Automotive NAND Flash Memory

MT29F2G08ABAEAH4-AITX:E, MT29F2G08ABAEAH4-AATX:E, MT29F2G08ABAEAWP-AITX:E, MT29F2G08ABAEAWP-AATX:E, MT29F2G08ABBEAH4-AITX:E, MT29F2G08ABBEAHC-AIT:E, MT29F2G16ABAEAWP-AIT:E, MT29F2G16ABBEAHC-AIT:E, MT29F2G16ABBEAH4-AAT:E, MT29F2G16ABAEAWP-AAT:E

Features

- Open NAND Flash Interface (ONFI) 1.0-compliant[1]
- Single-level cell (SLC) technology
- Organization
  - Page size x8: 2112 bytes (2048 + 64 bytes)
  - Page size x16: 1056 words (1024 + 32 words)
  - Block size: 64 pages (128K + 4K bytes)
  - Plane size: 2 planes x 1024 blocks per plane
  - Device size: 2Gb: 2048 blocks
- Asynchronous I/O performance
  - ^{t}RC/^{t}WC: 20ns (3.3V), 25ns (1.8V)
- Array performance
  - Read page: 25µs [3]
  - Program page: 200µs (TYP: 1.8V, 3.3V)[3]
  - Erase block: 700µs (TYP)
- Command set: ONFI NAND Flash Protocol
- Advanced command set
  - Program page cache mode[4]
  - Read page cache mode [4]
  - One-time programmable (OTP) mode
  - Two-plane commands [4]
  - Interleaved die (LUN) operations
  - Read unique ID
  - Block lock (1.8V only)
  - Internal data move
- Operation status byte provides software method for detecting
  - Operation completion
  - Pass/fail condition
  - Write-protect status
- Ready/Busy# (R/B#) signal provides a hardware method of detecting operation completion
- WP# signal: Write protect entire device
- First block (block address 00h) is valid when shipped from factory with ECC. For minimum required ECC, see Error Management.
- Block 0 requires 1-bit ECC if PROGRAM/ERASE cycles are less than 1000
- RESET (FFh) required as first command after power-on
- Alternate method of device initialization (Nand_Init) after power up (contact factory)
- Internal data move operations supported within the plane from which data is read
- Quality and reliability
  - Data retention: 10 years
  - Endurance: 100,000 PROGRAM/ERASE cycles
- Operating voltage range
  - V_{CC}: 2.7–3.6V
  - V_{CC}: 1.7–1.95V
- Operating temperature
  - Automotive Industrial (AIT): –40°C to +85°C
  - Automotive (AAT): –40°C to +105°C
- Package
  - 48-pin TSOP type 1, CPL[2]
  - 63-ball VFBGA

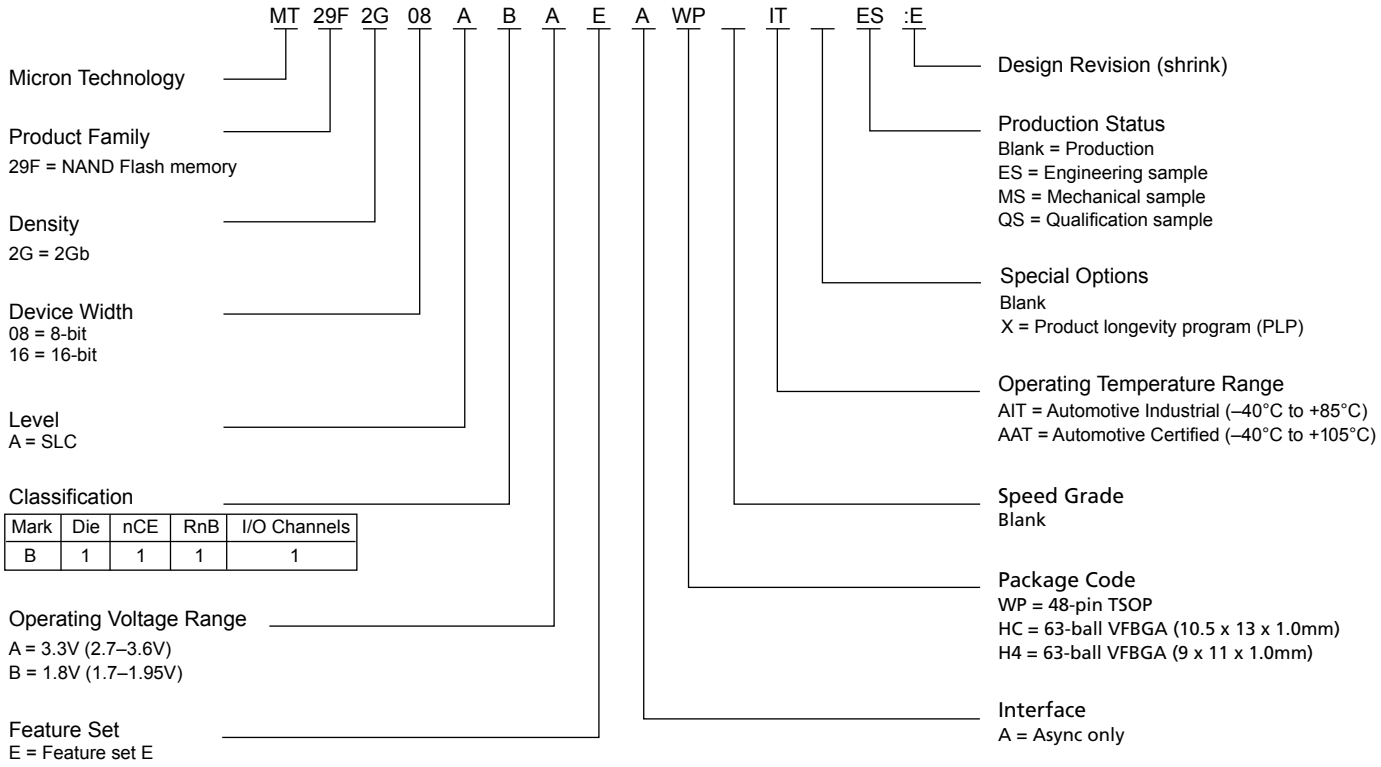
Notes:
1. The ONFI 1.0 specification is available at www.onfi.org.
2. CPL = Center parting line.
3. See Electrical Specifications – Program/Erase Characteristics for ^{t}R_ECC and ^{t}PROG_ECC specifications.
4. These commands supported only with ECC disabled.

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Part Numbering Information

Micron NAND Flash devices are available in different configurations and densities. Verify valid part numbers by using Micron's part catalog search at www.micron.com. To compare features and specifications by device type, visit www.micron.com/products. Contact the factory for devices not found.

Figure 1: Marketing Part Number Chart



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General Description

Micron NAND Flash devices include an asynchronous data interface for high-performance I/O operations. These devices use a highly multiplexed 8-bit bus (I/Ox) to transfer commands, address, and data. There are five control signals used to implement the asynchronous data interface: CE#, CLE, ALE, WE#, and RE#. Additional signals control hardware write protection and monitor device status (R/B#).

This hardware interface creates a low pin-count device with a standard pinout that remains the same from one density to another, enabling future upgrades to higher densities with no board redesign.

A target is the unit of memory accessed by a chip enable signal. A target contains one or more NAND Flash die. A NAND Flash die is the minimum unit that can independently execute commands and report status. A NAND Flash die, in the ONFI specification, is referred to as a logical unit (LUN). There is at least one NAND Flash die per chip enable signal. For further details, see Device and Array Organization.

This device has an internal 4-bit ECC that can be enabled using the GET/SET features. See Internal ECC and Spare Area Mapping for ECC for more information.

Signal Descriptions

Table 1: Signal Definitions

Signal[1]	Type	Description[2]
ALE	Input	**Address latch enable:** Loads an address from I/O[7:0] into the address register.
CE#	Input	**Chip enable:** Enables or disables one or more die (LUNs) in a target.
CLE	Input	**Command latch enable:** Loads a command from I/O[7:0] into the command register.
LOCK	Input	When LOCK is HIGH during power-up, the BLOCK LOCK function is enabled. To disable the BLOCK LOCK, connect LOCK to V_{SS} during power-up, or leave it disconnected (internal pull-down).
RE#	Input	**Read enable:** Transfers serial data from the NAND Flash to the host system.
WE#	Input	**Write enable:** Transfers commands, addresses, and serial data from the host system to the NAND Flash.
WP#	Input	**Write protect:** Enables or disables array PROGRAM and ERASE operations.
I/O[7:0] (x8) I/O[15:0] (x16)	I/O	**Data inputs/outputs:** The bidirectional I/Os transfer address, data, and command information.
R/B#	Output	**Ready/busy:** An open-drain, active-low output that requires an external pull-up resistor. This signal indicates target array activity.
V_{CC}	Supply	**V_{CC}:** Core power supply
V_{SS}	Supply	**V_{SS}:** Core ground connection
NC	–	**No connect:** NCs are not internally connected. They can be driven or left unconnected.
DNU	–	**Do not use:** DNUs must be left unconnected.

Notes:
1. See Device and Array Organization for detailed signal connections.
2. See Asynchronous Interface Bus Operation for detailed asynchronous interface signal descriptions.

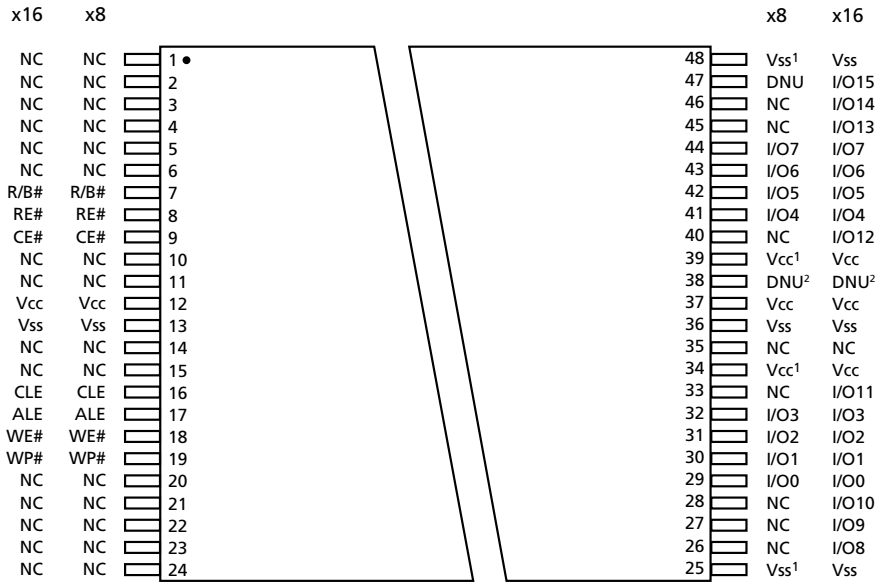
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Signal Assignments

Figure 2: 48-Pin TSOP – Type 1, CPL (Top View)



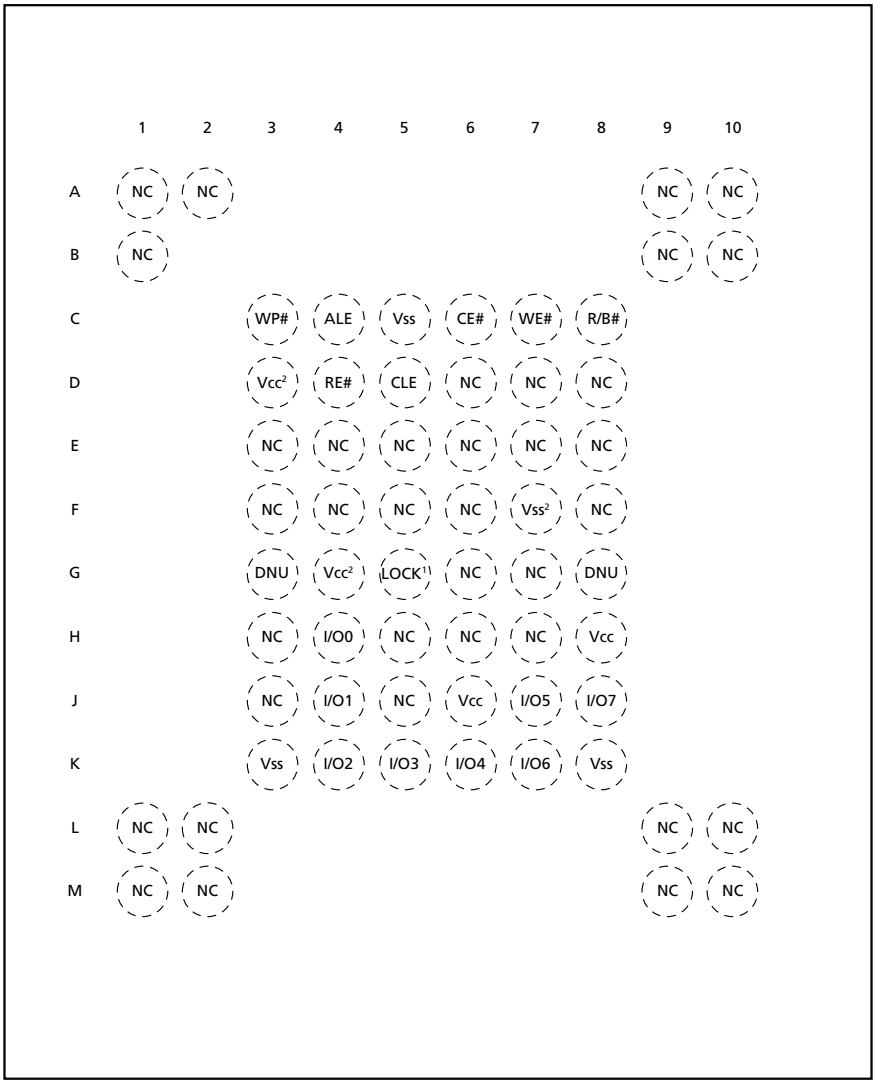
Notes:
1. These pins might not be bonded in the package; however, Micron recommends that the customer connect these pins to the designated external sources for ONFI compatibility.
2. For the 3V device, pin 38 is DNU. For the 1.8V device, pin 38 is LOCK.

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Figure 3: 63-Ball VFBGA, x8 (Balls Down, Top View)



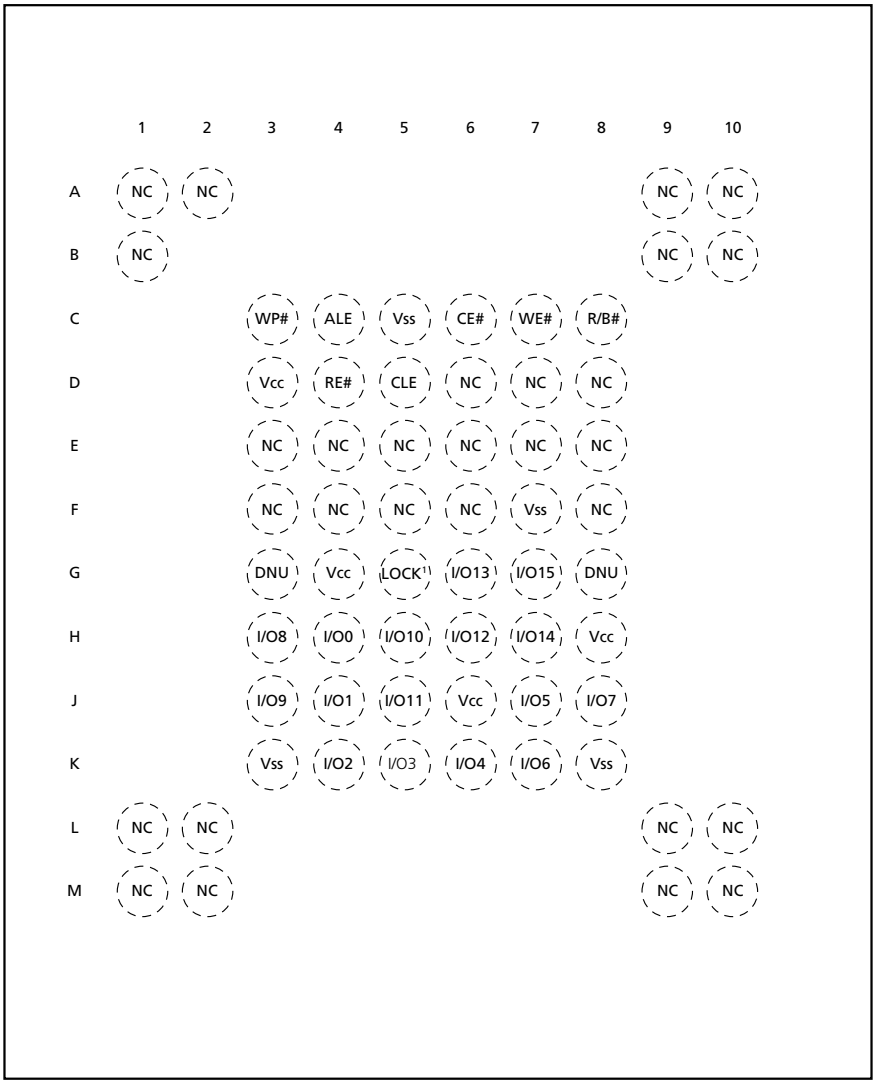
Notes:
1. For the 3V device, G5 changes to DNU. NO LOCK function is available on the 3.3V device.
2. These pins might not be bonded in the package; however, Micron recommends that the customer connect these pins to the designated external sources for ONFI compatibility.

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Figure 4: 63-Ball VFBGA, x16 (Balls Down, Top View)



Note: 1. For the 3V device, G5 changes to DNU. NO LOCK function is available on the 3.3V device.

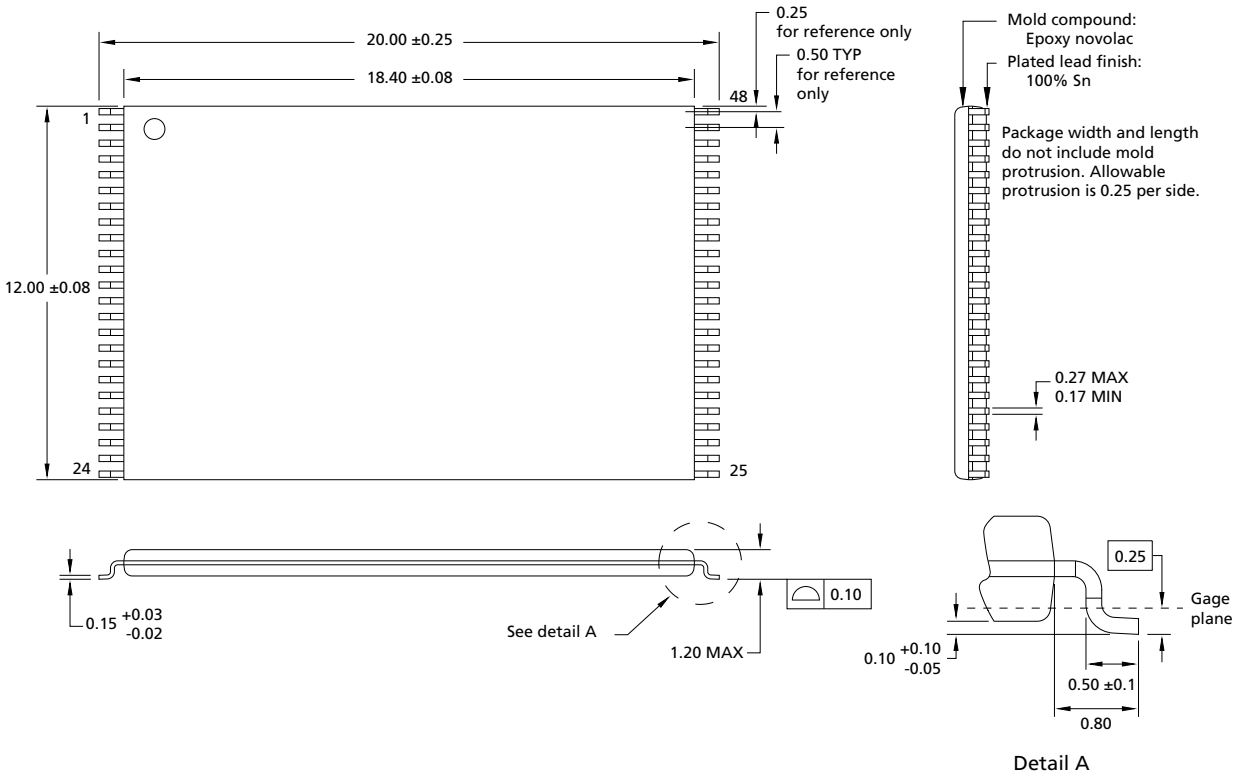
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Package Dimensions

Figure 5: 48-Pin TSOP – Type 1, CPL



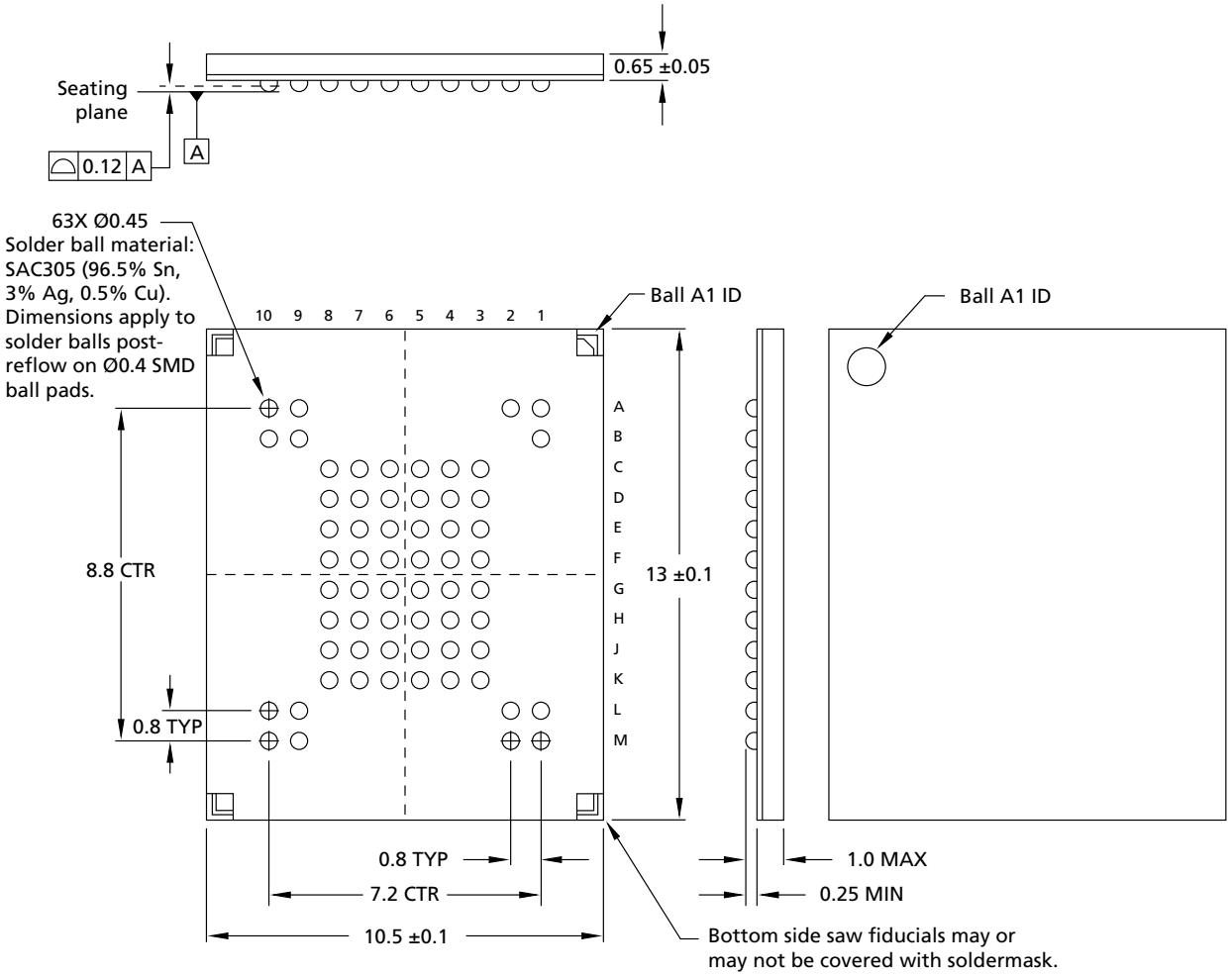
Note: 1. All dimensions are in millimeters.

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Figure 6: 63-Ball VFBGA (10.5mm x 13mm)



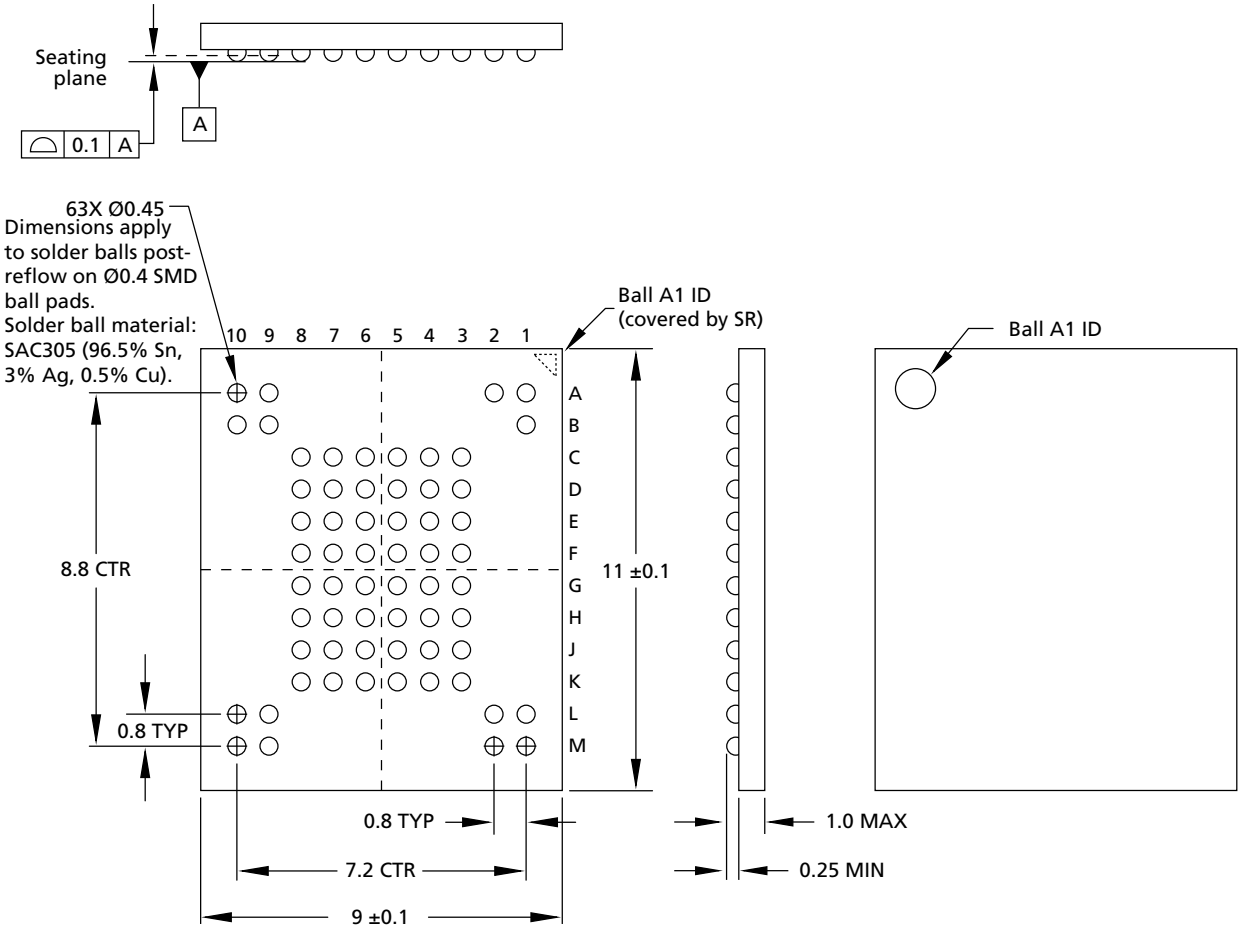
Note: 1. All dimensions are in millimeters.

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Figure 7: 63-Ball VFBGA (9mm x 11mm)



Note: 1. All dimensions are in millimeters.

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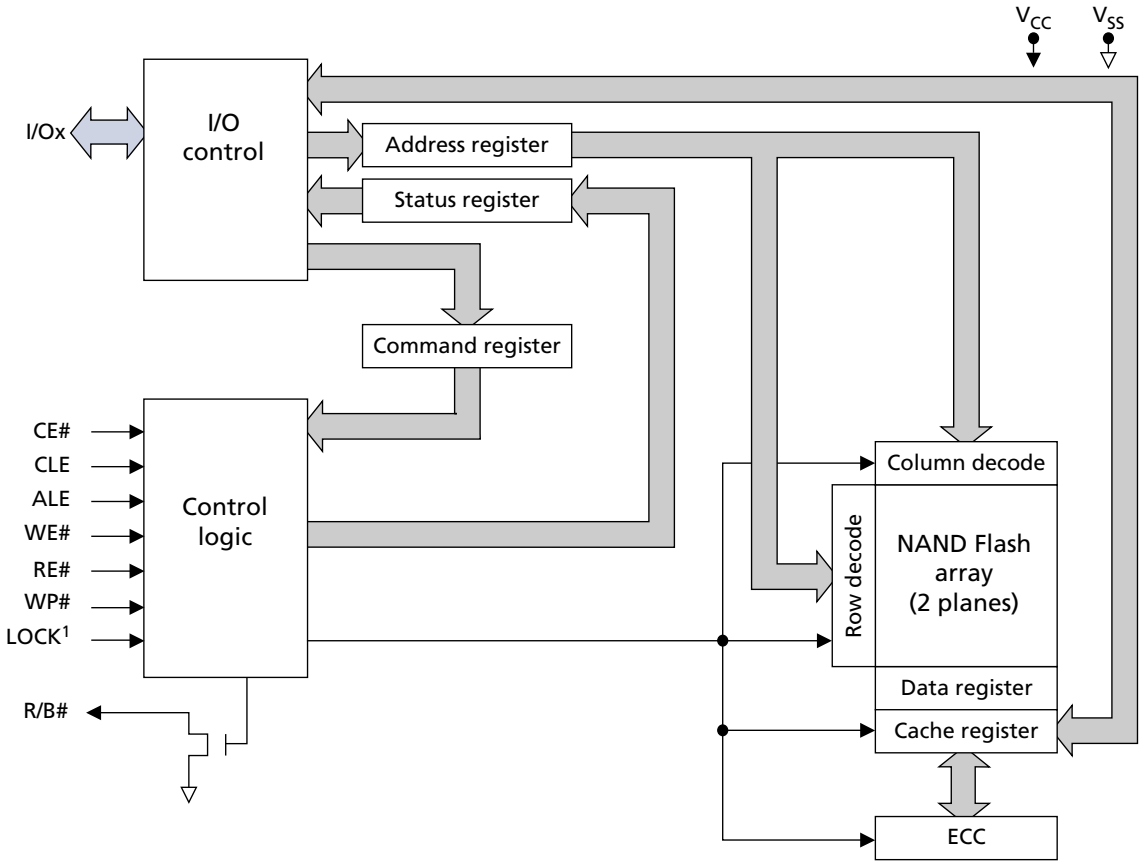
Architecture

These devices use NAND Flash electrical and command interfaces. Data, commands, and addresses are multiplexed onto the same pins and received by I/O control circuits. The commands received at the I/O control circuits are latched by a command register and are transferred to control logic circuits for generating internal signals to control device operations. The addresses are latched by an address register and sent to a row decoder to select a row address, or to a column decoder to select a column address.

Data is transferred to or from the NAND Flash memory array, byte by byte (x8) or word by word (x16), through a data register and a cache register.

The NAND Flash memory array is programmed and read using page-based operations and is erased using block-based operations. During normal page operations, the data and cache registers act as a single register. During cache operations, the data and cache registers operate independently to increase data throughput. The status register reports the status of die operations.

Figure 8: NAND Flash Die (LUN) Functional Block Diagram



Note: 1. The LOCK pin is used on the 1.8V device.

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Device and Array Organization

Figure 9: Array Organization – MT29F2G08 (x8)

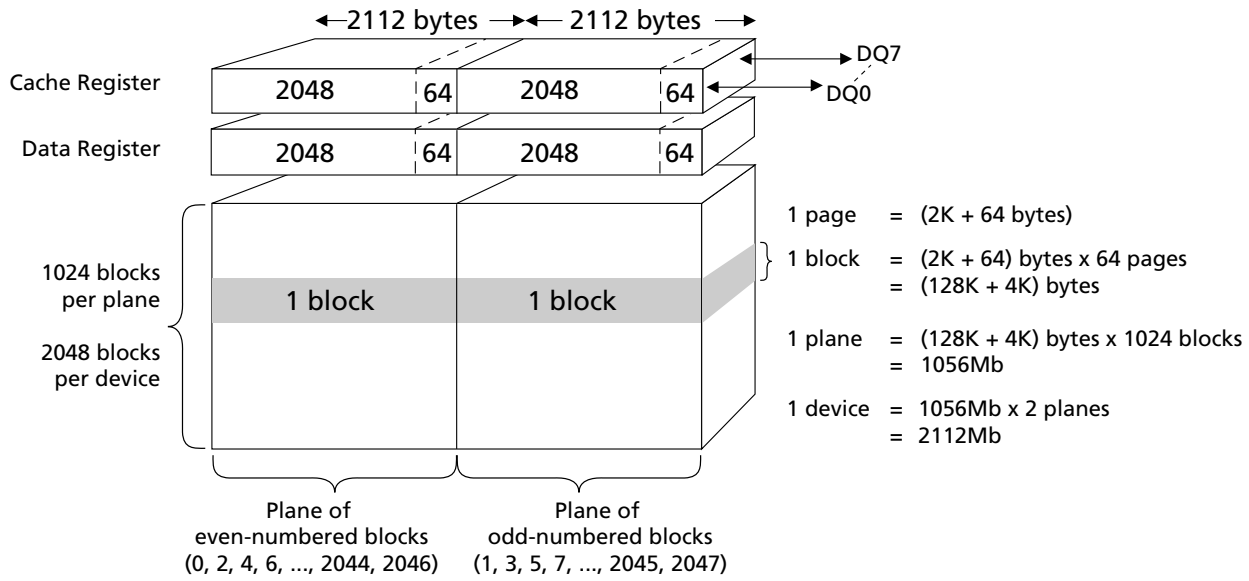


Table 2: Array Addressing – MT29F2G08 (x8)

Cycle	I/07	I/06	I/05	I/04	I/03	I/02	I/01	I/00
First	CA7	CA6	CA5	CA4	CA3	CA2	CA1	CA0
Second	LOW	LOW	LOW	LOW	CA11	CA10	CA9	CA8
Third	BA7	BA6	PA5	PA4	PA3	PA2	PA1	PA0
Fourth	BA15	BA14	BA13	BA12	BA11	BA10	BA9	BA8
Fifth	LOW	LOW	LOW	LOW	LOW	LOW	LOW	BA16

Notes:
1. Block address concatenated with page address = actual page address. CAx = column address; PAx = page address; BAx = block address.
2. If CA11 is 1, then CA[10:6] must be 0.
3. BA6 controls plane selection.

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Figure 10: Array Organization – MT29F2G16 (x16)

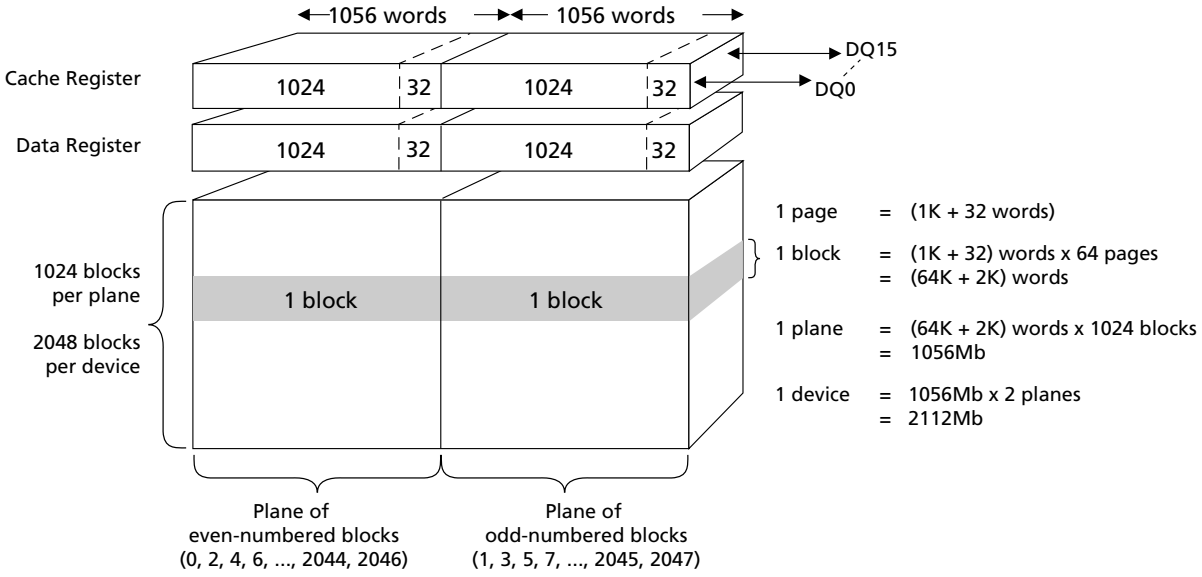


Table 3: Array Addressing – MT29F2G16 (x16)

Cycle	I/O[15:8]	I/07	I/06	I/05	I/04	I/03	I/02	I/01	I/00
First	LOW	CA7	CA6	CA5	CA4	CA3	CA2	CA1	CA0
Second	LOW	LOW	LOW	LOW	LOW	LOW	CA10	CA9	CA8
Third	LOW	BA7	BA6	PA5	PA4	PA3	PA2	PA1	PA0
Fourth	LOW	BA15	BA14	BA13	BA12	BA11	BA10	BA9	BA8
Fifth	LOW	LOW	LOW	LOW	LOW	LOW	LOW	LOW	BA16

Notes:
1. Block address concatenated with page address = actual page address. CAx = column address; PAx = page address; BAx = block address.
2. If CA10 = 1, then CA[9:5] must be 0.
3. BA6 controls plane selection.

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Asynchronous Interface Bus Operation

The bus on the device is multiplexed. Data I/O, addresses, and commands all share the same pins. I/O[15:8] are used only for data in the x16 configuration. Addresses and commands are always supplied on I/O[7:0].

The command sequence typically consists of a COMMAND LATCH cycle, address input cycles, and one or more data cycles, either READ or WRITE.

Table 4: Asynchronous Interface Mode Selection

Mode[1]	CE#	CLE	ALE	WE#	RE#	I/Ox	WP#
Standby[2]	H	X	X	X	X	X	0V/V_{CC}
Command input	L	H	L		H	X	H
Address input	L	L	H		H	X	H
Data input	L	L	L		H	X	H
Data output	L	L	L	H		X	X
Write protect	X	X	X	X	X	X	L

Notes:
1. Mode selection settings for this table: H = Logic level HIGH; L = Logic level LOW; X = V_{IH} or V_{IL}.
2. WP# should be biased to CMOS LOW or HIGH for standby.

Asynchronous Enable/Standby

When the device is not performing an operation, the CE# pin is typically driven HIGH and the device enters standby mode. The memory will enter standby if CE# goes HIGH while data is being transferred and the device is not busy. This helps reduce power consumption.

The CE# "Don't Care" operation enables the NAND Flash to reside on the same asynchronous memory bus as other Flash or SRAM devices. Other devices on the memory bus can then be accessed while the NAND Flash is busy with internal operations. This capability is important for designs that require multiple NAND Flash devices on the same bus.

A HIGH CLE signal indicates that a command cycle is taking place. A HIGH ALE signal signifies that an ADDRESS INPUT cycle is occurring.

Asynchronous Commands

An asynchronous command is written from I/O[7:0] to the command register on the rising edge of WE# when CE# is LOW, ALE is LOW, CLE is HIGH, and RE# is HIGH.

Commands are typically ignored by die (LUNs) that are busy (RDY = 0); however, some commands, including READ STATUS (70h) and READ STATUS ENHANCED (78h), are accepted by die (LUNs) even when they are busy.

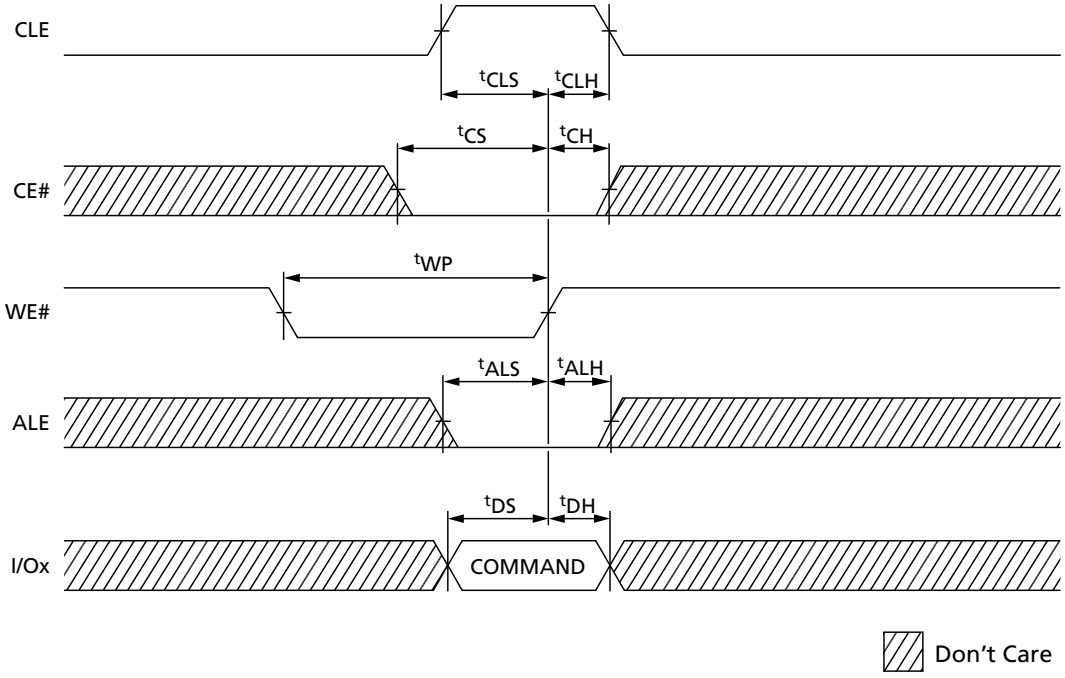
For devices with a x16 interface, I/O[15:8] must be written with zeros when a command is issued.

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Figure 11: Asynchronous Command Latch Cycle



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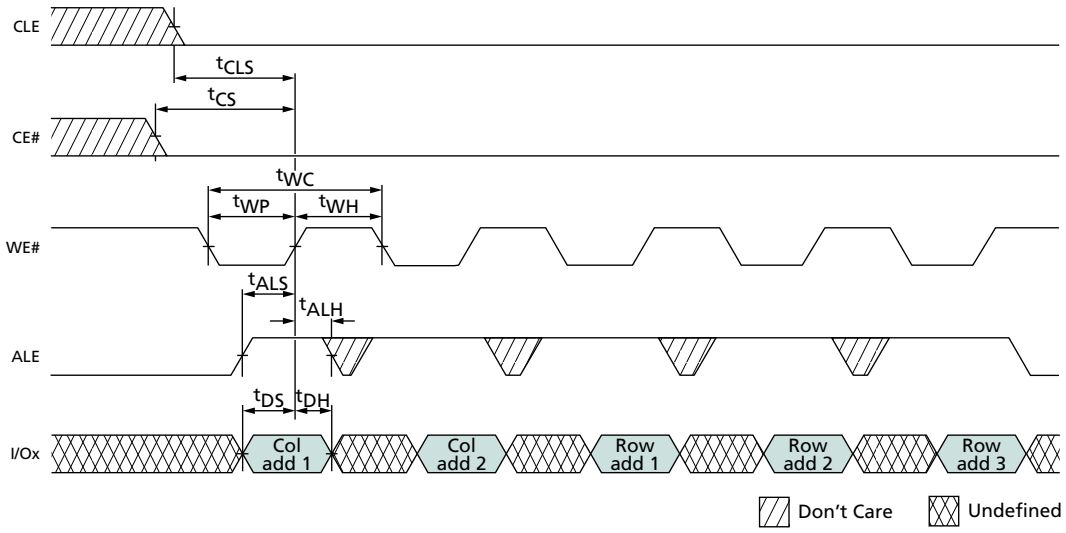
Asynchronous Addresses

An asynchronous address is written from I/O[7:0] to the address register on the rising edge of WE# when CE# is LOW, ALE is HIGH, CLE is LOW, and RE# is HIGH.

Bits that are not part of the address space must be LOW (see Device and Array Organization). The number of cycles required for each command varies. Refer to the command descriptions to determine addressing requirements.

Addresses are typically ignored by die (LUNs) that are busy (RDY = 0); however, some addresses are accepted by die (LUNs) even when they are busy; for example, like address cycles that follow the READ STATUS ENHANCED (78h) command.

Figure 12: Asynchronous Address Latch Cycle



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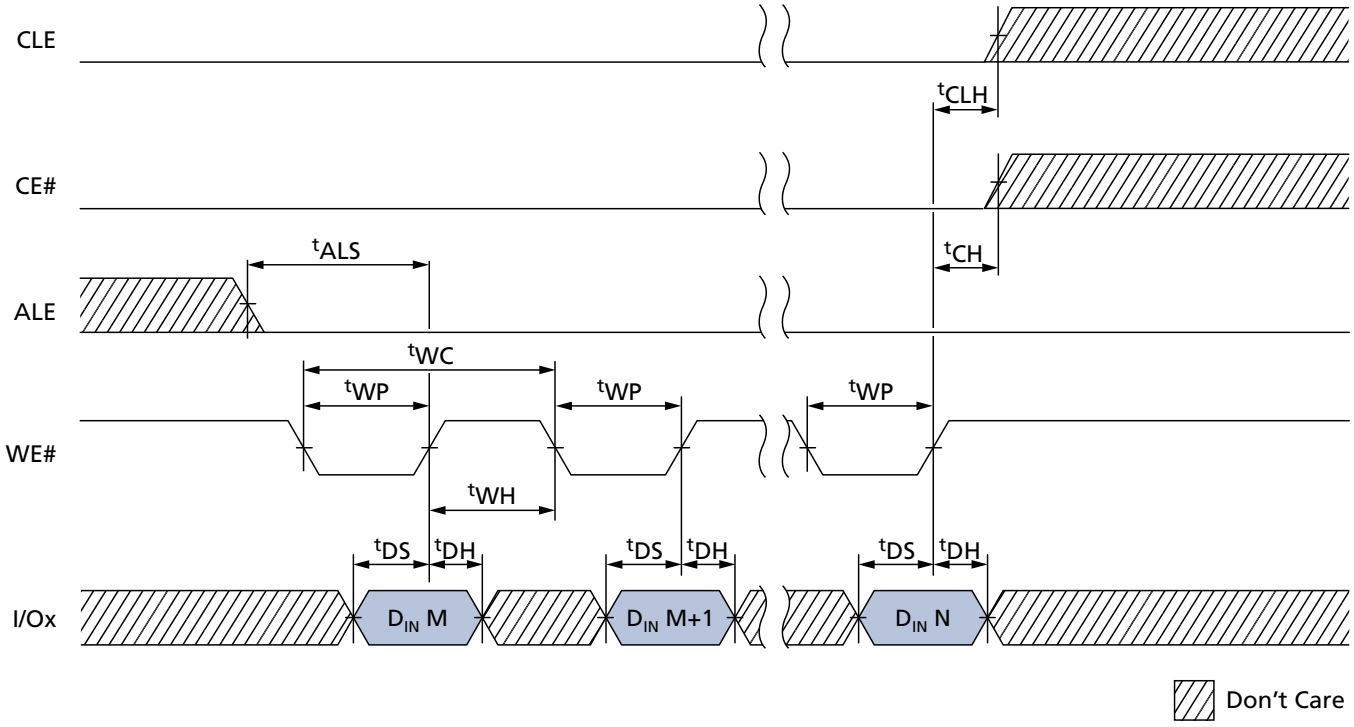
Asynchronous Data Input

Data is written from I/O[7:0] to the cache register of the selected die (LUN) on the rising edge of WE# when CE# is LOW, ALE is LOW, CLE is LOW, and RE# is HIGH.

Data input is ignored by die (LUNs) that are not selected or are busy (RDY = 0). Data is written to the data register on the rising edge of WE# when CE#, CLE, and ALE are LOW, and the device is not busy.

Data is input on I/O[7:0] on x8 devices and on I/O[15:0] on x16 devices.

Figure 13: Asynchronous Data Input Cycles



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Asynchronous Data Output

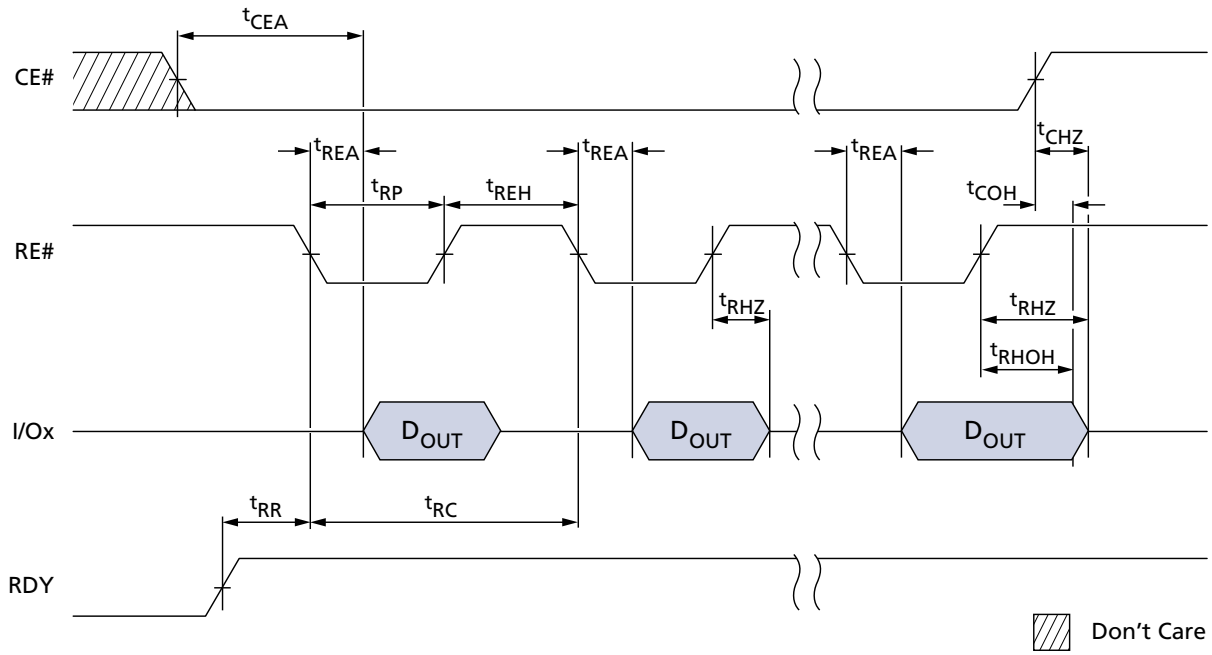
Data can be output from a die (LUN) if it is in a READY state. Data output is supported following a READ operation from the NAND Flash array. Data is output from the cache register of the selected die (LUN) to I/O[7:0] on the falling edge of RE# when CE# is LOW, ALE is LOW, CLE is LOW, and WE# is HIGH.

If the host controller is using a ^{t}RC of 30ns or greater, the host can latch the data on the rising edge of RE# (see the figure below for proper timing). If the host controller is using a ^{t}RC of less than 30ns, the host can latch the data on the next falling edge of RE#.

Using the READ STATUS ENHANCED (78h) command prevents data contention following an interleaved die (multi-LUN) operation. After issuing the READ STATUS ENHANCED (78h) command, to enable data output, issue the READ MODE (00h) command.

Data output requests are typically ignored by a die (LUN) that is busy (RDY = 0); however, it is possible to output data from the status register even when a die (LUN) is busy by first issuing the READ STATUS or READ STATUS ENHANCED (78h) command.

Figure 14: Asynchronous Data Output Cycles

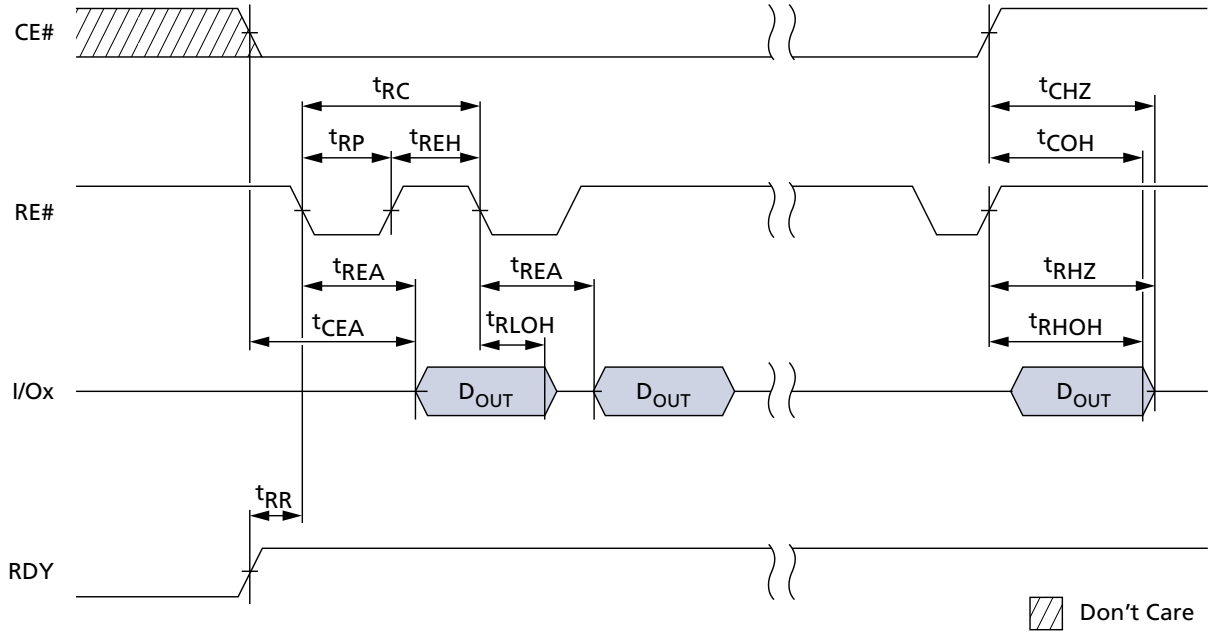


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Figure 15: Asynchronous Data Output Cycles (EDO Mode)



Write Protect#

The write protect# (WP#) signal enables or disables PROGRAM and ERASE operations to a target. When WP# is LOW, PROGRAM and ERASE operations are disabled. When WP# is HIGH, PROGRAM and ERASE operations are enabled. When WP# is LOW or toggled LOW during a READ operation, read will be performed as normal. It is recommended that the host drive WP# LOW during power-on until V_{CC} is stable to prevent inadvertent PROGRAM and ERASE operations (see Device Initialization for additional details).

If WP# is toggled during PROGRAM or ERASE (while RB# is LOW), then the following will occur

- The PROGRAM or ERASE operation is aborted
- In asynchronous mode, toggling WP# LOW during a NAND PROGRAM or ERASE operation will act like a RESET (FFh) command. In synchronous mode, it will act like a SYNCHRONOUS RESET (FCh) command
- The data that was being programmed or erased (targeted page or block) is not valid anymore
- The status register will be set to 60h until a RESET, new operation, or new power up command is given

After a command sequence is complete and the target is ready, WP# can be transitioned. After WP# is transitioned, the host must wait ^{t}WW before issuing a new command.

The WP# signal is always an active input, even when CE# is HIGH. This signal should not be multiplexed with other signals.

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Ready/Busy#

The ready/busy# (R/B#) signal provides a hardware method of indicating whether a target is ready or busy. A target is busy when one or more of its die (LUNs) are busy (RDY = 0). A target is ready when all of its die (LUNs) are ready (RDY = 1). Because each die (LUN) contains a status register, it is possible to determine the independent status of each die (LUN) by polling its status register instead of using the R/B# signal (see Status Operations for details regarding die (LUN) status).

This signal requires a pull-up resistor, Rp, for proper operation. R/B# is HIGH when the target is ready, and transitions LOW when the target is busy. The signal's open-drain driver enables multiple R/B# outputs to be OR-tied. Typically, R/B# is connected to an interrupt pin on the system controller.

The combination of Rp and capacitive loading of the R/B# circuit determines the rise time of the R/B# signal. The actual value used for Rp depends on the system timing requirements. Large values of Rp cause R/B# to be delayed significantly. Between the 10% and 90% points on the R/B# waveform, the rise time is approximately two time constants (TC).

$$T_C = R \times C$$

Where R = Rp (resistance of pull-up resistor), and C = total capacitive load.

The fall time of the R/B# signal is determined mainly by the output impedance of the R/B# signal and the total load capacitance. Approximate Rp values using a circuit load of 100pF are provided in Figure 21 (page 27).

The minimum value for Rp is determined by the output drive capability of the R/B# signal, the output voltage swing, and V_{CC}.

$$Rp = \frac{V_{CC}\,(MAX) - V_{OL}\,(MAX)}{I_{OL} + \Sigma_{IL}}$$

Where Σ_{IL} is the sum of the input currents of all devices tied to the R/B# pin.

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Figure 16: READ/BUSY# Open Drain

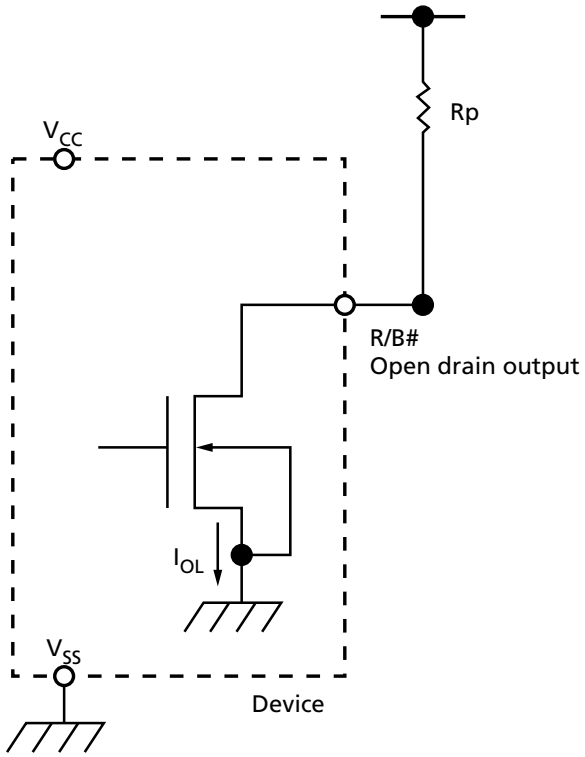
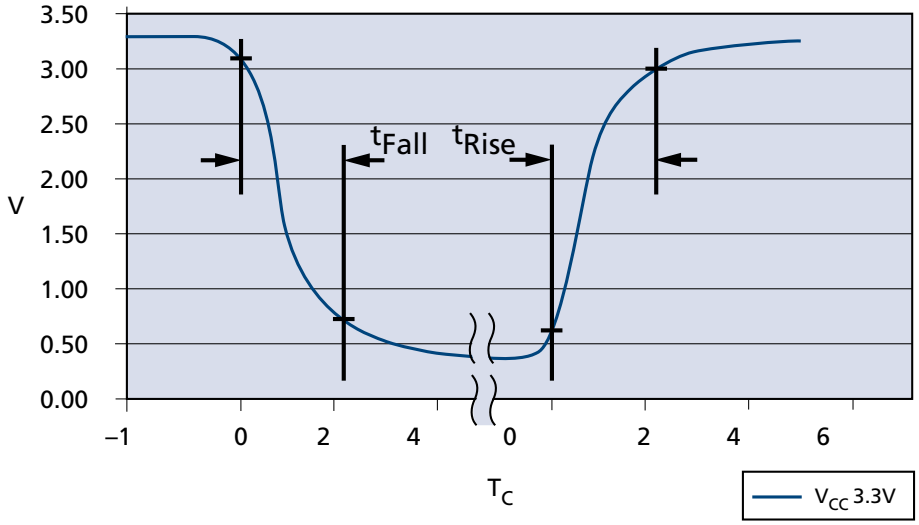


Figure 17: ^{t}Fall and ^{t}Rise (3.3V V_{CC})



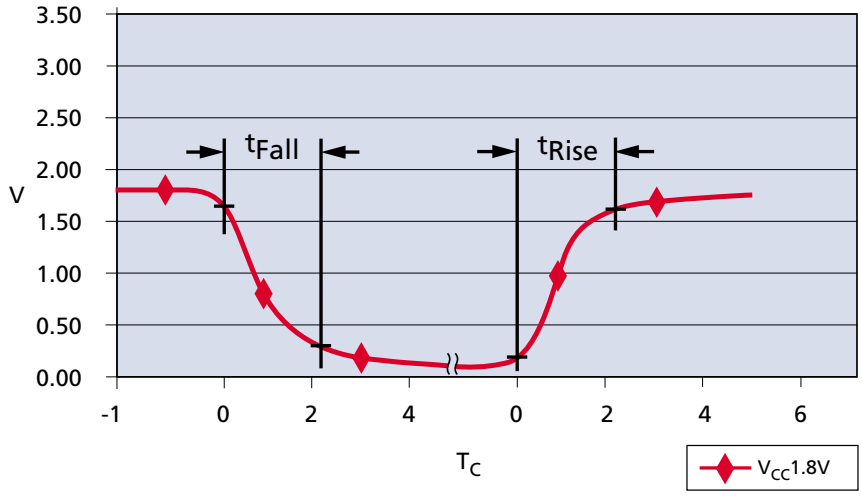
Notes:
1. ^{t}Fall and ^{t}Rise calculated at 10% and 90% points.
2. ^{t}Rise dependent on external capacitance and resistive loading and output transistor impedance.
3. ^{t}Rise primarily dependent on external pull-up resistor and external capacitive loading.
4. ^{t}Fall = 10ns at 3.3V.
5. See TC values in Figure 21 (page 27) for approximate Rp value and TC.

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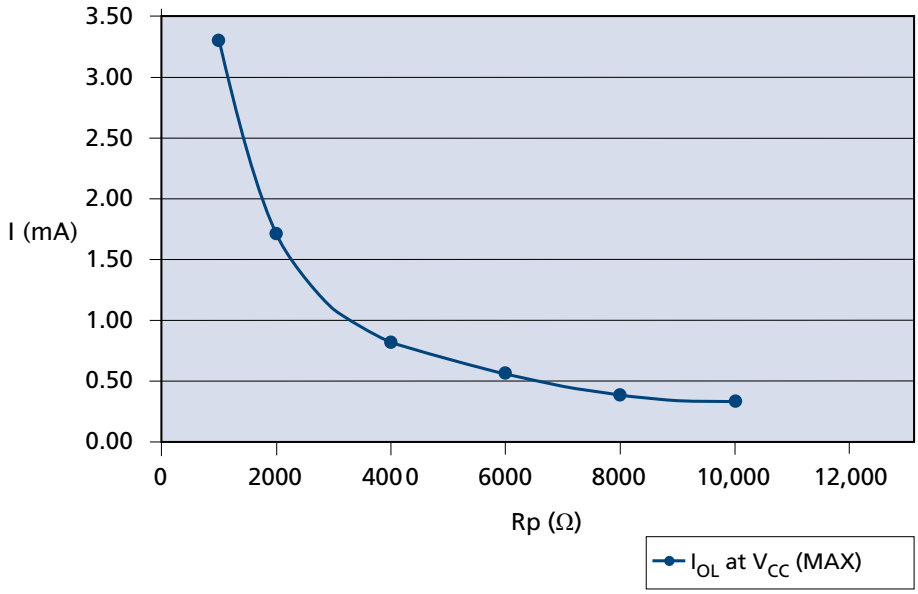
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Figure 18: ^{t}Fall and ^{t}Rise (1.8V V_{CC})



Notes:
1. ^{t}Fall and ^{t}Rise are calculated at 10% and 90% points.
2. ^{t}Rise is primarily dependent on external pull-up resistor and external capacitive loading.
3. ^{t}Fall ≈ 7ns at 1.8V.
4. See TC values in Figure 21 (page 27) for TC and approximate Rp value.

Figure 19: I_{OL} vs. Rp (V_{CC} = 3.3V V_{CC})



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Figure 20: I_{OL} vs. Rp (1.8V V_{CC})

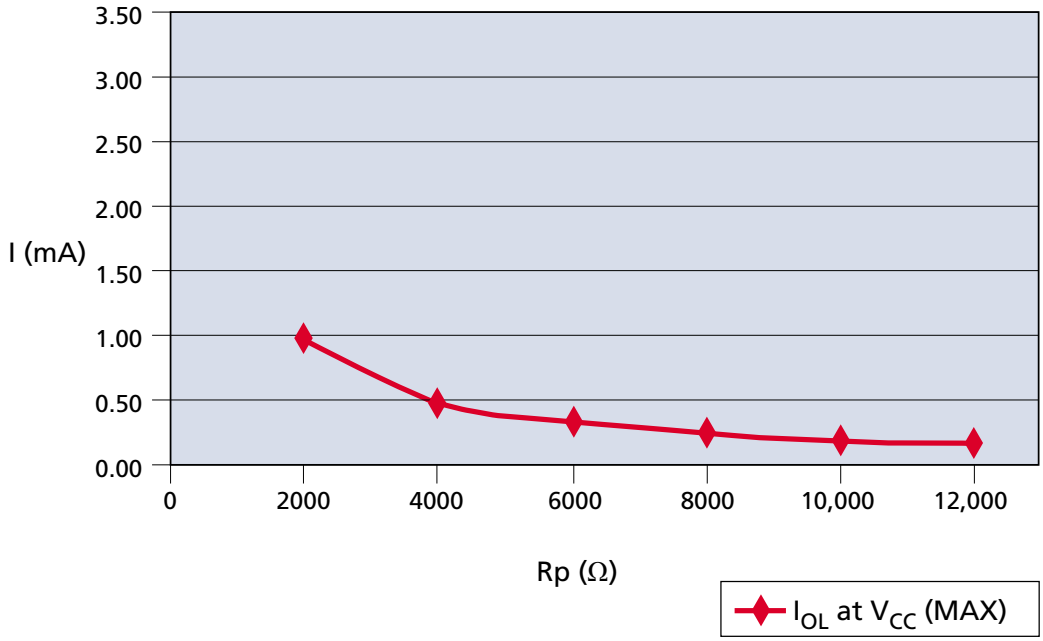
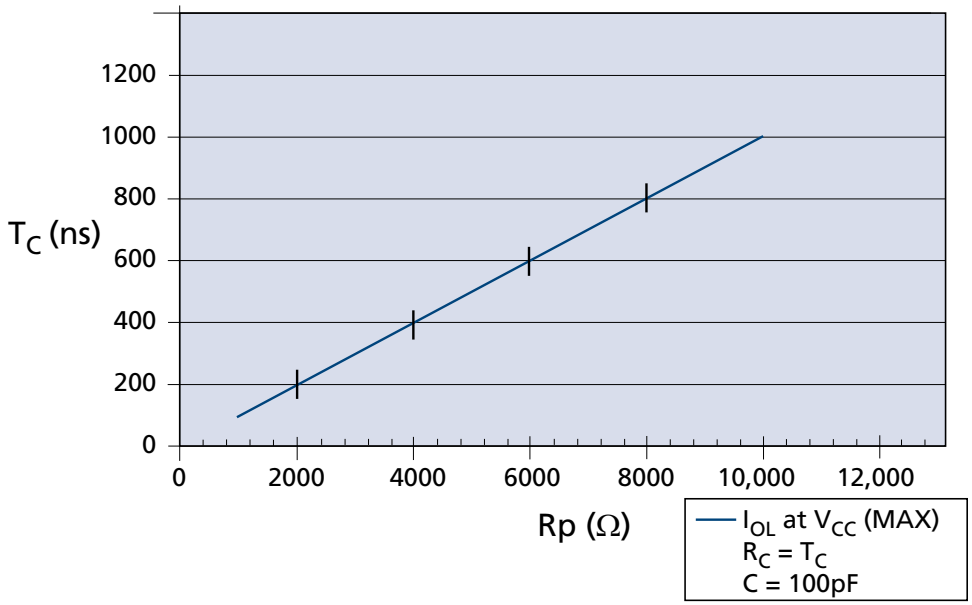


Figure 21: TC vs. Rp



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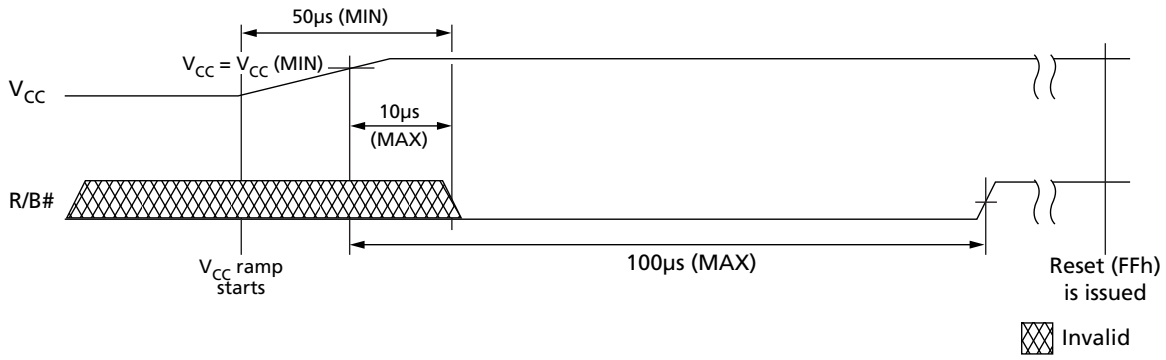
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Device Initialization

Micron NAND Flash devices are designed to prevent data corruption during power transitions. V_{CC} is internally monitored. (The WP# signal supports additional hardware protection during power transitions.) When ramping V_{CC}, use the following procedure to initialize the device:

1. Ramp V_{CC}.
2. The host must wait for R/B# to be valid and HIGH before issuing RESET (FFh) to any target. The R/B# signal becomes valid when 50µs has elapsed since the beginning the V_{CC} ramp, and 10µs has elapsed since V_{CC} reaches V_{CC} (MIN).
3. If not monitoring R/B#, the host must wait at least 100µs after V_{CC} reaches V_{CC} (MIN). If monitoring R/B#, the host must wait until R/B# is HIGH.
4. The asynchronous interface is active by default for each target. Each LUN draws less than an average of 10mA (I_{ST}) measured over intervals of 1ms until the RESET (FFh) command is issued.
5. The RESET (FFh) command must be the first command issued to all targets (CE#s) after the NAND Flash device is powered on. Each target will be busy for 1ms after a RESET command is issued. The RESET busy time can be monitored by polling R/B# or issuing the READ STATUS (70h) command to poll the status register.
6. The device is now initialized and ready for normal operation.

Figure 22: R/B# Power-On Behavior



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Command Definitions

Table 5: Command Set

Command	Command Cycle #1	Number of Valid Address Cycles	Data Input Cycles	Command Cycle #2	Valid While Selected LUN is Busy[1]	Valid While Other LUNs are Busy[2]	Notes
Reset Operations							
RESET	FFh	0	–	–	Yes	Yes	
Identification Operation							
READ ID	90h	1	–	–	No	No	
READ PARAMETER PAGE	ECh	1	–	–	No	No	
READ UNIQUE ID	EDh	1	–	–	No	No	
Feature Operations							
GET FEATURES	EEh	1	–	–	No	No	
SET FEATURES	EFh	1	4	–	No	No	
Status Operations							
READ STATUS	70h	0	–	–	Yes		
READ STATUS ENHANCED	78h	3	–	–	Yes	Yes	
Column Address Operations							
RANDOM DATA READ	05h	2	–	E0h	No	Yes	
RANDOM DATA INPUT	85h	2	Optional	–	No	Yes	
PROGRAM FOR INTERNAL DATA MOVE	85h	5	Optional	–	No	Yes	3
READ OPERATIONS							
READ MODE	00h	0	–	–	No	Yes	
READ PAGE	00h	5	–	30h	No	Yes	
READ PAGE CACHE SEQUENTIAL	31h	0	–	–	No	Yes	4, 5
READ PAGE CACHE RANDOM	00h	5	–	31h	No	Yes	4, 5
READ PAGE CACHE LAST	3Fh	0	–	–	No	Yes	4, 5
Program Operations							
PROGRAM PAGE	80h	5	Yes	10h	No	Yes	
PROGRAM PAGE CACHE	80h	5	Yes	15h	No	Yes	4, 6
Erase Operations							
ERASE BLOCK	60h	3	–	D0h	No	Yes	
Internal Data Move Operations							
READ FOR INTERNAL DATA MOVE	00h	5	–	35h	No	Yes	3

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Table 5: Command Set (Continued)

Command	Command Cycle #1	Number of Valid Address Cycles	Data Input Cycles	Command Cycle #2	Valid While Selected LUN is Busy[1]	Valid While Other LUNs are Busy[2]	Notes
PROGRAM FOR INTERNAL DATA MOVE	85h	5	Optional	10h	No	Yes	
Block Lock Operations							
BLOCK UNLOCK LOW	23h	3	–	–	No	Yes	
BLOCK UNLOCK HIGH	24h	3	–	–	No	Yes	
BLOCK LOCK	2Ah	–	–	–	No	Yes	
BLOCK LOCK-TIGHT	2Ch	–	–	–	No	Yes	
BLOCK LOCK READ STATUS	7Ah	3	–	–	No	Yes	
One-Time Programmable (OTP) Operations							
OTP DATA LOCK BY PAGE (ONFI)	80h	5	No	10h	No	No	7
OTP DATA PROGRAM (ONFI)	80h	5	Yes	10h	No	No	7
OTP DATA READ (ONFI)	00h	5	No	30h	No	No	7

Notes:
1. Busy means RDY = 0.
2. These commands can be used for interleaved die (multi-LUN) operations (see Interleaved Die (Multi-LUN) Operations (page 99)).
3. Do not cross plane address boundaries when using READ for INTERNAL DATA MOVE and PROGRAM for INTERNAL DATA MOVE.
4. These commands supported only with ECC disabled.
5. Issuing a READ PAGE CACHE series (31h, 00h-31h, 3Fh) command when the array is busy (RDY = 1, ARDY = 0) is supported if the previous command was a READ PAGE (00h-30h) or READ PAGE CACHE series command; otherwise, it is prohibited.
6. Issuing a PROGRAM PAGE CACHE (80h-15h) command when the array is busy (RDY = 1, ARDY = 0) is supported if the previous command was a PROGRAM PAGE CACHE (80h-15h) command; otherwise, it is prohibited.
7. OTP commands can be entered only after issuing the SET FEATURES command with the feature address.

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Table 6: Two-Plane Command Set

Note 4 applies to all parameters and conditions

Command	Command Cycle #1	Number of Valid Address Cycles	Command Cycle #2	Number of Valid Address Cycles	Command Cycle #3	Valid While Selected LUN is Busy	Valid While Other LUNs are Busy	Notes
READ PAGE TWO-PLANE	00h	5	00h	5	30h	No	Yes	
READ FOR TWO-PLANE INTERNAL DATA MOVE	00h	5	00h	5	35h	No	Yes	1
RANDOM DATA READ TWO-PLANE	06h	5	E0h	–	–	No	Yes	2
PROGRAM PAGE TWO-PLANE	80h	5	11h-80h	5	10h	No	Yes	
PROGRAM PAGE CACHE MODE TWO-PLANE	80h	5	11h-80h	5	15h	No	Yes	
PROGRAM FOR TWO-PLANE INTERNAL DATA MOVE	85h	5	11h-85h	5	10h	No	Yes	1
BLOCK ERASE TWO-PLANE	60h	3	D1h-60h	–	D0h	No	Yes	3

Notes:
1. Do not cross plane boundaries when using READ FOR INTERNAL DATA MOVE TWO-PLANE or PROGRAM FOR TWO-PLANE INTERNAL DATA MOVE.
2. The RANDOM DATA READ TWO-PLANE command is limited to use with the PAGE READ TWO-PLANE command.
3. D1h command can be omitted.
4. These commands supported only with ECC disabled.

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Reset Operations

RESET (FFh)

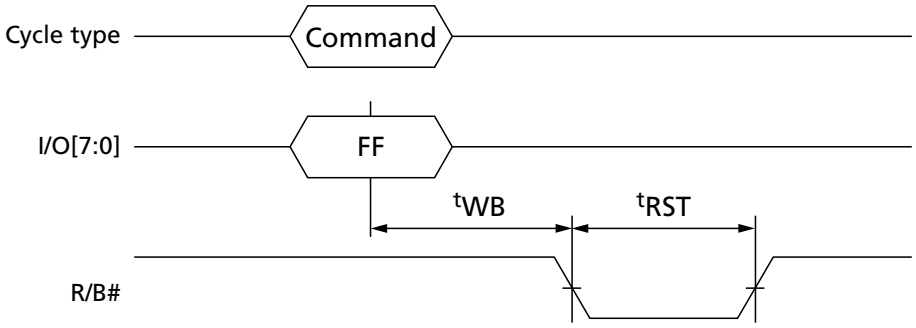
The RESET command is used to put the memory device into a known condition and to abort the command sequence in progress.

READ, PROGRAM, and ERASE commands can be aborted while the device is in the busy state. The contents of the memory location being programmed or the block being erased are no longer valid. The data may be partially erased or programmed, and is invalid. The command register is cleared and is ready for the next command. The data register and cache register contents are marked invalid.

The status register contains the value E0h when WP# is HIGH; otherwise it is written with a 60h value. R/B# goes LOW for ^{t}RST after the RESET command is written to the command register.

The RESET command must be issued to all CE#s as the first command after power-on. The device will be busy for a maximum of 1ms.

Figure 23: RESET (FFh) Operation



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Identification Operations

READ ID (90h)

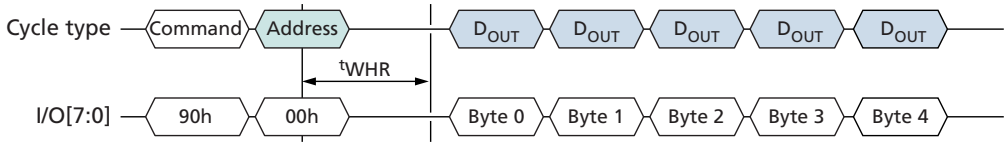
The READ ID (90h) command is used to read identifier codes programmed into the target. This command is accepted by the target only when all die (LUNs) on the target are idle.

Writing 90h to the command register puts the target in read ID mode. The target stays in this mode until another valid command is issued.

When the 90h command is followed by an 00h address cycle, the target returns a 5-byte identifier code that includes the manufacturer ID, device configuration, and part-specific information.

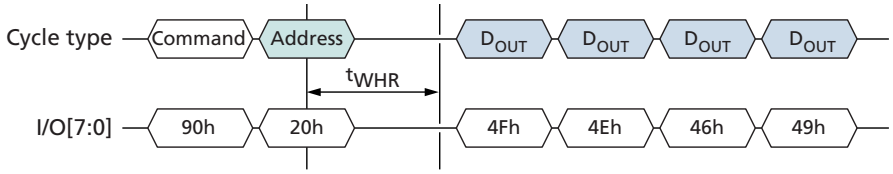
When the 90h command is followed by a 20h address cycle, the target returns the 4-byte ONFI identifier code.

Figure 24: READ ID (90h) with 00h Address Operation



Note: 1. See the READ ID Parameter tables for byte definitions.

Figure 25: READ ID (90h) with 20h Address Operation



Note: 1. See READ ID Parameter tables for byte definitions.

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READ ID Parameter Tables

Table 7: READ ID Parameters for Address 00h

		Options	I/07	I/06	I/05	I/04	I/03	I/02	I/01	I/00	Value[1]
Byte 0 – Manufacturer ID											
Manufacturer		Micron	0	0	1	0	1	1	0	0	2Ch
Byte 1 – Device ID											
MT29F2G08ABBEA		2Gb, x8, 1.8V	1	0	1	0	1	0	1	0	AAh
MT29F2G16ABBEA		2Gb, x16, 1.8V	1	0	1	1	1	0	1	0	BAh
MT29F2G08ABAEA		2Gb, x8, 3.3V	1	1	0	1	1	0	1	0	DAh
MT29F2G16ABAEA		2Gb, x16, 3.3V	1	1	0	0	1	0	1	0	CAh
Byte 2											
Number of die per CE		1							0	0	00b
Cell type		SLC					0	0			00b
Number of simultaneously programmed pages		2			0	1					01b
Interleaved operations between multiple die		Not supported		0							0b
Cache programming		Supported	1								1b
Byte value		MT29F2G08ABBEA	1	0	0	1	0	0	0	0	90h
		MT29F2G16ABBEA	1	0	0	1	0	0	0	0	90h
		MT29F2G08ABAEA	1	0	0	1	0	0	0	0	90h
		MT29F2G16ABAEA	1	0	0	1	0	0	0	0	90h
Byte 3											
Page size		2KB							0	1	01b
Spare area size (bytes)		64B						1			1b
Block size (without spare)		128KB			0	1					01b
Organization		x8		0							0b
		x16		1							1b
Serial access (MIN)	1.8V	25ns	0				0				0xxx0b
	3.3V	20ns	1				0				1xxx0b
Byte value		MT29F2G08ABBEA	0	0	0	1	0	1	0	1	15h
		MT29F2G16ABBEA	0	1	0	1	0	1	0	1	55h
		MT29F2G08ABAEA	1	0	0	1	0	1	0	1	95h
		MT29F2G16ABAEA	1	1	0	1	0	1	0	1	D5h
Byte 4											
ECC level		4-bit ECC/512 (main) + 4 (spare) + 8 (parity)bytes							1	0	10b
Planes per CE#		2					0	1			01b
Plane size		1Gb		0	0	0					000b

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Table 7: READ ID Parameters for Address 00h (Continued)

	Options	I/07	I/06	I/05	I/04	I/03	I/02	I/01	I/00	Value[1]
Internal ECC	ECC disabled	0								0b
	ECC enabled	1								1b
Byte value	MT29F2G08ABBEA	0	0	0	0	0	1	1	0	06h
	MT29F2G16ABBEA	0	0	0	0	0	1	1	0	06h
	MT29F2G08ABAEA	0	0	0	0	0	1	1	0	06h
	MT29F2G16ABAEA	0	0	0	0	0	1	1	0	06h

Note: 1. b = binary; h = hexadecimal.

Table 8: READ ID Parameters for Address 20h

Byte	Options	I/07	I/06	I/05	I/04	I/03	I/02	I/01	I/00	Value[1]
0	"O"	0	1	0	0	1	1	1	1	4Fh
1	"N"	0	1	0	0	1	1	1	0	4Eh
2	"F"	0	1	0	0	0	1	1	0	46h
3	"I"	0	1	0	0	1	0	0	1	49h
4	Undefined	X	X	X	X	X	X	X	X	XXh

Note: 1. h = hexadecimal.

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READ PARAMETER PAGE (ECh)

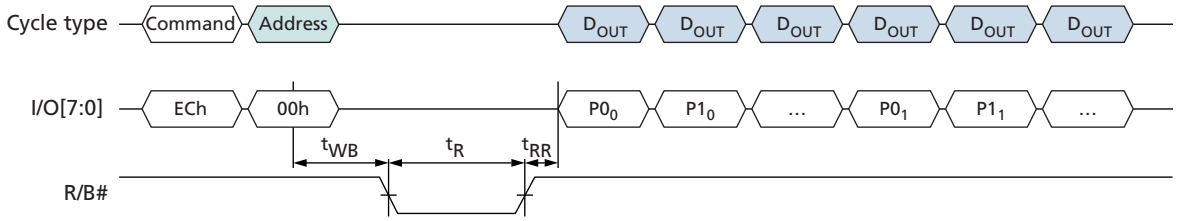
The READ PARAMETER PAGE (ECh) command is used to read the ONFI parameter page programmed into the target. This command is accepted by the target only when all die (LUNs) on the target are idle.

Writing ECh to the command register puts the target in read parameter page mode. The target stays in this mode until another valid command is issued.

When the ECh command is followed by an 00h address cycle, the target goes busy for ^{t}R. If the READ STATUS (70h) command is used to monitor for command completion, the READ MODE (00h) command must be used to re-enable data output mode. Use of the READ STATUS ENHANCED (78h) command is prohibited while the target is busy and during data output.

To insure data integrity, x8 devices contain at least eight copies of the parameter page, and x16 devices contain at least four copies of the parameter page. Each parameter page is 256 bytes. If the initial READ PARAMETER PAGE (ECh) command fails to retrieve a correct copy of the parameter page, the command can be reissued until a correct copy is retrieved. If desired, the RANDOM DATA READ (05h-E0h) command can be used to change the location of data output.

Figure 26: READ PARAMETER (ECh) Operation



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Parameter Page Data Structure Tables

Table 9: Parameter Page Data Structure

Byte	Description		Value[1]
0–3	Parameter page signature		4Fh, 4Eh, 46h, 49h
4–5	Revision number		02h, 00h
6–7	Features supported	MT29F2G08ABAEA3W	18h, 00h
		MT29F2G08ABBEA3W	18h, 00h
		MT29F2G16ABAEA3W	19h, 00h
		MT29F2G16ABBEA3W	19h, 00h
		MT29F2G08ABBEAH4	18h, 00h
		MT29F2G16ABBEAH4	19h, 00h
		MT29F2G08ABAEAWP	18h, 00h
		MT29F2G16ABAEAWP	19h, 00h
		MT29F2G08ABAEAH4	18h, 00h
		MT29F2G08ABBEAHC	18h, 00h
		MT29F2G16ABBEAHC	19h, 00h
8–9	Optional commands supported		3Fh, 00h
10–31	Reserved		00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h
32–43	Device manufacturer		4Dh, 49h, 43h, 52h, 4Fh, 4Eh, 20h, 20h, 20h, 20h, 20h, 20h

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Table 9: Parameter Page Data Structure (Continued)

Byte	Description		Value[1]
44–63	Device model	MT29F2G08ABAEA3W	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 41h, 45h, 41h, 33h, 57h, 20h, 20h, 20h, 20h
		MT29F2G08ABBEA3W	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 42h, 45h, 41h, 33h, 57h, 20h, 20h, 20h, 20h
		MT29F2G16ABAEA3W	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 31h, 36h, 41h, 42h, 41h, 45h, 41h, 33h, 57h, 20h, 20h, 20h, 20h
		MT29F2G16ABBEA3W	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 31h, 36h, 41h, 42h, 42h, 45h, 41h, 33h, 57h, 20h, 20h, 20h, 20h
		MT29F2G08ABBEAH4	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 42h, 45h, 41h, 48h, 34h, 20h, 20h, 20h, 20h
		MT29F2G16ABBEAH4	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 31h, 36h, 41h, 42h, 42h, 45h, 41h, 48h, 34h, 20h, 20h, 20h, 20h
		MT29F2G08ABAEAWP	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 41h, 45h, 41h, 57h, 50h, 20h, 20h, 20h, 20h
		MT29F2G16ABAEAWP	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 31h, 36h, 41h, 42h, 41h, 45h, 41h, 57h, 50h, 20h, 20h, 20h, 20h
		MT29F2G08ABAEAH4	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 41h, 45h, 41h, 48h, 34h, 20h, 20h, 20h, 20h
		MT29F2G08ABBEAHC	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 30h, 38h, 41h, 42h, 42h, 45h, 41h, 48h, 43h, 20h, 20h, 20h, 20h
		MT29F2G16ABBEAHC	4Dh, 54h, 32h, 39h, 46h, 32h, 47h, 31h, 36h, 41h, 42h, 42h, 45h, 41h, 48h, 43h, 20h, 20h, 20h, 20h
64	Manufacturer ID		2Ch
65–66	Date code		00h, 00h
67–79	Reserved		00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h
80–83	Number of data bytes per page		00h, 08h, 00h, 00h
84–85	Number of spare bytes per page		40h, 00h
86–89	Number of data bytes per partial page		00h, 02h, 00h, 00h
90–91	Number of spare bytes per partial page		10h, 00h
92–95	Number of pages per block		40h, 00h, 00h, 00h
96–99	Number of blocks per unit		00h, 08h, 00h, 00h
100	Number of logical units		01h
101	Number of address cycles		23h
102	Number of bits per cell		01h
103–104	Bad blocks maximum per unit		28h, 00h
105–106	Block endurance		01h, 05h
107	Guaranteed valid blocks at beginning of target		01h
108–109	Block endurance for guaranteed valid blocks		00h, 00h
110	Number of programs per page		04h
111	Partial programming attributes		00h

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Table 9: Parameter Page Data Structure (Continued)

Byte	Description		Value[1]
112	Number of bits ECC bits		04h
113	Number of interleaved address bits		01h
114	Interleaved operation attributes		0Eh
115–127	Reserved		00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h
128	I/O pin capacitance		0Ah
129–130	Timing mode support	MT29F2G08ABAEA3W	3Fh, 00h
		MT29F2G08ABBEA3W	1Fh, 00h
		MT29F2G16ABAEA3W	3Fh, 00h
		MT29F2G16ABBEA3W	1Fh, 00h
		MT29F2G08ABBEAH4	1Fh, 00h
		MT29F2G16ABBEAH4	1Fh, 00h
		MT29F2G08ABAEAWP	3Fh, 00h
		MT29F2G16ABAEAWP	3Fh, 00h
		MT29F2G08ABAEAH4	3Fh, 00h
		MT29F2G08ABBEAHC	1Fh, 00h
		MT29F2G16ABBEAHC	1Fh, 00h
131–132	Program cache timing mode support	MT29F2G08ABAEA3W	3Fh, 00h
		MT29F2G08ABBEA3W	1Fh, 00h
		MT29F2G16ABAEA3W	3Fh, 00h
		MT29F2G16ABBEA3W	1Fh, 00h
		MT29F2G08ABBEAH4	1Fh, 00h
		MT29F2G16ABBEAH4	1Fh, 00h
		MT29F2G08ABAEAWP	3Fh, 00h
		MT29F2G16ABAEAWP	3Fh, 00h
		MT29F2G08ABAEAH4	3Fh, 00h
		MT29F2G08ABBEAHC	1Fh, 00h
		MT29F2G16ABBEAHC	1Fh, 00h
133–134	^{t}PROG (MAX) page program time		58h, 02h
135–136	^{t}BERS (MAX) block erase time		B8h, 0Bh
137–138	^{t}R (MAX) page read time		19h, 00h
139–140	^{t}CCS (MIN)		64h, 00h
141–163	Reserved		00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h
164–165	Vendor-specific revision number		01h, 00h

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Table 9: Parameter Page Data Structure (Continued)

Byte	Description	Value[1]
166–253	Vendor-specific	01h, 00h, 00h, 02h, 04h, 80h, 01h, 81h, 04h, 01h, 02h, 01h,0Ah, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h,00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h,00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h,00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h,00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h, 00h,00h, 00h, 00h, 00h
254–255	Integrity CRC	Set at test
256–511	Value of bytes 0–255	
512–767	Value of bytes 0–255	
768+	Additional redundant parameter pages	

Note: 1. h = hexadecimal.

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READ UNIQUE ID (EDh)

The READ UNIQUE ID (EDh) command is used to read a unique identifier programmed into the target. This command is accepted by the target only when all die (LUNs) on the target are idle.

Writing EDh to the command register puts the target in read unique ID mode. The target stays in this mode until another valid command is issued.

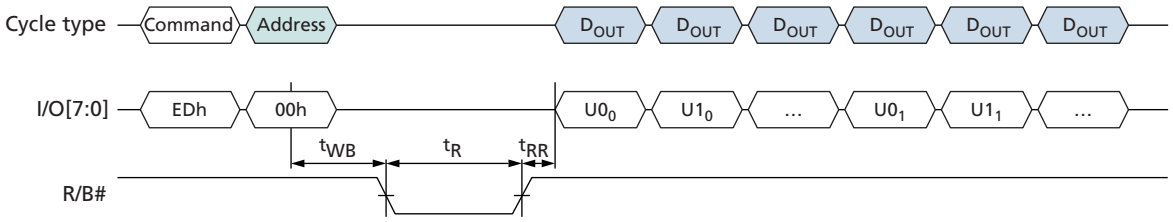
When the EDh command is followed by an 00h address cycle, the target goes busy for ^{t}R. If the READ STATUS (70h) command is used to monitor for command completion, the READ MODE (00h) command must be used to re-enable data output mode.

After ^{t}R completes, the host enables data output mode to read the unique ID. When the asynchronous interface is active, one data byte is output per RE# toggle.

Sixteen copies of the unique ID data are stored in the device. Each copy is 32 bytes. The first 16 bytes of a 32-byte copy are unique data, and the second 16 bytes are the complement of the first 16 bytes. The host should XOR the first 16 bytes with the second 16 bytes. If the result is 16 bytes of FFh, then that copy of the unique ID data is correct. In the event that a non-FFh result is returned, the host can repeat the XOR operation on a subsequent copy of the unique ID data. If desired, the RANDOM DATA READ (05h-E0h) command can be used to change the data output location.

The upper eight I/Os on a x16 device are not used and are a "Don't Care" for x16 devices.

Figure 27: READ UNIQUE ID (EDh) Operation



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Feature Operations

The SET FEATURES (EFh) and GET FEATURES (EEh) commands are used to modify the target's default power-on behavior. These commands use a one-byte feature address to determine which subfeature parameters will be read or modified. Each feature address (in the 00h to FFh range) is defined in below. The SET FEATURES (EFh) command writes subfeature parameters (P1–P4) to the specified feature address. The GET FEATURES command reads the subfeature parameters (P1–P4) at the specified feature address.

When a feature is set, by default it remains active until the device is power cycled. It is volatile. Unless otherwise specified in the features table, once a device is set it remains set, even if a RESET (FFh) command is issued. GET/SET FEATURES commands can be used after required RESET to enable features before system BOOT ROM process.

Internal ECC can be enabled/disabled using SET FEATURES (EFh). The SET FEATURES command (EFh), followed by address 90h, followed by four data bytes (only the first data byte is used) will enable/disable internal ECC.

The sequence to enable internal ECC with SET FEATURES is EFh(cmd)-90h(addr)-08h(data)-00h(data)-00h(data)-00h(data)-wait(t_{FEAT}).

The sequence to disable internal ECC with SET FEATURES is EFh(cmd)-90h(addr)-00h(data)-00h(data)-00h(data)-00h(data)-wait(t_{FEAT}). The GET FEATURES command is EEh.

Table 10: Feature Address Definitions

Feature Address	Definition
00h	Reserved
01h	Timing mode
02h–7Fh	Reserved
80h	Programmable output drive strength
81h	Programmable RB# pull-down strength
82h–FFh	Reserved
90h	Array operation mode

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Table 11: Feature Address 90h – Array Operation Mode

Subfeature Parameter	Options	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0	Value	Notes
P1											
Operation mode option	Normal	Reserved (0)							0	00h	1
	OTP operation	Reserved (0)							1	01h	
	OTP protection	Reserved (0)						1	1	03h	
	Disable ECC	Reserved (0)				0	0	0	0	00h	1
	Enable ECC	Reserved (0)				1	0	0	0	08h	1
P2											
Reserved		Reserved (0)								00h	
P3											
Reserved		Reserved (0)								00h	
P4											
Reserved		Reserved (0)								00h	

Note: 1. These bits are reset to 00h on power cycle.

SET FEATURES (EFh)

The SET FEATURES (EFh) command writes the subfeature parameters (P1–P4) to the specified feature address to enable or disable target-specific features. This command is accepted by the target only when all die (LUNs) on the target are idle.

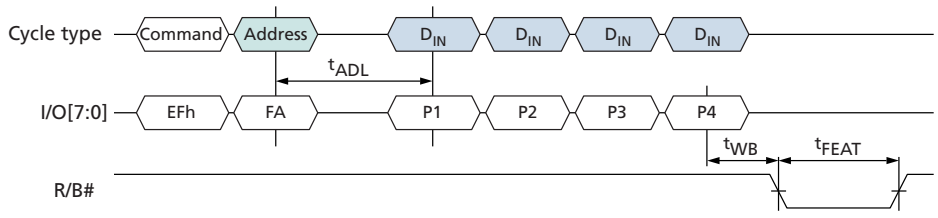
Writing EFh to the command register puts the target in the set features mode. The target stays in this mode until another command is issued.

The EFh command is followed by a valid feature address. The host waits for ^{t}ADL before the subfeature parameters are input. When the asynchronous interface is active, one subfeature parameter is latched per rising edge of WE#.

After all four subfeature parameters are input, the target goes busy for ^{t}FEAT. The READ STATUS (70h) command can be used to monitor for command completion.

Feature address 01h (timing mode) operation is unique. If SET FEATURES is used to modify the interface type, the target will be busy for ^{t}ITC.

Figure 28: SET FEATURES (EFh) Operation



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GET FEATURES (EEh)

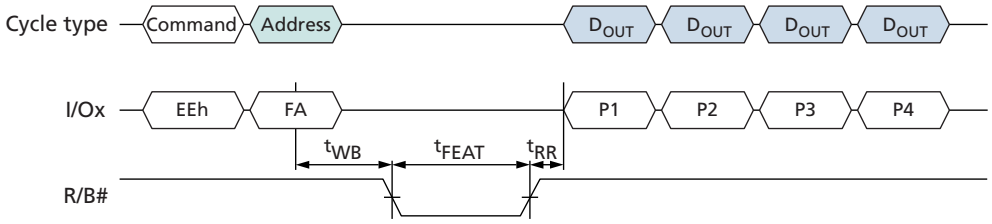
The GET FEATURES (EEh) command reads the subfeature parameters (P1–P4) from the specified feature address. This command is accepted by the target only when all die (LUNs) on the target are idle.

Writing EEh to the command register puts the target in get features mode. The target stays in this mode until another valid command is issued.

When the EEh command is followed by a feature address, the target goes busy for ^{t}FEAT. If the READ STATUS (70h) command is used to monitor for command completion, the READ MODE (00h) command must be used to re-enable data output mode.

After ^{t}FEAT completes, the host enables data output mode to read the subfeature parameters.

Figure 29: GET FEATURES (EEh) Operation



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Table 12: Feature Addresses 01h: Timing Mode

Subfeature Parameter	Options	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0	Value	Notes
P1											
Timing mode	Mode 0 (default)	Reserved (0)					0	0	0	00h	1, 2
	Mode 1	Reserved (0)					0	0	1	01h	2
	Mode 2	Reserved (0)					0	1	0	02h	2
	Mode 3	Reserved (0)					0	1	1	03h	2
	Mode 4	Reserved (0)					1	0	0	04h	2
	Mode 5	Reserved (0)					1	0	1	05h	3
P2											
		Reserved (0)								00h	
P3											
		Reserved (0)								00h	
P4											
		Reserved (0)								00h	

Notes:
1. The timing mode feature address is used to change the default timing mode. The timing mode should be selected to indicate the maximum speed at which the device will receive commands, addresses, and data cycles. The five supported settings for the timing mode are shown. The default timing mode is mode 0. The device returns to mode 0 when the device is power cycled. Supported timing modes are reported in the parameter page.
2. Supported for both 1.8V and 3.3V.
3. Supported for 3.3V only.

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Table 13: Feature Addresses 80h: Programmable I/O Drive Strength

Subfeature Parameter	Options	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0	Value	Notes
P1											
I/O drive strength	Full (default)	Reserved (0)						0	0	00h	1
	Three-quarters	Reserved (0)						0	1	01h	
	One-half	Reserved (0)						1	0	02h	
	One-quarter	Reserved (0)						1	1	03h	
P2											
		Reserved (0)								00h	
P3											
		Reserved (0)								00h	
P4											
		Reserved (0)								00h	

Note: 1. The programmable drive strength feature address is used to change the default I/O drive strength. Drive strength should be selected based on expected loading of the memory bus. This table shows the four supported output drive strength settings. The default drive strength is full strength. The device returns to the default drive strength mode when the device is power cycled. AC timing parameters may need to be relaxed if I/O drive strength is not set to full.

Table 14: Feature Addresses 81h: Programmable R/B# Pull-Down Strength

Subfeature Parameter	Options	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0	Value	Notes
P1											
R/B# pull-down strength	Full (default)							0	0	00h	1
	Three-quarters							0	1	01h	
	One-half							1	0	02h	
	One-quarter							1	1	03h	
P2											
		Reserved (0)								00h	
P3											
		Reserved (0)								00h	
P4											
		Reserved (0)								00h	

Note: 1. This feature address is used to change the default R/B# pull-down strength. Its strength should be selected based on the expected loading of R/B#. Full strength is the default, power-on value.

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Status Operations

Each die (LUN) provides its status independently of other die (LUNs) on the same target through its 8-bit status register.

After the READ STATUS (70h) or READ STATUS ENHANCED (78h) command is issued, status register output is enabled. The contents of the status register are returned on I/O[7:0] for each data output request.

When the asynchronous interface is active and status register output is enabled, changes in the status register are seen on I/O[7:0] as long as CE# and RE# are LOW; it is not necessary to toggle RE# to see the status register update.

While monitoring the status register to determine when a data transfer from the Flash array to the data register (^{t}R) is complete, the host must issue the READ MODE (00h) command to disable the status register and enable data output (see Read Operations).

The READ STATUS (70h) command returns the status of the most recently selected die (LUN). To prevent data contention during or following an interleaved die (multi-LUN) operation, the host must enable only one die (LUN) for status output by using the READ STATUS ENHANCED (78h) command (see Interleaved Die (Multi-LUN) Operations).

With internal ECC enabled, a READ STATUS command is required after completion of the data transfer (^{t}R_ECC) to determine whether an uncorrectable read error occurred.

Table 15: Status Register Definition

SR Bit	Program Page	Program Page Cache Mode	Page Read	Page Read Cache Mode	Block Erase	Description
7	Write protect	Write protect	Write protect	Write protect	Write protect	0 = Protected 1 = Not protected
6	RDY	RDY[1] cache	RDY	RDY[1] cache	RDY	0 = Busy 1 = Ready
5	ARDY	ARDY[2]	ARDY	ARDY[2]	ARDY	Don't Care
4	–	–	–	–	–	Don't Care
3	–	–	Rewrite recommended[3]	–	–	0 = Normal or uncorrectable 1 = Rewrite recommended
2	–	–	–	–	–	Don't Care
1	FAILC (N - 1)	FAILC (N - 1)	Reserved	–	–	Don't Care
0	FAIL	FAIL (N)	FAIL[4]	–	FAIL	0 = Successful PROGRAM/ERASE/READ 1 = Error in PROGRAM/ERASE/READ

Notes:
1. Status register bit 6 is 1 when the cache is ready to accept new data. R/B# follows bit 6.
2. Status register bit 5 is 0 during the actual programming operation. If cache mode is used, this bit will be 1 when all internal operations are complete.
3. A status register bit defined as Rewrite Recommended signifies that the page includes acertain number of READ errors per sector (512B (main) + 4B (spare) + 8B (parity). A re-writeof this page is recommended. (Up to a 4-bit error has been corrected if internal ECC was enabled.)

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4. A status register bit defined as FAIL signifies that an uncorrectable READ error has occurred.

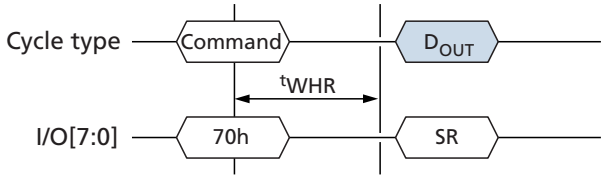
READ STATUS (70h)

The READ STATUS (70h) command returns the status of the last-selected die (LUN) on a target. This command is accepted by the last-selected die (LUN) even when it is busy (RDY = 0).

If there is only one die (LUN) per target, the READ STATUS (70h) command can be used to return status following any NAND command.

In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be used to select the die (LUN) that should report status. In this situation, using the READ STATUS (70h) command will result in bus contention, as two or more die (LUNs) could respond until the next operation is issued. The READ STATUS (70h) command can be used following all single-die (LUN) operations.

Figure 30: READ STATUS (70h) Operation



READ STATUS ENHANCED (78h)

The READ STATUS ENHANCED (78h) command returns the status of the addressed die (LUN) on a target even when it is busy (RDY = 0). This command is accepted by all die (LUNs), even when they are BUSY (RDY = 0).

Writing 78h to the command register, followed by three row address cycles containing the page, block, and LUN addresses, puts the selected die (LUN) into read status mode. The selected die (LUN) stays in this mode until another valid command is issued. Die (LUNs) that are not addressed are deselected to avoid bus contention.

The selected LUN's status is returned when the host requests data output. The RDY and ARDY bits of the status register are shared for all planes on the selected die (LUN). The FAILC and FAIL bits are specific to the plane specified in the row address.

The READ STATUS ENHANCED (78h) command also enables the selected die (LUN) for data output. To begin data output following a READ-series operation after the selected die (LUN) is ready (RDY = 1), issue the READ MODE (00h) command, then begin data output. If the host needs to change the cache register that will output data, use the RANDOM DATA READ TWO-PLANE (06h-E0h) command after the die (LUN) is ready.

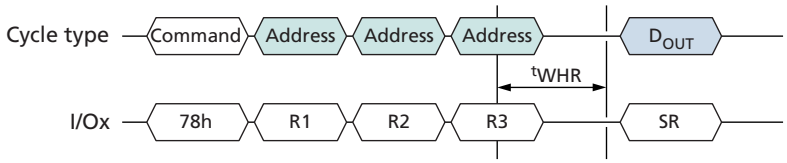
Use of the READ STATUS ENHANCED (78h) command is prohibited during the power-on RESET (FFh) command and when OTP mode is enabled. It is also prohibited following some of the other reset, identification, and configuration operations. See individual operations for specific details.

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Figure 31: READ STATUS ENHANCED (78h) Operation



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Column Address Operations

The column address operations affect how data is input to and output from the cache registers within the selected die (LUNs). These features provide host flexibility for managing data, especially when the host internal buffer is smaller than the number of data bytes or words in the cache register.

When the asynchronous interface is active, column address operations can address any byte in the selected cache register.

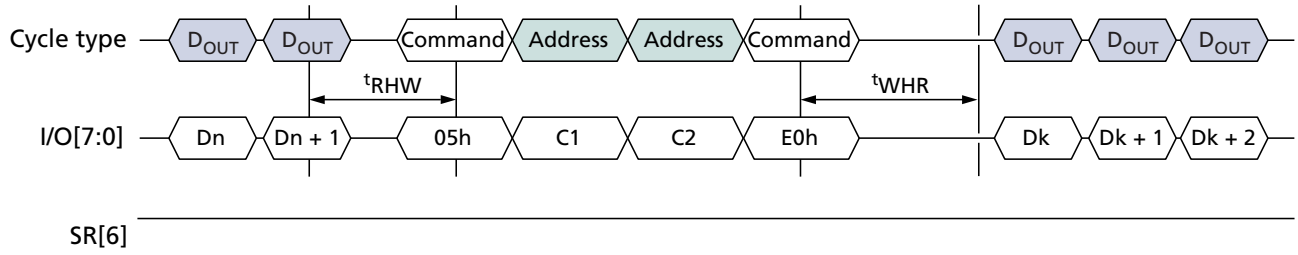
RANDOM DATA READ (05h-E0h)

The RANDOM DATA READ (05h-E0h) command changes the column address of the selected cache register and enables data output from the last selected die (LUN). This command is accepted by the selected die (LUN) when it is ready (RDY = 1; ARDY = 1). It is also accepted by the selected die (LUN) during CACHE READ operations (RDY = 1; ARDY = 0).

Writing 05h to the command register, followed by two column address cycles containing the column address, followed by the E0h command, puts the selected die (LUN) into data output mode. After the E0h command cycle is issued, the host must wait at least ^{t}WHR before requesting data output. The selected die (LUN) stays in data output mode until another valid command is issued.

In devices with more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be issued prior to issuing the RANDOM DATA READ (05h-E0h). In this situation, using the RANDOM DATA READ (05h-E0h) command without the READ STATUS ENHANCED (78h) command will result in bus contention because two or more die (LUNs) could output data.

Figure 32: RANDOM DATA READ (05h-E0h) Operation



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RANDOM DATA READ TWO-PLANE (06h-E0h)

The RANDOM DATA READ TWO-PLANE (06h-E0h) command enables data output on the addressed die's (LUN's) cache register at the specified column address. This command is accepted by a die (LUN) when it is ready (RDY = 1; ARDY = 1).

Writing 06h to the command register, followed by two column address cycles and three row address cycles, followed by E0h, enables data output mode on the address LUN's cache register at the specified column address. After the E0h command cycle is issued, the host must wait at least ^{t}WHR before requesting data output. The selected die (LUN) stays in data output mode until another valid command is issued.

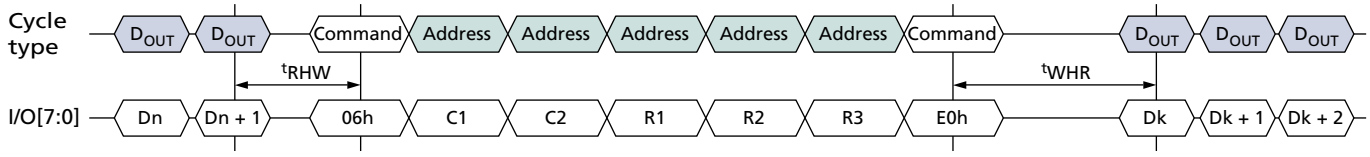
Following a two-plane read page operation, the RANDOM DATA READ TWO-PLANE (06h-E0h) command is used to select the cache register to be enabled for data output. After data output is complete on the selected plane, the command can be issued again to begin data output on another plane.

In devices with more than one die (LUN) per target, after all of the die (LUNs) on the target are ready (RDY = 1), the RANDOM DATA READ TWO-PLANE (06h-E0h) command can be used following an interleaved die (multi-LUN) read operation. Die (LUNs) that are not addressed are deselected to avoid bus contention.

In devices with more than one die (LUN) per target, during interleaved die (multi-LUN) operations where more than one or more die (LUNs) are busy (RDY = 1; ARDY = 0 or RDY = 0; ARDY = 0), the READ STATUS ENHANCED (78h) command must be issued to the die (LUN) to be selected prior to issuing the RANDOM DATA READ TWO-PLANE (06h-E0h). In this situation, using the RANDOM DATA READ TWO-PLANE (06h-E0h) command without the READ STATUS ENHANCED (78h) command will result in bus contention, as two or more die (LUNs) could output data.

If there is a need to update the column address without selecting a new cache register or LUN, the RANDOM DATA READ (05h-E0h) command can be used instead.

Figure 33: RANDOM DATA READ TWO-PLANE (06h-E0h) Operation



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RANDOM DATA INPUT (85h)

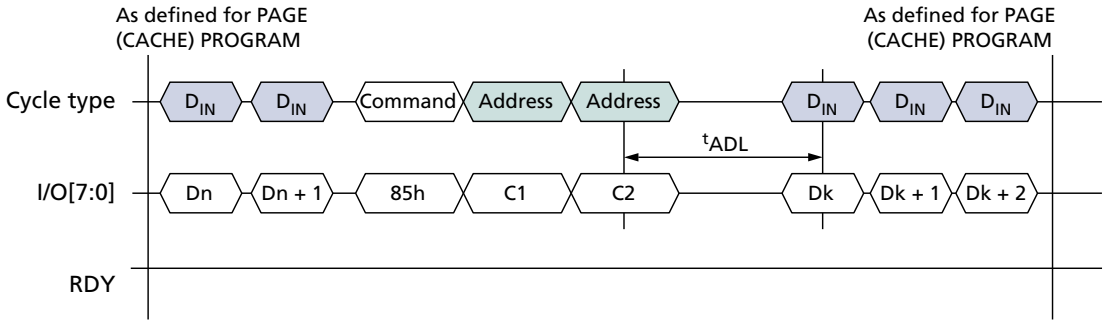
The RANDOM DATA INPUT (85h) command changes the column address of the selected cache register and enables data input on the last-selected die (LUN). This command is accepted by the selected die (LUN) when it is ready (RDY = 1; ARDY = 1). It is also accepted by the selected die (LUN) during cache program operations (RDY = 1; ARDY = 0).

Writing 85h to the command register, followed by two column address cycles containing the column address, puts the selected die (LUN) into data input mode. After the second address cycle is issued, the host must wait at least ^{t}ADL before inputting data. The selected die (LUN) stays in data input mode until another valid command is issued. Though data input mode is enabled, data input from the host is optional. Data input begins at the column address specified.

The RANDOM DATA INPUT (85h) command is allowed after the required address cycles are specified, but prior to the final command cycle (10h, 11h, 15h) of the following commands while data input is permitted: PROGRAM PAGE (80h-10h), PROGRAM PAGE CACHE (80h-15h), PROGRAM FOR INTERNAL DATA MOVE (85h-10h), and PROGRAM FOR TWO-PLANE INTERNAL DATA MOVE (85h-11h).

In devices that have more than one die (LUN) per target, the RANDOM DATA INPUT (85h) command can be used with other commands that support interleaved die (multi-LUN) operations.

Figure 34: RANDOM DATA INPUT (85h) Operation



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PROGRAM FOR INTERNAL DATA INPUT (85h)

The PROGRAM FOR INTERNAL DATA INPUT (85h) command changes the row address (block and page) where the cache register contents will be programmed in the NAND Flash array. It also changes the column address of the selected cache register and enables data input on the specified die (LUN). This command is accepted by the selected die (LUN) when it is ready (RDY = 1; ARDY = 1). It is also accepted by the selected die (LUN) during cache programming operations (RDY = 1; ARDY = 0).

Write 85h to the command register. Then write two column address cycles and three row address cycles. This updates the page and block destination of the selected device for the addressed LUN and puts the cache register into data input mode. After the fifth address cycle is issued the host must wait at least ^{t}ADL before inputting data. The selected LUN stays in data input mode until another valid command is issued. Though data input mode is enabled, data input from the host is optional. Data input begins at the column address specified.

The PROGRAM FOR INTERNAL DATA INPUT (85h) command is allowed after the required address cycles are specified, but prior to the final command cycle (10h, 11h, 15h) of the following commands while data input is permitted: PROGRAM PAGE (80h-10h), PROGRAM PAGE TWO-PLANE (80h-11h), PROGRAM PAGE CACHE (80h-15h), PROGRAM FOR INTERNAL DATA MOVE (85h-10h), and PROGRAM FOR TWO-PLANE INTERNAL DATA MOVE (85h-11h). When used with these commands, the LUN address and plane select bits are required to be identical to the LUN address and plane select bits originally specified.

The PROGRAM FOR INTERNAL DATA INPUT (85h) command enables the host to modify the original page and block address for the data in the cache register to a new page and block address.

In devices that have more than one die (LUN) per target, the PROGRAM FOR INTERNAL DATA INPUT (85h) command can be used with other commands that support interleaved die (multi-LUN) operations.

The PROGRAM FOR INTERNAL DATA INPUT (85h) command can be used with the RANDOM DATA READ (05h-E0h) or RANDOM DATA READ TWO-PLANE (06h-E0h) commands to read and modify cache register contents in small sections prior to programming cache register contents to the NAND Flash array. This capability can reduce the amount of buffer memory used in the host controller.

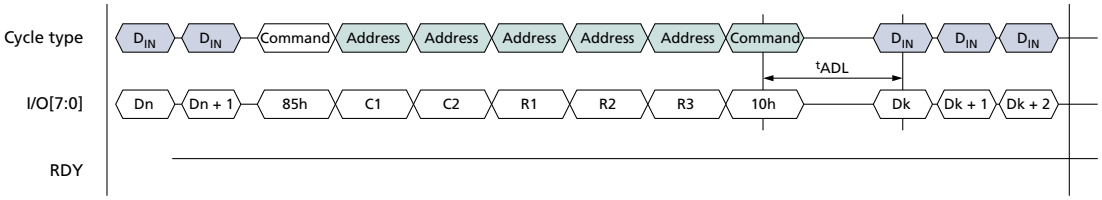
The RANDOM DATA INPUT (85h) command can be used during the PROGRAM FOR INTERNAL DATA MOVE command sequence to modify one or more bytes of the original data. First, data is copied into the cache register using the 00h-35h command sequence, then the RANDOM DATA INPUT (85h) command is written along with the address of the data to be modified next. New data is input on the external data pins. This copies the new data into the cache register.

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Figure 35: PROGRAM FOR INTERNAL DATA INPUT (85h) Operation



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Read Operations

The READ PAGE (00h-30h) command, when issued by itself, reads one page from the NAND Flash array to its cache register and enables data output for that cache register.

During data output the following commands can be used to read and modify the data in the cache registers: RANDOM DATA READ (05h-E0h) and RANDOM DATA INPUT (85h).

Read Cache Operations

To increase data throughput, the READ PAGE CACHE series (31h, 00h-31h) commands can be used to output data from the cache register while concurrently copying a page from the NAND Flash array to the data register.

To begin a read page cache sequence, begin by reading a page from the NAND Flash array to its corresponding cache register using the READ PAGE (00h-30h) command. R/B# goes LOW during ^{t}R and the selected die (LUN) is busy (RDY = 0, ARDY = 0). After ^{t}R (R/B# is HIGH and RDY = 1, ARDY = 1), issue either of these commands:

- READ PAGE CACHE SEQUENTIAL (31h) – copies the next sequential page from the NAND Flash array to the data register
- READ PAGE CACHE RANDOM (00h-31h) – copies the page specified in this command from the NAND Flash array to its corresponding data register

After the READ PAGE CACHE series (31h, 00h-31h) command has been issued, R/B# goes LOW on the target, and RDY = 0 and ARDY = 0 on the die (LUN) for ^{t}RCBSY while the next page begins copying data from the array to the data register. After ^{t}RCBSY, R/B# goes HIGH and the die's (LUN's) status register bits indicate the device is busy with a cache operation (RDY = 1, ARDY = 0). The cache register becomes available and the page requested in the READ PAGE CACHE operation is transferred to the data register. At this point, data can be output from the cache register, beginning at column address 0. The RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data output by the die (LUN).

After outputting the desired number of bytes from the cache register, either an additional READ PAGE CACHE series (31h, 00h-31h) operation can be started or the READ PAGE CACHE LAST (3Fh) command can be issued.

If the READ PAGE CACHE LAST (3Fh) command is issued, R/B# goes LOW on the target, and RDY = 0 and ARDY = 0 on the die (LUN) for ^{t}RCBSY while the data register is copied into the cache register. After ^{t}RCBSY, R/B# goes HIGH and RDY = 1 and ARDY = 1, indicating that the cache register is available and that the die (LUN) is ready. Data can then be output from the cache register, beginning at column address 0. The RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data being output.

For READ PAGE CACHE series (31h, 00h-31h, 3Fh), during the die (LUN) busy time, ^{t}RCBSY, when RDY = 0 and ARDY = 0, the only valid commands are status operations (70h, 78h) and RESET (FFh). When RDY = 1 and ARDY = 0, the only valid commands during READ PAGE CACHE series (31h, 00h-31h) operations are status operations (70h, 78h), READ MODE (00h), READ PAGE CACHE series (31h, 00h-31h), RANDOM DATA READ (05h-E0h), and RESET (FFh).

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Two-Plane Read Operations

Two-plane read page operations improve data throughput by copying data from more than one plane simultaneously to the specified cache registers. This is done by pre-pending one or more READ PAGE TWO-PLANE (00h-00h-30h) commands in front of the READ PAGE (00h-30h) command.

When the die (LUN) is ready, the RANDOM DATA READ TWO-PLANE (06h-E0h) command determines which plane outputs data. During data output, the following commands can be used to read and modify the data in the cache registers: RANDOM DATA READ (05h-E0h) and RANDOM DATA INPUT (85h).

Two-Plane Read Cache Operations

Two-plane read cache operations can be used to output data from more than one cache register while concurrently copying one or more pages from the NAND Flash array to the data register. This is done by prepending READ PAGE TWO-PLANE (00h-00h-30h) commands in front of the PAGE READ TWO-PLANE CACHE (00h-00h-31h) command.

To begin a two-plane read page cache sequence, begin by issuing a READ PAGE TWO-PLANE operation using the READ PAGE TWO-PLANE (00h-00h-30h) and READ PAGE (00h-30h) commands. R/B# goes LOW during ^{t}R and the selected die (LUN) is busy (RDY = 0, ARDY = 0). After ^{t}R (R/B# is HIGH and RDY = 1, ARDY = 1), issue either of these commands:

- READ PAGE CACHE SEQUENTIAL (31h) – copies the next sequential pages from the previously addressed planes from the NAND Flash array to the data registers.
- READ PAGE TWO-PLANE (00h-00h-30h) [in some cases, followed by READ PAGE TWO-PLANE CACHE (00h-00h-31h)] – copies the pages specified from the NAND Flash array to the corresponding data registers.

After the READ PAGE CACHE series (31h, 00h-00h-31h) command has been issued, R/B# goes LOW on the target, and RDY = 0 and ARDY = 0 on the die (LUN) for ^{t}RCBSY while the next pages begin copying data from the array to the data registers. After ^{t}RCBSY,
R/B# goes HIGH and the LUN's status register bits indicate the device is busy with a cache operation (RDY = 1, ARDY = 0). The cache registers become available and the pages requested in the READ PAGE CACHE operation are transferred to the data registers. Issue the RANDOM DATA READ TWO-PLANE (06h-E0h) command to determine which cache register will output data. After data is output, the RANDOM DATA READ TWO-PLANE (06h-E0h) command can be used to output data from other cache registers. After a cache register has been selected, the RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data output.

After outputting data from the cache registers, either an additional TWO-PLANE READ CACHE series (31h, 00h-00h-31h) operation can be started or the READ PAGE CACHE LAST (3Fh) command can be issued.

If the READ PAGE CACHE LAST (3Fh) command is issued, R/B# goes LOW on the target, and RDY = 0 and ARDY = 0 on the die (LUN) for ^{t}RCBSY while the data registers are copied into the cache registers. After ^{t}RCBSY, R/B# goes HIGH and RDY = 1 and ARDY = 1, indicating that the cache registers are available and that the die (LUN) is ready. Issue the RANDOM DATA READ TWO-PLANE (06h-E0h) command to determine which cache register will output data. After data is output, the RANDOM DATA READ TWO-PLANE (06h-E0h) command can be used to output data from other cache registers. After a

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cache register has been selected, the RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data output.

For READ PAGE CACHE series (31h, 00h-31h, 3Fh), during the die (LUN) busy time, ^{t}RCBSY, when RDY = 0 and ARDY = 0, the only valid commands are status operations (70h, 78h) and RESET (FFh). When RDY = 1 and ARDY = 0, the only valid commands during READ PAGE CACHE series (31h, 00h-31h) operations are status operations (70h, 78h), READ MODE (00h), two-plane read cache series (31h, 00h-00h-30h, 00h-00h-31h), RANDOM DATA READ (06h-E0h, 05h-E0h), and RESET (FFh).

READ MODE (00h)

The READ MODE (00h) command disables status output and enables data output for the last-selected die (LUN) and cache register after a READ operation (00h-30h, 00h-3Ah, 00h-35h) has been monitored with a status operation (70h, 78h). This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1). It is also accepted by the die (LUN) during READ PAGE CACHE (31h, 00h-31h) operations (RDY = 1 and ARDY = 0).

In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be used to select only one die (LUN) prior to issuing the READ MODE (00h) command. This prevents bus contention.

READ PAGE (00h-30h)

The READ PAGE (00h–30h) command copies a page from the NAND Flash array to its respective cache register and enables data output. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1).

To read a page from the NAND Flash array, write the 00h command to the command register, then write *n* address cycles to the address registers, and conclude with the 30h command. The selected die (LUN) will go busy (RDY = 0, ARDY = 0) for ^{t}R as data is transferred.

To determine the progress of the data transfer, the host can monitor the target's R/B# signal or, alternatively, the status operations (70h, 78h) can be used. If the status operations are used to monitor the LUN's status, when the die (LUN) is ready (RDY = 1, ARDY = 1), the host disables status output and enables data output by issuing the READ MODE (00h) command. When the host requests data output, output begins at the column address specified.

During data output the RANDOM DATA READ (05h-E0h) command can be issued.

When internal ECC is enabled, the READ STATUS (70h) command is required after the completion of the data transfer (^{t}R_ECC) to determine whether an uncorrectable read error occured. (^{t}R_ECC is the data transferred with internal ECC enabled.)

In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations the READ STATUS ENHANCED (78h) command must be used to select only one die (LUN) prior to the issue of the READ MODE (00h) command. This prevents bus contention.

The READ PAGE (00h-30h) command is used as the final command of a two-plane read operation. It is preceded by one or more READ PAGE TWO-PLANE (00h-00h-30h) com-

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mands. Data is transferred from the NAND Flash array for all of the addressed planes to their respective cache registers. When the die (LUN) is ready (RDY = 1, ARDY = 1), data output is enabled for the cache register linked to the plane addressed in the READ PAGE (00h-30h) command. When the host requests data output, output begins at the column address last specified in the READ PAGE (00h-30h) command. The RANDOM DATA READ TWO-PLANE (06h-E0h) command is used to enable data output in the other cache registers.

Figure 36: READ PAGE (00h-30h) Operation

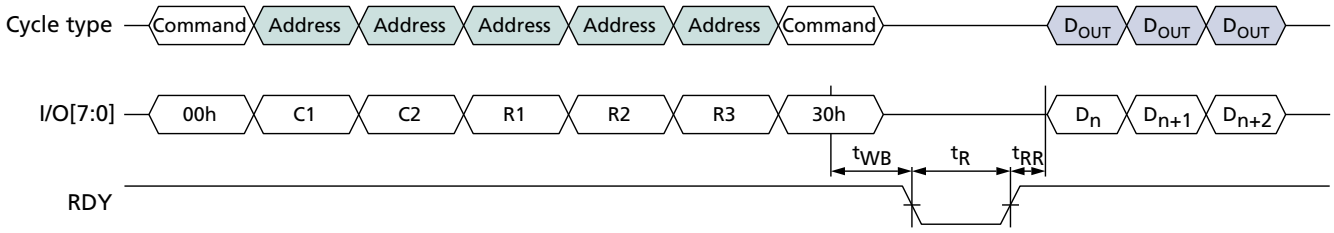
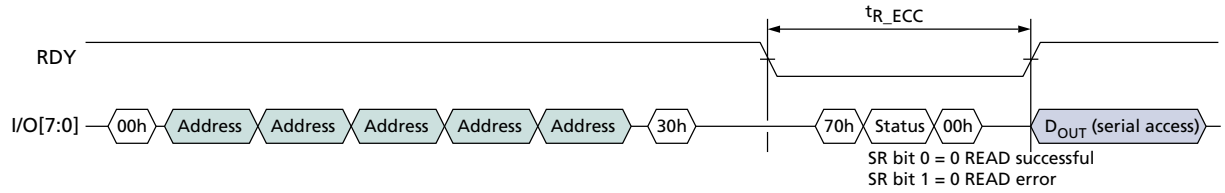


Figure 37: READ PAGE (00h-30h) Operation with Internal ECC Enabled



READ PAGE CACHE SEQUENTIAL (31h)

The READ PAGE CACHE SEQUENTIAL (31h) command reads the next sequential page within a block into the data register while the previous page is output from the cache register. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1). It is also accepted by the die (LUN) during READ PAGE CACHE (31h, 00h-31h) operations (RDY = 1 and ARDY = 0).

To issue this command, write 31h to the command register. After this command is issued, R/B# goes LOW and the die (LUN) is busy (RDY = 0, ARDY = 0) for tRCBSY. After tRCBSY, R/B# goes HIGH and the die (LUN) is busy with a cache operation (RDY = 1, ARDY = 0), indicating that the cache register is available and that the specified page is copying from the NAND Flash array to the data register. At this point, data can be output from the cache register beginning at column address 0. The RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data being output from the cache register.

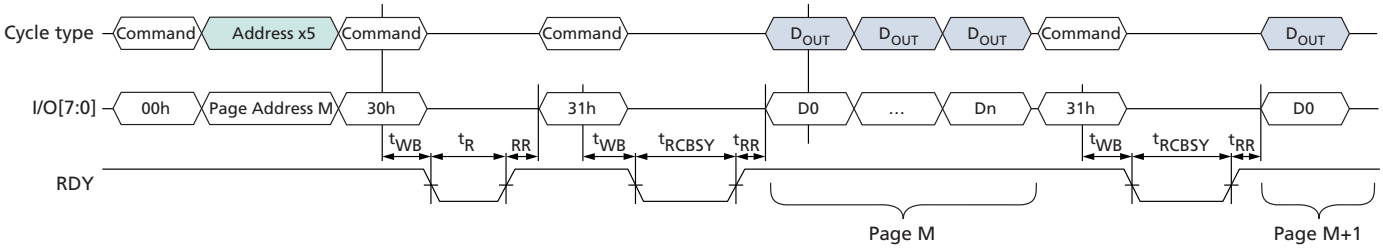
The READ PAGE CACHE SEQUENTIAL (31h) command can be used to cross block boundaries. If the READ PAGE CACHE SEQUENTIAL (31h) command is issued after the last page of a block is read into the data register, the next page read will be the next logical block in which the 31h command was issued. Do not issue the READ PAGE CACHE SEQUENTIAL (31h) to cross die (LUN) boundaries. Instead, issue the READ PAGE CACHE LAST (3Fh) command.

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Figure 38: READ PAGE CACHE SEQUENTIAL (31h) Operation



READ PAGE CACHE RANDOM (00h-31h)

The READ PAGE CACHE RANDOM (00h-31h) command reads the specified block and page into the data register while the previous page is output from the cache register. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1). It is also accepted by the die (LUN) during READ PAGE CACHE (31h, 00h-31h) operations (RDY = 1 and ARDY = 0).

To issue this command, write 00h to the command register, then write *n* address cycles to the address register, and conclude by writing 31h to the command register. The column address in the address specified is ignored. The die (LUN) address must match the same die (LUN) address as the previous READ PAGE (00h-30h) command or, if applicable, the previous READ PAGE CACHE RANDOM (00h-31h) command.

After this command is issued, R/B# goes LOW and the die (LUN) is busy (RDY = 0, ARDY = 0) for ^{t}RCBSY. After ^{t}RCBSY, R/B# goes HIGH and the die (LUN) is busy with a cache operation (RDY = 1, ARDY = 0), indicating that the cache register is available and that the specified page is copying from the NAND Flash array to the data register. At this point, data can be output from the cache register beginning at column address 0. The RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data being output from the cache register.

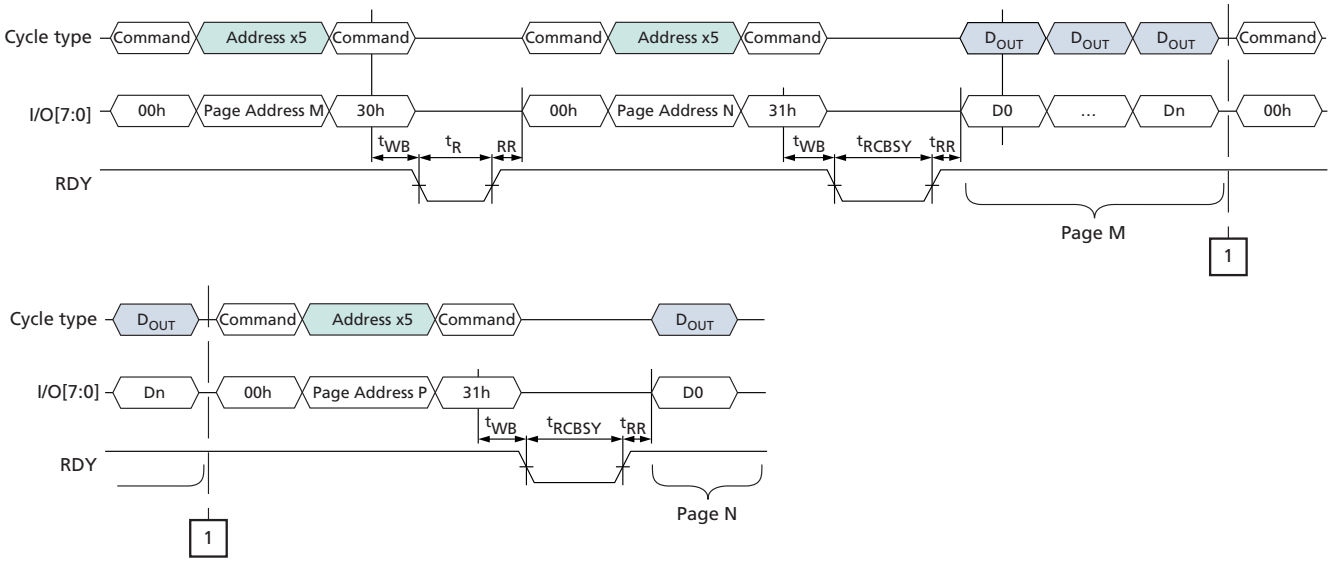
In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations the READ STATUS ENHANCED (78h) command followed by the READ MODE (00h) command must be used to select only one die (LUN) and prevent bus contention.

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Figure 39: READ PAGE CACHE RANDOM (00h-31h) Operation



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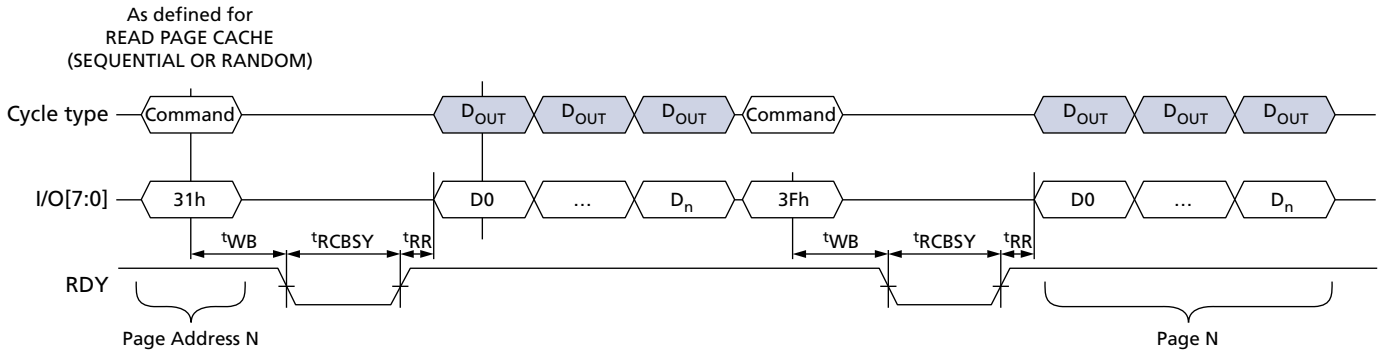
READ PAGE CACHE LAST (3Fh)

The READ PAGE CACHE LAST (3Fh) command ends the read page cache sequence and copies a page from the data register to the cache register. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1). It is also accepted by the die (LUN) during READ PAGE CACHE (31h, 00h-31h) operations (RDY = 1 and ARDY = 0).

To issue the READ PAGE CACHE LAST (3Fh) command, write 3Fh to the command register. After this command is issued, R/B# goes LOW and the die (LUN) is busy (RDY = 0, ARDY = 0) for ^{t}RCBSY. After ^{t}RCBSY, R/B# goes HIGH and the die (LUN) is ready (RDY = 1, ARDY = 1). At this point, data can be output from the cache register, beginning at column address 0. The RANDOM DATA READ (05h-E0h) command can be used to change the column address of the data being output from the cache register.

In devices that have more than one LUN per target, during and following interleaved die (multi-LUN) operations the READ STATUS ENHANCED (78h) command followed by the READ MODE (00h) command must be used to select only one die (LUN) and prevent bus contention.

Figure 40: READ PAGE CACHE LAST (3Fh) Operation



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READ PAGE TWO-PLANE 00h-00h-30h

The READ PAGE TWO-PLANE (00h-00h-30h) operation is similar to the PAGE READ (00h-30h) operation. It transfers two pages of data from the NAND Flash array to the data registers. Each page must be from a different plane on the same die.

To enter the READ PAGE TWO-PLANE mode, write the 00h command to the command register, and then write five address cycles for plane 0 (BA6 = 0). Next, write the 00h command to the command register, and five address cycles for plane 1 (BA6 = 1). Finally, issue the 30h command. The first-plane and second-plane addresses must meet the two-plane addressing requirements, and, in addition, they must have identical column addresses.

After the 30h command is written, page data is transferred from both planes to their respective data registers in ^{t}R. During these transfers, R/B# goes LOW. When the transfers are complete, R/B# goes HIGH. To read out the data from the plane 0 data register, pulse RE# repeatedly. After the data cycle from the plane 0 address completes, issue a RANDOM DATA READ TWO-PLANE (06h-E0h) command to select the plane 1 address, then repeatedly pulse RE# to read out the data from the plane 1 data register.

Alternatively, the READ STATUS (70h) command can monitor data transfers. When the transfers are complete, status register bit 6 is set to 1. To read data from the first of the two planes, the user must first issue the RANDOM DATA READ TWO-PLANE (06h-E0h) command and pulse RE# repeatedly.

When the data cycle is complete, issue a RANDOM DATA READ TWO-PLANE (06h-E0h) command to select the other plane. To output the data beginning at the specified column address, pulse RE# repeatedly.

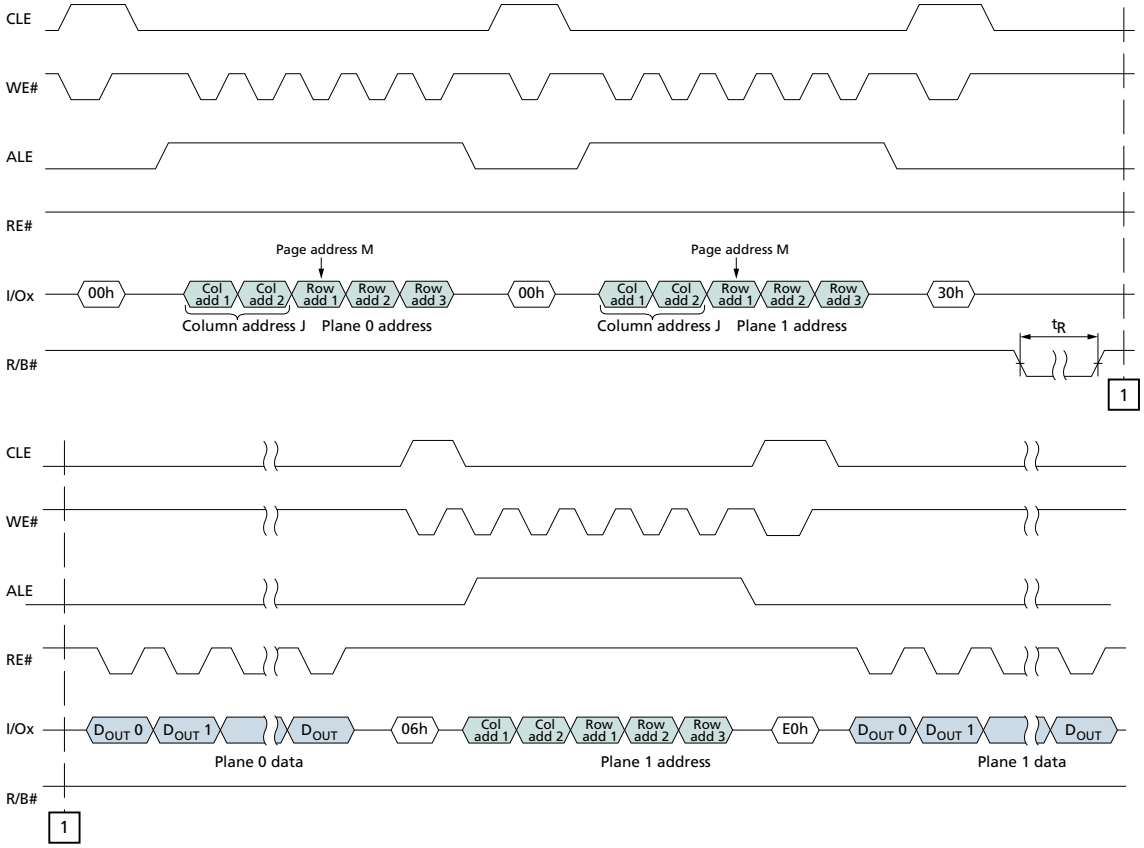
Use of the READ STATUS ENHANCED (78h) command is prohibited during and following a PAGE READ TWO-PLANE operation.

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Figure 41: READ PAGE TWO-PLANE (00h-00h-30h) Operation



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Program Operations

Program operations are used to move data from the cache or data registers to the NAND array. During a program operation the contents of the cache and/or data registers are modified by the internal control logic.

Within a block, pages must be programmed sequentially from the least significant page address to the most significant page address (0, 1, 2, ….., 63). During a program operation, the contents of the cache and/or data registers are modified by the internal control logic.

Program Operations

The PROGRAM PAGE (80h-10h) command, when not preceded by the PROGRAM PAGE TWO-PLANE (80h-11h) command, programs one page from the cache register to the NAND Flash array. When the die (LUN) is ready (RDY = 1, ARDY = 1), the host should check the FAIL bit to verify that the operation has completed successfully.

Program Cache Operations

The PROGRAM PAGE CACHE (80h-15h) command can be used to improve program operation system performance. When this command is issued, the die (LUN) goes busy (RDY = 0, ARDY = 0) while the cache register contents are copied to the data register, and the die (LUN) is busy with a program cache operation (RDY = 1, ARDY = 0. While the contents of the data register are moved to the NAND Flash array, the cache register is available for an additional PROGRAM PAGE CACHE (80h-15h) or PROGRAM PAGE (80h-10h) command.

For PROGRAM PAGE CACHE series (80h-15h) operations, during the die (LUN) busy times, ^{t}CBSY and ^{t}LPROG, when RDY = 0 and ARDY = 0, the only valid commands are status operations (70h, 78h) and reset (FFh). When RDY = 1 and ARDY = 0, the only valid commands during PROGRAM PAGE CACHE series (80h-15h) operations are status operations (70h, 78h), PROGRAM PAGE CACHE (80h-15h), PROGRAM PAGE (80h-10h), RANDOM DATA INPUT (85h), PROGRAM FOR INTERNAL DATA INPUT (85h), and RESET (FFh).

Two-Plane Program Operations

The PROGRAM PAGE TWO-PLANE (80h-11h) command can be used to improve program operation system performance by enabling multiple pages to be moved from the cache registers to different planes of the NAND Flash array. This is done by prepending one or more PROGRAM PAGE TWO-PLANE (80h-11h) commands in front of the PROGRAM PAGE (80h-10h) command.

Two-Plane Program Cache Operations

The PROGRAM PAGE TWO-PLANE (80h-11h) command can be used to improve program cache operation system performance by enabling multiple pages to be moved from the cache registers to the data registers and, while the pages are being transferred from the data registers to different planes of the NAND Flash array, free the cache registers to receive data input from the host. This is done by prepending one or more PROGRAM PAGE TWO-PLANE (80h-11h) commands in front of the PROGRAM PAGE CACHE (80h-15h) command.

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PROGRAM PAGE (80h-10h)

The PROGRAM PAGE (80h-10h) command enables the host to input data to a cache register, and moves the data from the cache register to the specified block and page address in the array of the selected die (LUN). This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1). It is also accepted by the die (LUN) when it is busy with a PROGRAM PAGE CACHE (80h-15h) operation (RDY = 1, ARDY = 0).

To input a page to the cache register and move it to the NAND array at the block and page address specified, write 80h to the command register. Unless this command has been preceded by a PROGRAM PAGE TWO-PLANE (80h-11h) command, issuing the 80h to the command register clears all of the cache registers' contents on the selected target. Then write *n* address cycles containing the column address and row address. Data input cycles follow. Serial data is input beginning at the column address specified. At any time during the data input cycle the RANDOM DATA INPUT (85h) and PROGRAM FOR INTERNAL DATA INPUT (85h) commands may be issued. When data input is complete, write 10h to the command register. The selected LUN will go busy (RDY = 0, ARDY = 0) for ^{t}PROG as data is transferred.

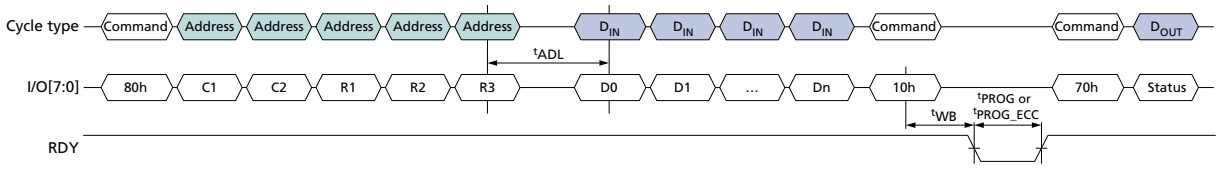
To determine the progress of the data transfer, the host can monitor the target's R/B# signal or, alternatively, the status operations (70h, 78h) may be used. When the die (LUN) is ready (RDY = 1, ARDY = 1), the host should check the status of the FAIL bit.

In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be used to select only one die (LUN) for status output. Use of the READ STATUS (70h) command could cause more than one die (LUN) to respond, resulting in bus contention.

The PROGRAM PAGE (80h-10h) command is used as the final command of a two-plane program operation. It is preceded by one or more PROGRAM PAGE TWO-PLANE (80h-11h) commands. Data is transferred from the cache registers for all of the addressed planes to the NAND array. The host should check the status of the operation by using the status operations (70h, 78h).

When internal ECC is enabled, the duration of array programming time is ^{t}PROG_ECC. During ^{t}PROG_ECC, the internal ECC generates parity bits when error detection is complete.

Figure 42: PROGRAM PAGE (80h-10h) Operation



PROGRAM PAGE CACHE (80h-15h)

The PROGRAM PAGE CACHE (80h-15h) command enables the host to input data to a cache register; copies the data from the cache register to the data register; then moves the data register contents to the specified block and page address in the array of the selected die (LUN). After the data is copied to the data register, the cache register is available for additional PROGRAM PAGE CACHE (80h-15h) or PROGRAM PAGE (80h-10h)

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commands. The PROGRAM PAGE CACHE (80h-15h) command is accepted by the die (LUN) when it is ready (RDY =1, ARDY = 1). It is also accepted by the die (LUN) when busy with a PROGRAM PAGE CACHE (80h-15h) operation (RDY = 1, ARDY = 0).

To input a page to the cache register to move it to the NAND array at the block and page address specified, write 80h to the command register. Unless this command has been preceded by a PROGRAM PAGE TWO-PLANE (80h-11h) command, issuing the 80h to the command register clears all of the cache registers' contents on the selected target. Then write *n* address cycles containing the column address and row address. Data input cycles follow. Serial data is input beginning at the column address specified. At any time during the data input cycle the RANDOM DATA INPUT (85h) and PROGRAM FOR INTERNAL DATA INPUT (85h) commands may be issued. When data input is complete, write 15h to the command register. The selected LUN will go busy (RDY = 0, ARDY = 0) for ^{t}CBSY to allow the data register to become available from a previous program cache operation, to copy data from the cache register to the data register, and then to begin moving the data register contents to the specified page and block address.

To determine the progress of ^{t}CBSY, the host can monitor the target's R/B# signal or, alternatively, the status operations (70h, 78h) can be used. When the LUN's status shows that it is busy with a PROGRAM CACHE operation (RDY = 1, ARDY = 0), the host should check the status of the FAILC bit to see if a previous cache operation was successful.

If, after ^{t}CBSY, the host wants to wait for the program cache operation to complete, without issuing the PROGRAM PAGE (80h-10h) command, the host should monitor ARDY until it is 1. The host should then check the status of the FAIL and FAILC bits.

In devices with more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be used to select only one die (LUN) for status output. Use of the READ STATUS (70h) command could cause more than one die (LUN) to respond, resulting in bus contention.

The PROGRAM PAGE CACHE (80h-15h) command is used as the final command of a two-plane program cache operation. It is preceded by one or more PROGRAM PAGE TWO-PLANE (80h-11h) commands. Data for all of the addressed planes is transferred from the cache registers to the corresponding data registers, then moved to the NAND Flash array. The host should check the status of the operation by using the status operations (70h, 78h).

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Figure 43: PROGRAM PAGE CACHE (80h–15h) Operation (Start)

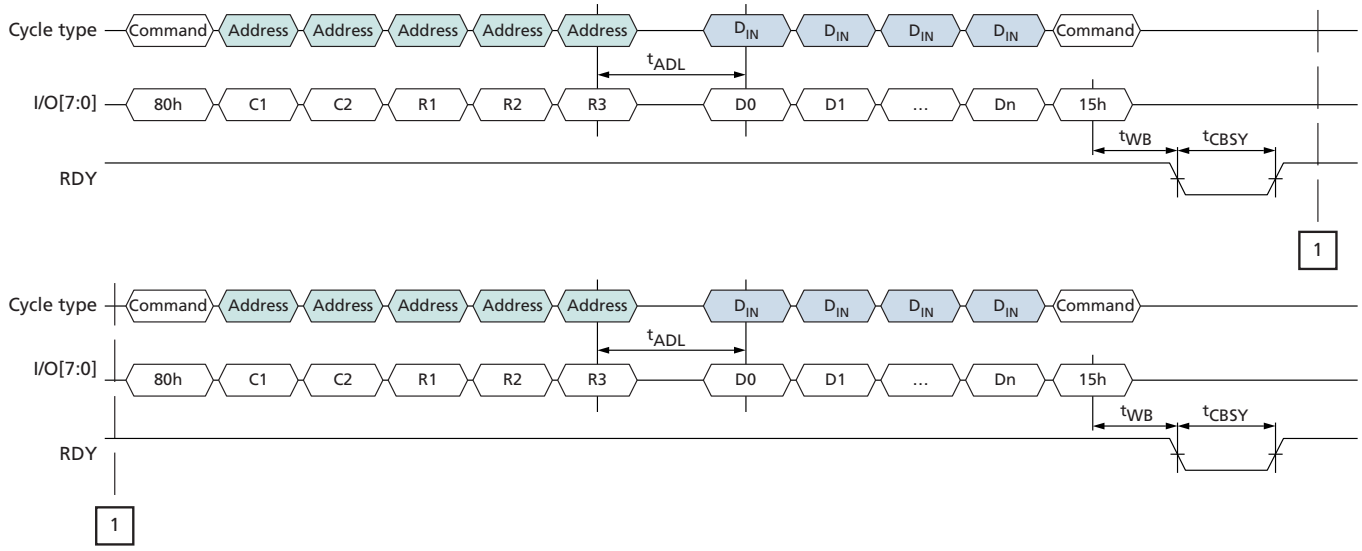
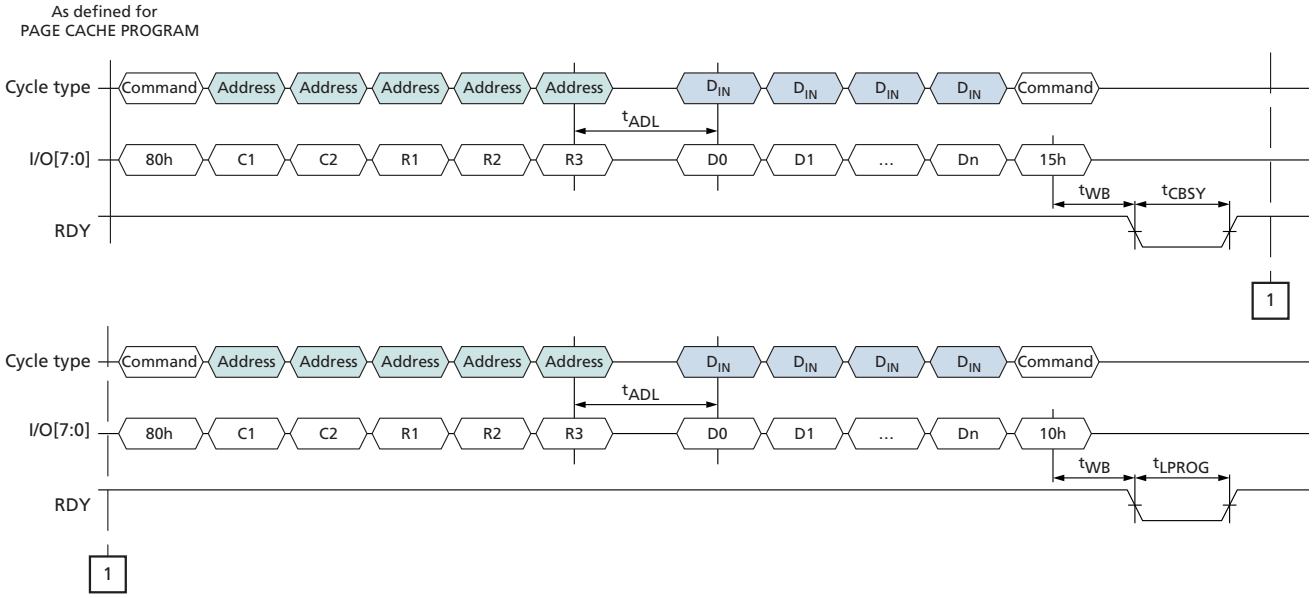


Figure 44: PROGRAM PAGE CACHE (80h–15h) Operation (End)



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PROGRAM PAGE TWO-PLANE (80h-11h)

The PROGRAM PAGE TWO-PLANE (80h-11h) command enables the host to input data to the addressed plane's cache register and queue the cache register to ultimately be moved to the NAND Flash array. This command can be issued one or more times. Each time a new plane address is specified that plane is also queued for data transfer. To input data for the final plane and to begin the program operation for all previously queued planes, issue either the PROGRAM PAGE (80h-10h) command or the PROGRAM PAGE CACHE (80h-15h) command. All of the queued planes will move the data to the NAND Flash array. This command is accepted by the die (LUN) when it is ready (RDY = 1).

To input a page to the cache register and queue it to be moved to the NAND Flash array at the block and page address specified, write 80h to the command register. Unless this command has been preceded by a PROGRAM PAGE TWO-PLANE (80h-11h) command, issuing the 80h to the command register clears all of the cache registers' contents on the selected target. Write five address cycles containing the column address and row address; data input cycles follow. Serial data is input beginning at the column address specified. At any time during the data input cycle, the RANDOM DATA INPUT (85h) and PROGRAM FOR INTERNAL DATA INPUT (85h) commands can be issued. When data input is complete, write 11h to the command register. The selected die (LUN) will go busy (RDY = 0, ARDY = 0) for ^{t}DBSY.

To determine the progress of ^{t}DBSY, the host can monitor the target's R/B# signal or, alternatively, the status operations (70h, 78h) can be used. When the LUN's status shows that it is ready (RDY = 1), additional PROGRAM PAGE TWO-PLANE (80h-11h) commands can be issued to queue additional planes for data transfer. Alternatively, the PROGRAM PAGE (80h-10h) or PROGRAM PAGE CACHE (80h-15h) commands can be issued.

When the PROGRAM PAGE (80h-10h) command is used as the final command of a two-plane program operation, data is transferred from the cache registers to the NAND Flash array for all of the addressed planes during ^{t}PROG. When the die (LUN) is ready (RDY = 1, ARDY = 1), the host should check the status of the FAIL bit for each of the planes to verify that programming completed successfully.

When the PROGRAM PAGE CACHE (80h-15h) command is used as the final command of a program cache two-plane operation, data is transferred from the cache registers to the data registers after the previous array operations finish. The data is then moved from the data registers to the NAND Flash array for all of the addressed planes. This occurs during ^{t}CBSY. After ^{t}CBSY, the host should check the status of the FAILC bit for each of the planes from the previous program cache operation, if any, to verify that programming completed successfully.

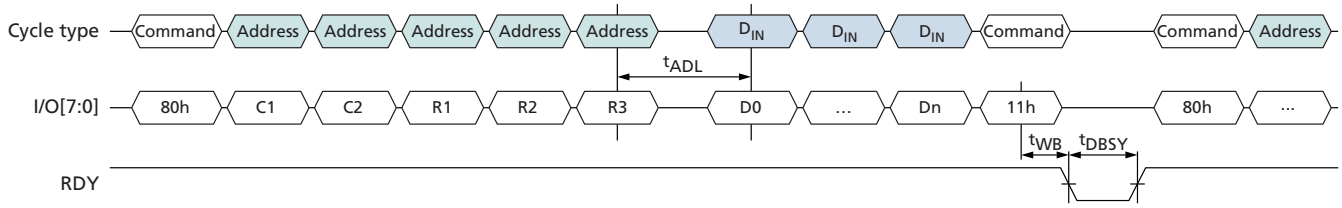
For the PROGRAM PAGE TWO-PLANE (80h-11h), PROGRAM PAGE (80h-10h), and PROGRAM PAGE CACHE (80h-15h) commands, see Two-Plane Operations for two-plane addressing requirements.

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Figure 45: PROGRAM PAGE TWO-PLANE (80h–11h) Operation



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Erase Operations

Erase operations are used to clear the contents of a block in the NAND Flash array to prepare its pages for program operations.

Erase Operations

The ERASE BLOCK (60h-D0h) command, when not preceded by the ERASE BLOCK TWO-PLANE (60h-D1h) command, erases one block in the NAND Flash array. When the die (LUN) is ready (RDY = 1, ARDY = 1), the host should check the FAIL bit to verify that this operation completed successfully.

TWO-PLANE ERASE Operations

The ERASE BLOCK TWO-PLANE (60h-D1h) command can be used to further system performance of erase operations by allowing more than one block to be erased in the NAND array. This is done by prepending one or more ERASE BLOCK TWO-PLANE (60h-D1h) commands in front of the ERASE BLOCK (60h-D0h) command. See Two-Plane Operations for details.

ERASE BLOCK (60h-D0h)

The ERASE BLOCK (60h-D0h) command erases the specified block in the NAND Flash array. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1).

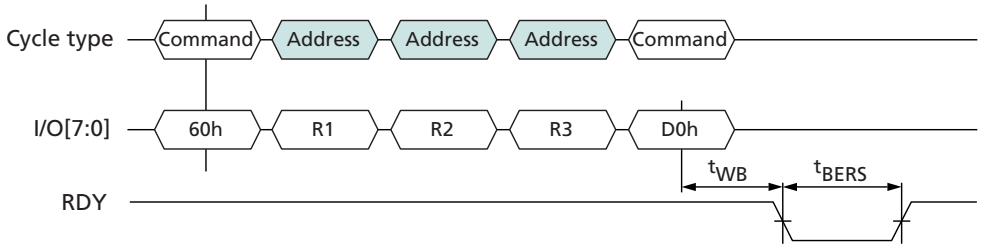
To erase a block, write 60h to the command register. Then write three address cycles containing the row address; the page address is ignored. Conclude by writing D0h to the command register. The selected die (LUN) will go busy (RDY = 0, ARDY = 0) for ^{t}BERS while the block is erased.

To determine the progress of an ERASE operation, the host can monitor the target's R/B# signal, or alternatively, the status operations (70h, 78h) can be used. When the die (LUN) is ready (RDY = 1, ARDY = 1) the host should check the status of the FAIL bit.

In devices that have more than one die (LUN) per target, during and following interleaved die (multi-LUN) operations, the READ STATUS ENHANCED (78h) command must be used to select only one die (LUN) for status output. Use of the READ STATUS (70h) command could cause more than one die (LUN) to respond, resulting in bus contention.

The ERASE BLOCK (60h-D0h) command is used as the final command of an erase two-plane operation. It is preceded by one or more ERASE BLOCK TWO-PLANE (60h-D1h) commands. All blocks in the addressed planes are erased. The host should check the status of the operation by using the status operations (70h, 78h). See Two-Plane Operations for two-plane addressing requirements.

Figure 46: ERASE BLOCK (60h-D0h) Operation



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ERASE BLOCK TWO-PLANE (60h-D1h)

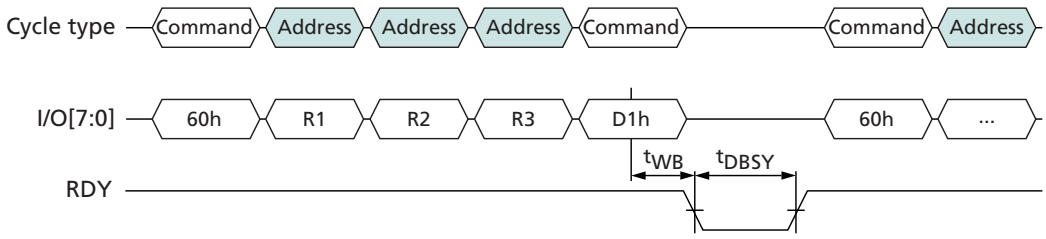
The ERASE BLOCK TWO-PLANE (60h-D1h) command queues a block in the specified plane to be erased in the NAND Flash array. This command can be issued one or more times. Each time a new plane address is specified, that plane is also queued for a block to be erased. To specify the final block to be erased and to begin the ERASE operation for all previously queued planes, issue the ERASE BLOCK (60h-D0h) command. This command is accepted by the die (LUN) when it is ready (RDY = 1, ARDY = 1).

To queue a block to be erased, write 60h to the command register, then write three address cycles containing the row address; the page address is ignored. Conclude by writing D1h to the command register. The selected die (LUN) will go busy (RDY = 0, ARDY = 0) for ^{t}DBSY.

To determine the progress of ^{t}DBSY, the host can monitor the target's R/B# signal, or alternatively, the status operations (70h, 78h) can be used. When the LUN's status shows that it is ready (RDY = 1, ARDY = 1), additional ERASE BLOCK TWO-PLANE (60h-D1h) commands can be issued to queue additional planes for erase. Alternatively, the ERASE BLOCK (60h-D0h) command can be issued to erase all of the queued blocks.

For two-plane addressing requirements for the ERASE BLOCK TWO-PLANE (60h-D1h) and ERASE BLOCK (60h-D0h) commands, see Two-Plane Operations.

Figure 47: ERASE BLOCK TWO-PLANE (60h–D1h) Operation



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Internal Data Move Operations

Internal data move operations make it possible to transfer data within a device from one page to another using the cache register. This is particularly useful for block management and wear leveling.

The INTERNAL DATA MOVE operation is a two-step process consisting of a READ FOR INTERNAL DATA MOVE (00h-35h) and a PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command. To move data from one page to another on the same plane, first issue the READ FOR INTERNAL DATA MOVE (00h-35h) command. When the die (LUN) is ready (RDY = 1, ARDY = 1), the host can transfer the data to a new page by issuing the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command. When the die (LUN) is again ready (RDY = 1, ARDY = 1), the host should check the FAIL bit to verify that this operation completed successfully.

To prevent bit errors from accumulating over multiple INTERNAL DATA MOVE operations, it is recommended that the host read the data out of the cache register after the READ FOR INTERNAL DATA MOVE (00h-35h) completes and prior to issuing the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command. The RANDOM DATA READ (05h-E0h) command can be used to change the column address. The host should check the data for ECC errors and correct them. When the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command is issued, any corrected data can be input. The PROGRAM FOR INTERNAL DATA INPUT (85h) command can be used to change the column address.

It is not possible to use the READ FOR INTERNAL DATA MOVE operation to move data from one plane to another or from one die (LUN) to another. Instead, use a READ PAGE (00h-30h) or READ FOR INTERNAL DATA MOVE (00h-35h) command to read the data out of the NAND, and then use a PROGRAM PAGE (80h-10h) command with data input to program the data to a new plane or die (LUN).

Between the READ FOR INTERNAL DATA MOVE (00h-35h) and PROGRAM FOR INTERNAL DATA MOVE (85h-10h) commands, the following commands are supported: status operations (70h, 78h) and column address operations (05h-E0h, 06h-E0h, 85h). The RESET operation (FFh) can be issued after READ FOR INTERNAL DATA MOVE (00h-35h), but the contents of the cache registers on the target are not valid.

In devices that have more than one die (LUN) per target, once the READ FOR INTERNAL DATA MOVE (00h-35h) is issued, interleaved die (multi-LUN) operations are prohibited until after the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command is issued.

Two-Plane Read for Internal Data Move Operations

Two-plane internal data move read operations improve read data throughput by copying data simultaneously from more than one plane to the specified cache registers. This is done by issuing the READ PAGE TWO-PLANE (00h-00h-30h) command or the READ FOR INTERNAL DATA MOVE (00h-00h-35h) command.

The INTERNAL DATA MOVE PROGRAM TWO-PLANE (85h-11h) command can be used to further system performance of PROGRAM FOR INTERNAL DATA MOVE operations by enabling movement of multiple pages from the cache registers to different planes of the NAND Flash array. This is done by prepending one or more PROGRAM FOR INTERNAL DATA MOVE (85h-11h) commands in front of the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command. See Two-Plane Operations for details.

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READ FOR INTERNAL DATA MOVE (00h-35h)

The READ FOR INTERNAL DATA MOVE (00h-35h) command is functionally identical to the READ PAGE (00h-30h) command, except that 35h is written to the command register instead of 30h.

Though it is not required, it is recommended that the host read the data out of the device to verify the data prior to issuing the PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command to prevent the propagation of data errors.

If internal ECC is enabled, the data does not need to be toggled out by the host to be corrected and moving data can then be written to a new page without data reloading, which improves system performance.

Figure 48: READ FOR INTERNAL DATA MOVE (00h-35h) Operation

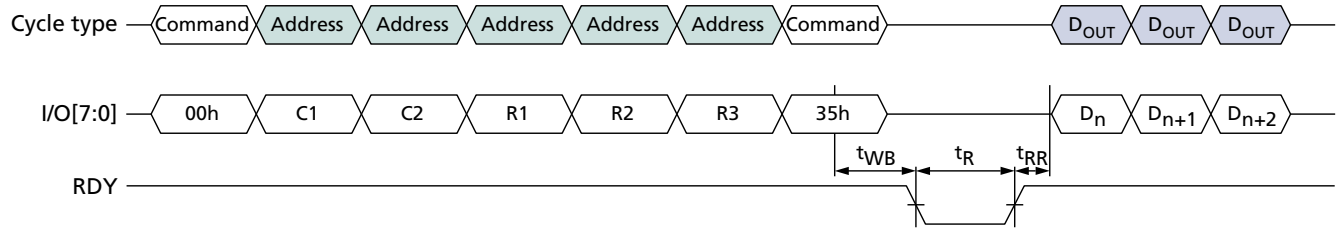
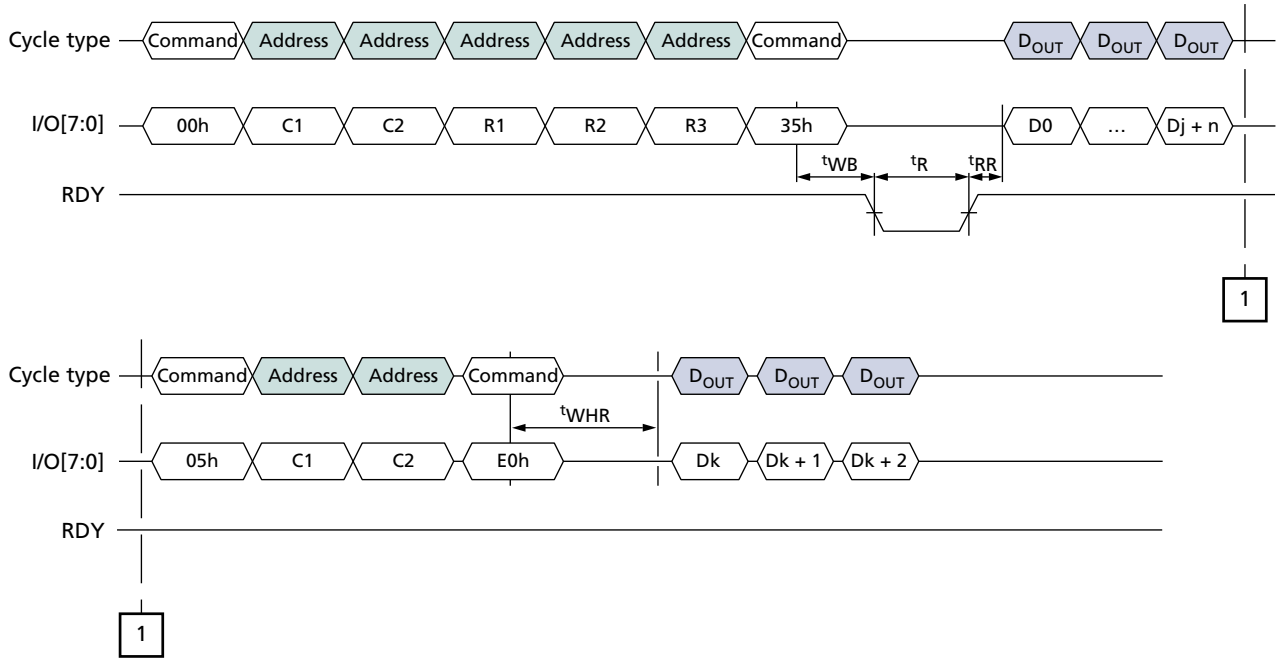


Figure 49: READ FOR INTERNAL DATA MOVE (00h–35h) with RANDOM DATA READ (05h–E0h)



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Figure 50: INTERNAL DATA MOVE (85h-10h) with Internal ECC Enabled

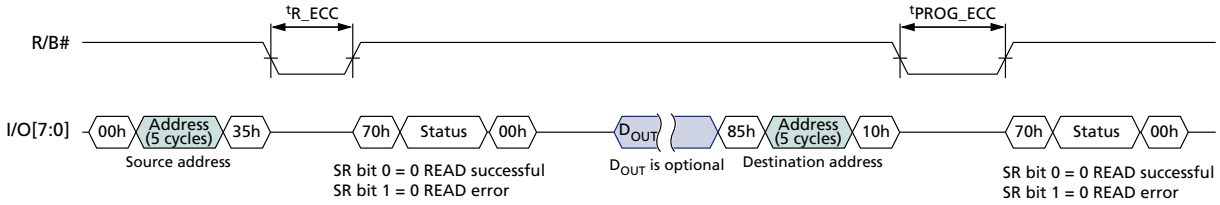
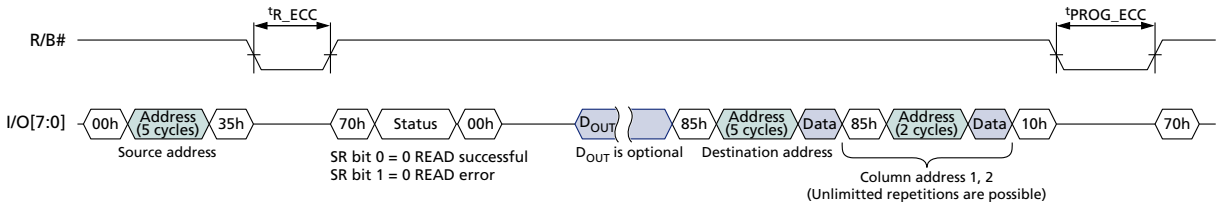


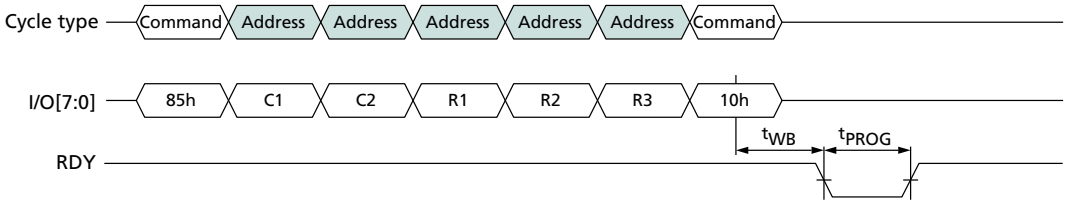
Figure 51: INTERNAL DATA MOVE (85h-10h) with RANDOM DATA INPUT with Internal ECC Enabled



PROGRAM FOR INTERNAL DATA MOVE (85h–10h)

The PROGRAM FOR INTERNAL DATA MOVE (85h-10h) command is functionally identical to the PROGRAM PAGE (80h-10h) command, except that when 85h is written to the command register, cache register contents are not cleared.

Figure 52: PROGRAM FOR INTERNAL DATA MOVE (85h–10h) Operation

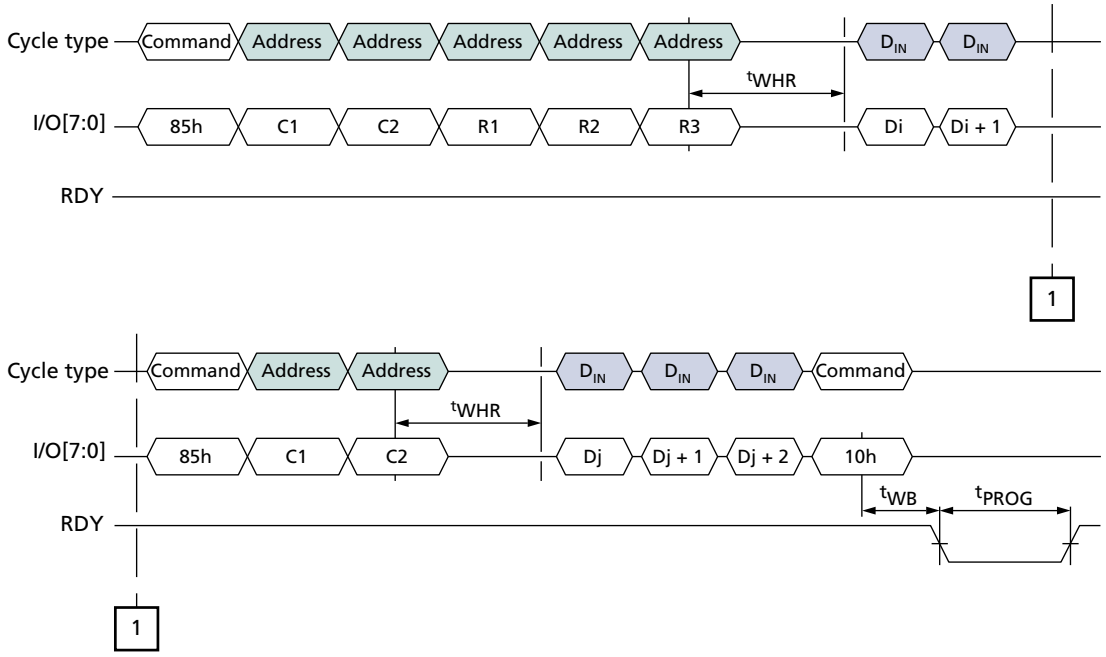


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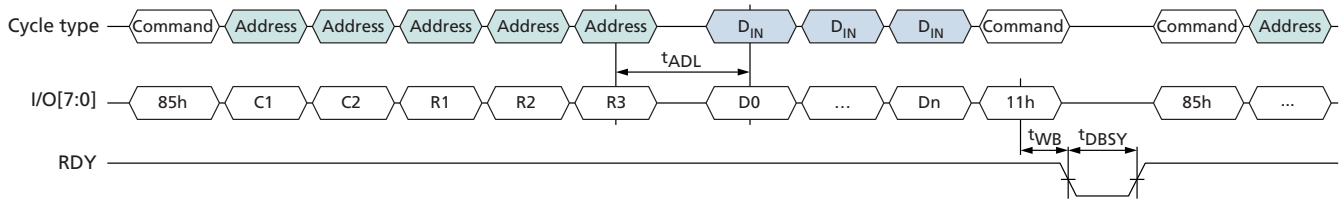
Figure 53: PROGRAM FOR INTERNAL DATA MOVE (85h-10h) with RANDOM DATA INPUT (85h)



PROGRAM FOR INTERNAL DATA MOVE TWO-PLANE (85h-11h)

The PROGRAM FOR INTERNAL DATA MOVE TWO-PLANE (85h-11h) command is functionally identical to the PROGRAM PAGE TWO-PLANE (85h-11h) command, except that when 85h is written to the command register, cache register contents are not cleared. See Program Operations for further details.

Figure 54: PROGRAM FOR INTERNAL DATA MOVE TWO-PLANE (85h-11h) Operation



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Block Lock Feature

The block lock feature protects either the entire device or ranges of blocks from being programmed and erased. Using the block lock feature is preferable to using WP# to prevent PROGRAM and ERASE operations.

Block lock is enabled and disabled at power-on through the LOCK pin. At power-on, if LOCK is LOW, all BLOCK LOCK commands are disabled. However if LOCK is HIGH at power-on, the BLOCK LOCK commands are enabled and, by default, all the blocks on the device are protected, or locked, from PROGRAM and ERASE operations, even if WP# is HIGH.

Before the contents of the device can be modified, the device must first be unlocked. Either a range of blocks or the entire device may be unlocked. PROGRAM and ERASE operations complete successfully only in the block ranges that have been unlocked. Blocks, once unlocked, can be locked again to protect them from further PROGRAM and ERASE operations.

Blocks that are locked can be protected further, or locked tight. When locked tight, the device's blocks can no longer be locked or unlocked.

WP# and Block Lock

The following is true when the block lock feature is enabled:

- Holding WP# LOW locks all blocks, provided the blocks are not locked tight.
- If WP# is held LOW to lock blocks, then returned to HIGH, a new UNLOCK command must be issued to unlock blocks.

UNLOCK (23h-24h)

By default at power-on, if LOCK is HIGH, all the blocks are locked and protected from PROGRAM and ERASE operations. The UNLOCK (23h) command is used to unlock a range of blocks. Unlocked blocks have no protection and can be programmed or erased.

The UNLOCK command uses two registers, a lower boundary block address register and an upper boundary block address register, and the invert area bit to determine what range of blocks are unlocked. When the invert area bit = 0, the range of blocks within the lower and upper boundary address registers are unlocked. When the invert area bit = 1, the range of blocks outside the boundaries of the lower and upper boundary address registers are unlocked. The lower boundary block address must be less than the upper boundary block address. The figures below show examples of how the lower and upper boundary address registers work with the invert area bit.

To unlock a range of blocks, issue the UNLOCK (23h) command followed by the appropriate address cycles that indicate the lower boundary block address. Then issue the 24h command followed by the appropriate address cycles that indicate the upper boundary block address. The least significant page address bit, PA0, should be set to 1 if setting the invert area bit; otherwise, it should be 0. The other page address bits should be 0.

Only one range of blocks can be specified in the lower and upper boundary block address registers. If after unlocking a range of blocks the UNLOCK command is again issued, the new block address range determines which blocks are unlocked. The previous unlocked block address range is not retained.

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Figure 55: Flash Array Protected: Invert Area Bit = 0

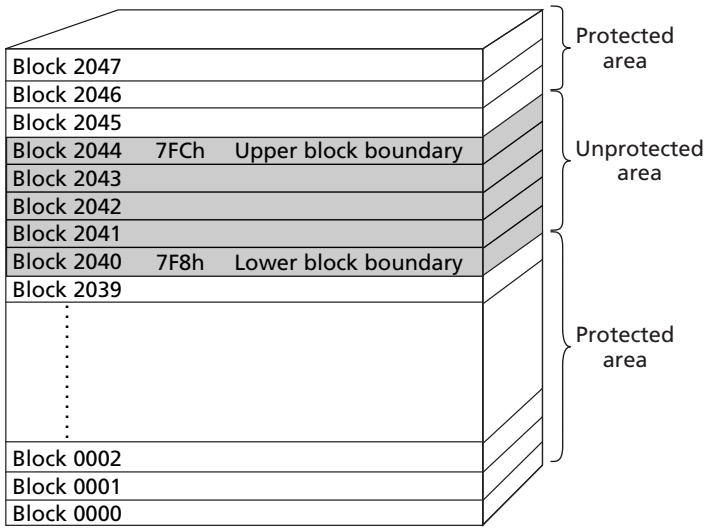
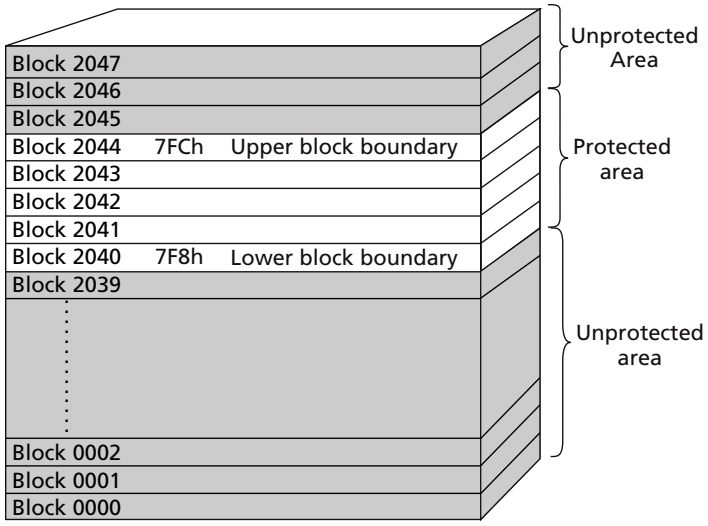


Figure 56: Flash Array Protected: Invert Area Bit = 1



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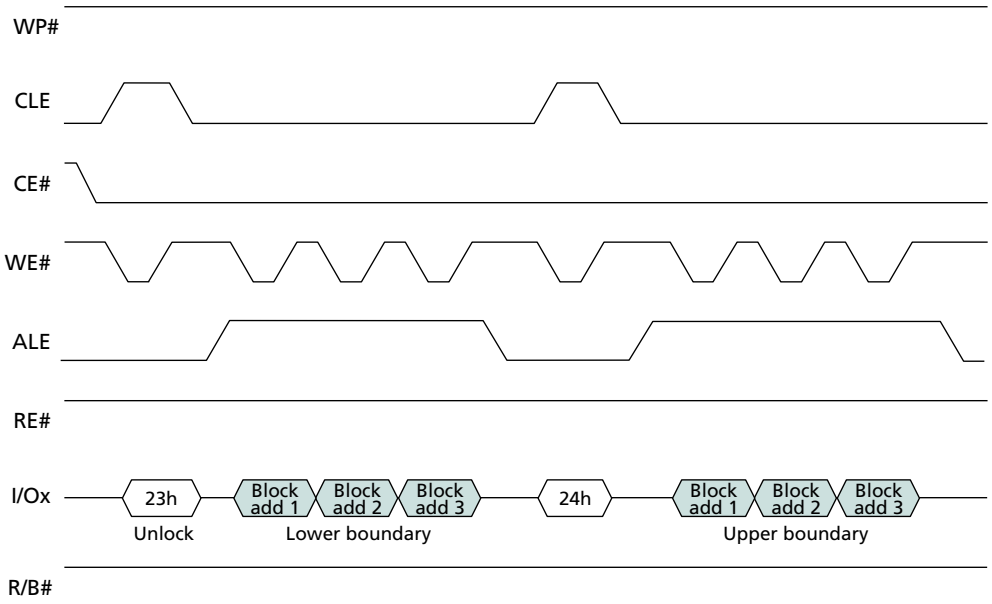
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Table 16: Block Lock Address Cycle Assignments

ALE Cycle	I/O[15:8][1]	I/O7	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0
First	LOW	BA7	BA6	LOW	LOW	LOW	LOW	LOW	Invert area bit[2]
Second	LOW	BA15	BA14	BA13	BA12	BA11	BA10	BA9	BA8
Third	LOW	LOW	LOW	LOW	LOW	LOW	LOW	BA17	BA16

Notes:
1. I/O[15:8] is applicable only for x16 devices.
2. Invert area bit is applicable for 24h command; it may be LOW or HIGH for 23h command.

Figure 57: UNLOCK Operation



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LOCK (2Ah)

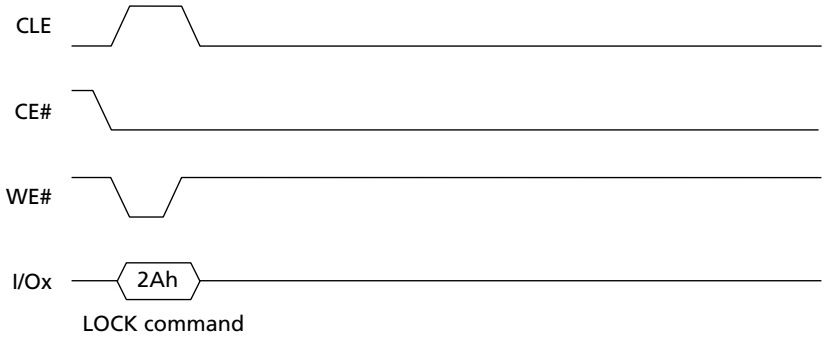
By default at power-on, if LOCK is HIGH, all the blocks are locked and protected from PROGRAM and ERASE operations. If portions of the device are unlocked using the UNLOCK (23h) command, they can be locked again using the LOCK (2Ah) command. The LOCK command locks all of the blocks in the device. Locked blocks are write-protected from PROGRAM and ERASE operations.

To lock all of the blocks in the device, issue the LOCK (2Ah) command.

When a PROGRAM or ERASE operation is issued to a locked block, R/B# goes LOW for ^{t}LBSY. The PROGRAM or ERASE operation does not complete. Any READ STATUS command reports bit 7 as 0, indicating that the block is protected.

The LOCK (2Ah) command is disabled if LOCK is LOW at power-on or if the device is locked tight.

Figure 58: LOCK Operation



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LOCK TIGHT (2Ch)

The LOCK TIGHT (2Ch) command prevents locked blocks from being unlocked and also prevents unlocked blocks from being locked. When this command is issued, the UNLOCK (23h) and LOCK (2Ah) commands are disabled. This provides an additional level of protection against inadvertent PROGRAM and ERASE operations to locked blocks.

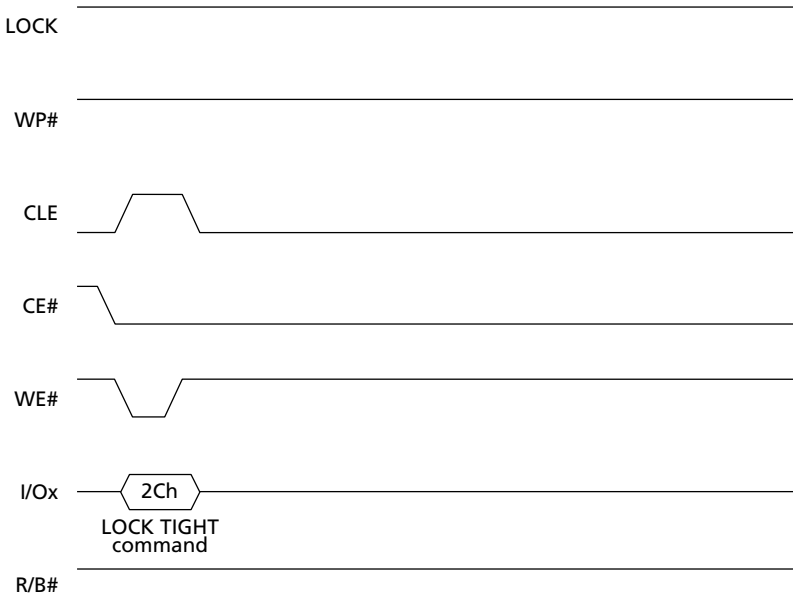
To implement LOCK TIGHT in all of the locked blocks in the device, verify that WP# is HIGH and then issue the LOCK TIGHT (2Ch) command.

When a PROGRAM or ERASE operation is issued to a locked block that has also been locked tight, R/B# goes LOW for ^{t}LBSY. The PROGRAM or ERASE operation does not complete. The READ STATUS (70h) command reports bit 7 as 0, indicating that the block is protected. PROGRAM and ERASE operations complete successfully to blocks that were not locked at the time the LOCK TIGHT command was issued.

After the LOCK TIGHT command is issued, the command cannot be disabled via a software command. Lock tight status can be disabled only by power cycling the device or toggling WP#. When the lock tight status is disabled, all of the blocks become locked, the same as if the LOCK (2Ah) command had been issued.

The LOCK TIGHT (2Ch) command is disabled if LOCK is LOW at power-on.

Figure 59: LOCK TIGHT Operation

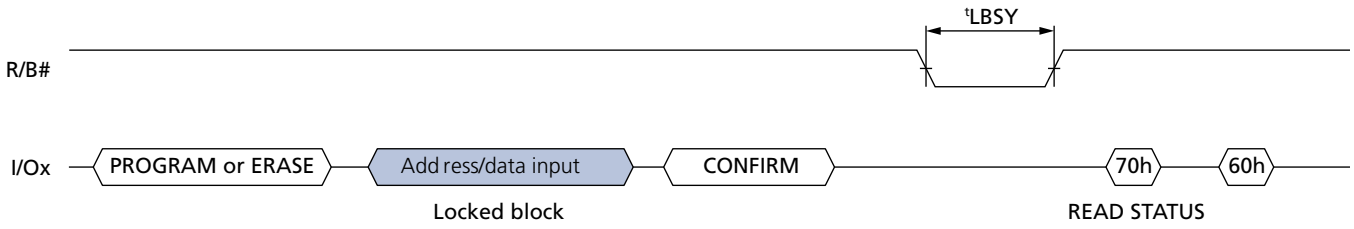


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Figure 60: PROGRAM/ERASE Issued to Locked Block



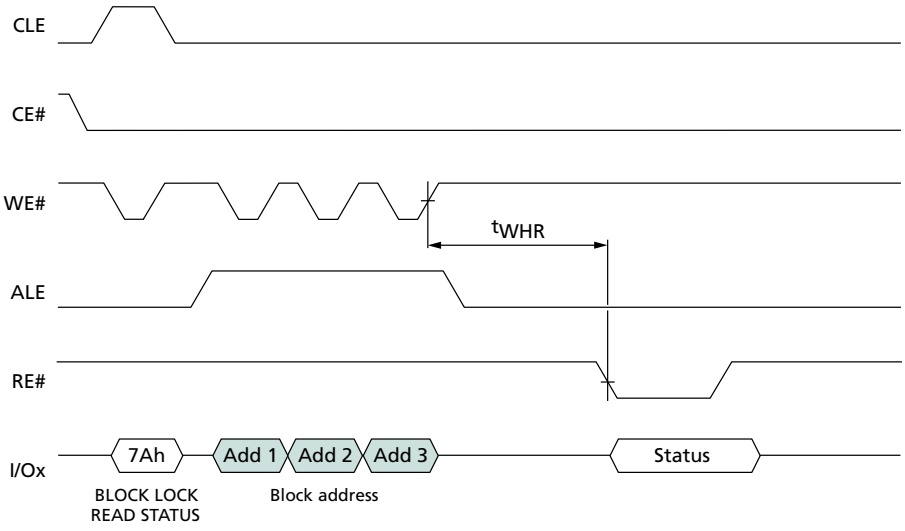
BLOCK LOCK READ STATUS (7Ah)

The BLOCK LOCK READ STATUS (7Ah) command is used to determine the protection status of individual blocks. The address cycles have the same format, as shown below, and the invert area bit should be set LOW. On the falling edge of RE# the I/O pins output the block lock status register, which contains the information on the protection status of the block.

Table 17: Block Lock Status Register Bit Definitions

Block Lock Status Register Definitions	I/O[7:3]	I/O2 (Lock#)	I/O1 (LT#)	I/O0 (LT)
Block is locked tight	X	0	0	1
Block is locked	X	0	1	0
Block is unlocked, and device is locked tight	X	1	0	1
Block is unlocked, and device is not locked tight	X	1	1	0

Figure 61: BLOCK LOCK READ STATUS

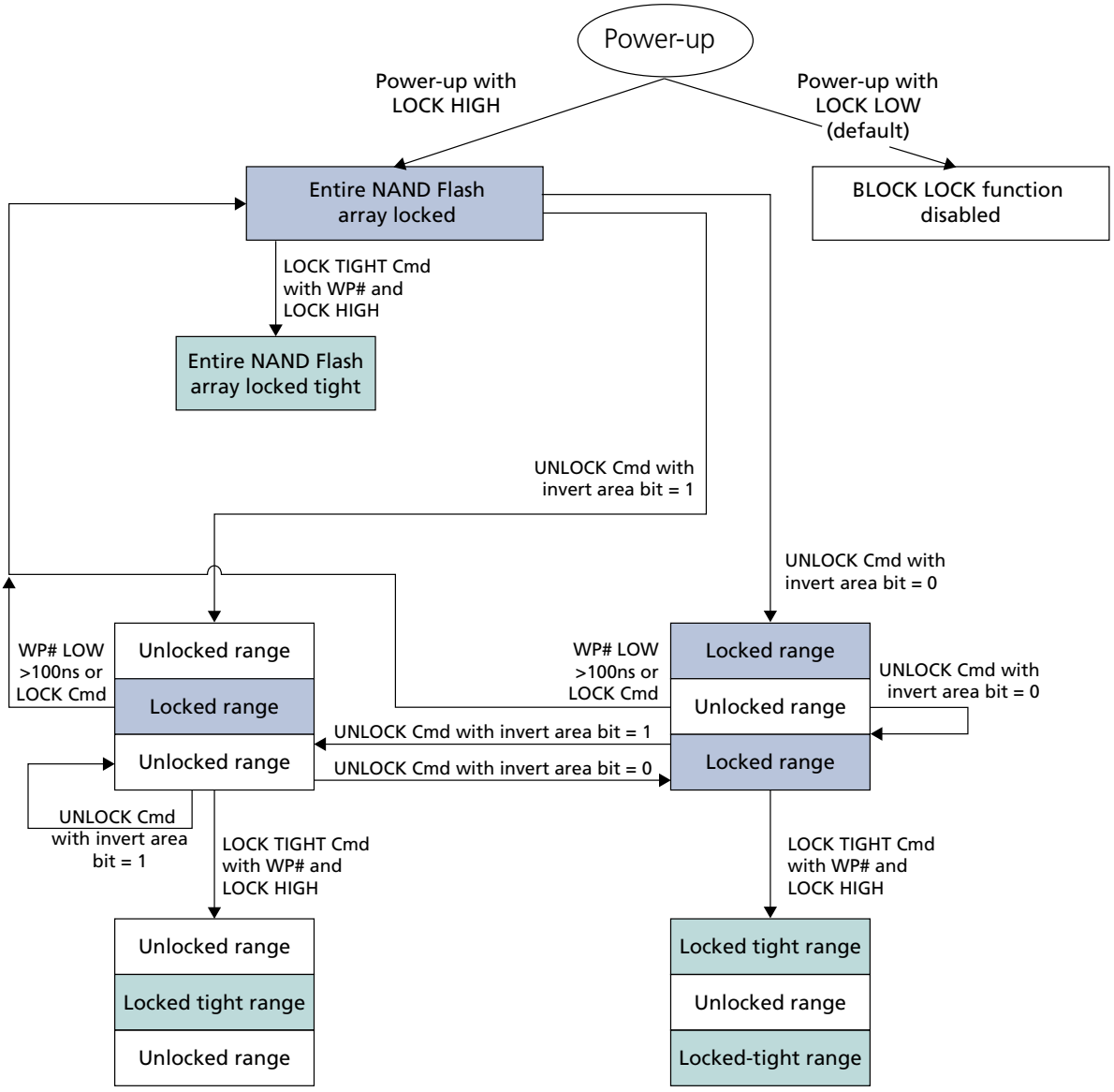


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Figure 62: BLOCK LOCK Flowchart



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One-Time Programmable (OTP) Operations

This Micron NAND Flash device offers a protected, one-time programmable NAND Flash memory area. Thirty full pages (2112 bytes per page) of OTP data are available on the device, and the entire range is guaranteed to be good. The OTP area is accessible only through the OTP commands. Customers can use the OTP area any way they choose; typical uses include programming serial numbers or other data for permanent storage.

The OTP area leaves the factory in an unwritten state (all bits are 1s). Programming or partial-page programming enables the user to program only 0 bits in the OTP area. The OTP area cannot be erased, whether it is protected or not. Protecting the OTP area prevents further programming of that area.

Micron provides a unique way to program and verify data before permanently protecting it and preventing future changes. The OTP area is only accessible while in OTP operation mode. To set the device to OTP operation mode, issue the SET FEATURE (EFh) command to feature address 90h and write 01h to P1, followed by three cycles of 00h to P2-P4. For parameters to enter OTP mode, see Features Operations.

When the device is in OTP operation mode, all subsequent PAGE READ (00h-30h) and PROGRAM PAGE (80h-10h) commands are applied to the OTP area. The OTP area is assigned to page addresses 02h-1Fh. To program an OTP page, issue the PROGRAM PAGE (80h-10h) command. The pages must be programmed in the ascending order. Similarly, to read an OTP page, issue the PAGE READ (00h-30h) command.

Protecting the OTP is done by entering OTP protect mode. To set the device to OTP protect mode, issue the SET FEATURE (EFh) command to feature address 90h and write 03h to P1, followed by three cycles of 00h to P2-P4.

To determine whether the device is busy during an OTP operation, either monitor R/B# or use the READ STATUS (70h) command.

To exit OTP operation or protect mode, write 00h to P1 at feature address 90h.

Legacy OTP Commands

For legacy OTP commands, OTP DATA PROGRAM (A0h-10h), OTP DATA PROTECT (A5h-10h), and OTP DATA READ (AFh-30h), refer to the MT29F4GxxAxC data sheet.

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OTP DATA PROGRAM (80h-10h)

The OTP DATA PROGRAM (80h-10h) command is used to write data to the pages within the OTP area. An entire page can be programmed at one time, or a page can be partially programmed up to eight times. Only the OTP area allows up to eight partial-page programs. The rest of the blocks support only four partial-page programs. There is no ERASE operation for OTP pages.

PROGRAM PAGE enables programming into an offset of an OTP page using two bytes of the column address (CA[12:0]). The command is compatible with the RANDOM DATA INPUT (85h) command. The PROGRAM PAGE command will not execute if the OTP area has been protected.

To use the PROGRAM PAGE command, issue the 80h command. Issue *n* address cycles. The first two address cycles are the column address. For the remaining cycles, select a page in the range of 02h-00h through 1Fh-00h. Next, write from 1–2112 bytes of data. After data input is complete, issue the 10h command. The internal control logic automatically executes the proper programming algorithm and controls the necessary timing for programming and verification.

R/B# goes LOW for the duration of the array programming time (^{t}PROG). The READ STATUS (70h) command is the only valid command for reading status in OTP operation mode. Bit 5 of the status register reflects the state of R/B#. When the device is ready, read bit 0 of the status register to determine whether the operation passed or failed (see Status Operations). Each OTP page can be programmed to 8 partial-page programming.

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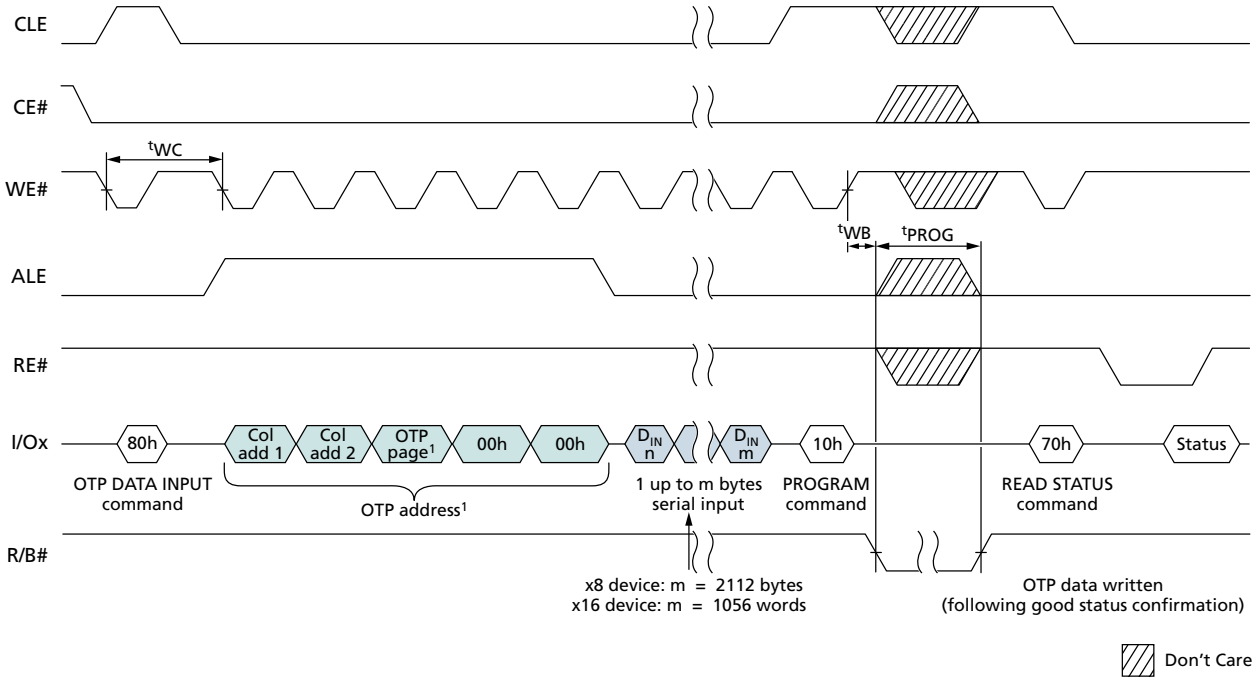
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RANDOM DATA INPUT (85h)

After the initial OTP data set is input, additional data can be written to a new column address with the RANDOM DATA INPUT (85h) command. The RANDOM DATA INPUT command can be used any number of times in the same page prior to the OTP PAGE WRITE (10h) command being issued.

Figure 63: OTP DATA PROGRAM (After Entering OTP Operation Mode)



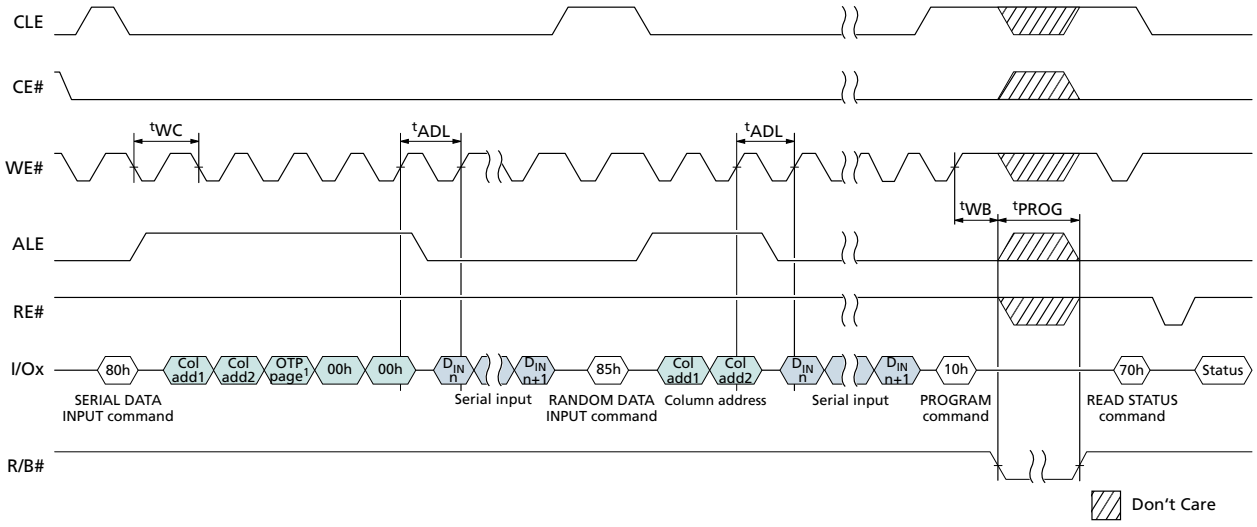
Note: 1. The OTP page must be within the 02h–1Fh range.

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Figure 64: OTP DATA PROGRAM Operation with RANDOM DATA INPUT (After Entering OTP Operation Mode)



OTP DATA PROTECT (80h-10)

The OTP DATA PROTECT (80h-10h) command is used to prevent further programming of the pages in the OTP area. To protect the OTP area, the target must be in OTP operation mode.

To protect all data in the OTP area, issue the 80h command. Issue n address cycles including the column address, OTP protect page address and block address; the column and block addresses are fixed to 0. Next, write 00h data for the first byte location and issue the 10h command. R/B# goes LOW for the duration of the array programming time, tPROG.

After the data is protected, it cannot be programmed further. When the OTP area is protected, the pages within the area are no longer programmable and cannot be unprotected.

The READ STATUS (70h) command is the only valid command for reading status in OTP operation mode. The RDY bit of the status register will reflect the state of R/B#. Use of the READ STATUS ENHANCED (78h) command is prohibited.

When the target is ready, read the FAIL bit of the status register to determine if the operation passed or failed.

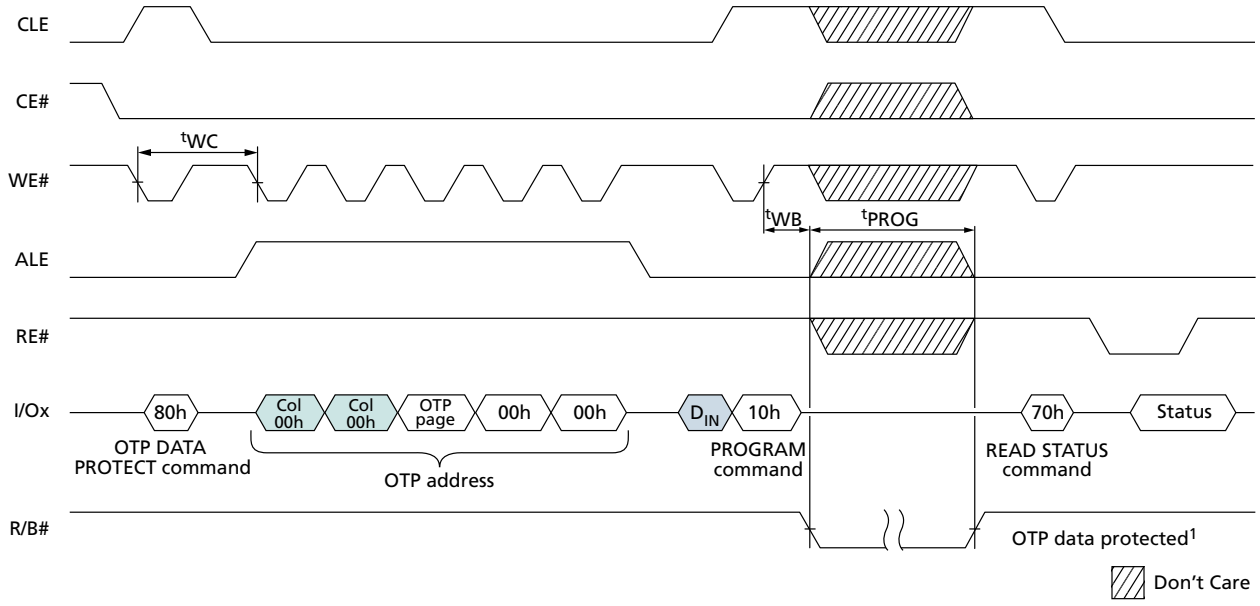
If the OTP DATA PROTECT (80h-10h) command is issued after the OTP area has already been protected, R/B# goes LOW for tOBSY. After tOBSY, the status register is set to 60h.

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Figure 65: OTP DATA PROTECT Operation (After Entering OTP Protect Mode)



Note: 1. OTP data is protected following a good status confirmation.

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OTP DATA READ (00h-30h)

To read data from the OTP area, set the device to OTP operation mode, then issue the PAGE READ (00h-30h) command. Data can be read from OTP pages within the OTP area whether the area is protected or not.

To use the PAGE READ command for reading data from the OTP area, issue the 00h command, and then issue five address cycles: for the first two cycles, the column address; and for the remaining address cycles, select a page in the range of 02h-00h-00h through 1Fh-00h-00h. Lastly, issue the 30h command. The PAGE READ CACHE MODE command is not supported on OTP pages.

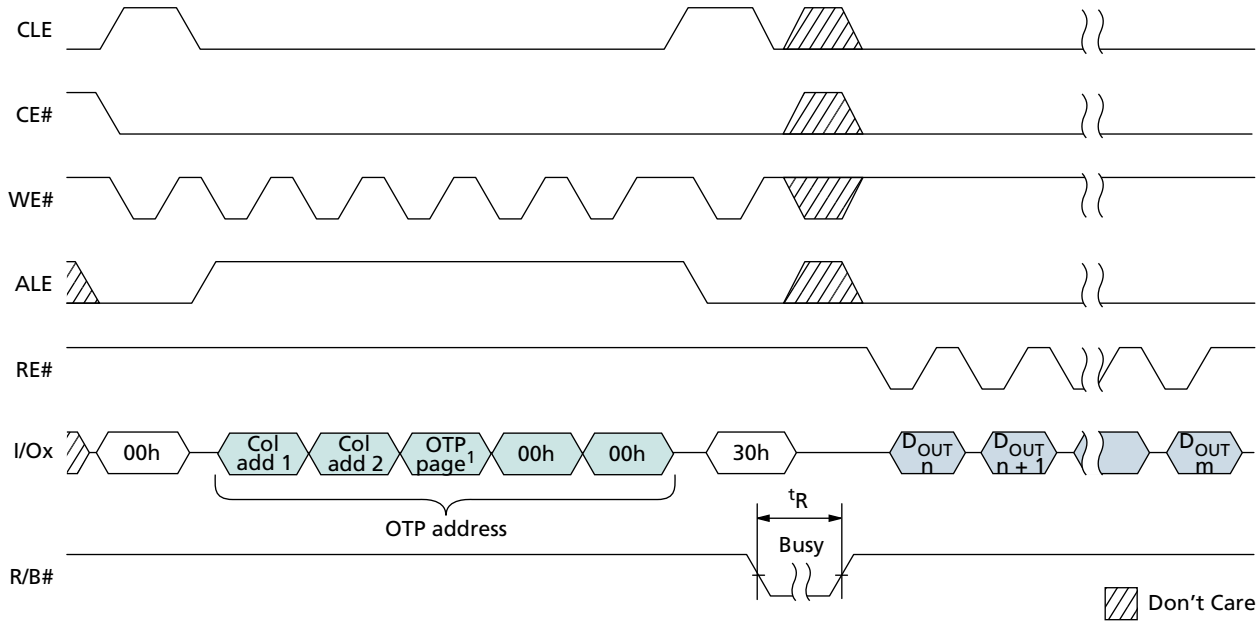
R/B# goes LOW (^{t}R) while the data is moved from the OTP page to the data register. The READ STATUS (70h) command is the only valid command for reading status in OTP operation mode. Bit 5 of the status register reflects the state of R/B# (see Status Operations).

Normal READ operation timings apply to OTP read accesses. Additional pages within the OTP area can be selected by repeating the OTP DATA READ command.

The PAGE READ command is compatible with the RANDOM DATA OUTPUT (05h-E0h) command.

Only data on the current page can be read. Pulsing RE# outputs data sequentially.

Figure 66: OTP DATA READ



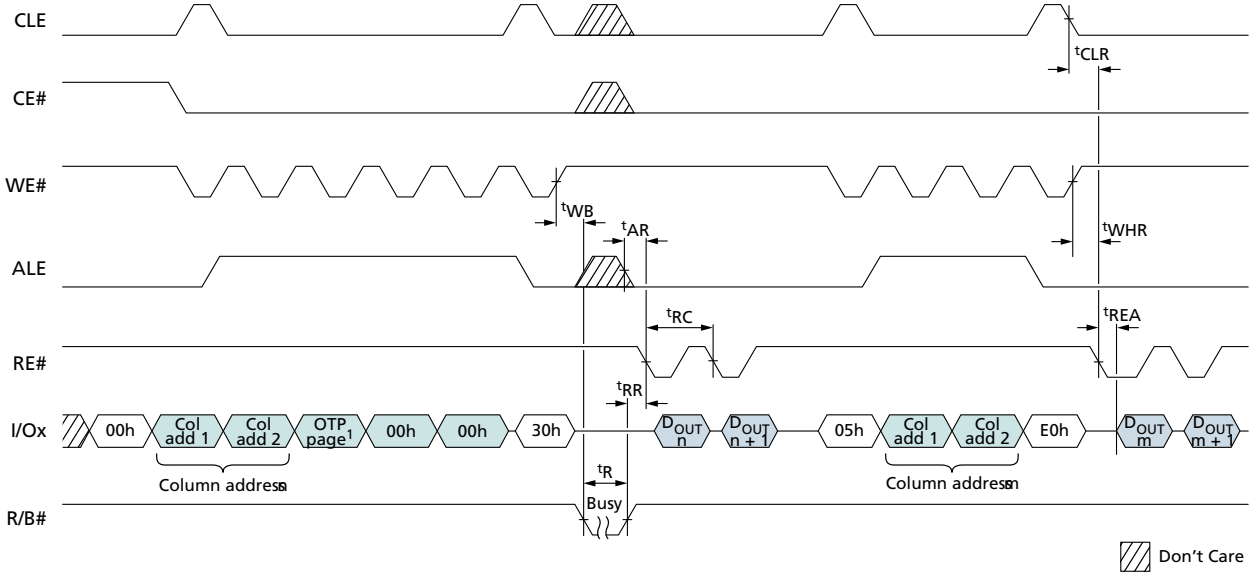
Note: 1. The OTP page must be within the 02h–1Fh range.

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Figure 67: OTP DATA READ with RANDOM DATA READ Operation



Note: 1. The OTP page must be within the range 02h–1Fh.

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Two-Plane Operations

Each NAND Flash logical unit (LUN) is divided into multiple physical planes. Each plane contains a cache register and a data register independent of the other planes. The planes are addressed via the low-order block address bits. Specific details are provided in Device and Array Organization.

Two-plane operations make better use of the NAND Flash arrays on these physical planes by performing concurrent READ, PROGRAM, or ERASE operations on multiple planes, significantly improving system performance. Two-plane operations must be of the same type across the planes; for example, it is not possible to perform a PROGRAM operation on one plane with an ERASE operation on another.

When issuing two-plane program or erase operations, use the READ STATUS (70h) command and check whether the previous operation(s) failed. If the READ STATUS (70h) command indicates that an error occurred (FAIL = 1 and/or FAILC = 1), use the READ STATUS ENHANCED (78h) command to determine which plane operation failed.

Two-Plane Addressing

Two-plane commands require multiple, five-cycle addresses, one address per operational plane. For a given two-plane operation, these addresses are subject to the following requirements:

- The LUN address bit(s) must be identical for all of the issued addresses.
- The plane select bit, BA[6], must be different for each issued address.
- The page address bits, PA[5:0], must be identical for each issued address.

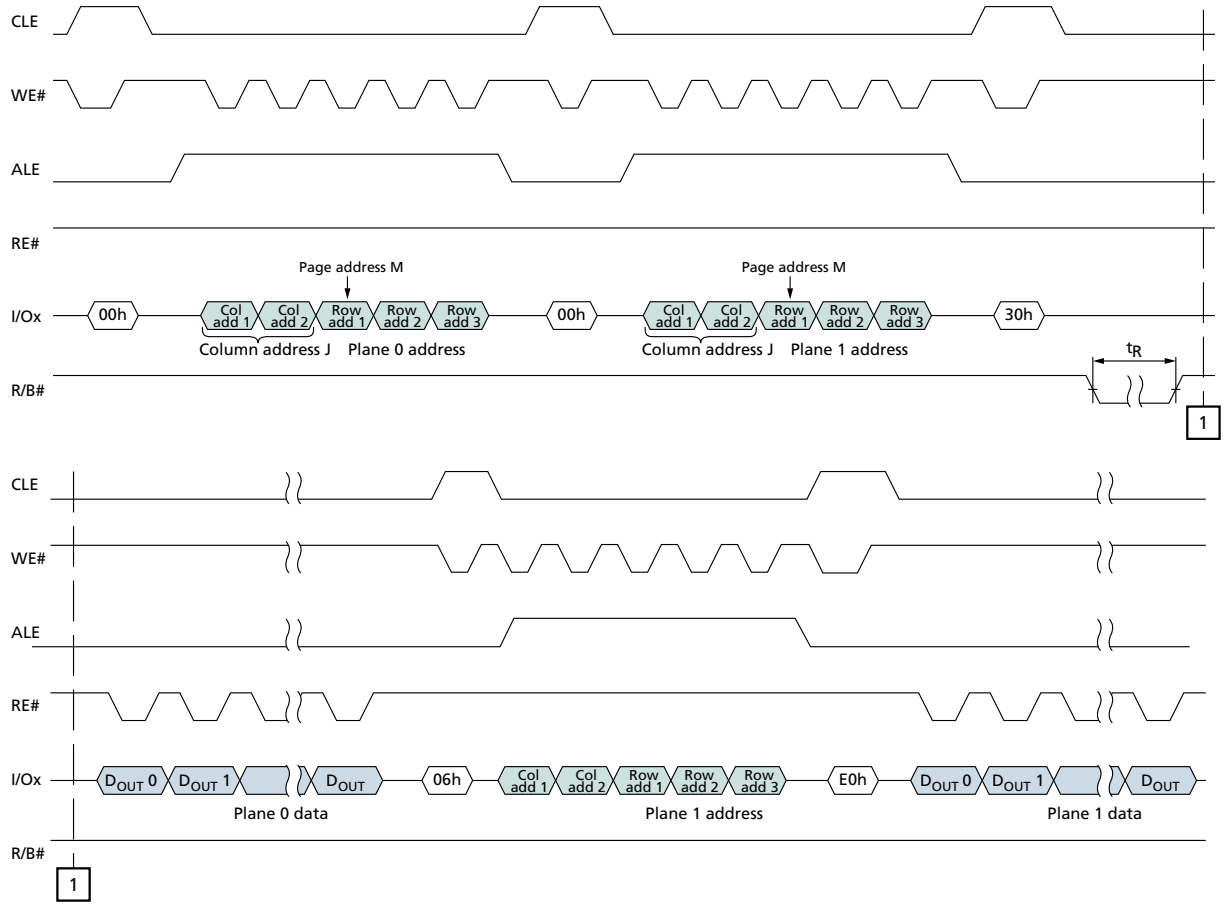
The READ STATUS (70h) command should be used following two-plane program page and erase block operations on a single die (LUN).

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Figure 68: TWO-PLANE PAGE READ



Notes: 1. Column and page addresses must be the same.
2. The least significant block address bit, BA6, must be different for the first- and second-plane addresses.

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Figure 69: TWO-PLANE PAGE READ with RANDOM DATA READ

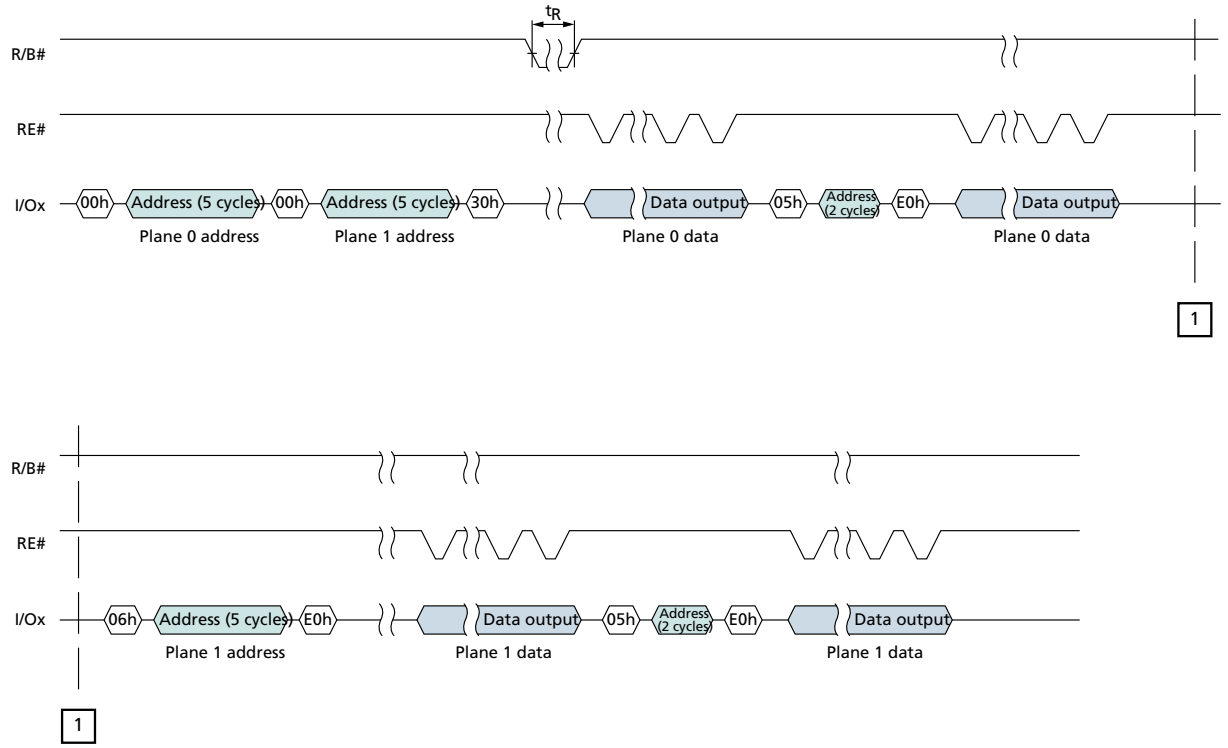
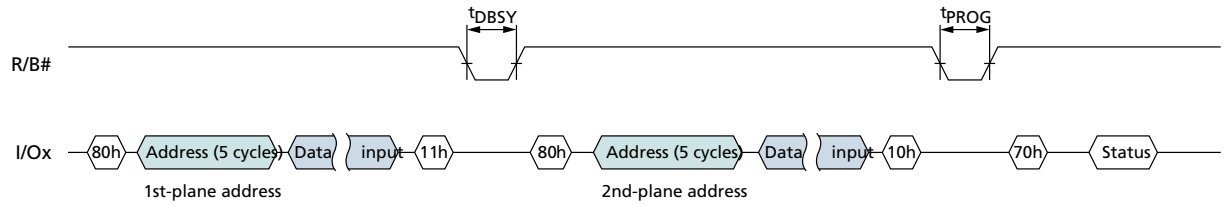


Figure 70: TWO-PLANE PROGRAM PAGE

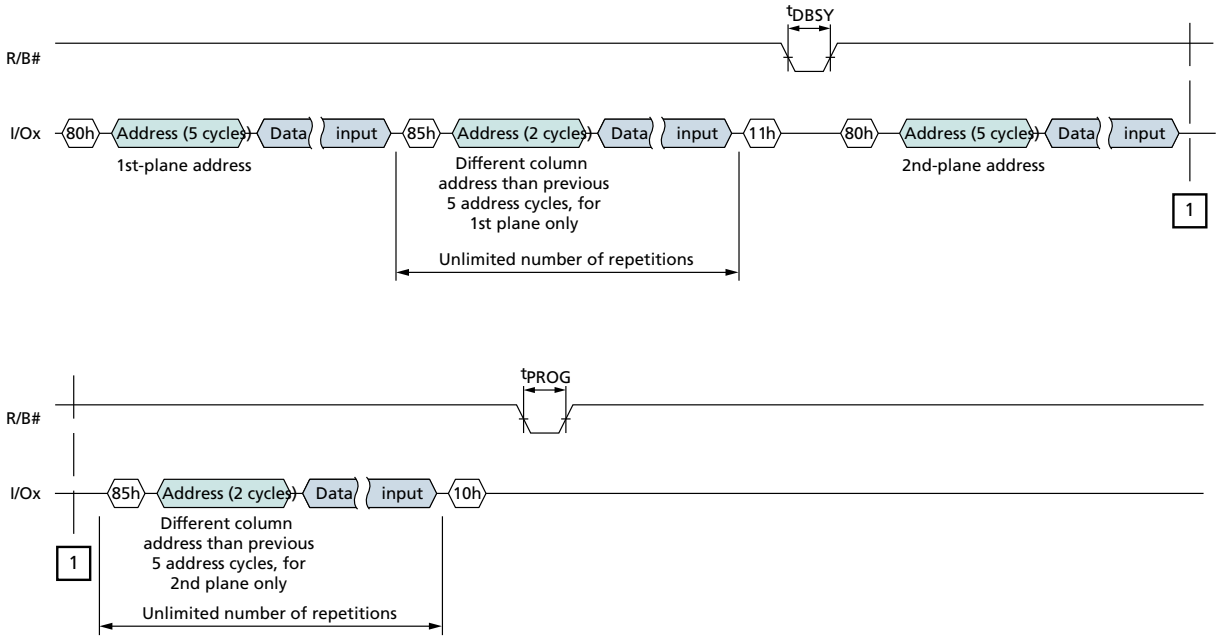


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Figure 71: TWO-PLANE PROGRAM PAGE with RANDOM DATA INPUT

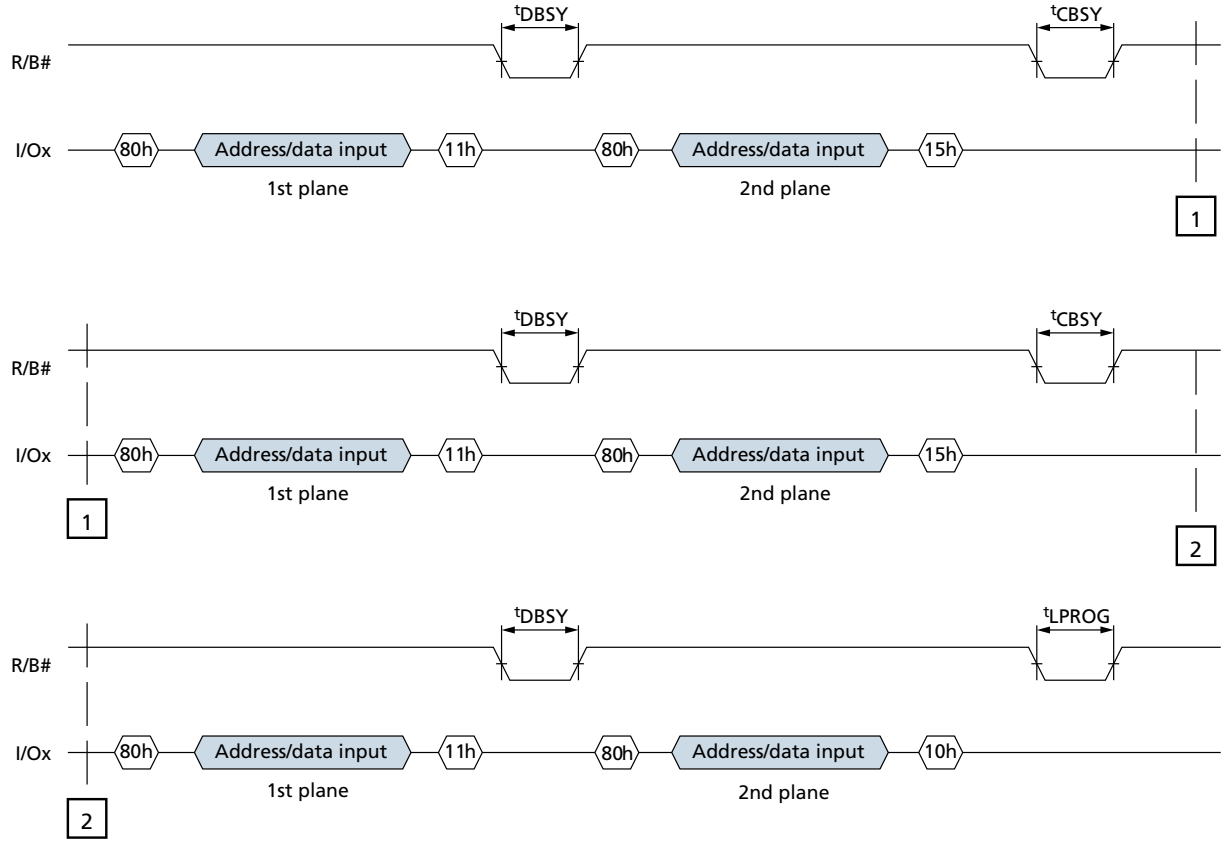


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Figure 72: TWO-PLANE PROGRAM PAGE CACHE MODE

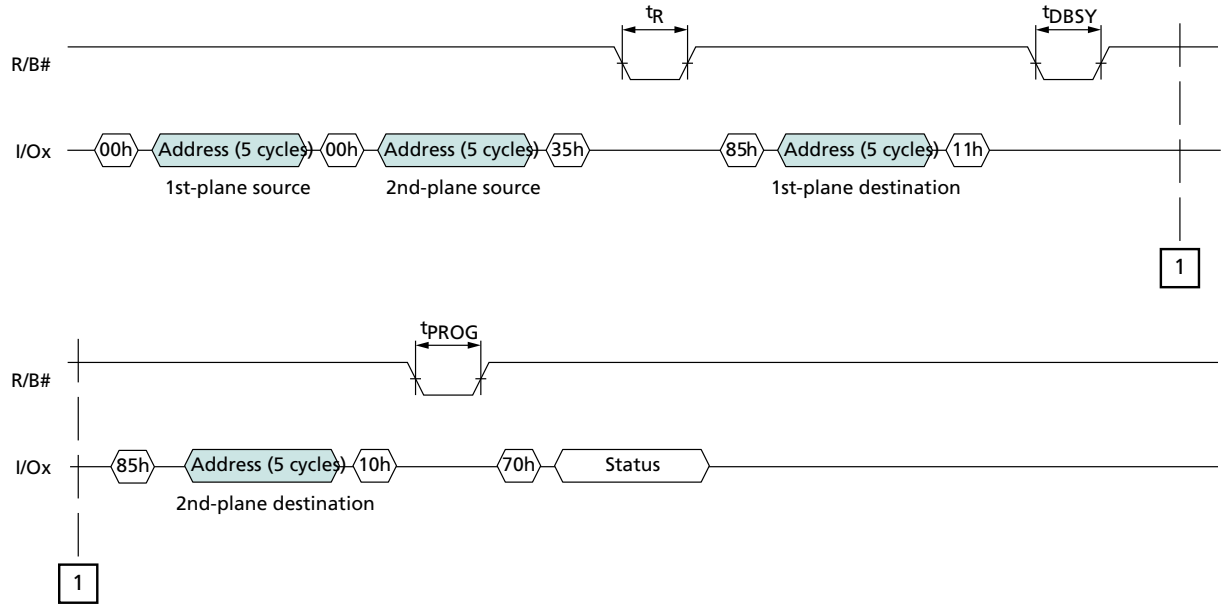


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Figure 73: TWO-PLANE INTERNAL DATA MOVE

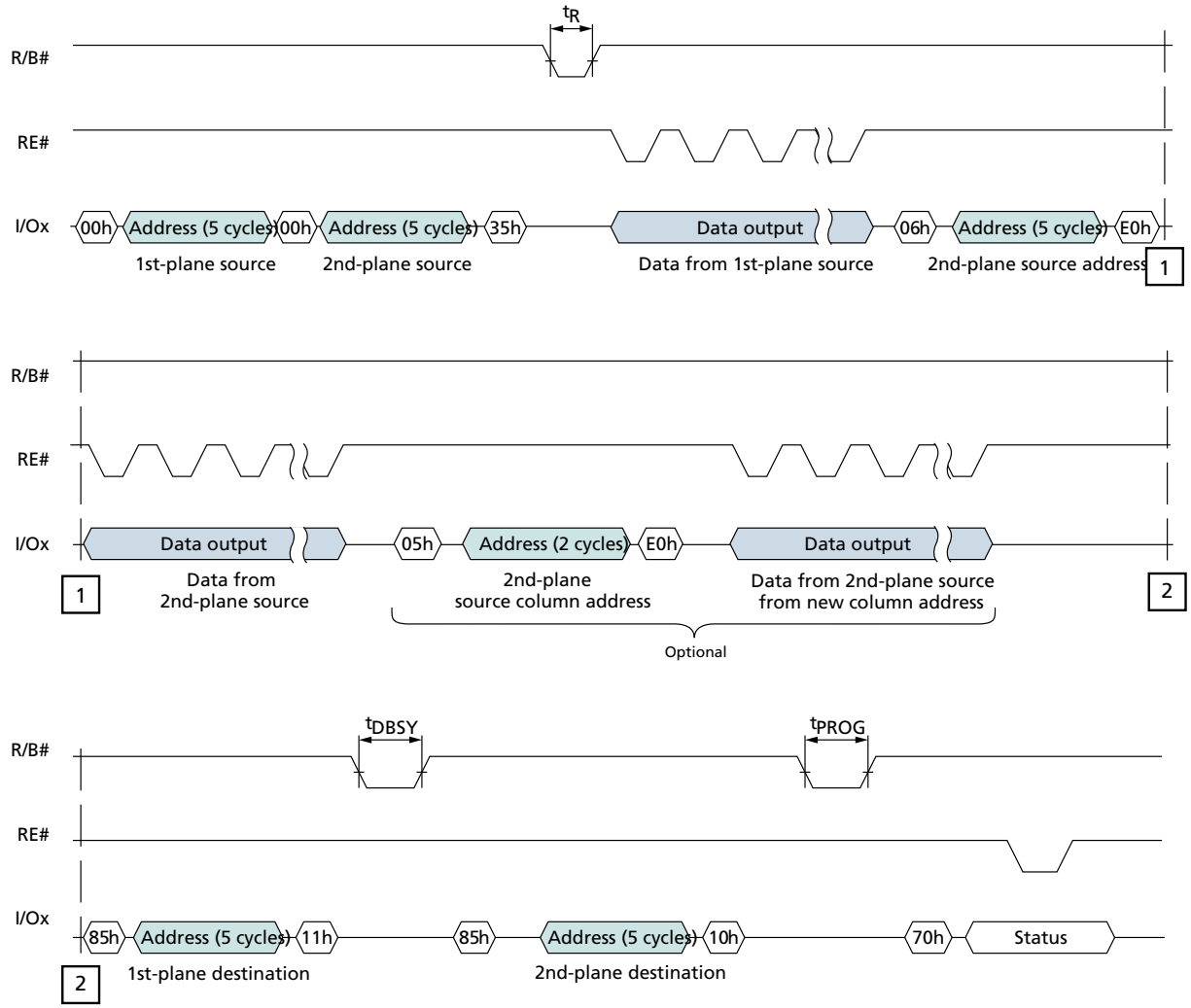


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Figure 74: TWO-PLANE INTERNAL DATA MOVE with TWO-PLANE RANDOM DATA READ

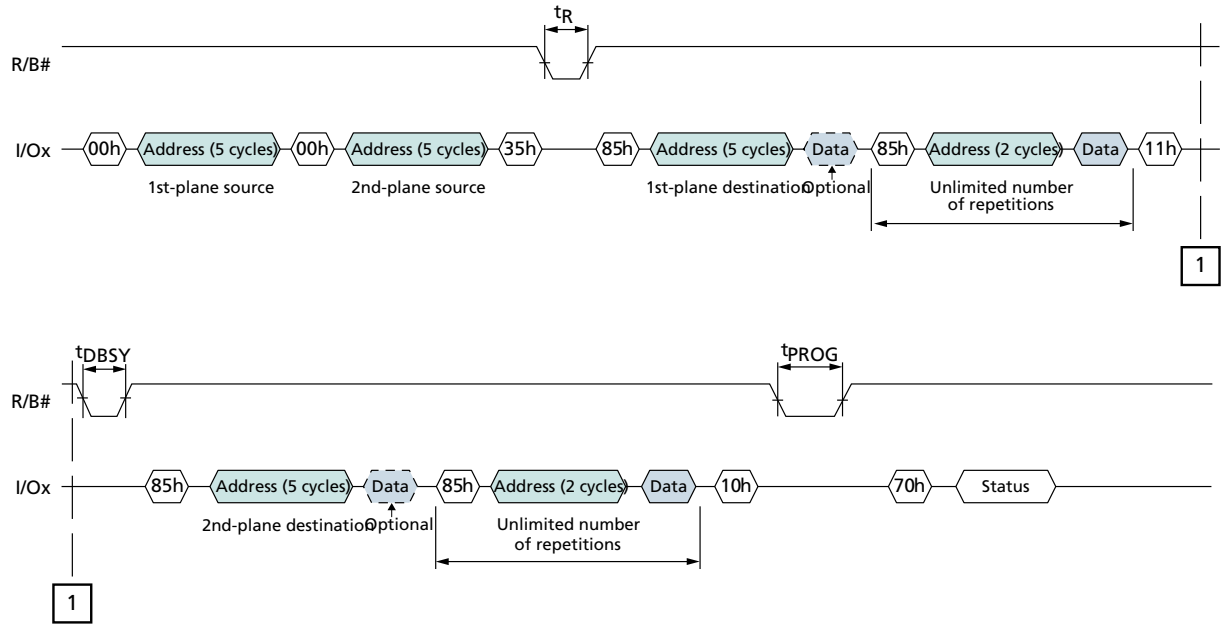


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Figure 75: TWO-PLANE INTERNAL DATA MOVE with RANDOM DATA INPUT



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Figure 76: TWO-PLANE BLOCK ERASE

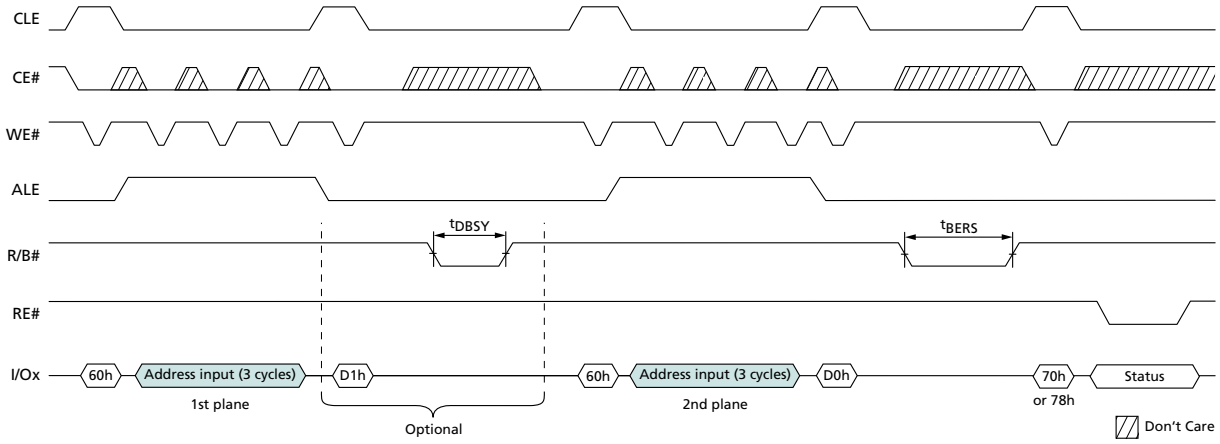
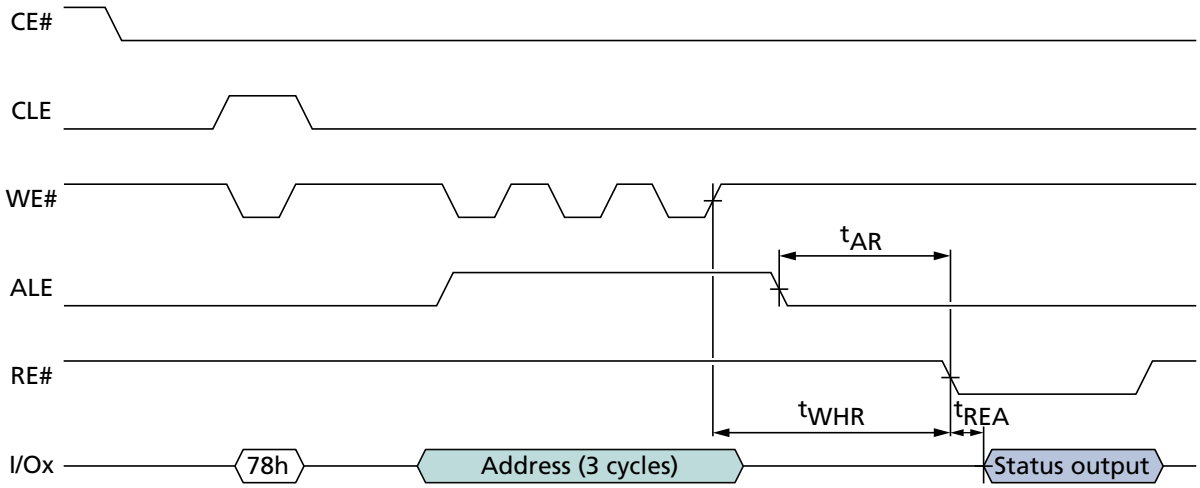


Figure 77: TWO-PLANE/MULTIPLE-DIE READ STATUS Cycle



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Interleaved Die (Multi-LUN) Operations

In devices that have more than one die (LUN) per target, it is possible to improve performance by interleaving operations between the die (LUNs). An interleaved die (multi-LUN) operation is one that is issued to an idle die (LUN) (RDY = 1) while another die (LUN) is busy (RDY = 0).

Interleaved die (multi-LUN) operations are prohibited following RESET (FFh), identification (90h, ECh, EDh), and configuration (EEh, EFh) operations until ARDY =1 for all of the die (LUNs) on the target.

During an interleaved die (multi-LUN) operation, there are two methods to determine operation completion. The R/B# signal indicates when all of the die (LUNs) have finished their operations. R/B# remains LOW while any die (LUN) is busy. When R/B# goes HIGH, all of the die (LUNs) are idle and the operations are complete. Alternatively, the READ STATUS ENHANCED (78h) command can report the status of each die (LUN) individually.

If a die (LUN) is performing a cache operation, like PROGRAM PAGE CACHE (80h-15h), then the die (LUN) is able to accept the data for another cache operation when status register bit 6 is 1. All operations, including cache operations, are complete on a die when status register bit 5 is 1.

During and following interleaved die (multi-LUN) operations, the READ STATUS (70h) command is prohibited. Instead, use the READ STATUS ENHANCED (78h) command to monitor status. This command selects which die (LUN) will report status. When two-plane commands are used with interleaved die (multi-LUN) operations, the two-plane commands must also meet the requirements in Two-Plane Operations.

See Command Definitions for the list of commands that can be issued while other die (LUNs) are busy.

During an interleaved die (multi-LUN) operation that involves a PROGRAM series (80h-10h, 80h-15h) operation and a READ operation, the PROGRAM series operation must be issued before the READ series operation. The data from the READ series operation must be output to the host before the next PROGRAM series operation is issued. This is because the 80h command clears the cache register contents of all cache registers on all planes.

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Error Management

Each NAND Flash die (LUN) is specified to have a minimum number of valid blocks (NVB) of the total available blocks. This means the die (LUNs) could have blocks that are invalid when shipped from the factory. An invalid block is one that contains at least one page that has more bad bits than can be corrected by the minimum required ECC. Additional blocks can develop with use. However, the total number of available blocks per die (LUN) will not fall below NVB during the endurance life of the product.

Although NAND Flash memory devices could contain bad blocks, they can be used quite reliably in systems that provide bad block management and error-correction algorithms. This type of software environment ensures data integrity.

Internal circuitry isolates each block from other blocks, so the presence of a bad block does not affect the operation of the rest of the NAND Flash array.

NAND Flash devices are shipped from the factory erased. The factory identifies invalid blocks before shipping by attempting to program the bad block mark into every location in the first page of each invalid block. It may not be possible to program every location with the bad block mark. However, the first spare area location in each bad block is guaranteed to contain the bad block mark. This method is compliant with ONFI Factory Defect Mapping requirements. See the following table for the first spare area location and the bad block mark.

System software should check the first spare area location on the first page of each block prior to performing any PROGRAM or ERASE operations on the NAND Flash device. A bad block table can then be created, enabling system software to map around these areas. Factory testing is performed under worst-case conditions. Because invalid blocks could be marginal, it may not be possible to recover this information if the block is erased.

Over time, some memory locations may fail to program or erase properly. In order to ensure that data is stored properly over the life of the NAND Flash device, the following precautions are required:

- Always check status after a PROGRAM or ERASE operation
- Under typical conditions, use the minimum required ECC (see table below)
- Use bad block management and wear-leveling algorithms

  The first block (physical block address 00h) for each CE# is guaranteed to be valid with ECC when shipped from the factory.

Table 18: Error Management Details

Description	Requirement
Minimum number of valid blocks (NVB) per LUN	2008
Total available blocks per LUN	2048
First spare area location	x8: byte 2048 x16: word 1024
Bad-block mark	x8: 00h x16: 0000h
Minimum required ECC	4-bit ECC per 528 bytes

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Table 18: Error Management Details (Continued)

Description	Requirement
Minimum ECC with internal ECC enabled	4-bit ECC per 516 bytes (user data) + 8 bytes (parity data)
Minimum required ECC for block 0 if PROGRAM/ ERASE cycles are less than 1000	1-bit ECC per 528 bytes

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Internal ECC and Spare Area Mapping for ECC

Internal ECC enables 5-bit detection and 4-bit error correction in 512 bytes (x8) or 256 words (x16) of the main area and 4 bytes (x8) or 2 words (x16) of metadata I in the spare area. The metadata II area, which consists of two bytes (x8) and one word (x16), is not ECC protected. During the busy time for PROGRAM operations, internal ECC generates parity bits when error detection is complete.

During READ operations the device executes the internal ECC engine (5-bit detection and 4-bit error correction). When the READ operaton is complete, read status bit 0 must be checked to determine whether errors larger than four bits have occurred.

Following the READ STATUS command, the device must be returned to read mode by issuing the 00h command.

Limitations of internal ECC include the spare area, defined in the figures below, and ECC parity areas that cannot be written to. Each ECC user area (referred to as main and spare) must be written within one partial-page program so that the NAND device can calculate the proper ECC parity. The number of partial-page programs within a page cannot exceed four.

Figure 78: Spare Area Mapping (x8)

Max Byte Address	Min Byte Address	ECC Protected	Area	Description
1FFh	000h	Yes	Main 0	User data
3FFh	200h	Yes	Main 1	User data
5FFh	400h	Yes	Main 2	User data
7FFh	600h	Yes	Main 3	User data
801h	800h	No		Reserved
803h	802h	No		User metadata II
807h	804h	Yes	Spare 0	User metadata I
80Fh	808h	Yes	Spare 0	ECC for main/spare 0
811h	810h	No		Reserved
813h	812h	No		User metadata II
817h	814h	Yes	Spare 1	User metadata I
81Fh	818h	Yes	Spare 1	ECC for main/spare 1
821h	820h	No		Reserved
823h	822h	No		User metadata II
827h	824h	Yes	Spare 2	User metadata I
82Fh	828h	Yes	Spare 2	ECC for main/spare 2
831h	830h	No		User data
833h	832h	No		User metadata II
837h	834h	Yes	Spare 3	User metadata I
83Fh	838h	Yes	Spare 3	ECC for main/spare 3

Bad Block Information	ECC Parity	User Data (Metadata)
2 bytes	8 bytes	6 bytes

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Figure 79: Spare Area Mapping (x16)

Max word Address	Min word Address	ECC Protected	Area	Description
0FFh	000h	Yes	Main 0	User data
1FFh	100h	Yes	Main 1	User data
2FFh	200h	Yes	Main 2	User data
3FFh	300h	Yes	Main 3	User data
400h	400h	No		Reserved
401h	401h	No		User metadata II
403h	402h	Yes	Spare 0	User metadata I
407h	404h	Yes	Spare 0	ECC for main/spare 0
408h	408h	No		Reserved
409h	409h	No		User metadata II
40Bh	40Ah	Yes	Spare 1	User metadata I
40Fh	40Ch	Yes	Spare 1	ECC for main/spare 1
410h	410h	No		Reserved
411h	411h	No		User metadata II
413h	412h	Yes	Spare 2	User metadata I
417h	414h	Yes	Spare 2	ECC for main/spare 2
418h	418h	No		User data
419h	419h	No		User metadata II
41Bh	41Ah	Yes	Spare 3	User metadata I
41Fh	41Ch	Yes	Spare 3	ECC for main/spare 3

Bad Block Information	ECC Parity	User Data (Metadata)
1 word	4 words	3 words

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Electrical Specifications

Stresses greater than those listed can cause permanent damage to the device. This is stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not guaranteed. Exposure to absolute maximum rating conditions for extended periods can affect reliability.

Table 19: Absolute Maximum Ratings

Voltage on any pin relative to V_{SS}

Parameter/Condition		Symbol	Min	Max	Unit
Voltage input	1.8V	V_{IN}	–0.6	2.4	V
	3.3V		–0.6	4.6	V
Vcc supply voltage	1.8V	V_{CC}	–0.6	2.4	V
	3.3V		–0.6	4.6	V
Storage temperature		T_{STG}	–65	150	°C
Short circuit output current, I/Os		–	–	5	mA

Table 20: Recommended Operating Conditions

Parameter/Condition		Symbol	Min	Typ	Max	Unit
Operating temperature	AIT	T_A	–40	–	85	°C
	AAT		–40	–	105	°C
Vcc supply voltage	1.8V	V_{CC}	1.7	1.8	1.95	V
	3.3V		2.7	3.3	3.6	V
Ground supply voltage		V_{SS}	0	0	0	V

Table 21: Valid Blocks

Parameter	Symbol	Device	Min	Max	Unit	Notes
Valid block number	NVB	MT29F2G	2008	2048	Blocks	1, 2

Notes:
1. Invalid blocks are blocks that contain one or more bad bits. The device may contain bad blocks upon shipment. Additional bad blocks may develop over time; however, the total number of available blocks will not drop below NVB during the endurance life of the device. Do not erase or program blocks marked invalid by the factory.
2. Block 00h (the first block) is guaranteed to be valid with ECC when shipped from the factory.

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Table 22: Capacitance

Notes 1–2 apply to all parameters and conditions

Description	Symbol	Max	Unit
Input capacitance	C_{IN}	10	pF
Input/output capacitance (I/O)	C_{IO}	10	pF

Notes:
1. These parameters are verified in device characterization and are not 100% tested.
2. Test conditions: T_C = 25°C; f = 1 MHz; Vin = 0V.

Table 23: Test Conditions

Parameter		Value	Notes
Input pulse levels		0.0V to V_{CC}	
Input rise and fall times	1.8V	2.5ns	
	3.3V	5.0ns	
Input and output timing levels		$V_{CC}/2$	
Output load		1 TTL GATE and CL = 30pF (1.8V)	1
		1 TTL GATE and CL = 50pF (3.3V)	
Output load		1 TTL GATE and CL = 30pF (1.8V)	1
		1 TTL GATE and CL = 50pF (3.3V)	

Note:
1. Verified in device characterization, not 100% tested.

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Electrical Specifications – DC Characteristics and Operating Conditions

Table 24: DC Characteristics and Operating Conditions (3.3V)

Parameter	Conditions	Symbol	Min	Typ	Max	Unit	Notes
Sequential READ current	$^{t}RC = {}^{t}RC$ (MIN); CE# = V_{IL}; I_{OUT} = 0mA	I_{CC1}	–	25	35	mA	
PROGRAM current	–	I_{CC2}	–	25	35	mA	
ERASE current	–	I_{CC3}	–	25	35	mA	
Standby current (TTL)	CE# = V_{IH}; WP# = 0V/V_{CC}	I_{SB1}	–	–	1	mA	
Standby current (CMOS)	CE# = V_{CC} - 0.2V; WP# = 0V/V_{CC}	I_{SB2}	–	20	100	µA	
Staggered power-up current	Rise time = 1ms Line capacitance = 0.1µF	I_{ST}	–	–	10 per die	mA	1
Input leakage current	V_{IN} = 0V to V_{CC}	I_{LI}	–	–	±10	µA	
Output leakage current	V_{OUT} = 0V to V_{CC}	I_{LO}	–	–	±10	µA	
Input high voltage	I/O[7:0], I/O[15:0], CE#, CLE, ALE, WE#, RE#, WP#	V_{IH}	0.8 x V_{CC}	–	V_{CC} + 0.3	V	
Input low voltage, all inputs	–	V_{IL}	–0.3	–	0.2 x V_{CC}	V	
Output high voltage	I_{OH} = –400µA	V_{OH}	0.67 x V_{CC}	–	–	V	2
Output low voltage	I_{OL} = 2.1mA	V_{OL}	–	–	0.4	V	2
Output low current	V_{OL} = 0.4V	I_{OL} (R/B#)	8	10	–	mA	3

Notes:
1. Measurement is taken with 1ms averaging intervals and begins after V_{CC} reaches V_{CC}(MIN).
2. V_{OH} and V_{OL} may need to be relaxed if I/O drive strength is not set to full.
3. I_{OL} (R/B#) may need to be relaxed if R/B pull-down strength is not set to full.

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Table 25: DC Characteristics and Operating Conditions (1.8V)

Parameter	Conditions	Symbol	Min	Typ	Max	Unit	Notes
Sequential READ current	$^{t}RC = {}^{t}RC$ (MIN); CE# = V_{IL}; I_{OUT} = 0mA	I_{CC1}	–	13	20	mA	1, 2
PROGRAM current	–	I_{CC2}	–	10	20	mA	1, 2
ERASE current	–	I_{CC3}	–	10	20	mA	1, 2
Standby current (TTL)	CE# = V_{IH}; WP# = 0V/V_{CC}	I_{SB1}	–	–	1	mA	
Standby current (CMOS)	CE# = V_{CC} - 0.2V; WP# = 0V/V_{CC}	I_{SB2}	–	10	50	µA	
Staggered power-up current	Rise time = 1ms Line capacitance = 0.1µF	I_{ST}	–	–	10 per die	mA	3
Input leakage current	V_{IN} = 0V to V_{CC}	I_{LI}	–	–	±10	µA	
Output leakage current	V_{OUT} = 0V to V_{CC}	I_{LO}	–	–	±10	µA	
Input high voltage	I/O[7:0], I/O[15:0], CE#, CLE, ALE, WE#, RE#, WP#	V_{IH}	0.8 x V_{CC}	–	V_{CC} + 0.3	V	
Input low voltage, all inputs	–	V_{IL}	–0.3	–	0.2 x V_{CC}	V	
Output high voltage	I_{OH} = –100µA	V_{OH}	V_{CC} - 0.1	–	–	V	4
Output low voltage	I_{OL} = +100µA	V_{OL}	–	–	0.1	V	4
Output low current (R/B#)	V_{OL} = 0.2V	I_{OL} (R/B#)	3	4	–	mA	5

Notes:
1. Typical and maximum values are for single-plane operation only. If device supports dual-plane operation, values are 20mA (TYP) and 40mA (MAX).
2. Values are for single-die operations. Values could be higher for interleaved-die operations.
3. Measurement is taken with 1ms averaging intervals and begins after V_{CC} reaches V_{CC}(MIN).
4. Test conditions for V_{OH} and V_{OL}.
5. DC characteristics may need to be relaxed if R/B# pull-down strength is not set to full.

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Electrical Specifications – AC Characteristics and Operating Conditions

Table 26: AC Characteristics: Command, Data, and Address Input (3.3V)

Note 1 applies to all

Parameter	Symbol	Min	Max	Unit	Notes
ALE to data start	tADL	70	–	ns	2
ALE hold time	tALH	5	–	ns	
ALE setup time	tALS	10	–	ns	
CE# hold time	tCH	5	–	ns	
CLE hold time	tCLH	5	–	ns	
CLE setup time	tCLS	10	–	ns	
CE# setup time	tCS	15	–	ns	
Data hold time	tDH	5	–	ns	
Data setup time	tDS	7	–	ns	
WRITE cycle time	tWC	20	–	ns	2
WE# pulse width HIGH	tWH	7	–	ns	2
WE# pulse width	tWP	10	–	ns	2
WP# transition to WE# LOW	tWW	100	–	ns	

Notes:
1. Operating mode timings meet ONFI timing mode 5 parameters.
2. Timing for tADL begins in the address cycle, on the final rising edge of WE#, and ends with the first rising edge of WE# for data input.

Table 27: AC Characteristics: Command, Data, and Address Input (1.8V)

Note 1 applies to all

Parameter	Symbol	Min	Max	Unit	Notes
ALE to data start	tADL	70	–	ns	2
ALE hold time	tALH	5	–	ns	
ALE setup time	tALS	10	–	ns	
CE# hold time	tCH	5	–	ns	
CLE hold time	tCLH	5	–	ns	
CLE setup time	tCLS	10	–	ns	
CE# setup time	tCS	20	–	ns	
Data hold time	tDH	5	–	ns	
Data setup time	tDS	10	–	ns	
WRITE cycle time	tWC	25	–	ns	2
WE# pulse width HIGH	tWH	10	–	ns	2
WE# pulse width	tWP	12	–	ns	2
WP# transition to WE# LOW	tWW	100	–	ns	

Notes:
1. Operating mode timings meet ONFI timing mode 4 parameters.
2. Timing for tADL begins in the address cycle on the final rising edge of WE#, and ends with the first rising edge of WE# for data input.

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Table 28: AC Characteristics: Normal Operation (3.3V)

Note 1 applies to all

Parameter	Symbol	Min	Max	Unit	Notes
ALE to RE# delay	tAR	10	–	ns	
CE# access time	tCEA	–	25	ns	
CE# HIGH to output High-Z	tCHZ	–	50	ns	2
CLE to RE# delay	tCLR	10	–	ns	
CE# HIGH to output hold	tCOH	15	–	ns	
Output High-Z to RE# LOW	tIR	0	–	ns	
READ cycle time	tRC	20	–	ns	
RE# access time	tREA	–	16	ns	
RE# HIGH hold time	tREH	7	–	ns	
RE# HIGH to output hold	tRHOH	15	–	ns	
RE# HIGH to WE# LOW	tRHW	100	–	ns	
RE# HIGH to output High-Z	tRHZ	–	100	ns	2
RE# LOW to output hold	tRLOH	5	–	ns	
RE# pulse width	tRP	10	–	ns	
Ready to RE# LOW	tRR	20	–	ns	
Reset time (READ/PROGRAM/ERASE)	tRST	–	5/10/500	µs	3
WE# HIGH to busy	tWB	–	100	ns	
WE# HIGH to RE# LOW	tWHR	60	–	ns	

Notes:
1. AC characteristics may need to be relaxed if I/O drive strength is not set to full.
2. Transition is measured ±200mV from steady-state voltage with load. This parameter is sampled and not 100% tested.
3. The first time the RESET (FFh) command is issued while the device is idle, the device will go busy for a maximum of 1ms. Thereafter, the device goes busy for a maximum of 5µs.

Table 29: AC Characteristics: Normal Operation (1.8V)

Note 1 applies to all

Parameter	Symbol	Min	Max	Unit	Notes
ALE to RE# delay	tAR	10	–	ns	
CE# access time	tCEA	–	25	ns	
CE# HIGH to output High-Z	tCHZ	–	50	ns	2
CLE to RE# delay	tCLR	10	–	ns	
CE# HIGH to output hold	tCOH	15	–	ns	
Output High-Z to RE# LOW	tIR	0	–	ns	
READ cycle time	tRC	25	–	ns	
RE# access time	tREA	–	22	ns	
RE# HIGH hold time	tREH	10	–	ns	
RE# HIGH to output hold	tRHOH	15	–	ns	

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Table 29: AC Characteristics: Normal Operation (1.8V) (Continued)

Note 1 applies to all

Parameter	Symbol	Min	Max	Unit	Notes
RE# HIGH to WE# LOW	^{t}RHW	100	–	ns	
RE# HIGH to output High-Z	^{t}RHZ	–	65	ns	2
RE# LOW to output hold	^{t}RLOH	3	–	ns	
RE# pulse width	^{t}RP	12	–	ns	
Ready to RE# LOW	^{t}RR	20	–	ns	
Reset time (READ/PROGRAM/ERASE)	^{t}RST	–	5/10/500	µs	3
WE# HIGH to busy	^{t}WB	–	100	ns	
WE# HIGH to RE# LOW	^{t}WHR	80	–	ns	

Notes:
1. AC characteristics may need to be relaxed if I/O drive strength is not set to full.
2. Transition is measured ±200mV from steady-state voltage with load. This parameter is sampled and not 100% tested.
3. The first time the RESET (FFh) command is issued while the device is idle, the device will be busy for a maximum of 1ms. Thereafter, the device is busy for a maximum of 5µs.

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Electrical Specifications – Program/Erase Characteristics

Table 30: Program/Erase Characteristics

Parameter	Symbol	Typ	Max	Unit	Notes
Number of partial-page programs	NOP	–	4	cycles	1
BLOCK ERASE operation time	tBERS	0.7	3	ms	
Busy time for PROGRAM CACHE operation	tCBSY	3	600	µs	2
Cache read busy time	tRCBSY	3	25	µs	
Busy time for SET FEATURES and GET FEATURES operations	tFEAT	–	1	µs	
Busy time for OTP DATA PROGRAM operation if OTP is protected	tOBSY	–	30	µs	
Busy time for PROGRAM/ERASE on locked blocks	tLBSY	–	3	µs	
PROGRAM PAGE operation time, internal ECC disabled	tPROG	200	600	µs	8
PROGRAM PAGE operation time, internal ECC enabled	tPROG_ECC	220	600	µs	3, 8
Data transfer from Flash array to data register, internal ECC disabled	tR	–	25	µs	6, 7
Data transfer from Flash array to data register, internal ECC enabled	tR_ECC	45	70	µs	3, 5
Busy time for OTP DATA PROGRAM operation if OTP is protected, internal ECC enabled	tOBSY_ECC	–	50	µs	
Busy time for TWO-PLANE PROGRAM PAGE or TWO-PLANE BLOCK ERASE operation	tDBSY	0.5	1	µs	

Notes:
1. Four total partial-page programs to the same page. If ECC is enabled, then the device is limited to one partial-page program per ECC user area, not exceeding four partial-page programs per page.
2. tCBSY MAX time depends on timing between internal program completion and data-in.
3. Parameters are with internal ECC enabled.
4. Typical is nominal voltage and room temperature.
5. Typical tR_ECC is under typical process corner, nominal voltage, and at room temperature.
6. Data transfer from Flash array to data register with internal ECC disabled.
7. AC characteristics may need to be relaxed if I/O drive strength is not set to full.
8. Typical program time is defined as the time within which more than 50% of the pages are programmed at nominal voltage and room temperature.

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Asynchronous Interface Timing Diagrams

Figure 80: RESET Operation

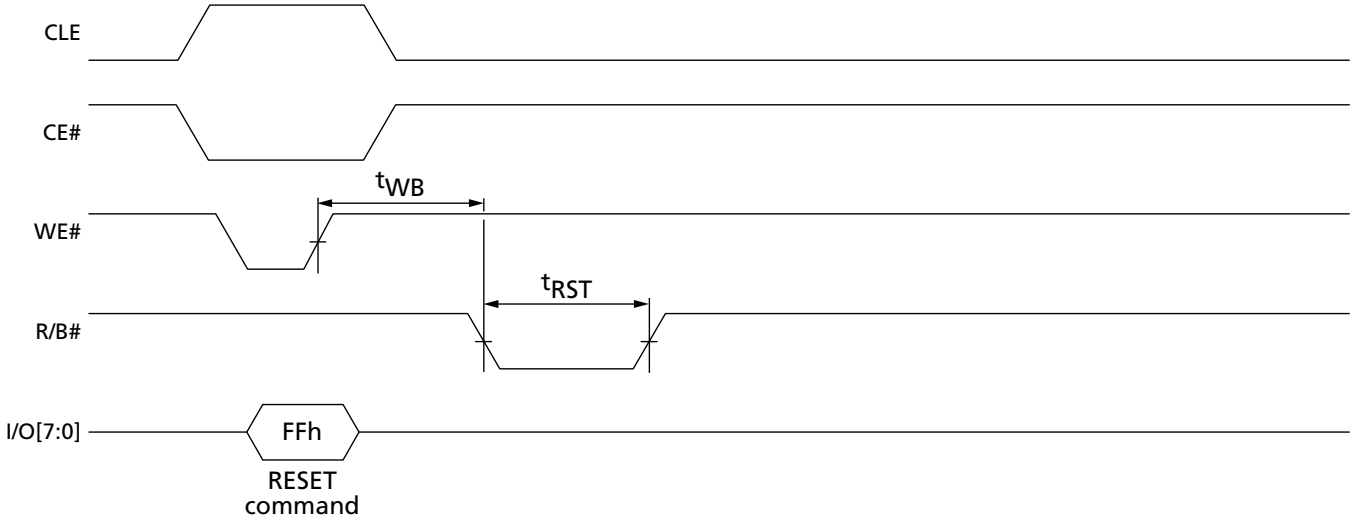
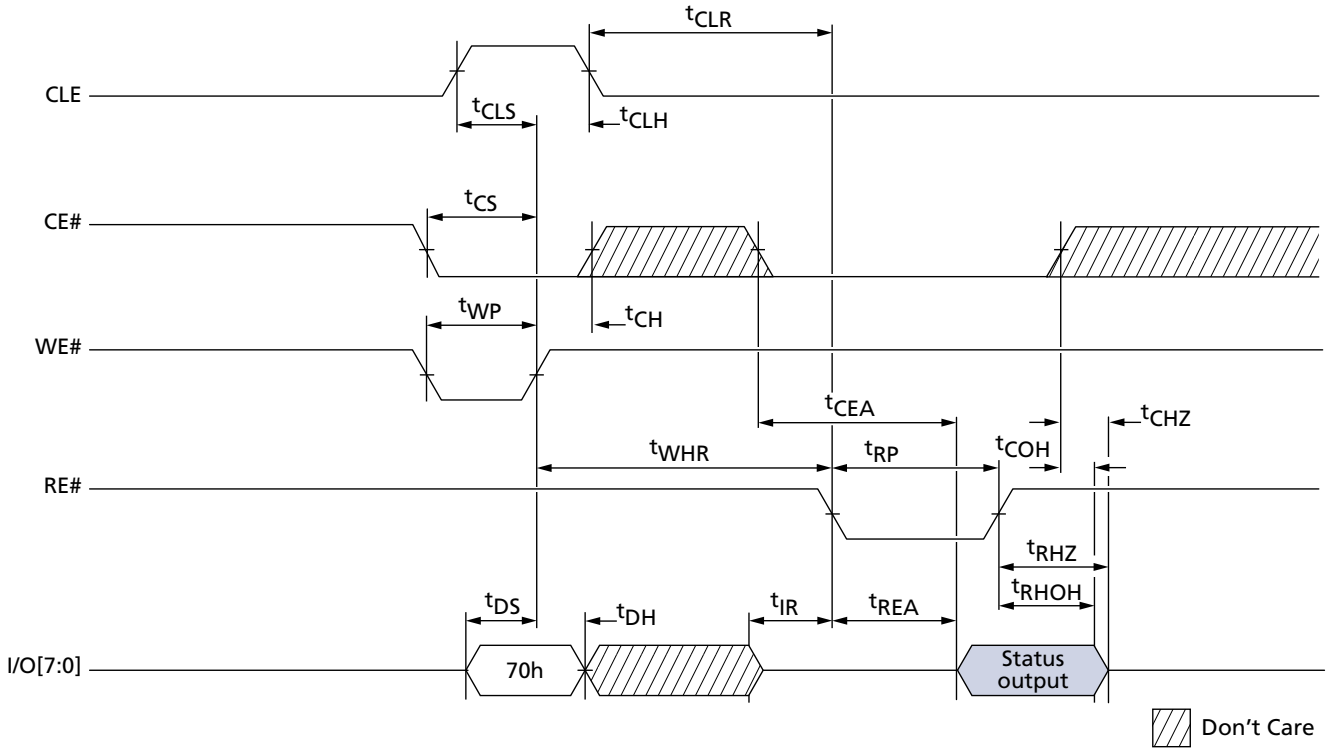


Figure 81: READ STATUS Cycle



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Figure 82: READ STATUS ENHANCED Cycle

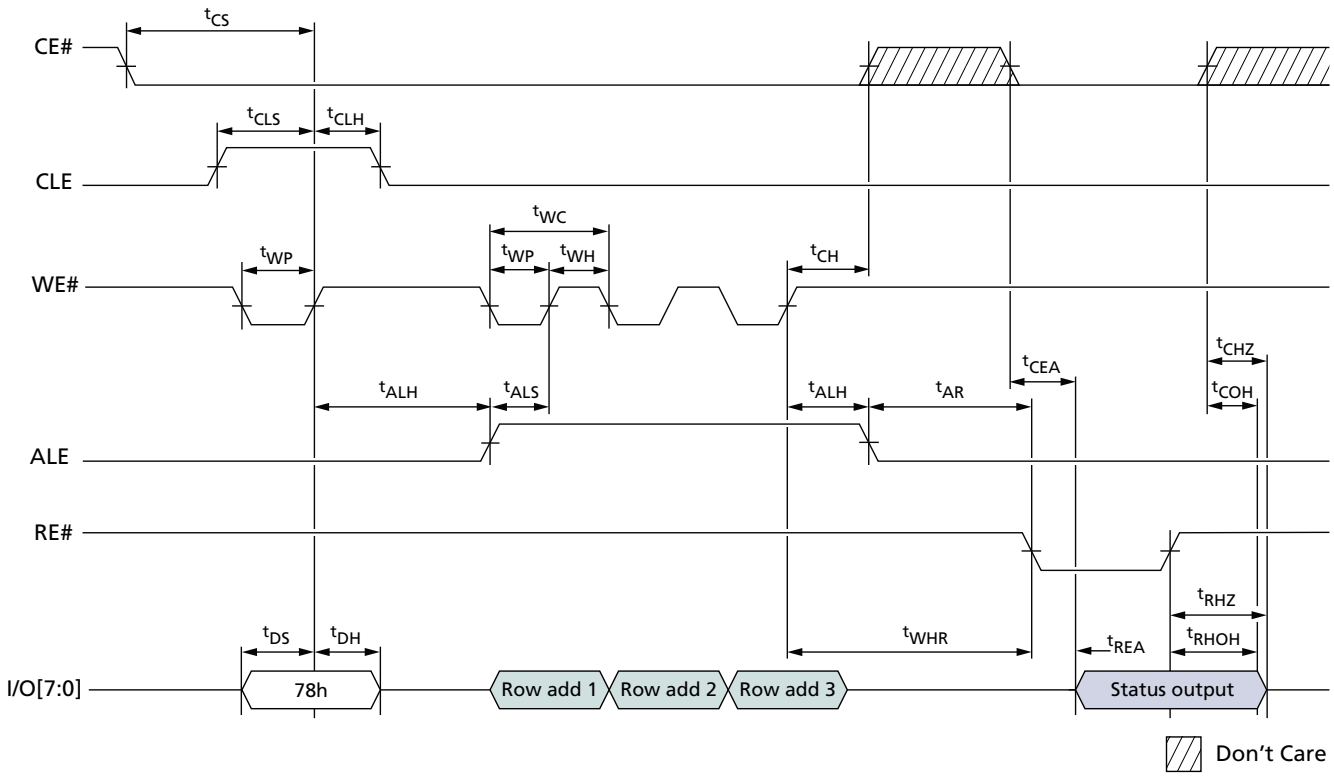
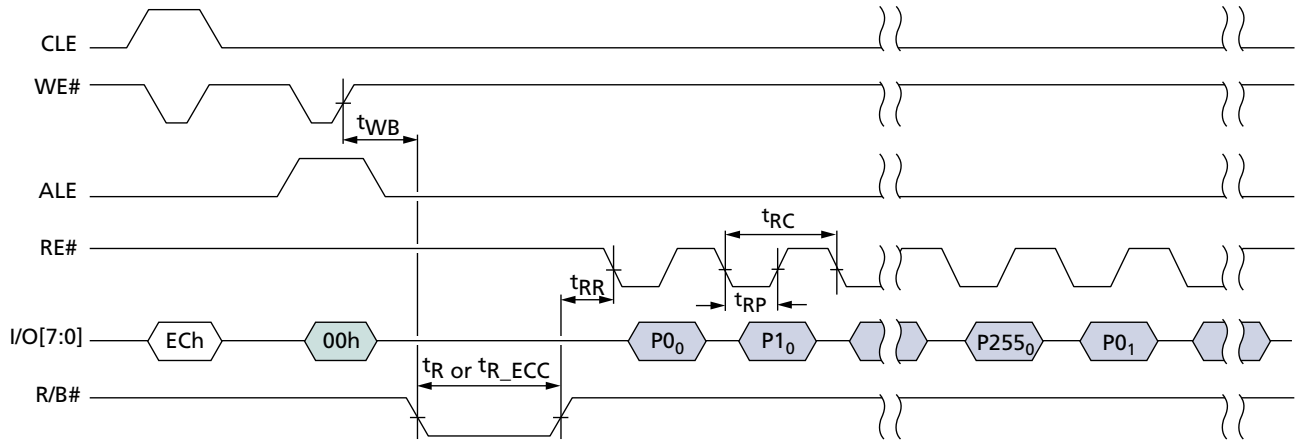


Figure 83: READ PARAMETER PAGE

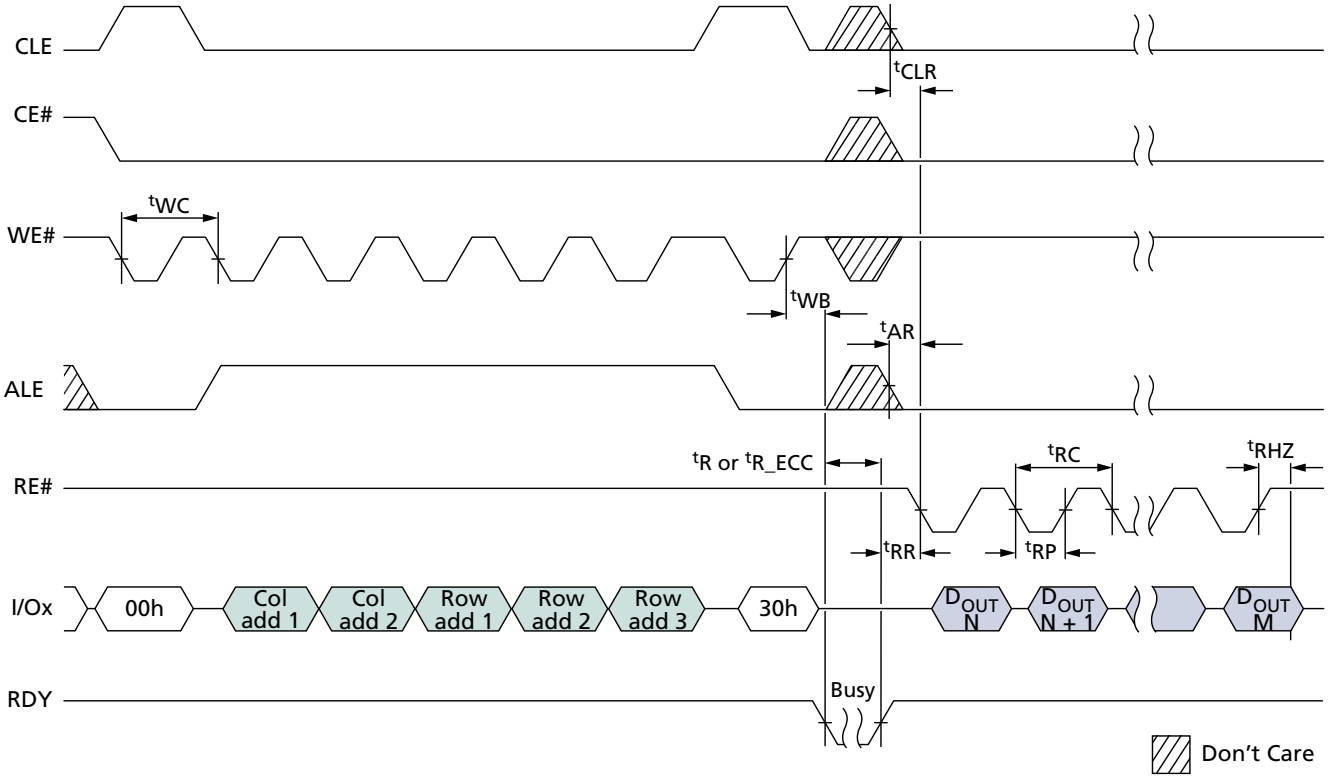


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Figure 84: READ PAGE

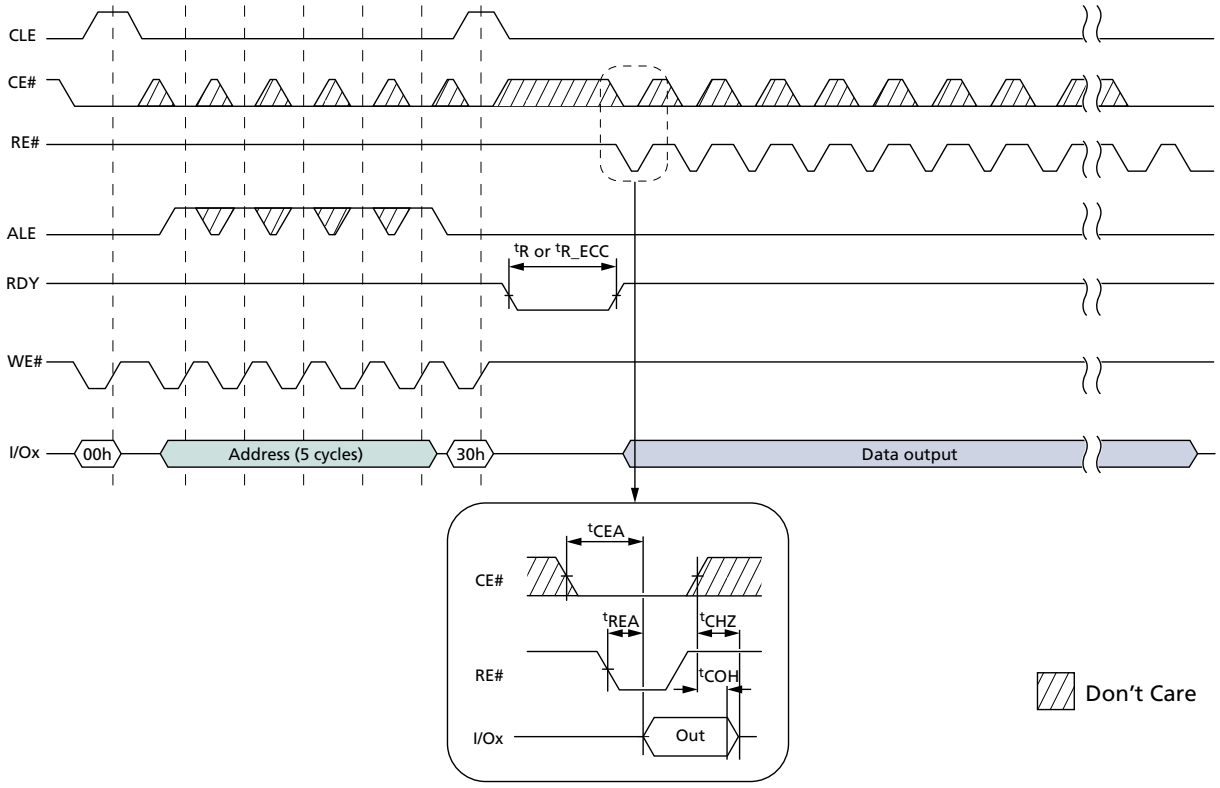


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Figure 85: READ PAGE Operation with CE# "Don't Care"

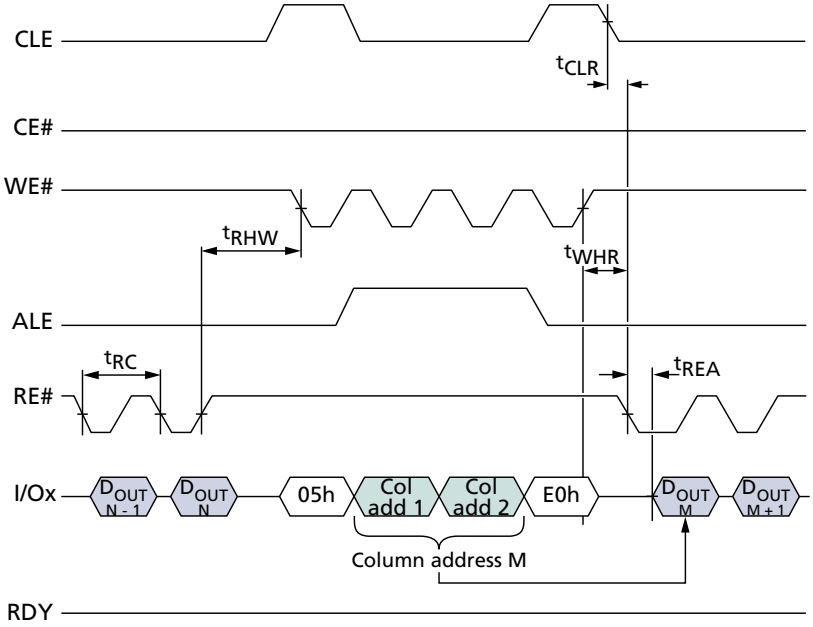


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Figure 86: RANDOM DATA READ

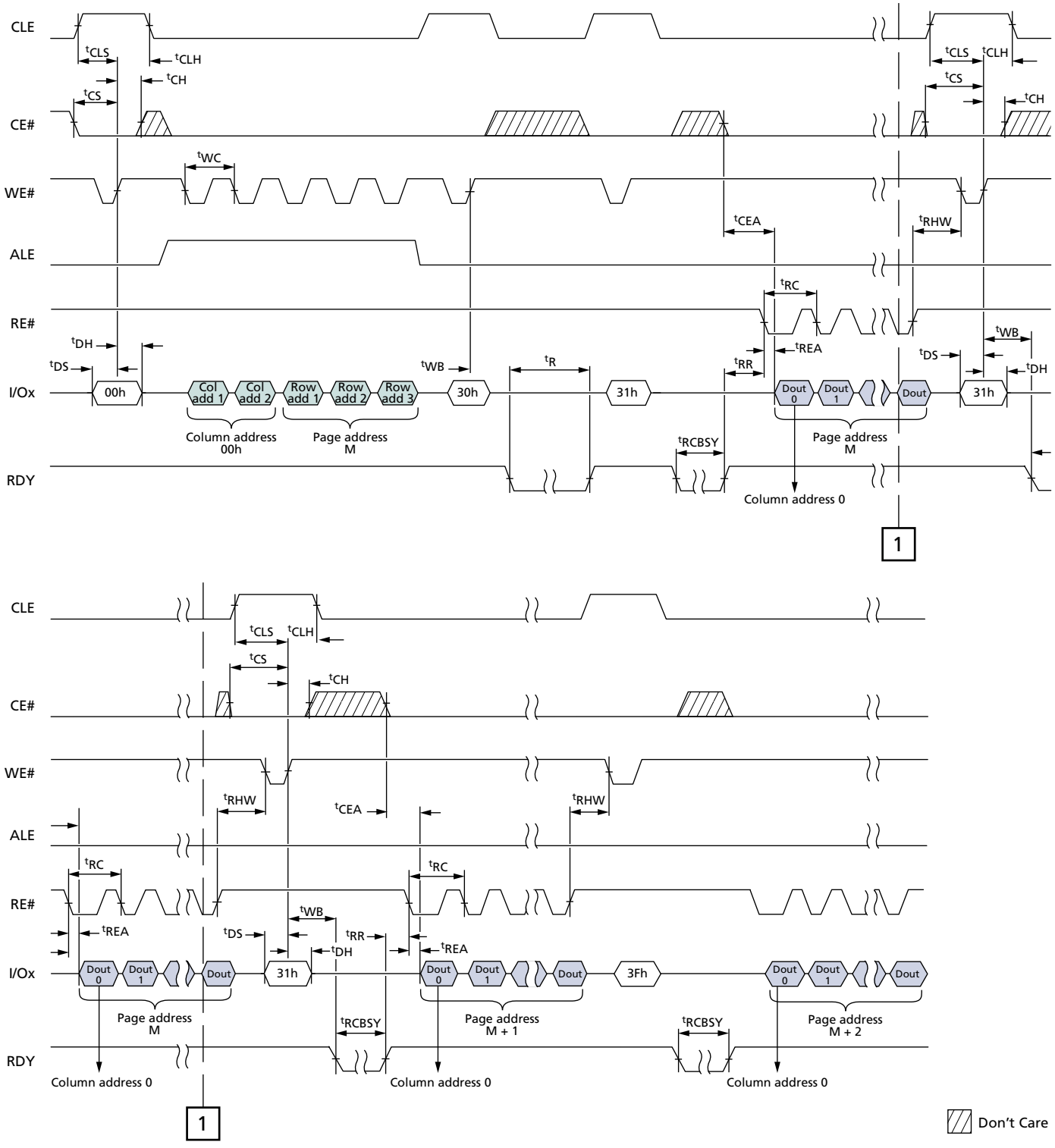


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Figure 87: READ PAGE CACHE SEQUENTIAL

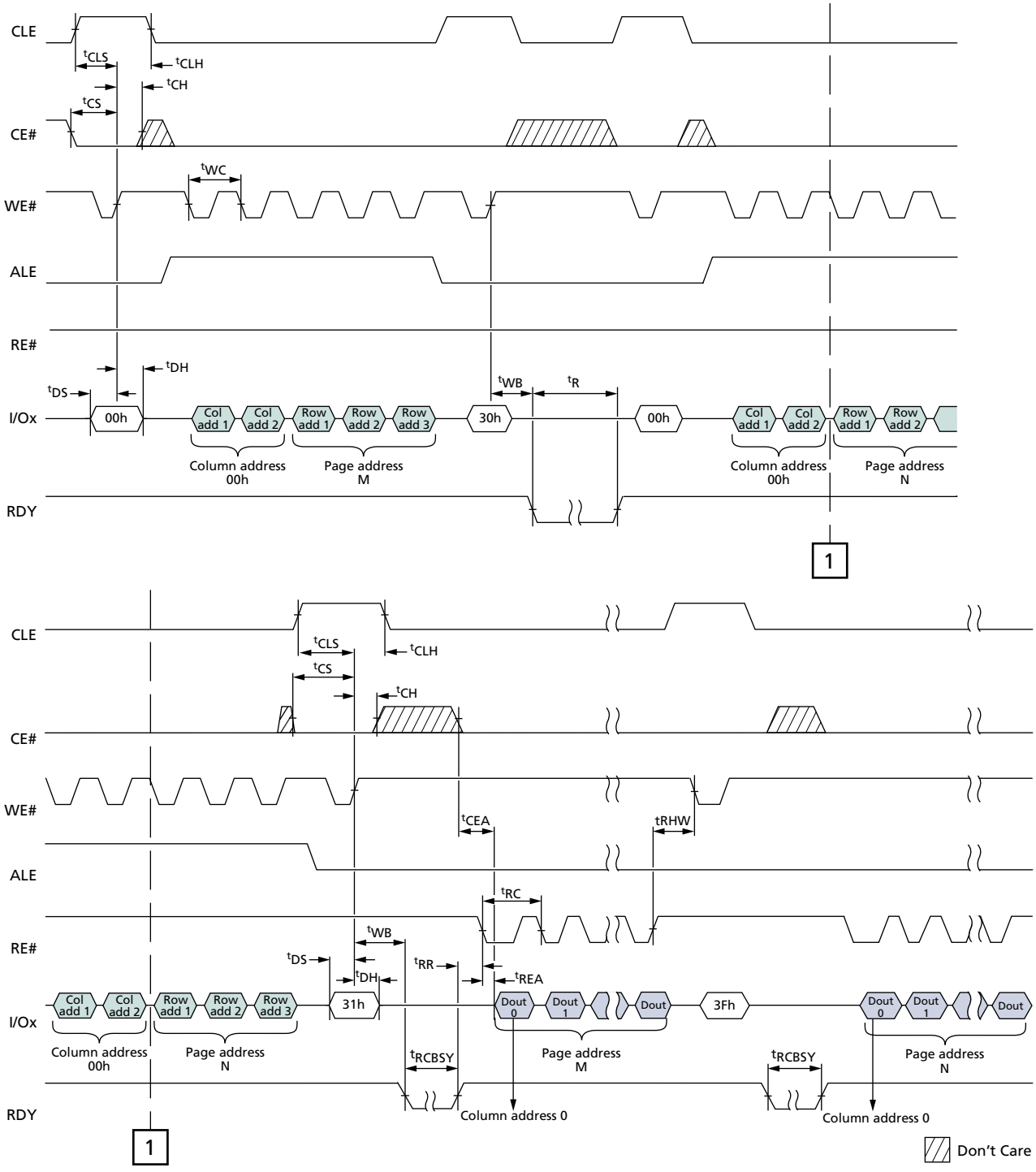


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Figure 88: READ PAGE CACHE RANDOM



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Figure 89: READ ID Operation

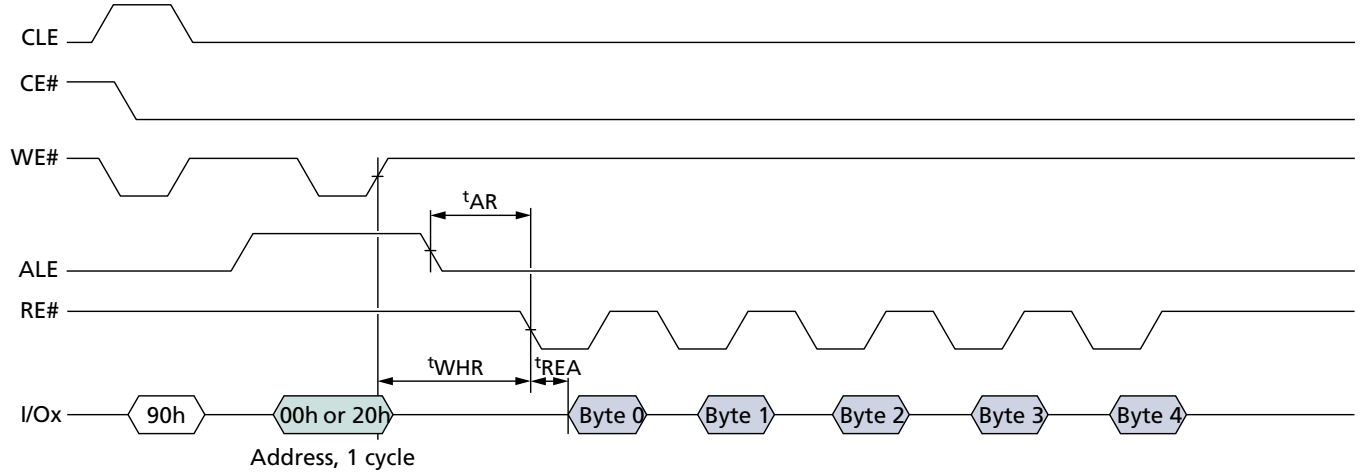
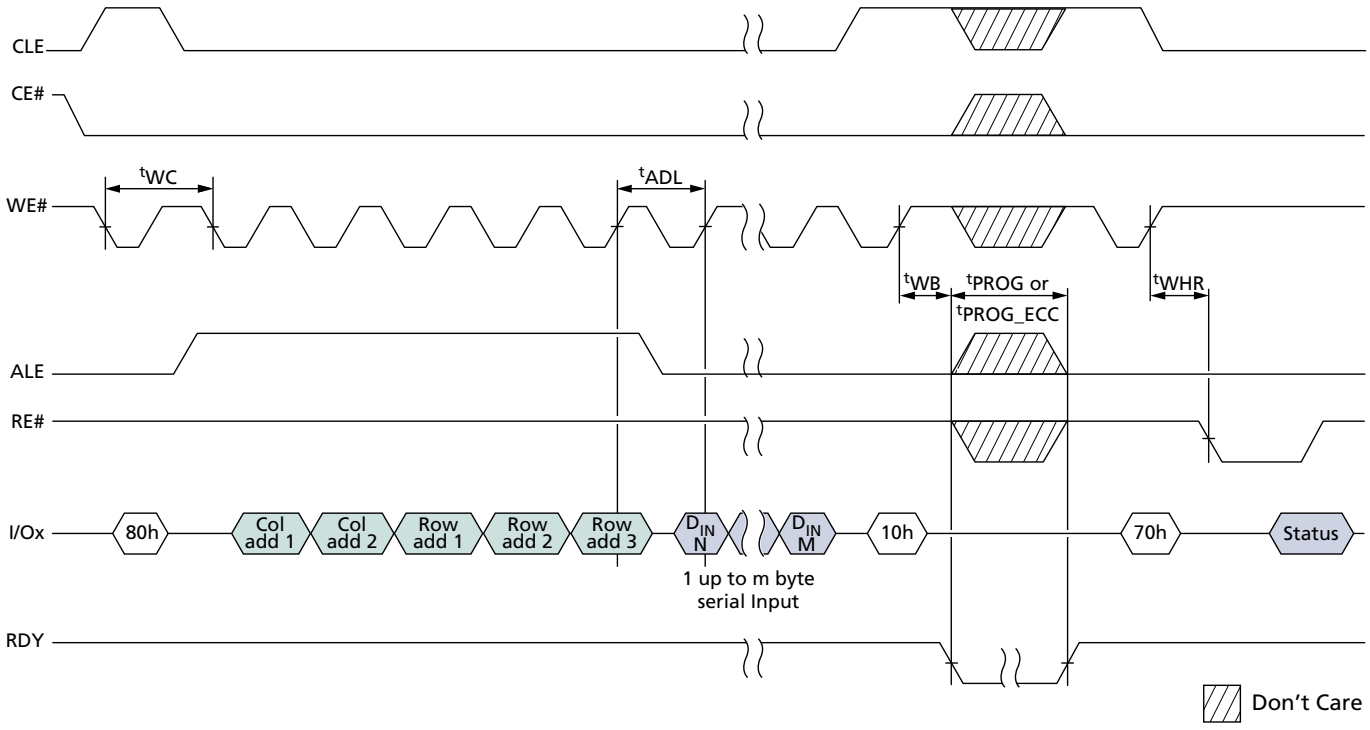


Figure 90: PROGRAM PAGE Operation



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Figure 91: PROGRAM PAGE Operation with CE# "Don't Care"

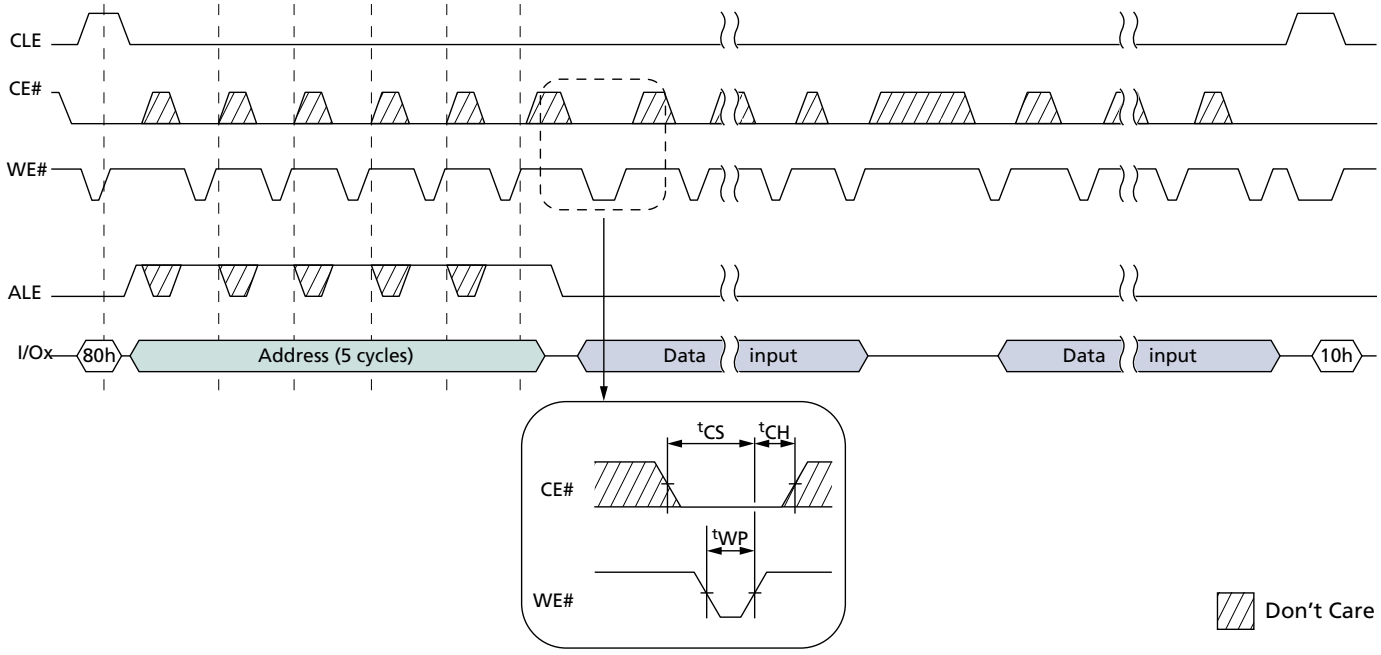
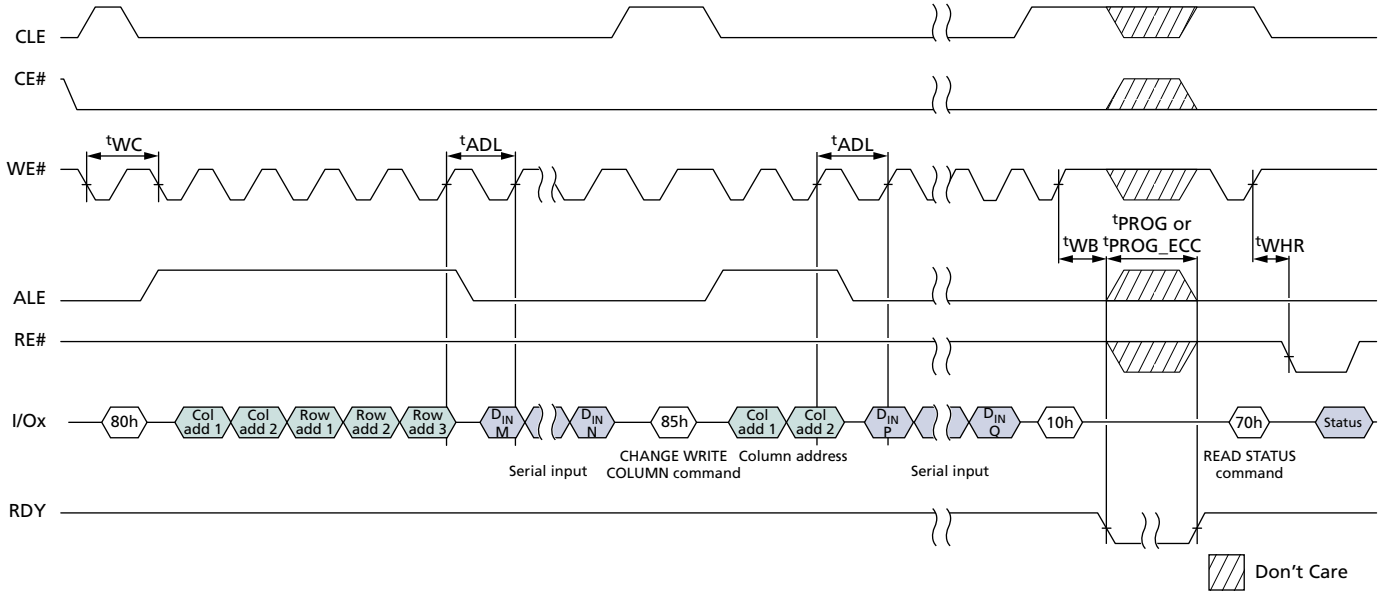


Figure 92: PROGRAM PAGE Operation with RANDOM DATA INPUT



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Figure 93: PROGRAM PAGE CACHE

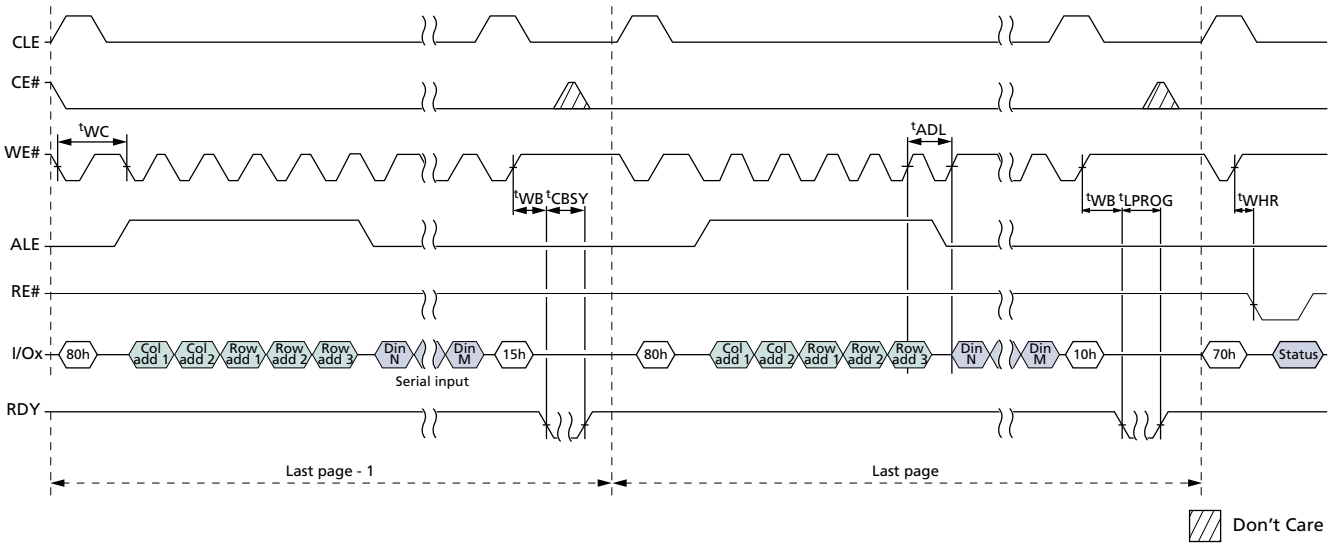
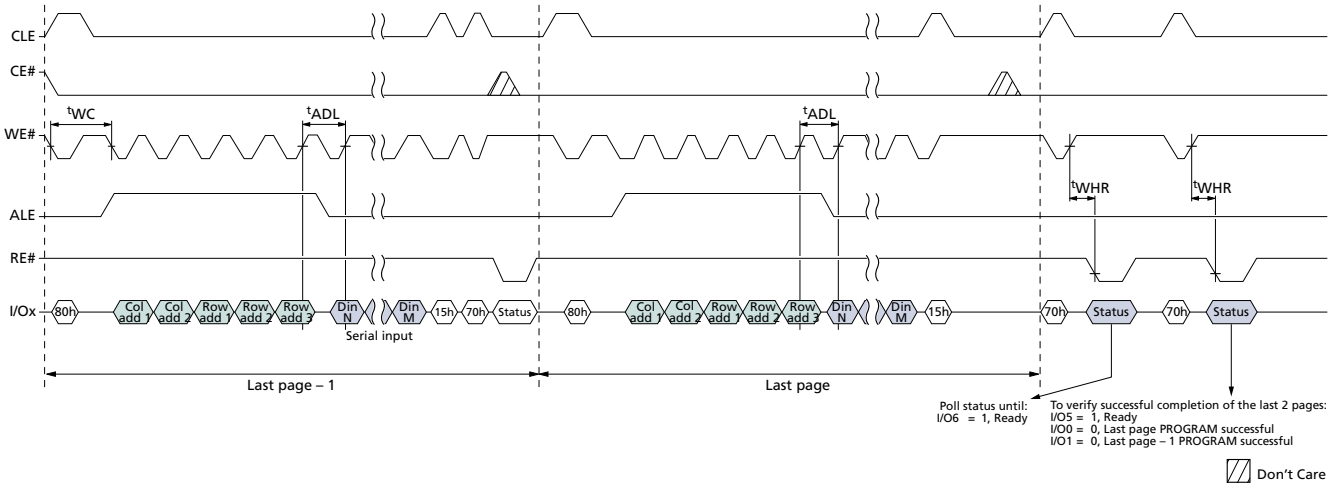


Figure 94: PROGRAM PAGE CACHE Ending on 15h



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Figure 95: INTERNAL DATA MOVE

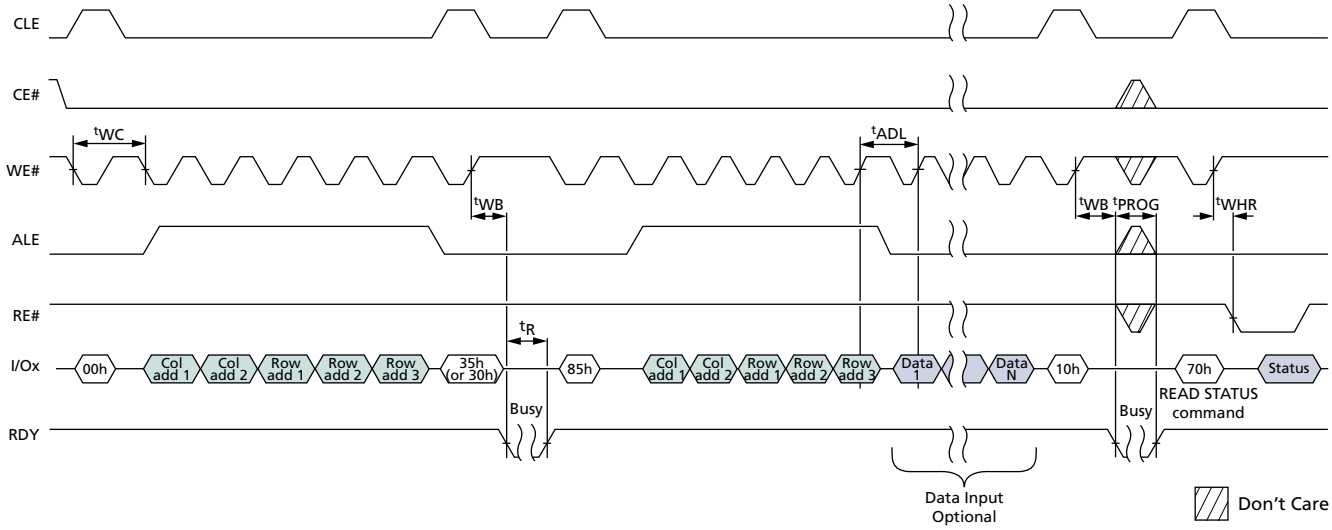
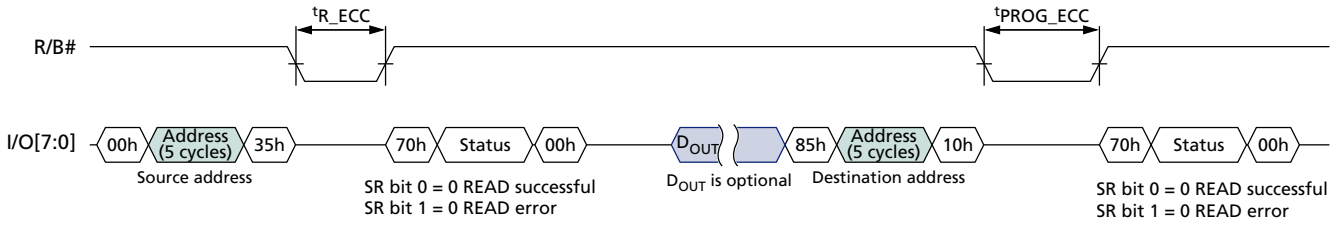


Figure 96: INTERNAL DATA MOVE (85h-10h) with Internal ECC Enabled



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Figure 97: INTERNAL DATA MOVE (85h-10h) with Random Data Input with Internal ECC Enabled

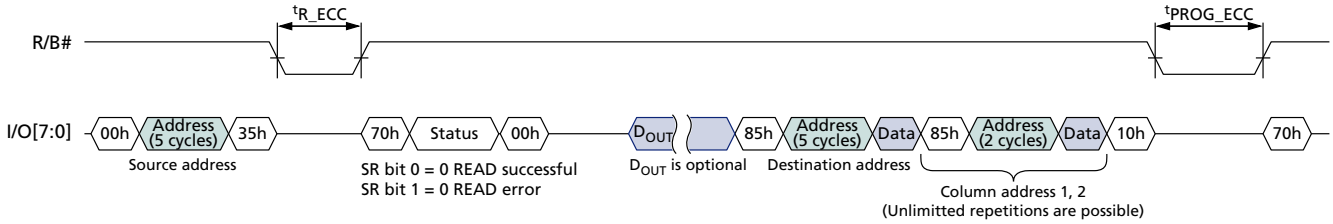
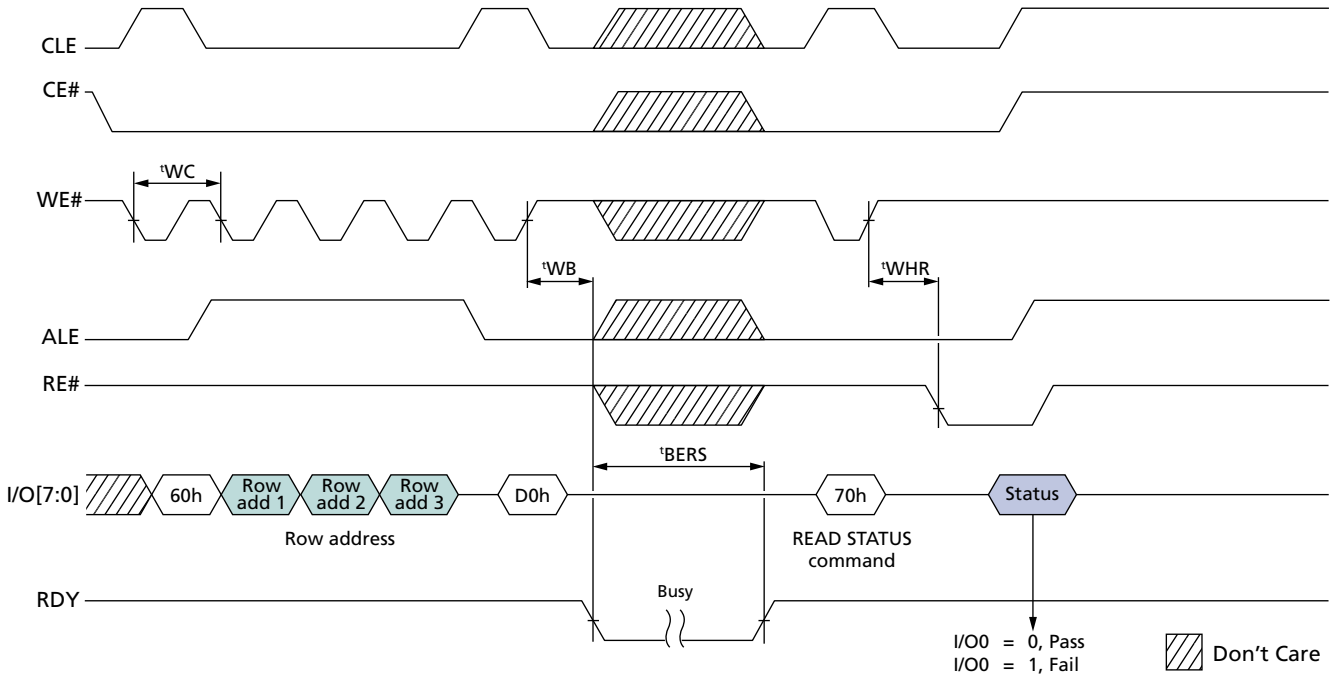


Figure 98: ERASE BLOCK Operation



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Revision History

Rev. F – 11/16

- Added new MPN: MT29F2G16ABAEAWP-AAT

Rev. E – 06/16

- Added new MPN: MT29F2G16ABBEAH4-AAT
- AAT MPNs included

Rev. D – 07/15

- Updated the Read Page Two-Plane Cache section
- Updated WP# (write protect) in Asynchronous Interface Bus Operation

Rev. C – 04/15

- Updated MPNs

Rev. B – 06/14

- Specified automotive grade temp in the Recommended Operating Conditions table

Rev. A – 03/14

- Initial release

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This data sheet contains minimum and maximum limits specified over the power supply and temperature range set forth herein.
Although considered final, these specifications are subject to change, as further product development and data characterization sometimes occur.

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