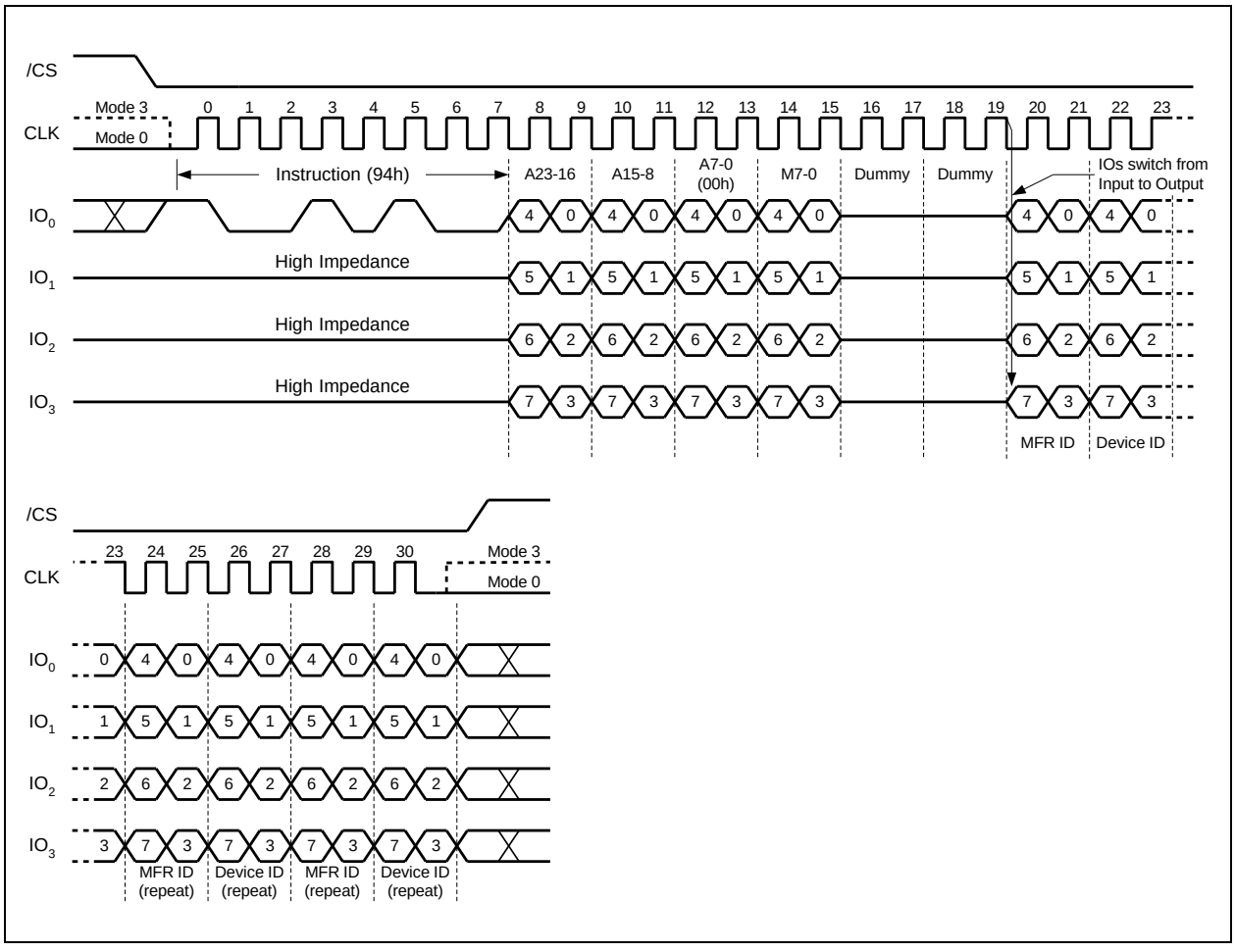



Figure 48. Read Manufacturer / Device ID Quad I/O Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*

Note:

The “Continuous Read Mode” bits M(7-0) must be set to FFh to be compatible with Fast Read Quad I/O instruction.



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### 8.2.39 Read Unique ID Number (4Bh)

The Read Unique ID Number instruction accesses a factory-set read-only 64-bit number that is unique to each W25Q256JW device. The ID number can be used in conjunction with user software methods to help prevent copying or cloning of a system. The Read Unique ID instruction is initiated by driving the /CS pin low and shifting the instruction code “4Bh” followed by a four bytes of dummy clocks. After which, the 64-bit ID is shifted out on the falling edge of CLK as shown in Figure 49.

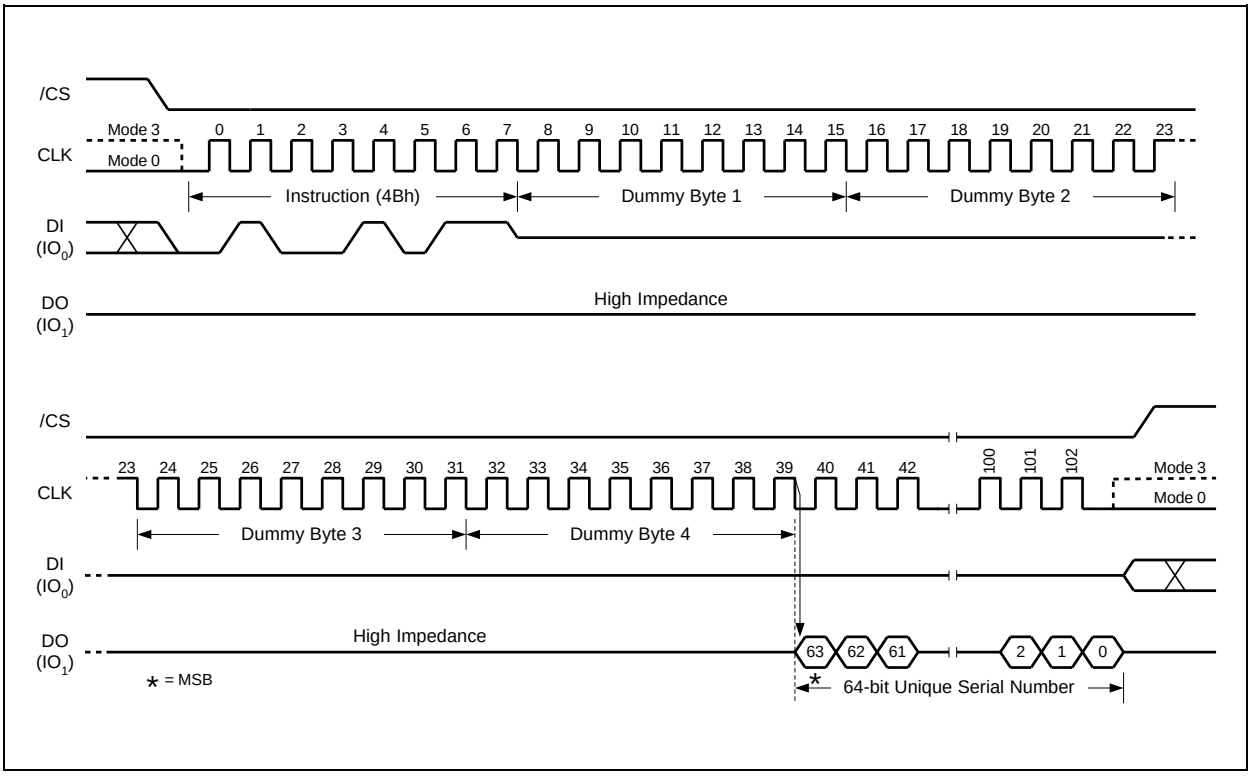



Figure 49. Read Unique ID Number Instruction

*5 Dummy Bytes are required when the device is operating in 4-Byte Address Mode*



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### 8.2.40 Read JEDEC ID (9Fh)

For compatibility reasons, the W25Q256JW provides several instructions to electronically determine the identity of the device. The Read JEDEC ID instruction is compatible with the JEDEC standard for SPI compatible serial memories that was adopted in 2003. The instruction is initiated by driving the /CS pin low and shifting the instruction code “9Fh”. The JEDEC assigned Manufacturer ID byte for Winbond (EFh) and two Device ID bytes, Memory Type (ID15-ID8) and Capacity (ID7-ID0) are then shifted out on the falling edge of CLK with most significant bit (MSB) first as shown in Figure 50. For memory type and capacity values refer to Manufacturer and Device Identification table.

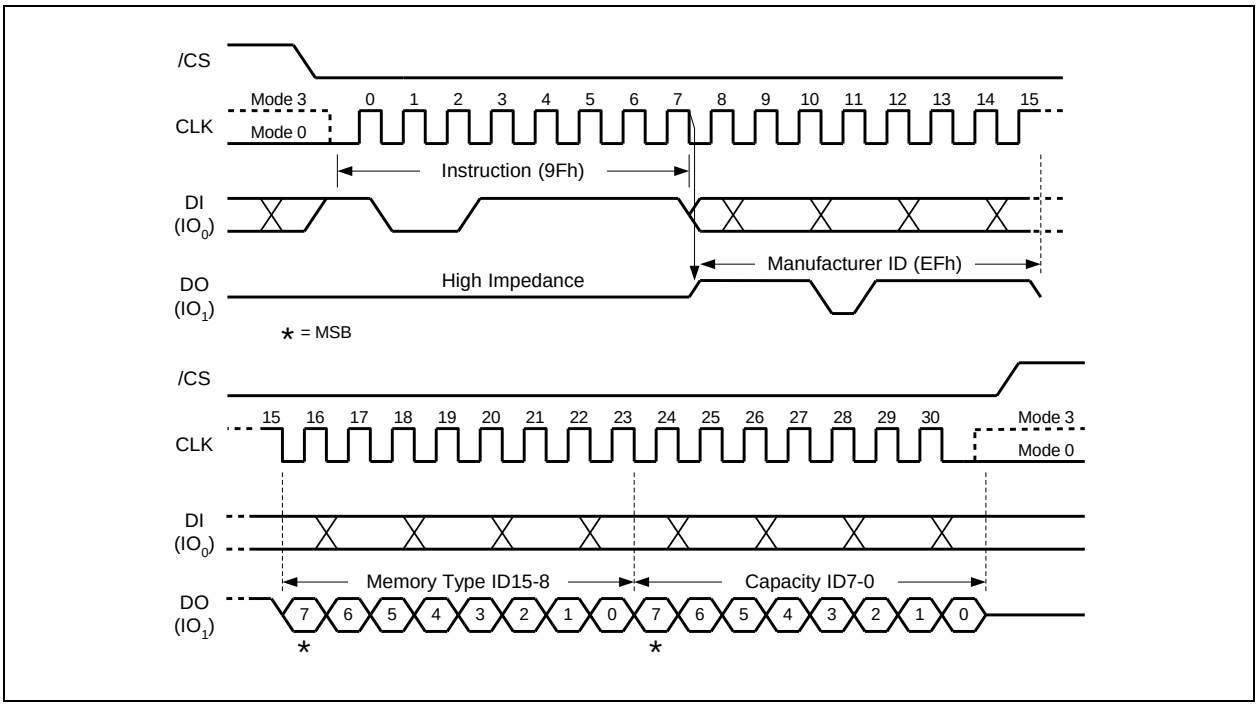



Figure 50. Read JEDEC ID Instruction



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### 8.2.41 Read SFDP Register (5Ah)

The W25Q256JW features a 256-Byte Serial Flash Discoverable Parameter (SFDP) register that contains information about device configurations, available instructions and other features. The SFDP parameters are stored in one or more Parameter Identification (PID) tables. Currently only one PID table is specified, but more may be added in the future. The Read SFDP Register instruction is compatible with the SFDP standard initially established in 2010 for PC and other applications, as well as the JEDEC standard JESD216 that is published in 2011. Most Winbond SpiFlash Memories shipped after June 2011 (date code 1124 and beyond) support the SFDP feature as specified in the applicable datasheet.

The Read SFDP instruction is initiated by driving the /CS pin low and shifting the instruction code "5Ah" followed by a 24-bit address (A23-A0)(1) into the DI pin. Eight "dummy" clocks are also required before the SFDP register contents are shifted out on the falling edge of the 40th CLK with most significant bit (MSB) first as shown in Figure 51. For SFDP register values and descriptions, please refer to the Winbond Application Note for SFDP Definition Table.

Note: 1. A23-A8 = 0; A7-A0 are used to define the starting byte address for the 256-Byte SFDP Register.

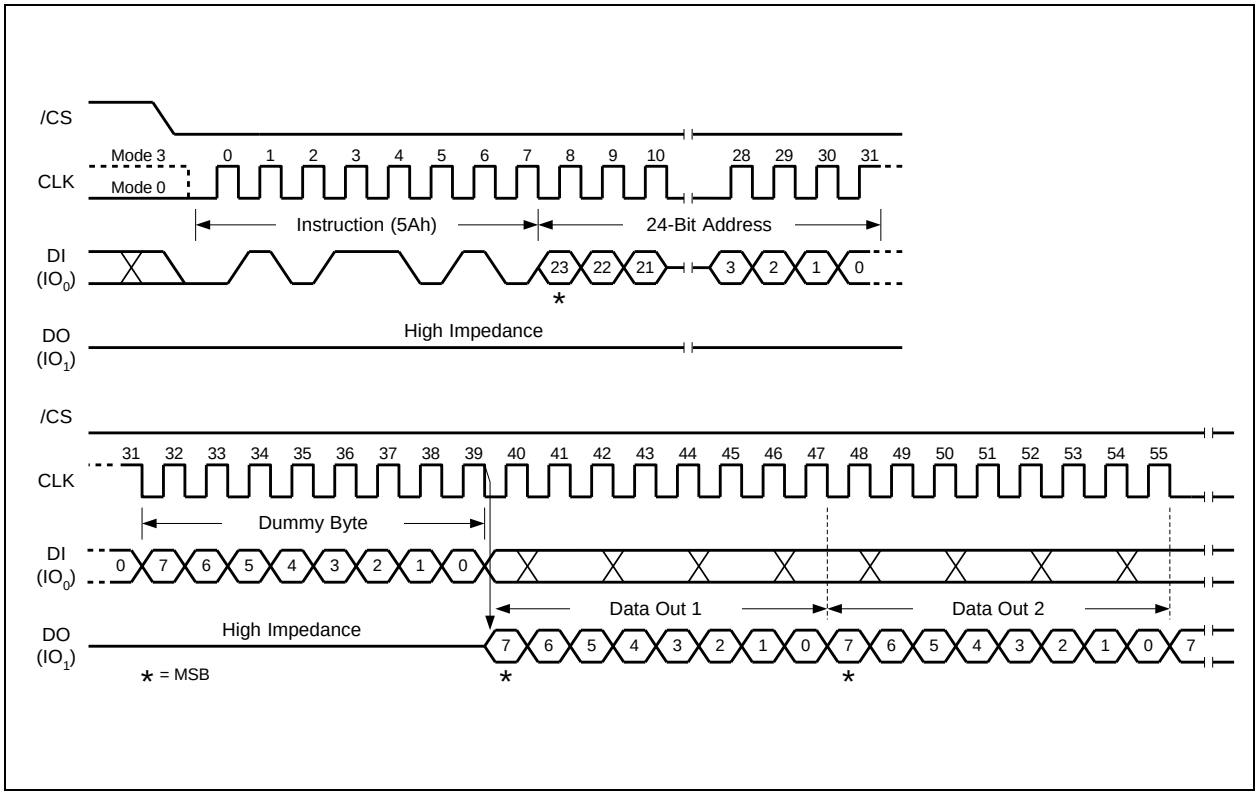



Figure 51. Read SFDP Register Instruction Sequence Diagram

*Only 24-Bit Address is required when the device is operating in either 3-Byte or 4-Byte Address Mode*



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### 8.2.42 Erase Security Registers (44h)

The W25Q256JW offers three 256-byte Security Registers which can be erased and programmed individually. These registers may be used by the system manufacturers to store security and other important information separately from the main memory array.

The Erase Security Register instruction is similar to the Sector Erase instruction. A Write Enable instruction must be executed before the device will accept the Erase Security Register Instruction (Status Register bit WEL must equal 1). The instruction is initiated by driving the /CS pin low and shifting the instruction code “44h” followed by a 24/32-bit address (A23/A31-A0) to erase one of the three security registers.

| ADDRESS | {A23/A31}-16 | A15-12 | A11-8 | A7-0 |
|---|---|---|---|---|
| Security Register #1 | 00h/0000h | 0 0 0 1 | 0 0 0 0 | Don’t Care |
| Security Register #2 | 00h/0000h | 0 0 1 0 | 0 0 0 0 | Don’t Care |
| Security Register #3 | 00h/0000h | 0 0 1 1 | 0 0 0 0 | Don’t Care |

The Erase Security Register instruction sequence is shown in Figure 52. The /CS pin must be driven high after the eighth bit of the last byte has been latched. If this is not done the instruction will not be executed. After /CS is driven high, the self-timed Erase Security Register operation will commence for a time duration of $t_{SE}$ (See AC Characteristics). While the Erase Security Register cycle is in progress, the Read Status Register instruction may still be accessed for checking the status of the BUSY bit. The BUSY bit is a 1 during the erase cycle and becomes a 0 when the cycle is finished and the device is ready to accept other instructions again. After the Erase Security Register cycle has finished the Write Enable Latch (WEL) bit in the Status Register is cleared to 0. The Security Register Lock Bits (LB3-1) in the Status Register-2 can be used to OTP protect the security registers. Once a lock bit is set to 1, the corresponding security register will be permanently locked, Erase Security Register instruction to that register will be ignored (Refer to section 7.1.8 for detail descriptions).

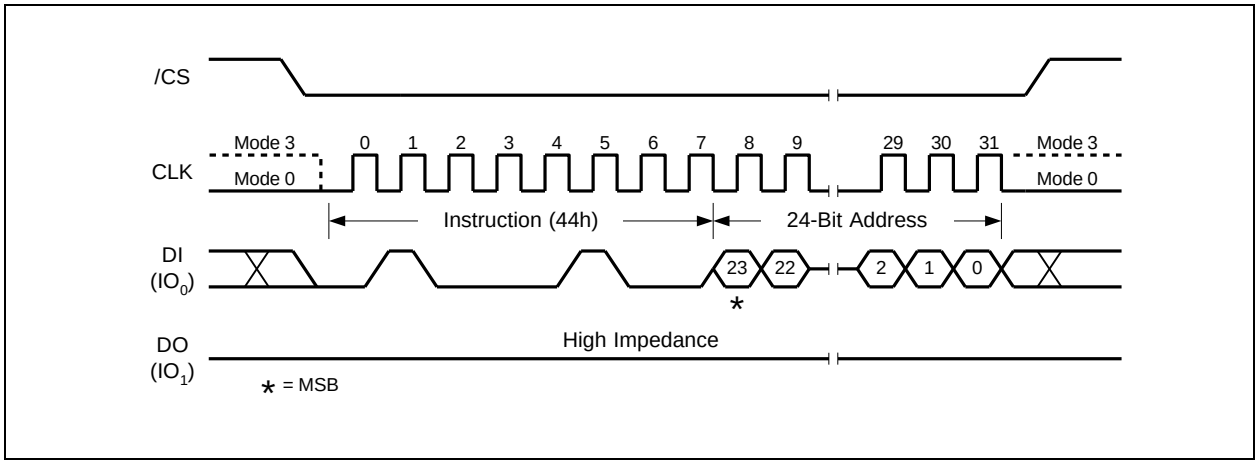



Figure 52. Erase Security Registers Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.43 Program Security Registers (42h)

The Program Security Register instruction is similar to the Page Program instruction. It allows from one byte to 256 bytes of security register data to be programmed at previously erased (FFh) memory locations. A Write Enable instruction must be executed before the device will accept the Program Security Register Instruction (Status Register bit WEL= 1). The instruction is initiated by driving the /CS pin low then shifting the instruction code “42h” followed by a 24/32-bit address (A23/A31-A0) and at least one data byte, into the DI pin. The /CS pin must be held low for the entire length of the instruction while data is being sent to the device.

| ADDRESS | {A23/A31}-16 | A15-12 | A11-8 | A7-0 |
|---|---|---|---|---|
| Security Register #1 | 00h/0000h | 0 0 0 1 | 0 0 0 0 | Byte Address |
| Security Register #2 | 00h/0000h | 0 0 1 0 | 0 0 0 0 | Byte Address |
| Security Register #3 | 00h/0000h | 0 0 1 1 | 0 0 0 0 | Byte Address |

The Program Security Register instruction sequence is shown in Figure 53. The Security Register Lock Bits (LB3-1) in the Status Register-2 can be used to OTP protect the security registers. Once a lock bit is set to 1, the corresponding security register will be permanently locked, Program Security Register instruction to that register will be ignored (See 7.1.8, 8.2.25 for detail descriptions).

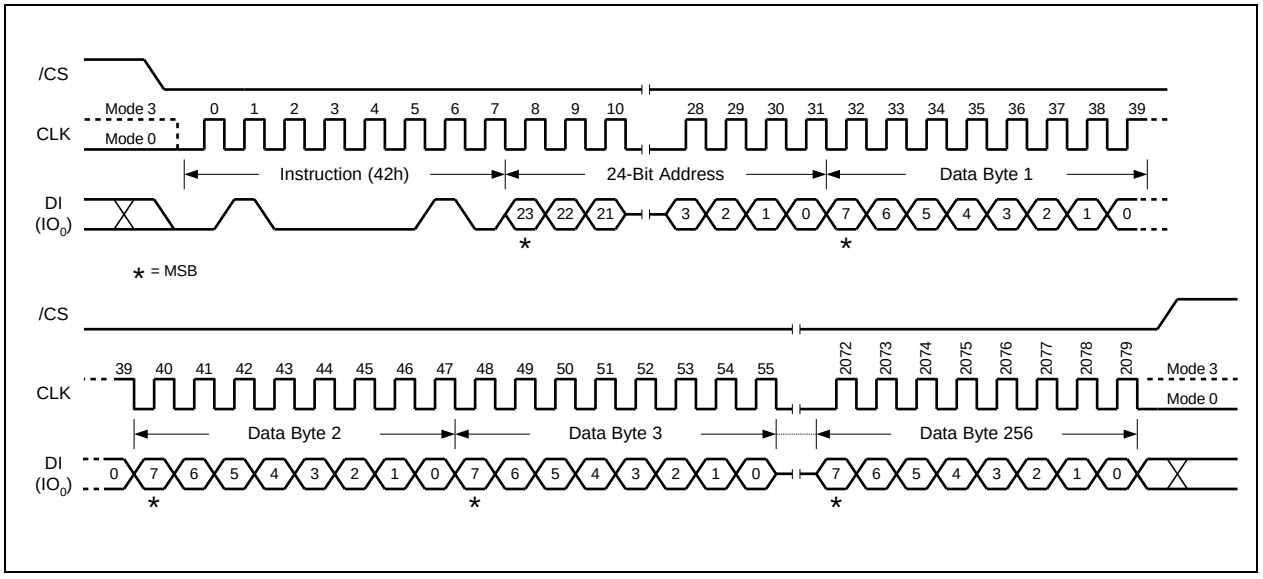



Figure 53. Program Security Registers Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.44 Read Security Registers (48h)

The Read Security Register instruction is similar to the Fast Read instruction and allows one or more data bytes to be sequentially read from one of the four security registers. The instruction is initiated by driving the /CS pin low and then shifting the instruction code “48h” followed by a 24/32-bit address (A23/A31-A0) and eight “dummy” clocks into the DI pin. The code and address bits are latched on the rising edge of the CLK pin. After the address is received, the data byte of the addressed memory location will be shifted out on the DO pin at the falling edge of CLK with most significant bit (MSB) first. The byte address is automatically incremented to the next byte address after each byte of data is shifted out. Once the byte address reaches the last byte of the register (byte address FFh), it will reset to address 00h, the first byte of the register, and continue to increment. The instruction is completed by driving /CS high. The Read Security Register instruction sequence is shown in Figure 54. If a Read Security Register instruction is issued while an Erase, Program or Write cycle is in process (BUSY=1) the instruction is ignored and will not have any effects on the current cycle. The Read Security Register instruction allows clock rates from D.C. to a maximum of FR (see AC Electrical Characteristics).

| ADDRESS | {A23/A31}-16 | A15-12 | A11-8 | A7-0 |
|---|---|---|---|---|
| Security Register #1 | 00h/0000h | 0 0 0 1 | 0 0 0 0 | Byte Address |
| Security Register #2 | 00h/0000h | 0 0 1 0 | 0 0 0 0 | Byte Address |
| Security Register #3 | 00h/0000h | 0 0 1 1 | 0 0 0 0 | Byte Address |

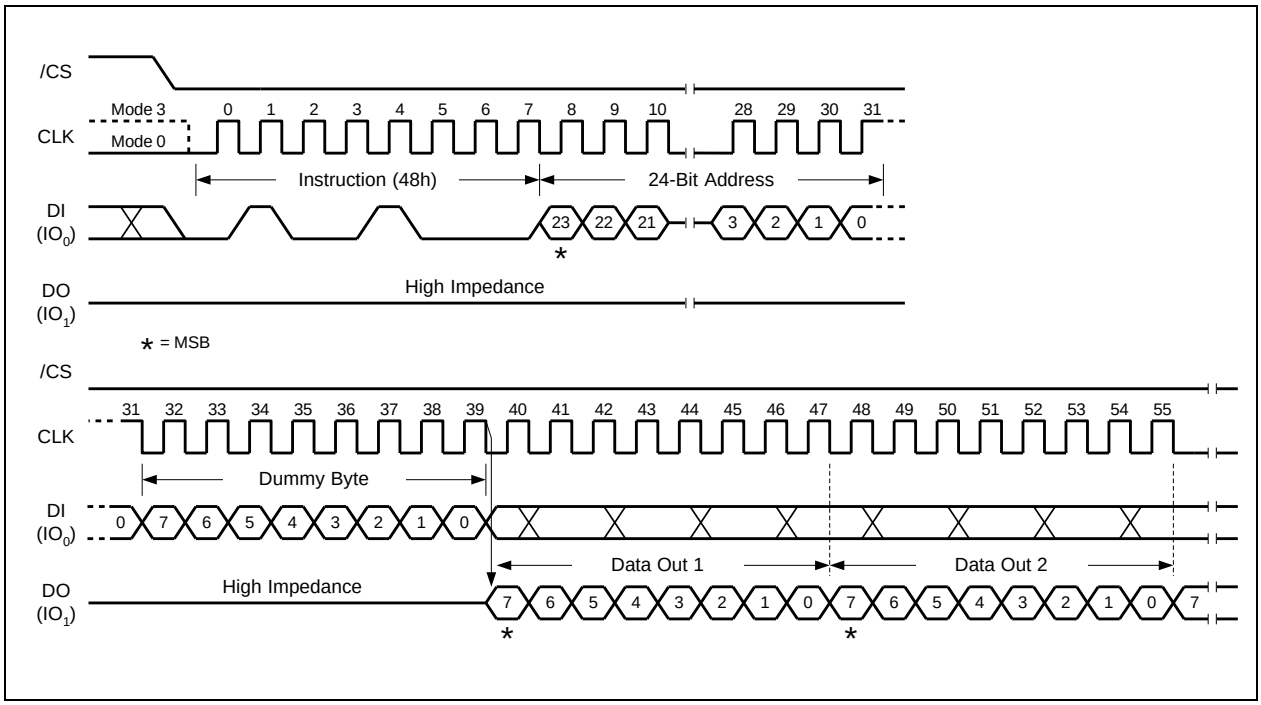



Figure 54. Read Security Registers Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.45 Individual Block/Sector Lock (36h)

The Individual Block/Sector Lock provides an alternative way to protect the memory array from adverse Erase/Program. In order to use the Individual Block/Sector Locks, the WPS bit in Status Register-3 must be set to 1. If WPS=0, the write protection will be determined by the combination of CMP, TB, BP[3:0] bits in the Status Registers. The Individual Block/Sector Lock bits are volatile bits. The default values after device power up or after a Reset are 1, so the entire memory array is being protected.

To lock a specific block or sector as illustrated in Figure 4d, an Individual Block/Sector Lock command must be issued by driving /CS low, shifting the instruction code “36h” into the Data Input (DI) pin on the rising edge of CLK, followed by a 24/32-bit address and then driving /CS high.

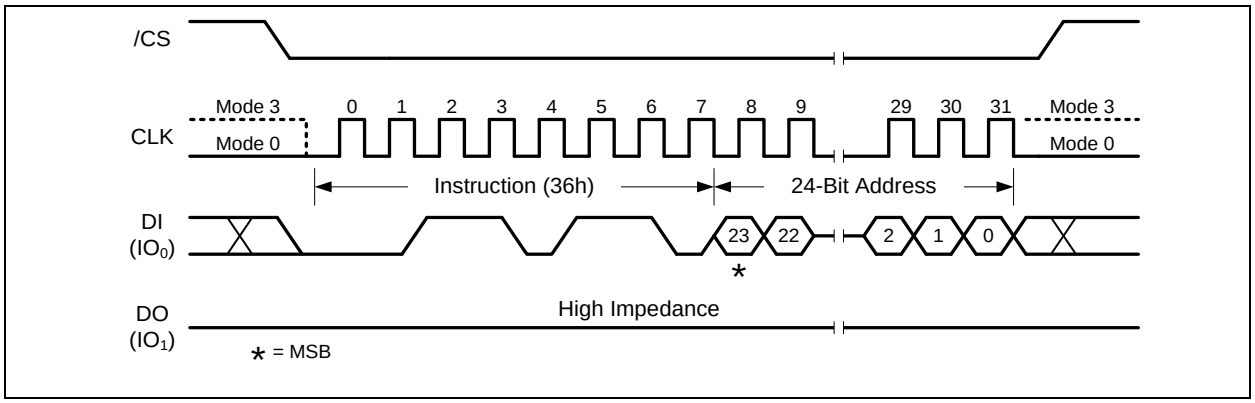



Figure 55. Individual Block/Sector Lock Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.46 Individual Block/Sector Unlock (39h)

The Individual Block/Sector Lock provides an alternative way to protect the memory array from adverse Erase/Program. In order to use the Individual Block/Sector Locks, the WPS bit in Status Register-3 must be set to 1. If WPS=0, the write protection will be determined by the combination of CMP, TB, BP[3:0] bits in the Status Registers. The Individual Block/Sector Lock bits are volatile bits. The default values after device power up or after a Reset are 1, so the entire memory array is being protected.

To unlock a specific block or sector as illustrated in Figure 4d, an Individual Block/Sector Unlock command must be issued by driving /CS low, shifting the instruction code “39h” into the Data Input (DI) pin on the rising edge of CLK, followed by a 24/32-bit address and then driving /CS high.

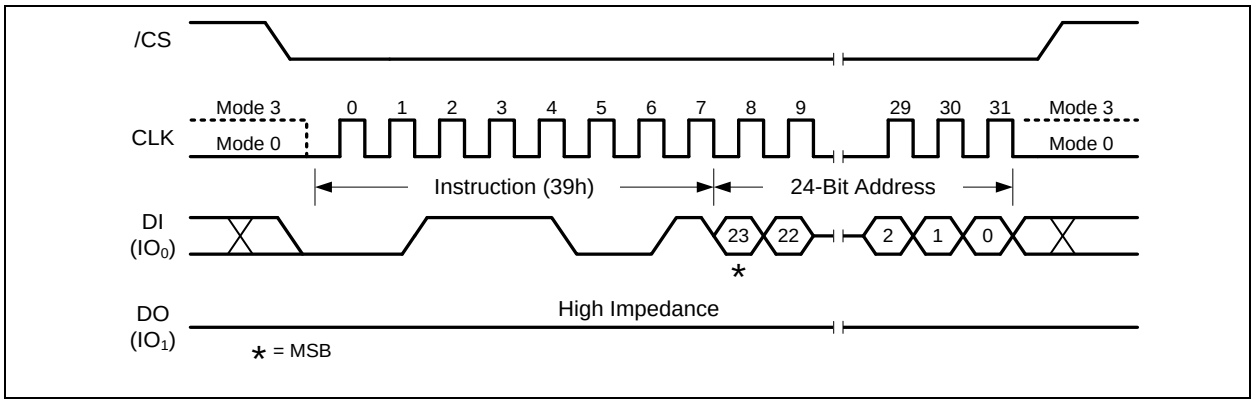



Figure 56. Individual Block Unlock Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.47 Read Block/Sector Lock (3Dh)

The Individual Block/Sector Lock provides an alternative way to protect the memory array from adverse Erase/Program. In order to use the Individual Block/Sector Locks, the WPS bit in Status Register-3 must be set to 1. If WPS=0, the write protection will be determined by the combination of CMP, TB, BP[3:0] bits in the Status Registers. The Individual Block/Sector Lock bits are volatile bits. The default values after device power up or after a Reset are 1, so the entire memory array is being protected.

To read out the lock bit value of a specific block or sector as illustrated in Figure 4d, a Read Block/Sector Lock command must be issued by driving /CS low, shifting the instruction code “3Dh” into the Data Input (DI) pin on the rising edge of CLK, followed by a 24/32-bit address. The Block/Sector Lock bit value will be shifted out on the DO pin at the falling edge of CLK with most significant bit (MSB) first as shown in Figure 57. If the least significant bit (LSB) is 1, the corresponding block/sector is locked; if LSB=0, the corresponding block/sector is unlocked, Erase/Program operation can be performed.

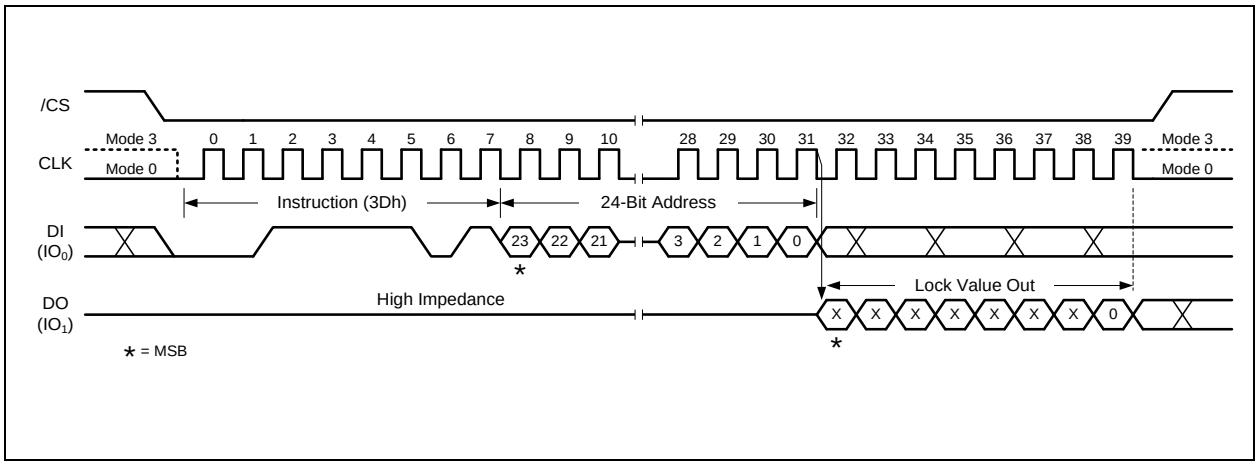



Figure 57. Read Block Lock Instruction

*32-Bit Address is required when the device is operating in 4-Byte Address Mode*



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### 8.2.48 Global Block/Sector Lock (7Eh)

All Block/Sector Lock bits can be set to 1 by the Global Block/Sector Lock instruction. The command must be issued by driving /CS low, shifting the instruction code “7Eh” into the Data Input (DI) pin on the rising edge of CLK, and then driving /CS high.

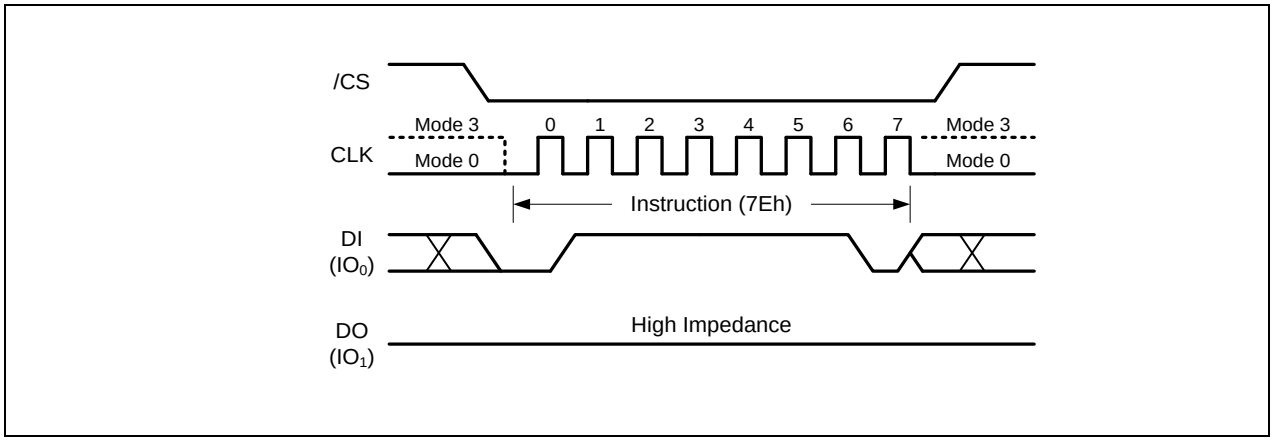



Figure 58. Global Block Lock Instruction for SPI

### 8.2.49 Global Block/Sector Unlock (98h)

All Block/Sector Lock bits can be set to 0 by the Global Block/Sector Unlock instruction. The command must be issued by driving /CS low, shifting the instruction code “98h” into the Data Input (DI) pin on the rising edge of CLK, and then driving /CS high.

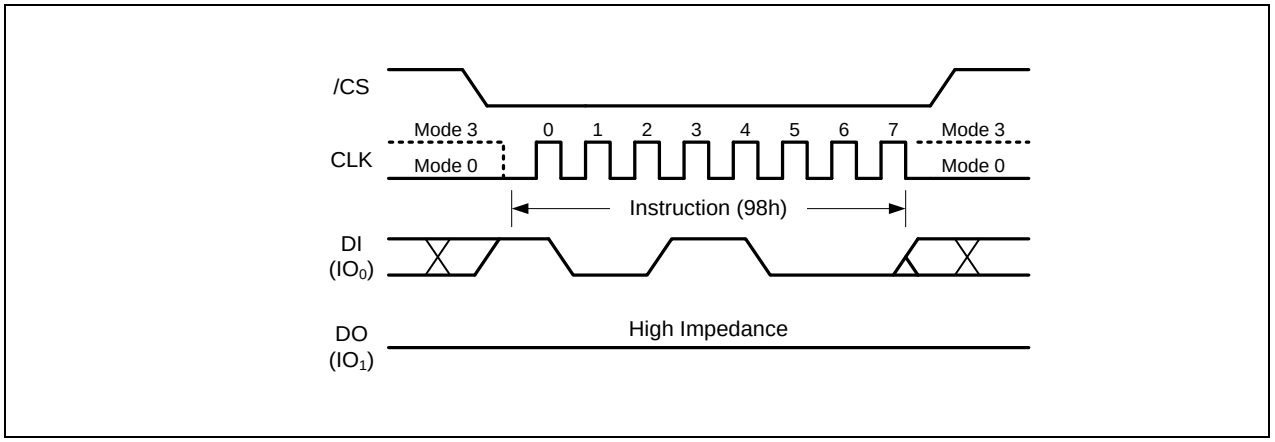



Figure 59. Global Block Unlock Instruction



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### 8.2.50 Enable Reset (66h) and Reset Device (99h)

Because of the small package and the limitation on the number of pins, the W25Q256JW provide a software Reset instruction instead of a dedicated RESET pin. Once the Reset instruction is accepted, any on-going internal operations will be terminated and the device will return to its default power-on state and lose all the current volatile settings, such as Volatile Status Register bits, Write Enable Latch (WEL) status, Program/Erase Suspend status, Read parameter setting (P7-P0), and Continuous Read Mode bit setting (M7-M0).

"Enable Reset (66h)" and "Reset (99h)" instructions can be issued in SPI. To avoid accidental reset, both instructions must be issued in sequence. Any other commands other than "Reset (99h)" after the "Enable Reset (66h)" command will disable the "Reset Enable" state. A new sequence of "Enable Reset (66h)" and "Reset (99h)" is needed to reset the device. Once the Reset command is accepted by the device, the device will take approximately tRST=30us to reset. During this period, no command will be accepted.

Data corruption may happen if there is an on-going or suspended internal Erase or Program operation when Reset command sequence is accepted by the device. It is recommended to check the BUSY bit and the SUS bit in Status Register before issuing the Reset command sequence.

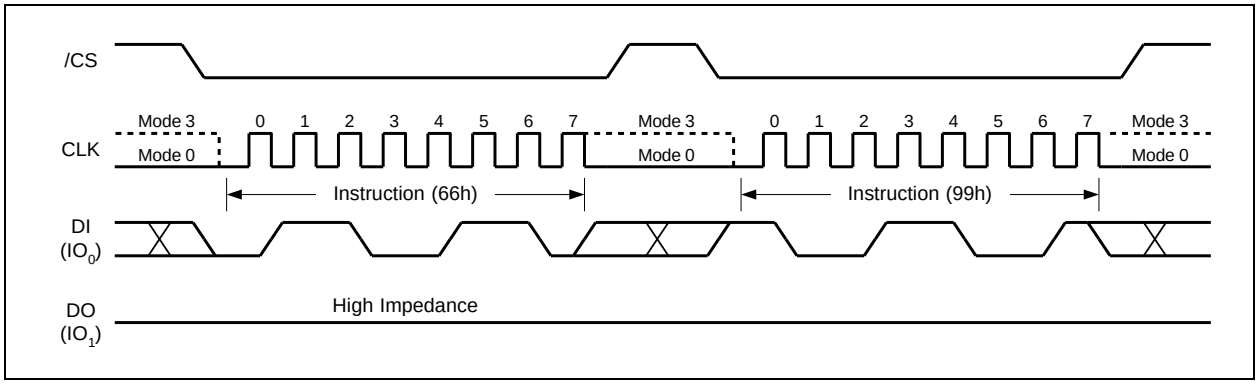



Figure 60. Enable Reset and Reset Instruction Sequence



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# 9. ELECTRICAL CHARACTERISTICS

## 9.1 Absolute Maximum Ratings (1)

| PARAMETERS | SYMBOL | CONDITIONS | RANGE | UNIT |
|---|---|---|---|---|
| Supply Voltage | VCC | | –0.6 to +2.5V | V |
| Voltage Applied to Any Pin | VIO | Relative to Ground | –0.6 to VCC+0.4 | V |
| Transient Voltage on any Pin | VIOT | <20nS Transient Relative to Ground | –2.0 to VCC+2.0 | V |
| Storage Temperature | TSTG | | –65 to +150 | °C |
| Lead Temperature | TLEAD | | See Note (2) | °C |
| Electrostatic Discharge Voltage | VESD | Human Body Model(3) | –2000 to +2000 | V |

**Notes:**

1. This device has been designed and tested for the specified operation ranges. Proper operation outside of these levels is not guaranteed. Exposure to absolute maximum ratings may affect device reliability. Exposure beyond absolute maximum ratings may cause permanent damage.
2. Compliant with JEDEC Standard J-STD-20C for small body Sn-Pb or Pb-free (Green) assembly and the European directive on restrictions on hazardous substances (RoHS) 2002/95/EU.
3. JEDEC Std JESD22-A114A (C1=100pF, R1=1500 ohms, R2=500 ohms).

## 9.2 Operating Ranges

| PARAMETER | SYMBOL | CONDITIONS | SPEC | | UNIT |
|---|---|---|---|---|---|
| | | | MIN | MAX | |
| Supply Voltage(1) | VCC | FR = 133MHz, fR = 50MHz | 1.7 | 1.95 | V |
| Ambient Temperature, Operating | TA | Industrial | –40 | +85 | °C |
| | | Industrial Plus | –40 | +105 | °C |

**Note:**

1. VCC voltage during Read can operate across the min and max range but should not exceed ±10% of the programming (erase/write) voltage.



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## 9.3 Power-up Power-down Timing and Requirements

| PARAMETER | SYMBOL | SPEC | | UNIT |
|---|---|---|---|---|
| | | MIN | MAX | |
| VCC (min) to /CS Low | $t_{VSL}$(1) | 20 | | µs |
| Time Delay Before Write Instruction | $t_{PUW}$(1) | 5 | | ms |
| Write Inhibit Threshold Voltage | $V_{WI}$(1) | 1.0 | 1.4 | V |
| The minimum duration for ensuring initialization will occur | $t_{PWD}$(1) | 100 | | µs |
| VCC voltage needed to below $V_{PWD}$ for ensuring initialization will occur | $V_{PWD}$(1) | | 0.8 | V |

**Note:**

1. These parameters are characterized only.

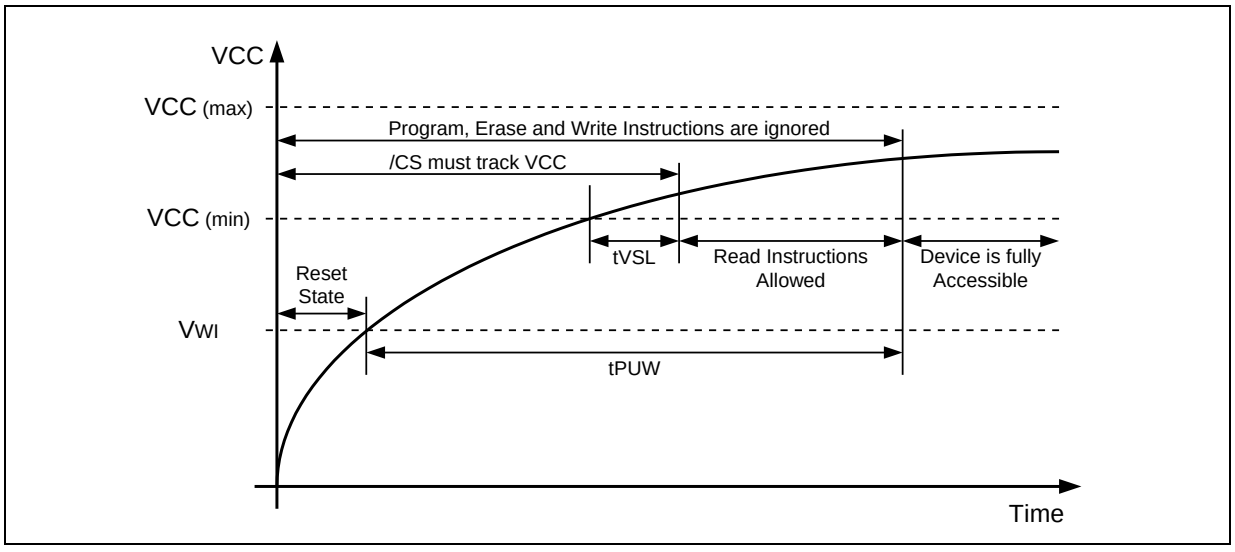



Figure 65a. Power-up Timing and Voltage Levels



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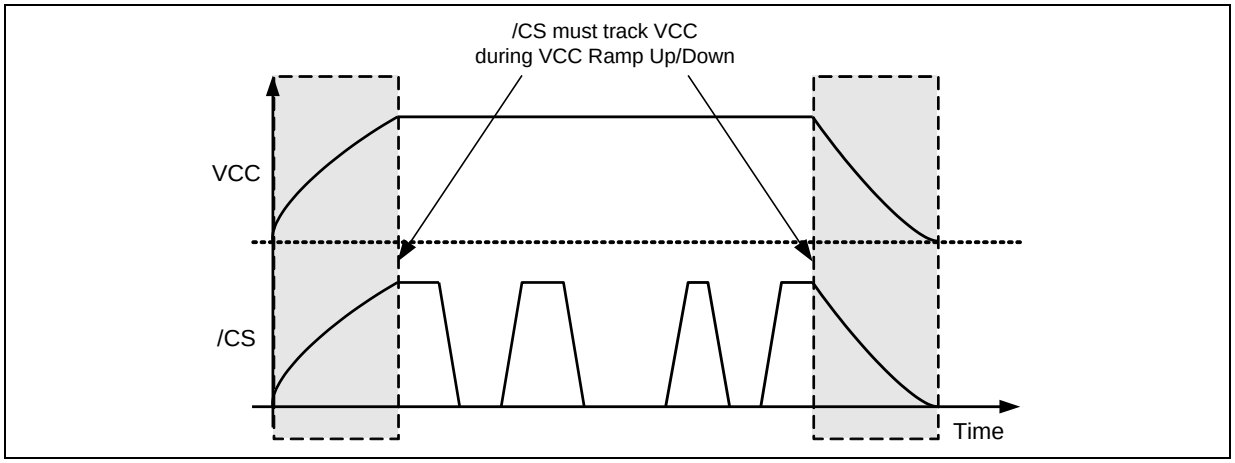



Figure 65b. Power-up, Power-Down Requirement

### 9.3.1 Power Cycle Requirement

For power cycle, the system must not initial the power-up sequence until Vcc drops down to $V_{PWD}$ and keeps a $t_{PWD}$ for device to initialize correctly.

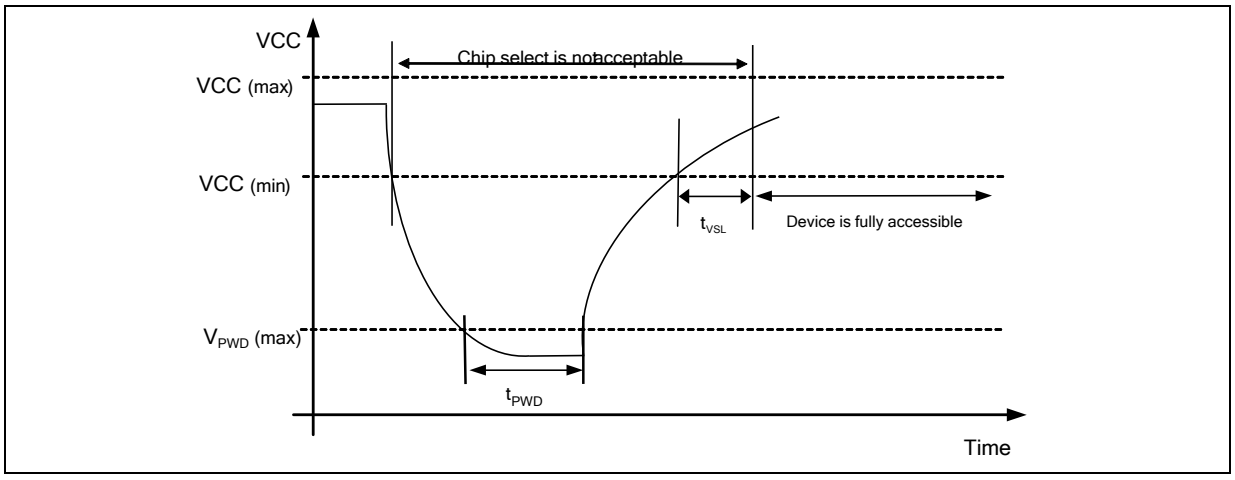



Figure 65c. Power Cycle Requirement



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## 9.4 DC Electrical Characteristics

| PARAMETER | SYMBOL | CONDITIONS | SPEC | | | UNIT |
|---|---|---|---|---|---|---|
| | | | MIN | TYP | MAX | |
| Input Capacitance | $C_{IN}$(1) | $V_{IN}$ = 0V | | | 6 | pF |
| Output Capacitance | $C_{OUT}$(1) | $V_{OUT}$ = 0V | | | 8 | pF |
| Input Leakage | $I_{LI}$ | | | | ±2 | µA |
| I/O Leakage | $I_{LO}$ | | | | ±2 | µA |
| Standby Current | $I_{CC1}$ | /CS = VCC, VIN = GND or VCC (85℃) | | 10 | 35 | µA |
| | | /CS = VCC, VIN = GND or VCC(105℃) | | 10 | 100 | µA |
| Power-down Current | $I_{CC2}$ | /CS = VCC, VIN = GND or VCC(85℃) | | 1 | 15 | µA |
| | | /CS = VCC, VIN = GND or VCC(105℃) | | 1 | 50 | µA |
| Current Read Data 1MHz | $I_{CC3}$(2) | C = 0.1 VCC / 0.9 VCC DO = Open | | 1 | 3 | mA |
| Current Read Data / Dual /Quad 50MHz | $I_{CC3}$(2) | C = 0.1 VCC / 0.9 VCC DO = Open | | 6 | 8 | mA |
| Current Read Data / Dual /Quad 80MHz | $I_{CC3}$(2) | C = 0.1 VCC / 0.9 VCC DO = Open | | 8 | 10 | mA |
| Current Read Data / Dual Output Read/Quad Output Read 104MHz | $I_{CC3}$(2) | C = 0.1 VCC / 0.9 VCC DO = Open | | 10 | 12 | mA |
| Current Write Status Register | $I_{CC4}$ | /CS = VCC | | 12 | 20 | mA |
| Current Page Program | $I_{CC5}$ | /CS = VCC | | 12 | 20 | mA |
| Current Sector/Block Erase | $I_{CC6}$ | /CS = VCC | | 12 | 20 | mA |
| Current Chip Erase | $I_{CC7}$ | /CS = VCC | | 12 | 20 | mA |
| Input Low Voltage | $V_{IL}$ | | –0.5 | | VCC x 0.3 | V |
| Input High Voltage | $V_{IH}$ | | VCC x 0.7 | | | V |
| Output Low Voltage | $V_{OL}$ | $I_{OL}$ = 100 µA | | | 0.2 | V |
| Output High Voltage | $V_{OH}$ | $I_{OH}$ = –100 µA | VCC – 0.2 | | | V |

**Notes:**

1. Tested on sample basis and specified through design and characterization data. TA = 25° C, VCC = 1.8V.
2. Checker Board Pattern.



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## 9.5 AC Measurement Conditions

| PARAMETER | SYMBOL | SPEC | | UNIT |
|---|---|---|---|---|
| | | MIN | MAX | |
| Load Capacitance | $C_L$ | | 30 | pF |
| Input Rise and Fall Times | $T_R$, $T_F$ | | 5 | ns |
| Input Pulse Voltages | $V_{IN}$ | 0.1 VCC to 0.9 VCC | | V |
| Input Timing Reference Voltages | IN | 0.3 VCC to 0.7 VCC | | V |
| Output Timing Reference Voltages | OUT | 0.5 VCC to 0.5 VCC | | V |

**Note:**

1. Output Hi-Z is defined as the point where data out is no longer driven.

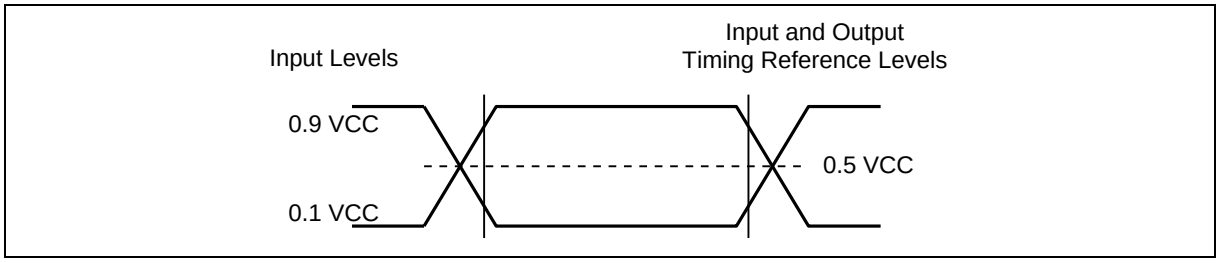



Figure 66. AC Measurement I/O Waveform



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## 9.6 AC Electrical Characteristics[4,5] - Operating Temperature –40°C to +85°C

| DESCRIPTION | SYMBOL | ALT | SPEC | | | UNIT |
|---|---|---|---|---|---|---|
| | | | MIN | TYP | MAX | |
| Clock frequency for SPI-EBh instruction | $F_R$ | $f_{C1}$ | D.C. | | 133 | MHz |
| Clock frequency except for Read Data (03h/13h) | $F_R$ | $f_{C2}$ | D.C. | | 104 | MHz |
| Clock frequency for Read Data instruction (03h/13h) | $f_R$ | | D.C. | | 50 | MHz |
| Clock High, Low Time for all instructions except for Read Data (03h) | $t_{CLH}$, $t_{CLL}$[1] | | 45% $P_C$ | | | ns |
| Clock High, Low Time for Read Data (03h) instruction | $t_{CRLH}$, $t_{CRLL}$[1] | | 45% $P_C$ | | | ns |
| Clock Rise Time peak to peak | $t_{CLCH}$[2] | | 0.1 | | | V/ns |
| Clock Fall Time peak to peak | $t_{CHCL}$[2] | | 0.1 | | | V/ns |
| /CS Active Setup Time relative to CLK | $t_{SLCH}$ | $t_{CSS}$ | 3 | | | ns |
| /CS Not Active Hold Time relative to CLK | $t_{CHSL}$ | | 3 | | | ns |
| Data In Setup Time | $t_{DVCH}$ | $t_{DSU}$ | 1 | | | ns |
| Data In Hold Time | $t_{CHDX}$ | $t_{DH}$ | 2 | | | ns |
| /CS Active Hold Time relative to CLK | $t_{CHSH}$ | | 5 | | | ns |
| /CS Not Active Setup Time relative to CLK | $t_{SHCH}$ | | 5 | | | ns |
| /CS Deselect Time (During Read) | $t_{SHSL1}$ | $t_{CSH}$ | 10 | | | ns |
| /CS Deselect Time (During Erase or Program or Write) | $t_{SHSL2}$ | $t_{CSH}$ | 50 | | | ns |
| Output Disable Time | $t_{SHQZ}$[2] | $t_{DIS}$ | | | 10 | ns |
| Clock Low to Output Valid | $t_{CLQV1}$ | $t_{V1}$ | | | 6 | ns |
| Output Hold Time | $t_{CLQX}$ | $t_{HO}$ | 2 | | | ns |

Continued – next page



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AC Electrical Characteristics (cont'd) - Operating Temperature –40°C to +85°C

| DESCRIPTION | SYMBOL | ALT | SPEC | | | UNIT |
|---|---|---|---|---|---|---|
| | | | MIN | TYP | MAX | |
| Write Protect Setup Time Before /CS Low | $t_{WHSL}$(3) | | 20 | | | ns |
| Write Protect Hold Time After /CS High | $t_{SHWL}$(3) | | 100 | | | ns |
| /CS High to Power-down Mode | $t_{DP}$(2) | | | | 3 | µs |
| /CS High to Standby Mode without ID Read | $t_{RES1}$(2) | | | | 30 | µs |
| /CS High to next Instruction after Suspend | $t_{SUS}$(2) | | | | 20 | µs |
| /CS High to next Instruction after Reset | $t_{RST}$(2) | | | | 30 | µs |
| /RESET pin Low period to reset the device | $t_{RESET}$(2) | | 1(3) | | | µs |
| Write Status Register Time | $t_W$ | | | 2 | 30 | ms |
| Page Program Time | $t_{PP}$ | | | 0.8 | 5 | ms |
| Sector Erase Time (4KB) | $t_{SE}$ | | | 50 | 400 | ms |
| Block Erase Time (32KB) | $t_{BE_1}$ | | | 120 | 1,600 | ms |
| Block Erase Time (64KB) | $t_{BE_2}$ | | | 200 | 2,000 | ms |
| Chip Erase Time | $t_{CE}$ | | | 90 | 400 | s |

**Notes:**

1. Clock high + Clock low must be less than or equal to $P_C = 1/f_{C(MAX.)}$.
2. Value guaranteed by design and/or characterization, not 100% tested in production.
3. It is possible to reset the device with shorter tRESET (as short as a few hundred ns), a 1us minimum is recommended to ensure reliable operation.
4. Tested on sample basis and specified through design and characterization data. TA = 25° C, VCC = 1.8V, 25% driver strength.
5. 4-bytes address alignment: read address always start from (A1,A0)=[0,0]



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## 9.7 AC Electrical Characteristics[4,5] - Operating Temperature Range –40°C to +105°C

| DESCRIPTION | SYMBOL | ALT | SPEC | | | UNIT |
|---|---|---|---|---|---|---|
| | | | MIN | TYP | MAX | |
| Clock frequency for all instructions except for Read Data (03h) | $F_R$ | $f_C$ | D.C. | | 104 | MHz |
| Clock frequency for Read Data instruction (03h/13h) | $f_R$ | | D.C. | | 50 | MHz |
| Clock High, Low Time for all instructions except for Read Data (03h) | $t_{CLH}$, $t_{CLL}$[1] | | 45% $P_C$ | | | ns |
| Clock High, Low Time for Read Data (03h) instruction | $t_{CRLH}$, $t_{CRLL}$[1] | | 45% $P_C$ | | | ns |
| Clock Rise Time peak to peak | $t_{CLCH}$[2] | | 0.1 | | | V/ns |
| Clock Fall Time peak to peak | $t_{CHCL}$[2] | | 0.1 | | | V/ns |
| /CS Active Setup Time relative to CLK | $t_{SLCH}$ | $t_{CSS}$ | 3 | | | ns |
| /CS Not Active Hold Time relative to CLK | $t_{CHSL}$ | | 3 | | | ns |
| Data In Setup Time | $t_{DVCH}$ | $t_{DSU}$ | 1 | | | ns |
| Data In Hold Time | $t_{CHDX}$ | $t_{DH}$ | 2 | | | ns |
| /CS Active Hold Time relative to CLK | $t_{CHSH}$ | | 5 | | | ns |
| /CS Not Active Setup Time relative to CLK | $t_{SHCH}$ | | 5 | | | ns |
| /CS Deselect Time (During Read) | $t_{SHSL1}$ | $t_{CSH}$ | 10 | | | ns |
| /CS Deselect Time (During Erase or Program or Write) | $t_{SHSL2}$ | $t_{CSH}$ | 50 | | | ns |
| Output Disable Time | $t_{SHQZ}$[2] | $t_{DIS}$ | | | 10 | ns |
| Clock Low to Output Valid | $t_{CLQV1}$ | $t_{V1}$ | | | 6 | ns |
| Output Hold Time | $t_{CLQX}$ | $t_{HO}$ | 2 | | | ns |

Continued – next page



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AC Electrical Characteristics (cont'd) - Operating Temperature Range –40°C to +105°C

| DESCRIPTION | SYMBOL | ALT | SPEC | | | UNIT |
|---|---|---|---|---|---|---|
| | | | MIN | TYP | MAX | |
| Write Protect Setup Time Before /CS Low | $t_{WHSL}$(3) | | 20 | | | ns |
| Write Protect Hold Time After /CS High | $t_{SHWL}$(3) | | 100 | | | ns |
| /CS High to Power-down Mode | $t_{DP}$(2) | | | | 3 | µs |
| /CS High to Standby Mode without ID Read | $t_{RES1}$(2) | | | | 30 | µs |
| /CS High to next Instruction after Suspend | $t_{SUS}$(2) | | | | 20 | µs |
| /CS High to next Instruction after Reset | $t_{RST}$(2) | | | | 30 | µs |
| /RESET pin Low period to reset the device | $t_{RESET}$(2) | | 1(3) | | | µs |
| Write Status Register Time | $t_W$ | | | 2 | 30 | ms |
| Page Program Time | $t_{PP}$ | | | 0.8 | 5 | ms |
| Sector Erase Time (4KB) | $t_{SE}$ | | | 50 | 400 | ms |
| Block Erase Time (32KB) | $t_{BE_1}$ | | | 120 | 1,600 | ms |
| Block Erase Time (64KB) | $t_{BE_2}$ | | | 200 | 2,000 | ms |
| Chip Erase Time | $t_{CE}$ | | | 90 | 400 | s |

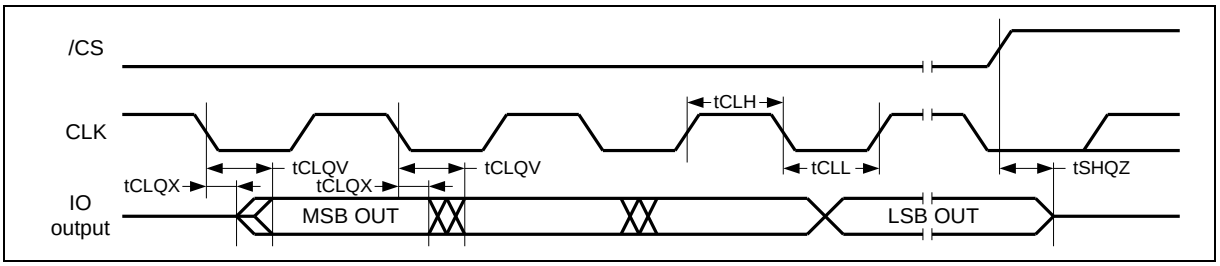
**Notes:**

1. Clock high + Clock low must be less than or equal to $P_C = 1/f_{C(MAX.)}$.
2. Value guaranteed by design and/or characterization, not 100% tested in production.
3. It is possible to reset the device with shorter tRESET (as short as a few hundred ns), a 1us minimum is recommended to ensure reliable operation.
4. Tested on sample basis and specified through design and characterization data. TA = 25° C, VCC = 1.8V, 25% driver strength.
5. 4-bytes address alignment: read address always start from (A1,A0)=[0,0]

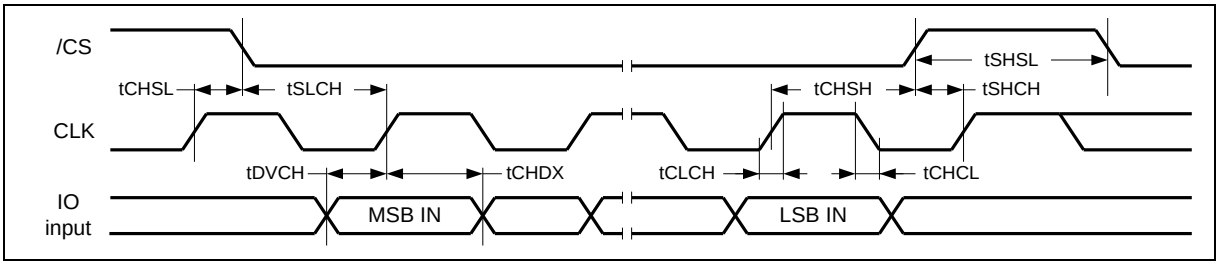


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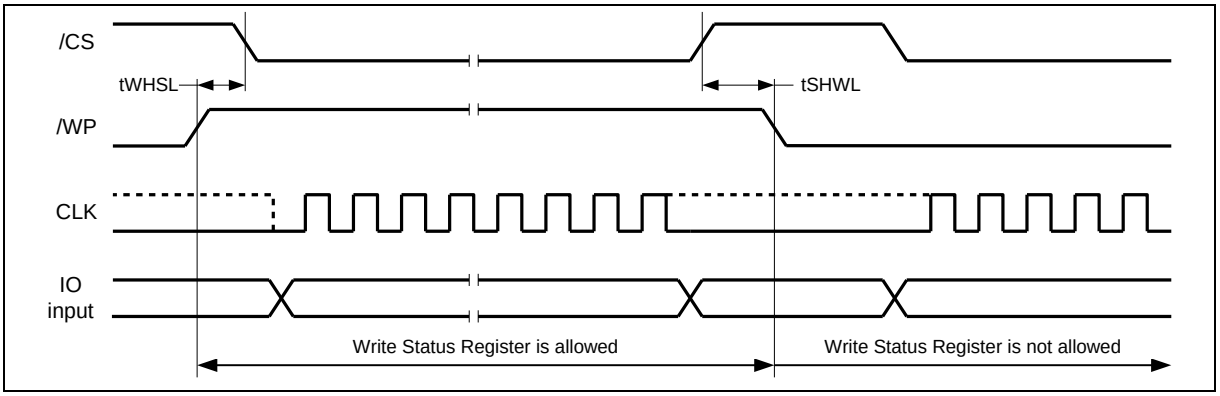
## 9.8 Serial Output Timing




## 9.9 Serial Input Timing




## 9.10 /WP Timing

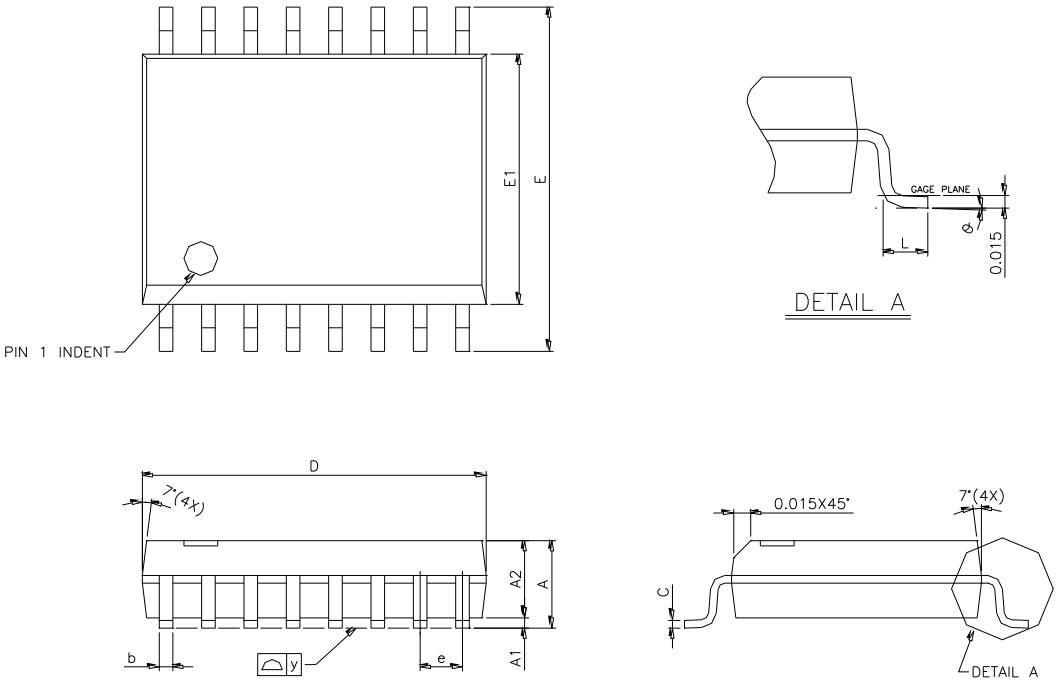





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# 10. PACKAGE SPECIFICATIONS

## 10.1 16-Pin SOIC 300-mil (Package Code F)

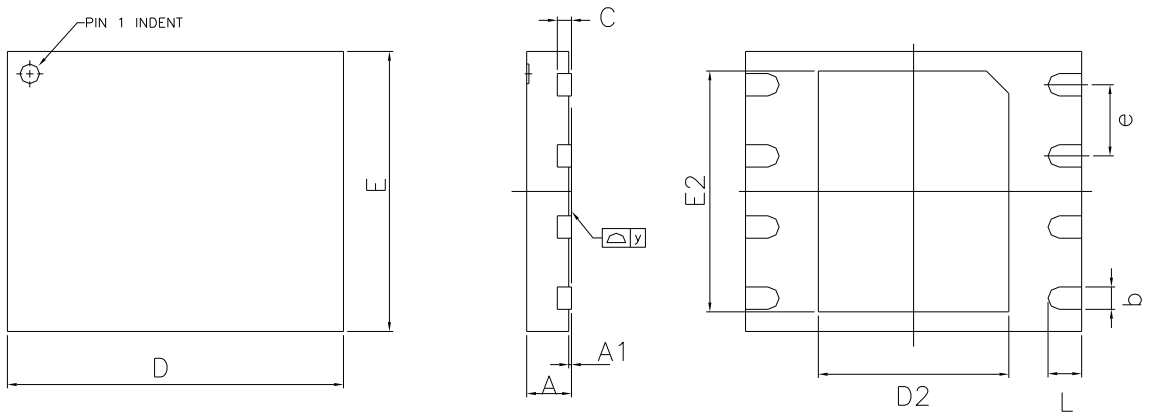



| Symbol | Millimeters | | | Inches | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | 2.36 | 2.49 | 2.64 | 0.093 | 0.098 | 0.104 |
| A1 | 0.10 | --- | 0.30 | 0.004 | --- | 0.012 |
| A2 | --- | 2.31 | --- | --- | 0.091 | --- |
| b | 0.33 | 0.41 | 0.51 | 0.013 | 0.016 | 0.020 |
| C | 0.18 | 0.23 | 0.28 | 0.007 | 0.009 | 0.011 |
| D | 10.08 | 10.31 | 10.49 | 0.397 | 0.406 | 0.413 |
| E | 10.01 | 10.31 | 10.64 | 0.394 | 0.406 | 0.419 |
| E1 | 7.39 | 7.49 | 7.59 | 0.291 | 0.295 | 0.299 |
| e | 1.27 BSC | | | 0.050 BSC | | |
| L | 0.38 | 0.81 | 1.27 | 0.015 | 0.032 | 0.050 |
| y | --- | --- | 0.076 | --- | --- | 0.003 |
| θ | 0° | --- | 8° | 0° | --- | 8° |



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## 10.1 8-Pad WSON 6x5-mm (Package Code P)




| Symbol | Millimeters | | | Inches | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | 0.70 | 0.75 | 0.80 | 0.028 | 0.030 | 0.031 |
| A1 | 0.00 | 0.02 | 0.05 | 0.000 | 0.001 | 0.002 |
| b | 0.35 | 0.40 | 0.48 | 0.014 | 0.016 | 0.019 |
| C | --- | 0.20 REF | --- | --- | 0.008 REF | --- |
| D | 5.90 | 6.00 | 6.10 | 0.232 | 0.236 | 0.240 |
| D2 | 2.9 | 3.0 | 3.10 | 0.114 | 0.118 | 0.136 |
| E | 4.90 | 5.00 | 5.10 | 0.193 | 0.197 | 0.201 |
| E2 | 4.20 | 4.30 | 4.40 | 0.167 | 0.169 | 0.171 |
| e | 1.27 BSC | | | 0.050 BSC | | |
| L | 0.55 | 0.60 | 0.65 | 0.022 | 0.024 | 0.026 |
| y | 0.00 | --- | 0.075 | 0.000 | --- | 0.003 |

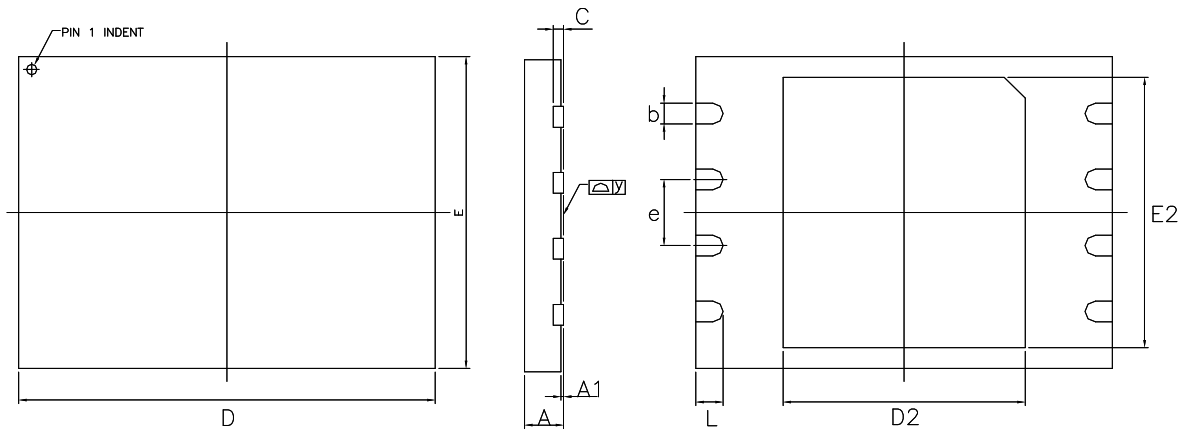
Note:

*The metal pad area on the bottom center of the package is not connected to any internal electrical signals. It can be left floating or connected to the device ground (GND pin). Avoid placement of exposed PC*B vias under the pad.



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## 10.2 8-Pad WSON 8x6-mm (Package Code E)




| SYMBOL | MILLIMETERS | | | INCHES | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | 0.70 | 0.75 | 0.80 | 0.028 | 0.030 | 0.031 |
| A1 | 0.00 | 0.02 | 0.05 | 0.000 | 0.001 | 0.002 |
| b | 0.35 | 0.40 | 0.48 | 0.014 | 0.016 | 0.019 |
| C | --- | 0.20 Ref. | --- | --- | 0.008 Ref. | --- |
| D | 7.90 | 8.00 | 8.10 | 0.311 | 0.315 | 0.319 |
| D2 | 3.35 | 3.40 | 3.45 | 0.132 | 0.134 | 0.136 |
| E | 5.90 | 6.00 | 6.10 | 0.232 | 0.236 | 0.240 |
| E2 | 4.25 | 4.30 | 4.35 | 0.167 | 0.169 | 0.171 |
| e | 1.27 BSC | | | 0.050 BSC | | |
| L | 0.45 | 0.50 | 0.55 | 0.018 | 0.020 | 0.022 |
| y | 0.00 | --- | 0.05 | 0.000 | --- | 0.002 |

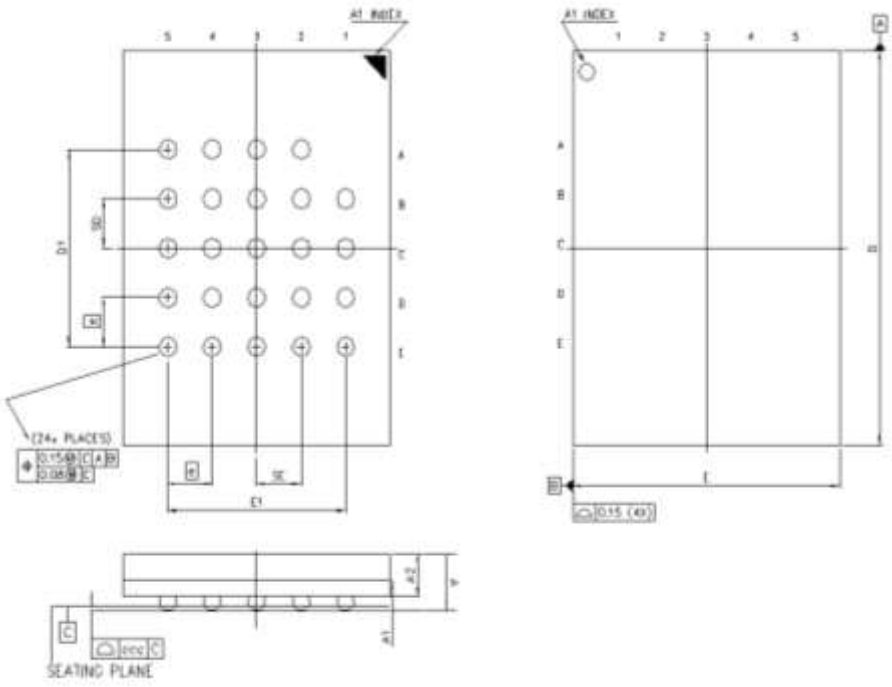
Note:

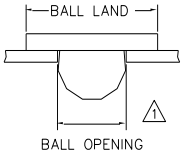
The metal pad area on the bottom center of the package is not connected to any internal electrical signals. It can be left floating or connected to the device ground (GND pin). Avoid placement of exposed PCB vias under the pad.



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## 10.3 24-Ball TFBGA 8x6-mm (Package Code B, 5x5-1 Ball Array)




Note:

Ball land: 0.45mm. Ball Opening: 0.35mm

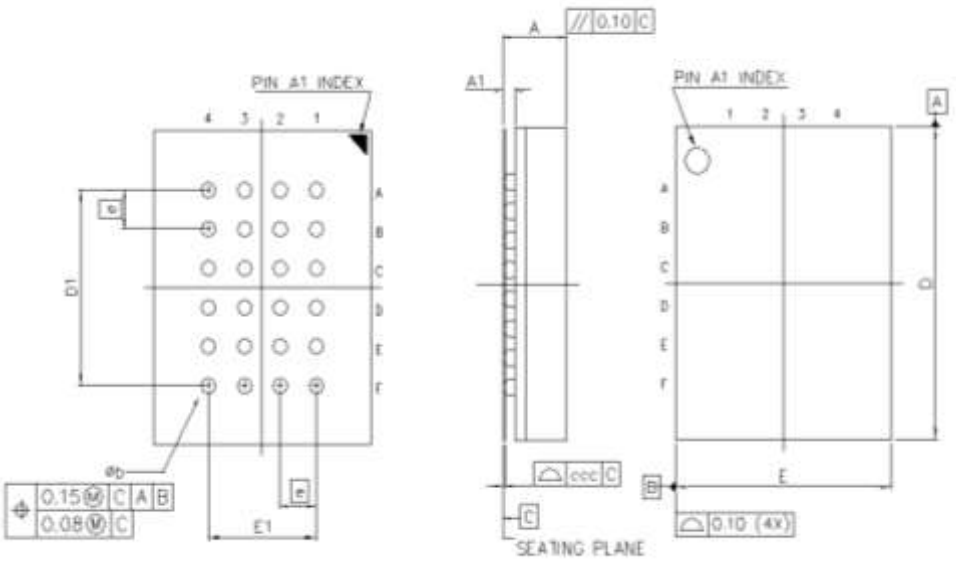
PCB ball land suggested <= 0.35mm

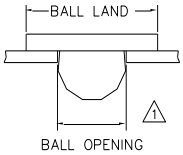
| Symbol | Millimeters | | | Inches | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | --- | --- | 1.20 | --- | --- | 0.047 |
| A1 | 0.26 | 0.31 | 0.36 | 0.010 | 0.012 | 0.014 |
| A2 | --- | 0.85 | --- | --- | 0.033 | --- |
| b | 0.35 | 0.40 | 0.45 | 0.014 | 0.016 | 0.018 |
| D | 7.90 | 8.00 | 8.10 | 0.311 | 0.315 | 0.319 |
| D1 | 4.00 BSC | | | 0.157 BSC | | |
| E | 5.90 | 6.00 | 6.10 | 0.232 | 0.236 | 0.240 |
| E1 | 4.00 BSC | | | 0.157 BSC | | |
| SE | 1.00 TYP | | | 0.039 TYP | | |
| SD | 1.00 TYP | | | 0.039 TYP | | |
| e | 1.00 BSC | | | 0.039 BSC | | |
| ccc | --- | --- | 0.10 | --- | --- | 0.0039 |



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## 10.4 24-Ball TFBGA 8x6-mm (Package Code C, 6x4 Ball Array)




Note:

Ball land: 0.45mm. Ball Opening: 0.35mm

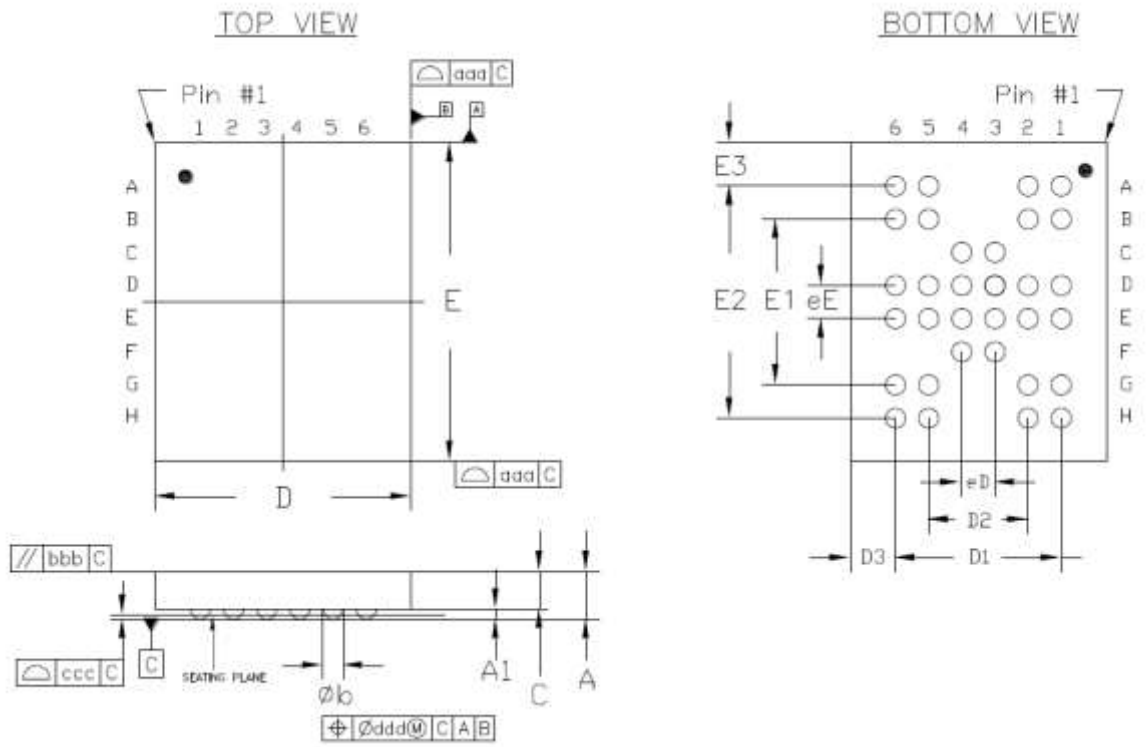
PCB ball land suggested <= 0.35mm

| Symbol | Millimeters | | | Inches | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | --- | --- | 1.20 | --- | --- | 0.047 |
| A1 | 0.25 | 0.30 | 0.35 | 0.010 | 0.012 | 0.014 |
| b | 0.35 | 0.40 | 0.45 | 0.014 | 0.016 | 0.018 |
| D | 7.95 | 8.00 | 8.05 | 0.313 | 0.315 | 0.317 |
| D1 | | 5.00 BSC | | | 0.197 BSC | |
| E | 5.95 | 6.00 | 6.05 | 0.234 | 0.236 | 0.238 |
| E1 | | 3.00 BSC | | | 0.118 BSC | |
| e | | 1.00 BSC | | | 0.039 BSC | |
| ccc | --- | --- | 0.10 | --- | --- | 0.039 |



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## 10.5 32-Ball WLCSP (Package Code Y, Ball pitch:0.50mm)




| Symbol | Millimeters | | | Inches | | |
|---|---|---|---|---|---|---|
| | Min | Nom | Max | Min | Nom | Max |
| A | 0.454 | 0.497 | 0.540 | 0.018 | 0.02 | 0.021 |
| A1 | 0.152 | 0.167 | 0.182 | 0.006 | 0.007 | 0.007 |
| c | 0.302 | 0.330 | 0.358 | 0.012 | 0.013 | 0.014 |
| b | 0.240 | 0.300 | 0.360 | 0.009 | 0.01 | 0.014 |
| D1 | | 2.50 | | | 0.098 | |
| D2 | | 1.50 | | | 0.059 | |
| D3 | | 0.663 | | | 0.02 | |
| E1 | | 2.50 | | | 0.154 | |
| E2 | | 3.50 | | | 0.114 | |
| E3 | | 0.633 | | | 0.047 | |
| eD | 0.5 BSC | | | 0.0197 BSC | | |
| eE | 0.5 BSC | | | 0.0197 BSC | | |
| aaa | 0.10 | | | 0.004 | | |
| bbb | 0.10 | | | 0.004 | | |
| ccc | 0.03 | | | 0.001 | | |
| ddd | 0.15 | | | 0.006 | | |

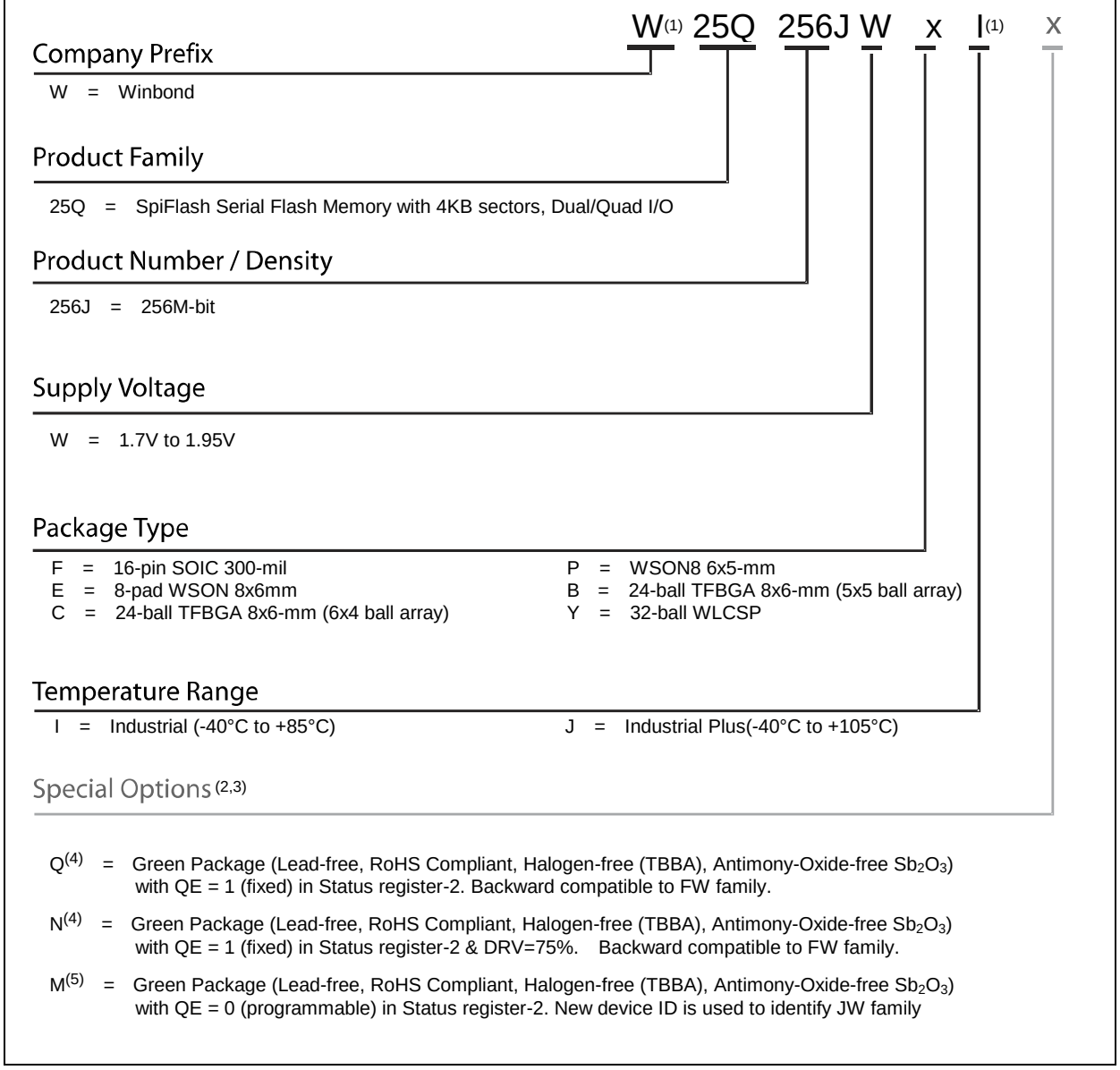
Note:

1. Dimension b is measured at the maximum solder bump diameter, parallel to primary datum C.
2. For dimension D & E; please contact Winbond.



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## 10.6 Ordering Information




Notes:

1. The “W” prefix and the Temperature designator “I” are not included on the part marking.
2. Standard bulk shipments are in Tube (shape E). Please specify alternate packing method, such as Tape and Reel (shape T) or Tray (shape S), when placing orders.
3. For shipments with special order options, please contact Winbond.
4. /HOLD function is disabled to support Standard, Dual and Quad I/O without user setting.
5. For DTR, QPI supporting, please refer to W25Q256JW-M DTR datasheet



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## 10.7 Valid Part Numbers and Top Side Marking

The following table provides the valid part numbers for the W25Q256JW SpiFlash Memory. Please contact Winbond for specific availability by density and package type. Winbond SpiFlash memories use a 12-digit Product Number for ordering. However, due to limited space, the Top Side Marking on all packages uses an abbreviated 10-digit number.

**W25Q256JW-IQ(-40°C to +85°C) valid part numbers:**

| PACKAGE TYPE | DENSITY | PRODUCT NUMBER | TOP SIDE MARKING |
|---|---|---|---|
| **F**<br>SOIC-16 300mil | 256M-bit | W25Q256JWFIQ | 25Q256JWFQ |
| **P**<br>WSON-8 6x5-mm | 256M-bit | W25Q256JWPIQ | 25Q256JWPQ |
| **E**<br>WSON-8 8x6mm | 256M-bit | W25Q256JWEIQ | 25Q256JWEQ |
| **B**<br>TFBGA-24 8x6mm<br>(5x5-1 Ball Array) | 256M-bit | W25Q256JWBIQ | 25Q256JWBQ |
| **C**<br>TFBGA-24 8x6mm<br>(6x4 Ball Array) | 256M-bit | W25Q256JWCIQ | 25Q256JWCQ |
| **Y**[(1)]<br>32-ball WLCSP | 256M-bit | W25Q256JWYIQ | Q256JWY<br>IQ-yyww |

**W25Q256JW-IN(-40°C to +85°C) valid part numbers**

| PACKAGE TYPE | DENSITY | PRODUCT NUMBER | TOP SIDE MARKING |
|---|---|---|---|
| **F**<br>SOIC-16 300mil | 256M-bit | W25Q256JWFIN | 25Q256JWFN |
| **E**<br>WSON-8 8x6mm | 256M-bit | W25Q256JWEIN | 25Q256JWEN |

**W25Q256JW-JQ (-40°C to +105°C) valid part numbers:**

| PACKAGE TYPE | DENSITY | PRODUCT NUMBER | TOP SIDE MARKING |
|---|---|---|---|
| **F**<br>SOIC-16 300mil | 256M-bit | W25Q256JWFJQ | Q256JWFJQ |
| **P**<br>WSON-8 6x5-mm | 256M-bit | W25Q256JWPJQ | Q256JWPJQ |
| **E**<br>WSON-8 8x6mm | 256M-bit | W25Q256JWEJQ | Q256JWEJQ |



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**W25Q256JW-IM[2] (-40°C to +85°C) valid part numbers:**

| PACKAGE TYPE | DENSITY | PRODUCT NUMBER | TOP SIDE MARKING |
|---|---|---|---|
| **F**<br>SOIC-16 300mil | 256M-bit | W25Q256JWFIM | 25Q256JWFM |
| **P**<br>WSON-8 6x5-mm | 256M-bit | W25Q256JWPIM | 25Q256JWPM |
| **E**<br>WSON-8 8x6mm | 256M-bit | W25Q256JWEIM | 25Q256JWEM |
| **B**<br>TFBGA-24 8x6mm<br>(5x5-1 Ball Array) | 256M-bit | W25Q256JWBIM | 25Q256JWBM |
| **C**<br>TFBGA-24 8x6mm<br>(6x4 Ball Array) | 256M-bit | W25Q256JWCIM | 25Q256JWCM |
| **Y[1]**<br>32-ball WLCSP | 256M-bit | W25Q256JWYIM | Q256JWY<br>IM-yyww |

Note:

1. WLCSP package type Y has special top marking due to size limitation.
2. For DTR, QPI supporting, please refer to W25Q256JW-M DTR datasheet.



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## 11. REVISION HISTORY

| VERSION | DATE | PAGE | DESCRIPTION |
|---|---|---|---|
| A | 09/09/2016 | | New Create Preliminary<br>Removed 77h command<br>Updated /WP information<br>Updated instruction set table – 03h<br>Updated ICC1-3<br>Updated tPP(max.), tCHSH, tSHCH, tSHQZ, tCLQV<br>Added WLCSP information<br>Added WSON6X5 information |
| B | 12/08/2017 | 81<br>88 | Removed “Preliminary”<br>Updated Icc1(max.)<br>Updated WSON6X5 D2 information |
| C | 08/01/2018 | 33,60,62 | Modified Power-down & Suspend description |
| D | 09/04/2018 | 84 | Modified tRES1 and removed tRES2 |
| E | 10/09/2018 | 89<br>29 | Updated WSON 6X5 E2 value<br>Updated 3Ch clock number |
| F | 10/18/2019 | 5<br>5, 83 | Updated cycling description<br>Updated Clock description of EBh |
| G | 11/25/2019 | 94-95 | Updated 105C package information |
| H | 08/06/2020 | 7<br>14 | Updated PIN1<br>Updated Special order to flow |
| I | 11/12/2020 | 83,85<br>95-96 | Added 13h<br>Updated available package type. |
| J | 2021/03/21 | 18<br>18,20,94,95 | Updated LB typo<br>Added DRV@75% information |

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