Micron Serial NOR Flash Memory

3V, Multiple I/O, 4KB, 32KB, 64KB, Sector Erase

MT25QL128ABA

Features

- SPI-compatible serial bus interface
- Single and double transfer rate (STR/DTR)
- Clock frequency
  - 133 MHz (MAX) for all protocols in STR
  - 90 MHz (MAX) for all protocols in DTR
- Dual/quad I/O commands for increased throughput up to 90 MB/s
- Supported protocols in both STR and DTR
  - Extended I/O protocol
  - Dual I/O protocol
  - Quad I/O protocol
- Execute-in-place (XIP)
- PROGRAM/ERASE SUSPEND operations
- Volatile and nonvolatile configuration settings
- Software reset
- Additional reset pin for selected part numbers
- Dedicated 64-byte OTP area outside main memory
  - Readable and user-lockable
  - Permanent lock with PROGRAM OTP command
- Erase capability
  - Bulk erase
  - Sector erase 64KB uniform granularity
  - Subsector erase 4KB, 32KB granularity
- Security and write protection
  - Volatile and nonvolatile locking and software write protection for each 64KB sector
  - Nonvolatile configuration locking
  - Password protection
  - Hardware write protection: nonvolatile bits (BP[3:0] and TB) define protected area size
  - Program/erase protection during power-up
  - CRC detects accidental changes to raw data
- Electronic signature
  - JEDEC-standard 3-byte signature (BA18h)
  - Extended device ID: two additional bytes identify device factory options
- JESD47H-compliant
  - Minimum 100,000 ERASE cycles per sector
  - Data retention: 20 years (TYP)

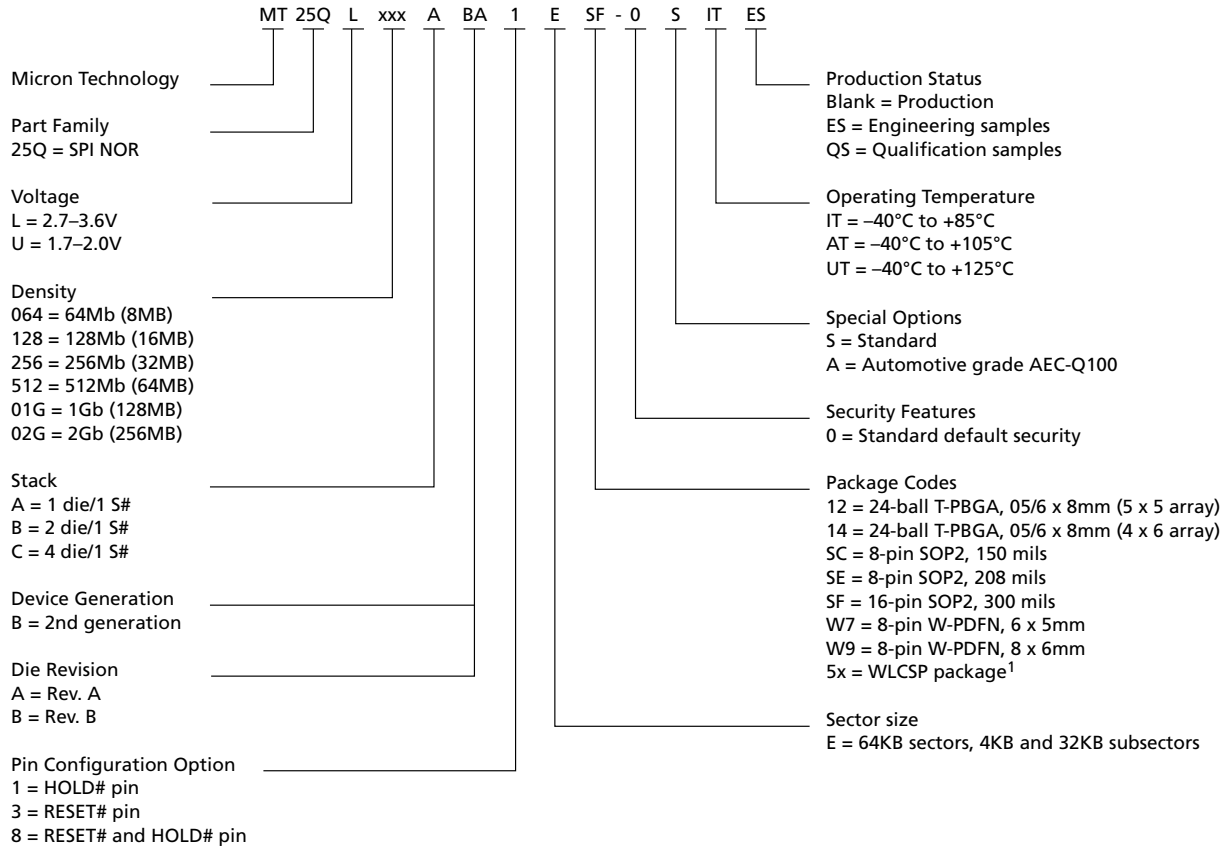
Options	Marking
• Voltage	
– 2.7–3.6V	L
• Density	
– 128Mb	128
• Device stacking	
– Monolithic	A
• Device generation	B
• Die revision	A
• Pin configuration	
– RESET# and HOLD#	8
• Sector Size	
– 64KB	E
• Packages – JEDEC-standard, RoHS-compliant	
– 16-pin SOP2, 300 mils body width (SO16W)	SF
– 8-pin SOP2, 208 mils body width (SO8W)	SE
– 24-ball T-PBGA, 05/6mm x 8mm (TBGA24)	12
– 24-ball T-PBGA 05/6mm x 8mm (4 x 6 array)	14
– W-PDFN-8 8mm x 6mm (MLP8 8mm x 6mm)	W9
– W-PDFN-8 6mm x 5mm (MLP8 6mm x 5mm)	W7
• Standard security	0
• Special options	
– Standard	S
– Automotive	A
• Operating temperature range	
– From –40°C to +85°C	IT
– From –40°C to +105°C	AT

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Part Number Ordering

Micron Serial NOR Flash devices are available in different configurations and densities. Verify valid part numbers by using Micron's part catalog search at www.micron.com. To compare features and specifications by device type, visit www.micron.com/products. Contact the factory for devices not found.

Figure 1: Part Number Ordering Information



Note: 1. WLCSP package codes, package size, and availability are density-specific. Contact the factory for availability.

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Contents

Important Notes and Warnings 8
Device Description 9
Device Logic Diagram 10
Advanced Security Protection 10
Signal Assignments – Package Code: 12 11
Signal Assignments – Package Code: 14 12
Signal Assignments – Package Code: SE, W7, W9 12
Signal Assignments – Package Code: SF 13
Signal Descriptions 14
Package Dimensions – Package Code: 12 15
Package Dimensions – Package Code: 14 17
Package Dimensions – Package Code: SE 18
Package Dimensions – Package Code: SF 19
Package Dimensions – Package Code: W7 20
Package Dimensions – Package Code: W9 21
Memory Map – 128Mb Density 22
Status Register 23
Block Protection Settings 24
Flag Status Register 25
Internal Configuration Register 26
Nonvolatile Configuration Register 27
Volatile Configuration Register 29
Supported Clock Frequencies 30
Enhanced Volatile Configuration Register 32
Security Registers 33
Sector Protection Security Register 34
Nonvolatile and Volatile Sector Lock Bits Security 35
Volatile Lock Bit Security Register 35
Device ID Data 36
Serial Flash Discovery Parameter Data 37
Command Definitions 38
Software RESET Operations 43
RESET ENABLE and RESET MEMORY Commands 43
READ ID Operations 44
READ ID and MULTIPLE I/O READ ID Commands 44
READ SERIAL FLASH DISCOVERY PARAMETER Operation 45
READ SERIAL FLASH DISCOVERY PARAMETER Command 45
READ MEMORY Operations 46
READ MEMORY Operations Timings 46
WRITE ENABLE/DISABLE Operations 53
READ REGISTER Operations 54
WRITE REGISTER Operations 55
CLEAR FLAG STATUS REGISTER Operation 57
PROGRAM Operations 58
PROGRAM Operations Timings 59
ERASE Operations 62
SUSPEND/RESUME Operations 64
PROGRAM/ERASE SUSPEND Operations 64
PROGRAM/ERASE RESUME Operations 64
ONE-TIME PROGRAMMABLE Operations 66

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READ OTP ARRAY Command 66
PROGRAM OTP ARRAY Command 66
DEEP POWER-DOWN Operations 67
ENTER DEEP POWER-DOWN Command 67
RELEASE FROM DEEP POWER-DOWN Command 68
DEEP POWER-DOWN Timings 69
QUAD PROTOCOL Operations 70
ENTER or RESET QUAD INPUT/OUTPUT MODE Command 70
CYCLIC REDUNDANCY CHECK Operations 72
State Table 74
XIP Mode 75
Activate and Terminate XIP Using Volatile Configuration Register 75
Activate and Terminate XIP Using Nonvolatile Configuration Register 75
Confirmation Bit Settings Required to Activate or Terminate XIP 76
Terminating XIP After a Controller and Memory Reset 76
Power-Up and Power-Down 77
Power-Up and Power-Down Requirements 77
Active, Standby, and Deep Power-Down Modes 79
Power Loss and Interface Rescue 79
Recovery 79
Power Loss Recovery 80
Interface Rescue 80
Initial Delivery Status 80
Absolute Ratings and Operating Conditions 81
DC Characteristics and Operating Conditions 83
AC Characteristics and Operating Conditions 85
AC Reset Specifications 87
Program/Erase Specifications 91
Revision History 92
Rev. K – 04/19 92
Rev. J – 05/18 92
Rev. I - 09/16 92
Rev. H - 07/16 92
Rev. G – 06/16 92
Rev. F – 12/15 92
Rev. E – 10/15 92
Rev. D – 9/15 92
Rev. C – 7/15 93
Rev. B – 7/14 93
Rev. A – 01/14 93

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List of Figures

Figure 1: Part Number Ordering Information 2
Figure 2: Block Diagram 9
Figure 3: Logic Diagram 10
Figure 4: 24-Ball T-BGA, 5 x 5 (Balls Down) 11
Figure 5: 24-Ball TBGA, 4 x 6 (Balls Down) 12
Figure 6: 8-Pin, SOP2 or W-PDFN (Top View) 12
Figure 7: 16-Pin, Plastic Small Outline – SO16 (Top View) 13
Figure 8: 24-Ball T-PBGA (5 x 5 ball grid array) – 6mm x 8mm 15
Figure 9: 24-Ball T-PBGA (24b05) – 6mm x 8mm 17
Figure 10: 8-Pin SOP2 (SO8W) – 208 Mils Body Width 18
Figure 11: 16-Pin SOP2 – 300 Mils Body Width 19
Figure 12: W-PDFN-8 (MLP8) – 6mm x 5mm 20
Figure 13: W-PDFN-8 (MLP8) – 8mm x 6mm 21
Figure 14: Internal Configuration Register 26
Figure 15: Sector and Password Protection 33
Figure 16: RESET ENABLE and RESET MEMORY Command 43
Figure 17: READ ID and MULTIPLE I/O READ ID Commands 44
Figure 18: READ SERIAL FLASH DISCOVERY PARAMETER Command – 5Ah 45
Figure 19: READ – 03h 46
Figure 20: FAST READ – 0Bh 47
Figure 21: DUAL OUTPUT FAST READ – 3Bh 47
Figure 22: DUAL INPUT/OUTPUT FAST READ – BBh 48
Figure 23: QUAD OUTPUT FAST READ – 6Bh 48
Figure 24: QUAD INPUT/OUTPUT FAST READ – EBh 49
Figure 25: QUAD INPUT/OUTPUT WORD READ – E7h 49
Figure 26: DTR FAST READ – 0Dh 50
Figure 27: DTR DUAL OUTPUT FAST READ – 3Dh 50
Figure 28: DTR DUAL INPUT/OUTPUT FAST READ – BDh 51
Figure 29: DTR QUAD OUTPUT FAST READ – 6Dh 51
Figure 30: DTR QUAD INPUT/OUTPUT FAST READ – EDh 52
Figure 31: WRITE ENABLE and WRITE DISABLE Timing 53
Figure 32: READ REGISTER Timing 54
Figure 33: WRITE REGISTER Timing 56
Figure 34: CLEAR FLAG STATUS REGISTER Timing 57
Figure 35: PAGE PROGRAM Command 59
Figure 36: DUAL INPUT FAST PROGRAM Command 60
Figure 37: EXTENDED DUAL INPUT FAST PROGRAM Command 60
Figure 38: QUAD INPUT FAST PROGRAM Command 61
Figure 39: EXTENDED QUAD INPUT FAST PROGRAM Command 61
Figure 40: SUBSECTOR and SECTOR ERASE Timing 63
Figure 41: BULK ERASE Timing 63
Figure 42: PROGRAM/ERASE SUSPEND and RESUME Timing 65
Figure 43: READ OTP ARRAY Command Timing 66
Figure 44: PROGRAM OTP Command Timing 67
Figure 45: ENTER DEEP POWER-DOWN Timing 69
Figure 46: RELEASE FROM DEEP POWER-DOWN Timing 70
Figure 47: XIP Mode Directly After Power-On 75
Figure 48: Power-Up Timing 78
Figure 49: AC Timing Input/Output Reference Levels 82
Figure 50: Reset AC Timing During PROGRAM and ERASE Cycle 88

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Figure 51: Reset Enable and Reset Memory Timing 88
Figure 52: Serial Input Timing STR 88
Figure 53: Serial Input Timing DTR 89
Figure 54: Write Protect Setup and Hold During WRITE STATUS REGISTER Operation (SRWD = 1) 89
Figure 55: Hold Timing 89
Figure 56: Output Timing for STR 90
Figure 57: Output Timing for DTR 90

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List of Tables

Table 1: Signal Descriptions 14
Table 2: Memory Map 22
Table 3: Status Register 23
Table 4: Protected Area 24
Table 5: Flag Status Register 25
Table 6: Nonvolatile Configuration Register 27
Table 7: Volatile Configuration Register 29
Table 8: Sequence of Bytes During Wrap 29
Table 9: Clock Frequencies – STR (in MHz) 30
Table 10: Clock Frequencies – DTR (in MHz) 31
Table 11: Enhanced Volatile Configuration Register 32
Table 12: Sector Protection Register 34
Table 13: Global Freeze Bit 34
Table 14: Nonvolatile and Volatile Lock Bits 35
Table 15: Volatile Lock Bit Register 35
Table 16: Device ID Data 36
Table 17: Extended Device ID Data, First Byte 36
Table 18: Command Set 38
Table 19: RESET ENABLE and RESET MEMORY Operations 43
Table 20: READ ID and MULTIPLE I/O READ ID Operations 44
Table 21: READ MEMORY Operations 46
Table 22: WRITE ENABLE/DISABLE Operations 53
Table 23: READ REGISTER Operations 54
Table 24: WRITE REGISTER Operations 55
Table 25: CLEAR FLAG STATUS REGISTER Operation 57
Table 26: PROGRAM Operations 58
Table 27: ERASE Operations 62
Table 28: SUSPEND/RESUME Operations 64
Table 29: OTP Control Byte (Byte 64) 67
Table 30: DEEP POWER-DOWN Operations 68
Table 31: ENTER and RESET QUAD PROTOCOL Operations 71
Table 32: CRC Command Sequence on Entire Device 72
Table 33: CRC Command Sequence on a Range 73
Table 34: Operations Allowed/Disallowed During Device States 74
Table 35: XIP Confirmation Bit 76
Table 36: Effects of Running XIP in Different Protocols 76
Table 37: Power-Up Timing and V_{WI} Threshold 78
Table 38: Absolute Ratings 81
Table 39: Operating Conditions 81
Table 40: Input/Output Capacitance 81
Table 41: AC Timing Input/Output Conditions 82
Table 42: DC Current Characteristics and Operating Conditions 83
Table 43: DC Voltage Characteristics and Operating Conditions 83
Table 44: AC Characteristics and Operating Conditions 85
Table 45: AC RESET Conditions 87
Table 46: Program/Erase Specifications 91

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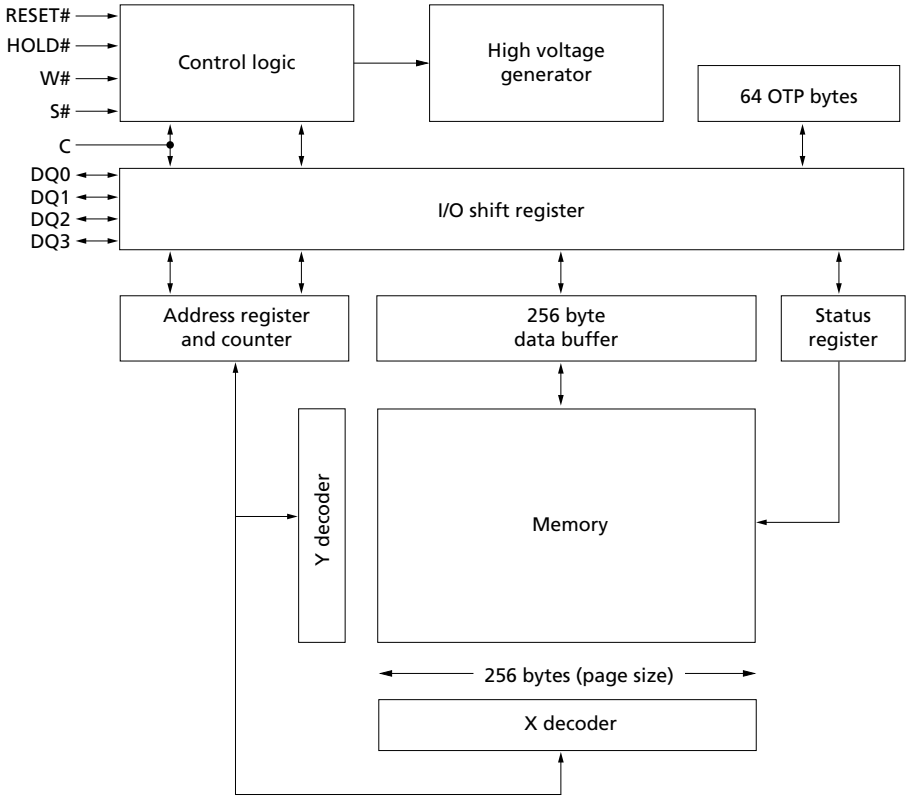
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Device Description

The MT25Q is a high-performance multiple input/output serial Flash memory device. It features a high-speed SPI-compatible bus interface, execute-in-place (XIP) functionality, advanced write protection mechanisms, and extended address access. Innovative, high-performance, dual and quad input/output commands enable double or quadruple the transfer bandwidth for READ and PROGRAM operations.

Figure 2: Block Diagram



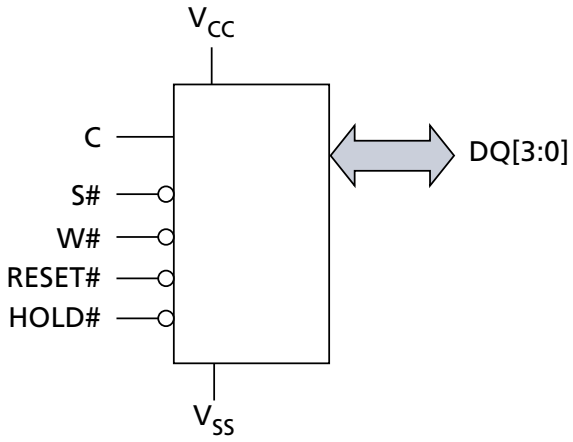
Note: 1. Each page of memory can be individually programmed, but the device is not page-erasable.

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Device Logic Diagram

Figure 3: Logic Diagram



Notes:
1. Depending on the selected device (see Part Numbering Ordering Information), DQ3 = DQ3/RESET# or DQ3/HOLD#.
2. A separate RESET pin is available on dedicated part numbers (see Part Numbering Ordering Information).

Advanced Security Protection

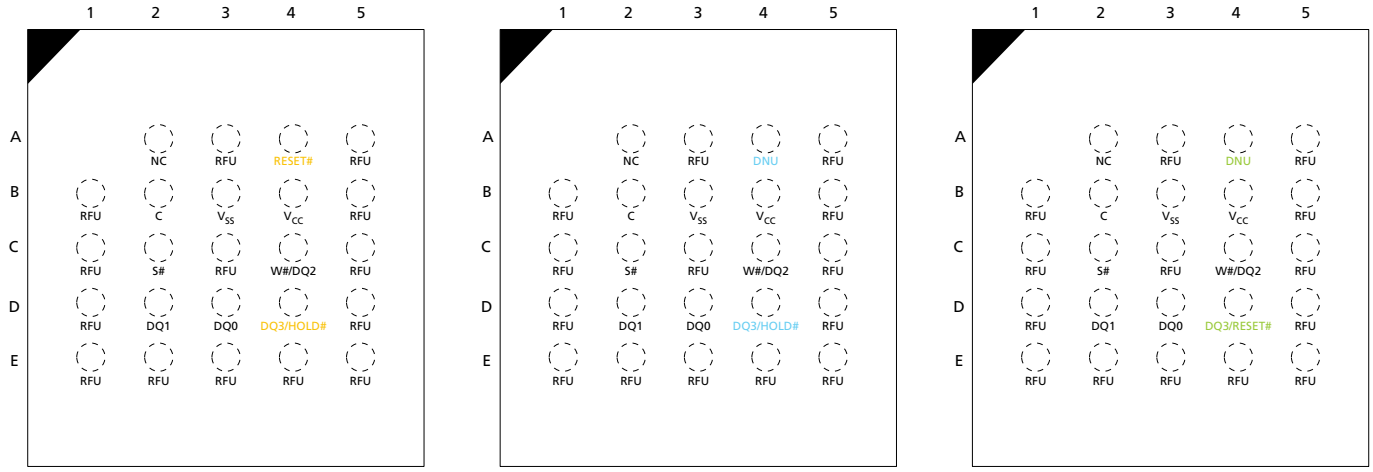
The device offers an advanced security protection scheme where each sector can be independently locked, by either volatile or nonvolatile locking features. The nonvolatile locking configuration can also be locked, as well password-protected. See Block Protection Settings and Sector and Password Protection for more details.

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Signal Assignments – Package Code: 12

Figure 4: 24-Ball T-BGA, 5 x 5 (Balls Down)



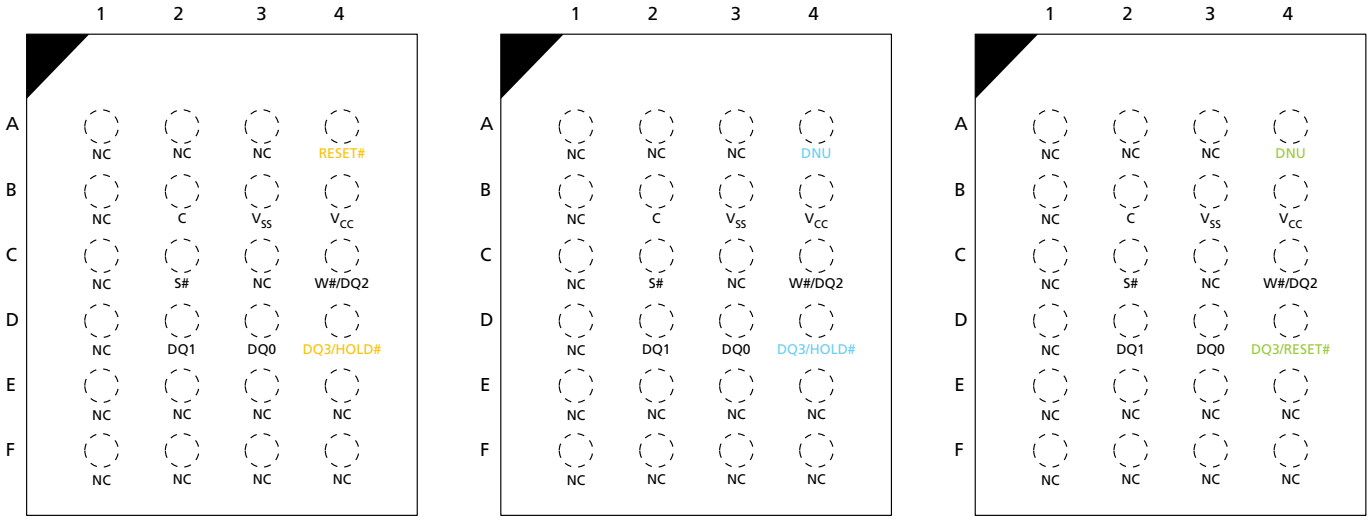
Notes:
1. RESET# or HOLD# signals can share ball D4 with DQ3, depending on the selected device (see Part Numbering Ordering Information). When using single and dual I/O commands on these parts, DQ3 must be driven HIGH by the host, or an external pull-up resistor must be placed on the PCB, in order to avoid allowing the HOLD# or RESET# input to float.
2. Ball A4 = RESET# or DNU, depending on the part number. This signal has an internal pull-up resistor and may be left unconnected if not used.

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Signal Assignments – Package Code: 14

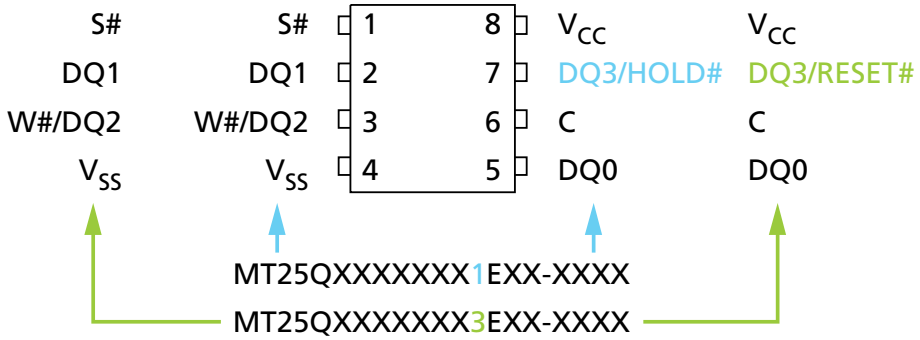
Figure 5: 24-Ball TBGA, 4 x 6 (Balls Down)



Notes:
1. RESET# or HOLD# signals can share ball D4 with DQ3, depending on the selected device (see Part Numbering Ordering Information). When using single and dual I/O commands on these parts, DQ3 must be driven HIGH by the host, or an external pull-up resistor must be placed on the PCB, in order to avoid allowing the HOLD# or RESET# input to float.
2. Ball A4 = RESET# or DNU, depending on the part number. This signal has an internal pull-up resistor and may be left unconnected if not used.

Signal Assignments – Package Code: SE, W7, W9

Figure 6: 8-Pin, SOP2 or W-PDFN (Top View)



Notes:
1. RESET# or HOLD# signals can share pin 7 with DQ3, depending on the selected device (see Part Numbering Ordering Information). When using single and dual I/O commands on these parts, DQ3 must be driven HIGH by the host, or an external pull-up resistor must be placed on the PCB, in order to avoid allowing the HOLD# or RESET# input to float.

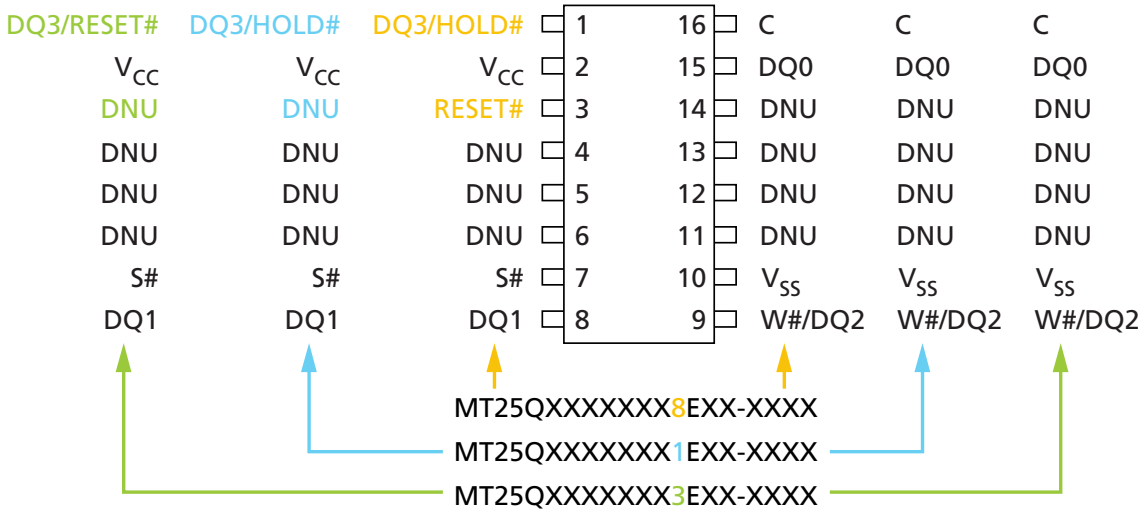
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2. On the underside of the W-PDFN package, there is an exposed central pad that is pulled internally to V_{SS}. It can be left floating or can be connected to V_{SS}. It must not be connected to any other voltage or signal line on the PCB.
3. MT25QXXXXXXX8EXX-XXXX not available in 8-pin package.

Signal Assignments – Package Code: SF

Figure 7: 16-Pin, Plastic Small Outline – SO16 (Top View)



Notes:
1. RESET# or HOLD# signals can share pin 1 with DQ3, depending on the selected device (see Part Numbering Ordering Information). When using single and dual I/O commands on these parts, DQ3 must be driven HIGH by the host, or an external pull-up resistor must be placed on the PCB, in order to avoid allowing the HOLD# or RESET# input to float.
2. Pin 3 = RESET# or DNU, depending on the part number. This signal has an internal pull-up resistor and may be left unconnected if not used.

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Signal Descriptions

The signal description table below is a comprehensive list of signals for the MT25Q family devices. All signals listed may not be supported on this device. See Signal Assignments for information specific to this device.

Table 1: Signal Descriptions

Symbol	Type	Description
S#	Input	**Chip select:** When S# is driven HIGH, the device will enter standby mode, unless an internal PROGRAM, ERASE, or WRITE STATUS REGISTER cycle is in progress. All other input pins are ignored and the output pins are tri-stated. On parts with the pin configuration offering a dedicated RESET# pin, however, the RESET# input pin remains active even when S# is HIGH. Driving S# LOW enables the device, placing it in the active mode. After power-up, a falling edge on S# is required prior to the start of any command.
C	Input	**Clock:** Provides the timing of the serial interface. Command inputs are latched on the rising edge of the clock. In STR commands or protocol, address and data inputs are latched on the rising edge of the clock, while data is output on the falling edge of the clock. In DTR commands or protocol, address and data inputs are latched on both edges of the clock, and data is output on both edges of the clock.
RESET#	Input	**RESET#:** When RESET# is driven LOW, the device is reset and the outputs are tri-stated. If RESET# is driven LOW while an internal WRITE, PROGRAM, or ERASE operation is in progress, data may be lost. The RESET# functionality can be disabled using bit 4 of the nonvolatile configuration register or bit 4 of the enhanced volatile configuration register. For pin configurations that share the DQ3 pin with RESET#, the RESET# functionality is disabled in QIO-SPI mode.
HOLD#	Input	**HOLD:** Pauses serial communications with the device without deselecting or resetting the device. Outputs are tri-stated and inputs are ignored. The HOLD# functionality can be disabled using bit 4 of the nonvolatile configuration register or bit 4 of the enhanced volatile configuration register. For pin configurations that share the DQ3 pin with HOLD#, the HOLD# functionality is disabled in QIO-SPI mode or when DTR operation is enabled.
W#	Input	**Write protect:** Freezes the status register in conjunction with the enable/disable bit of the status register. When the enable/disable bit of the status register is set to 1 and the W# signal is driven LOW, the status register nonvolatile bits become read-only and the WRITE STATUS REGISTER operation will not execute. During the extended-SPI protocol with QOFR and QIOFR instructions, and with QIO-SPI protocol, this pin function is an input/output as DQ2 functionality. This signal does not have internal pull-ups, it cannot be left floating and must be driven, even if none of W#/DQ2 function is used.
DQ[3:0]	I/O	**Serial I/O:** The bidirectional DQ signals transfer address, data, and command information. When using legacy (x1) SPI commands in extended I/O protocol (XIO-SPI), DQ0 is an input and DQ1 is an output. DQ[3:2] are not used. When using dual commands in XIO-SPI or when using DIO-SPI, DQ[1:0] are I/O. DQ[3:2] are not used. When using quad commands in XIO-SPI or when using QIO-SPI, DQ[3:0] are I/O.
V_{CC}	Supply	Core and I/O power supply.

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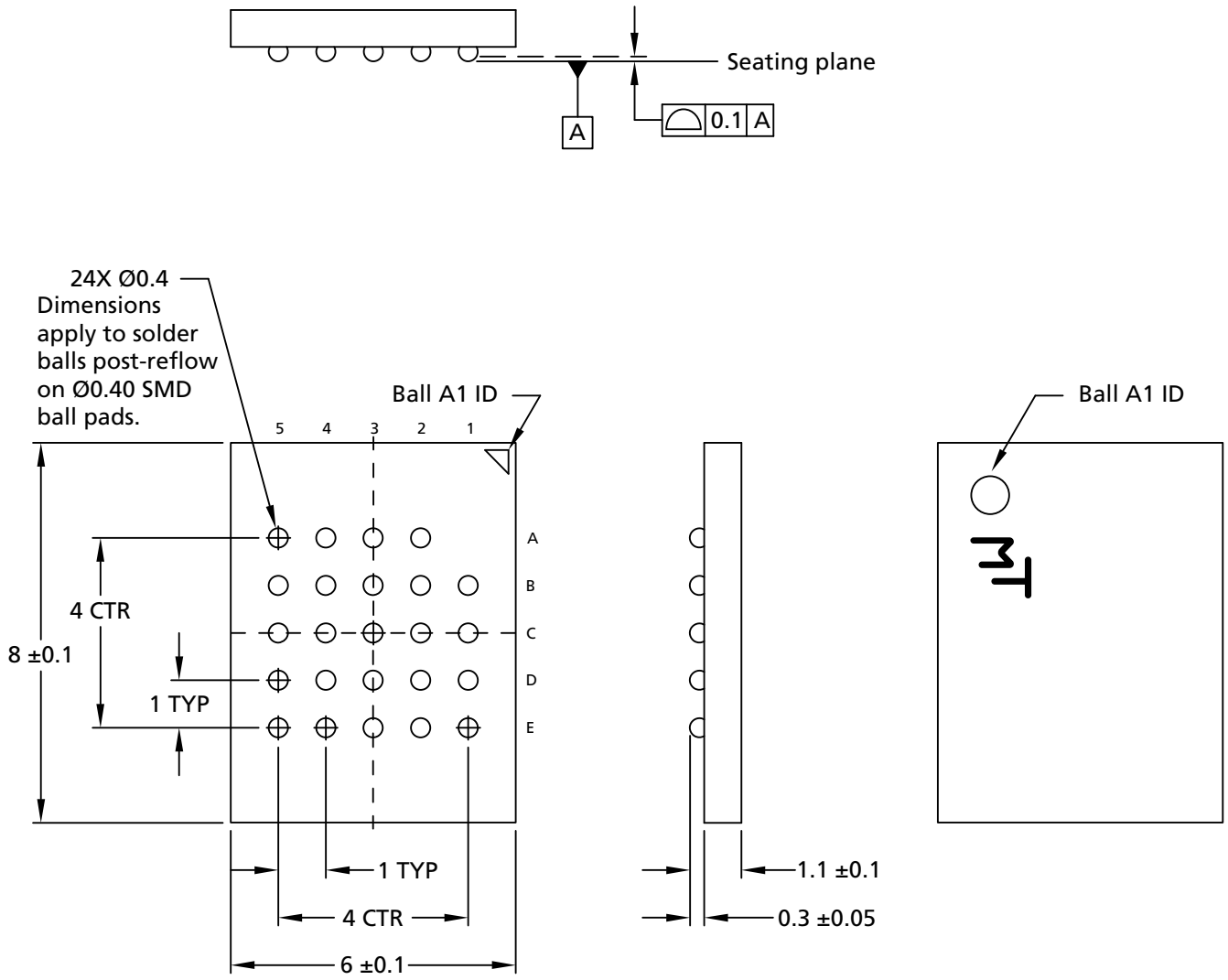
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Table 1: Signal Descriptions (Continued)

Symbol	Type	Description
V_{SS}	Supply	Core and I/O ground connection.
DNU	–	**Do not use:** Do not connect to any other signal, or power supply; must be left floating.
RFU	–	**Reserved for future use:** Reserved by Micron for future device functionality and enhancement. Recommend that these be left floating. May be connected internally, but external connections will not affect operation.
NC	–	**No connect:** No internal connection; can be driven or floated.

Package Dimensions – Package Code: 12

Figure 8: 24-Ball T-PBGA (5 x 5 ball grid array) – 6mm x 8mm



Notes: 1. All dimensions are in millimeters.

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2. See Part Number Ordering Information for complete package names and details.

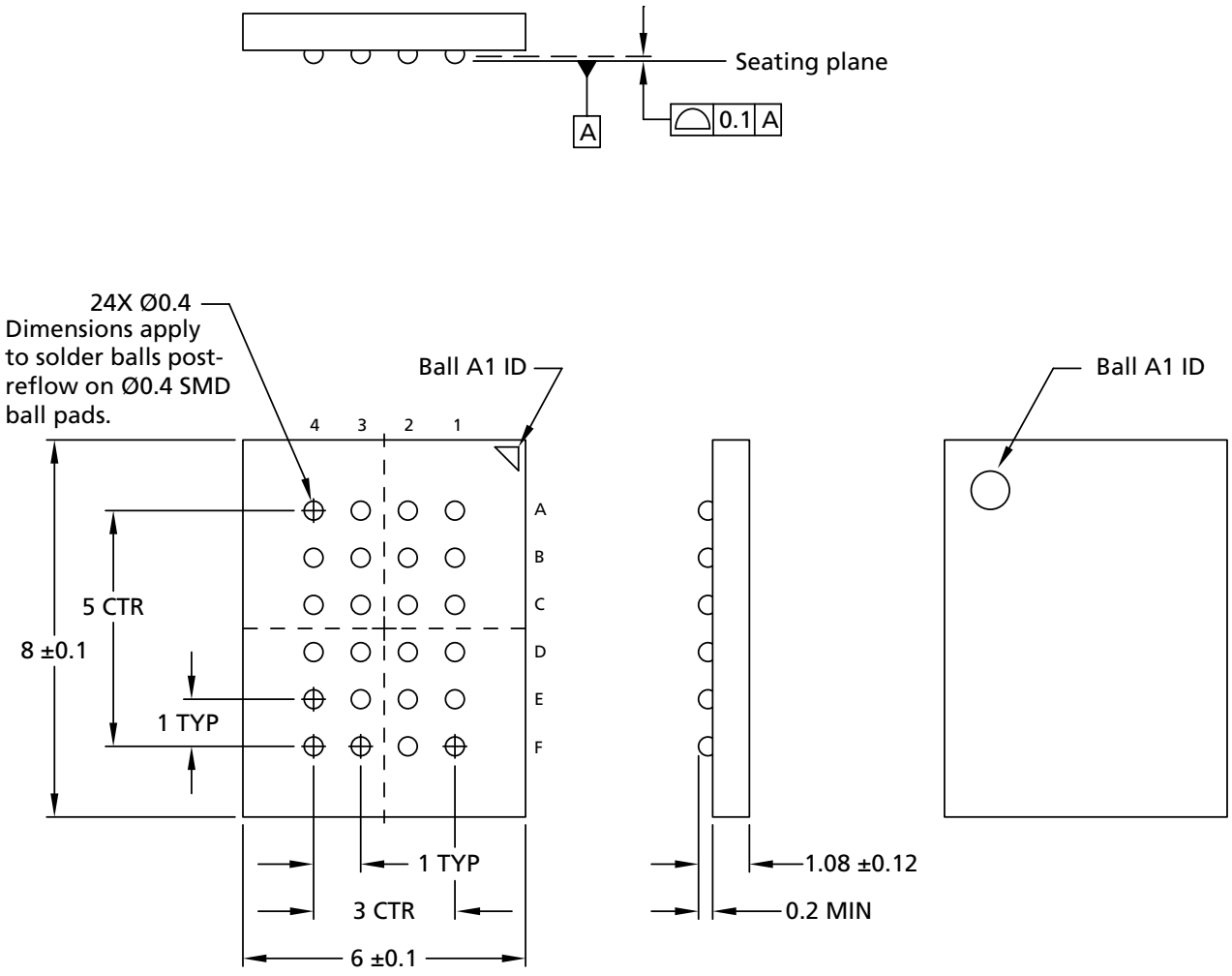
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Package Dimensions – Package Code: 14

Figure 9: 24-Ball T-PBGA (24b05) – 6mm x 8mm



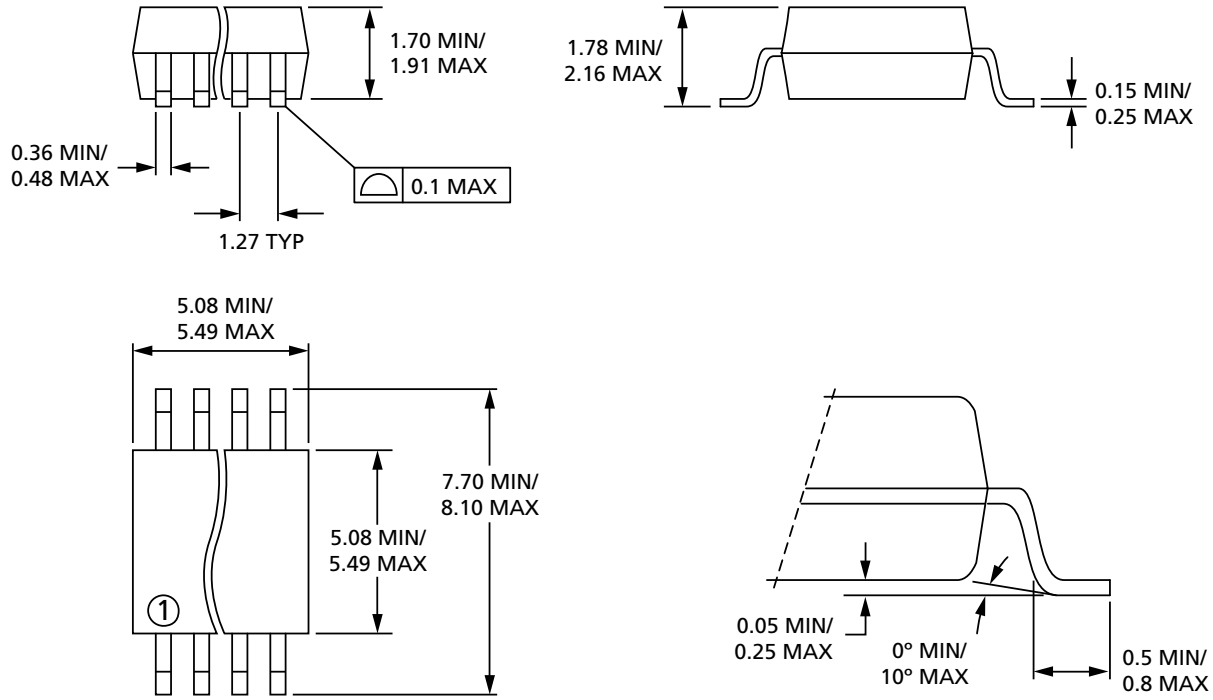
Notes:
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Package Dimensions – Package Code: SE

Figure 10: 8-Pin SOP2 (SO8W) – 208 Mils Body Width



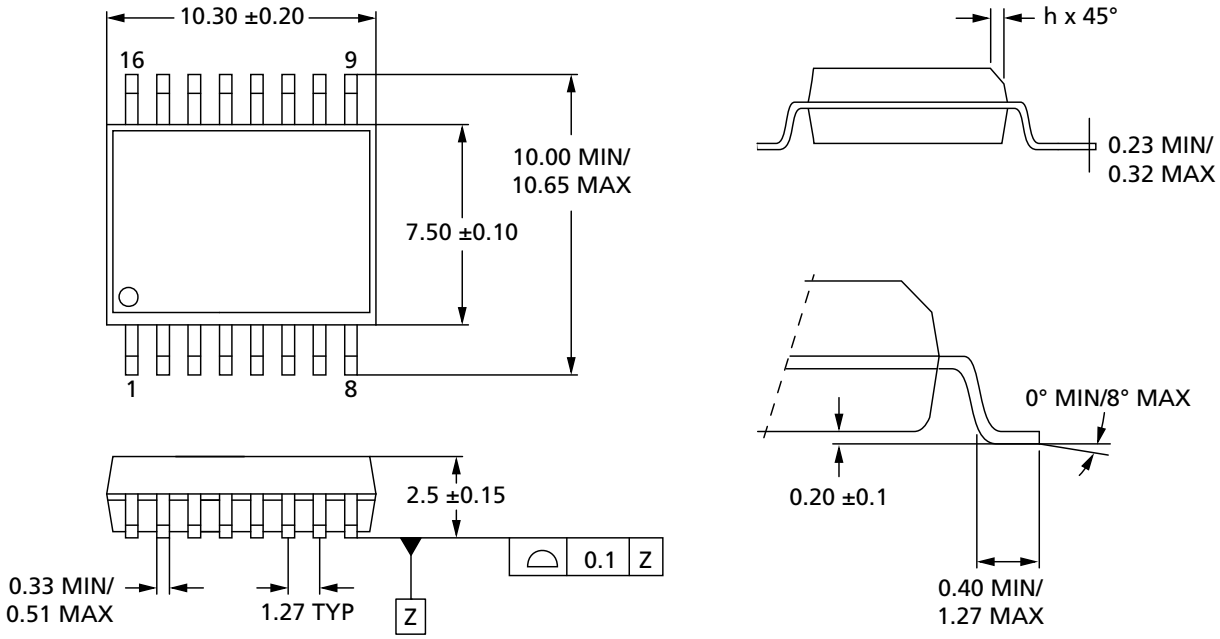
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Package Dimensions – Package Code: SF

Figure 11: 16-Pin SOP2 – 300 Mils Body Width



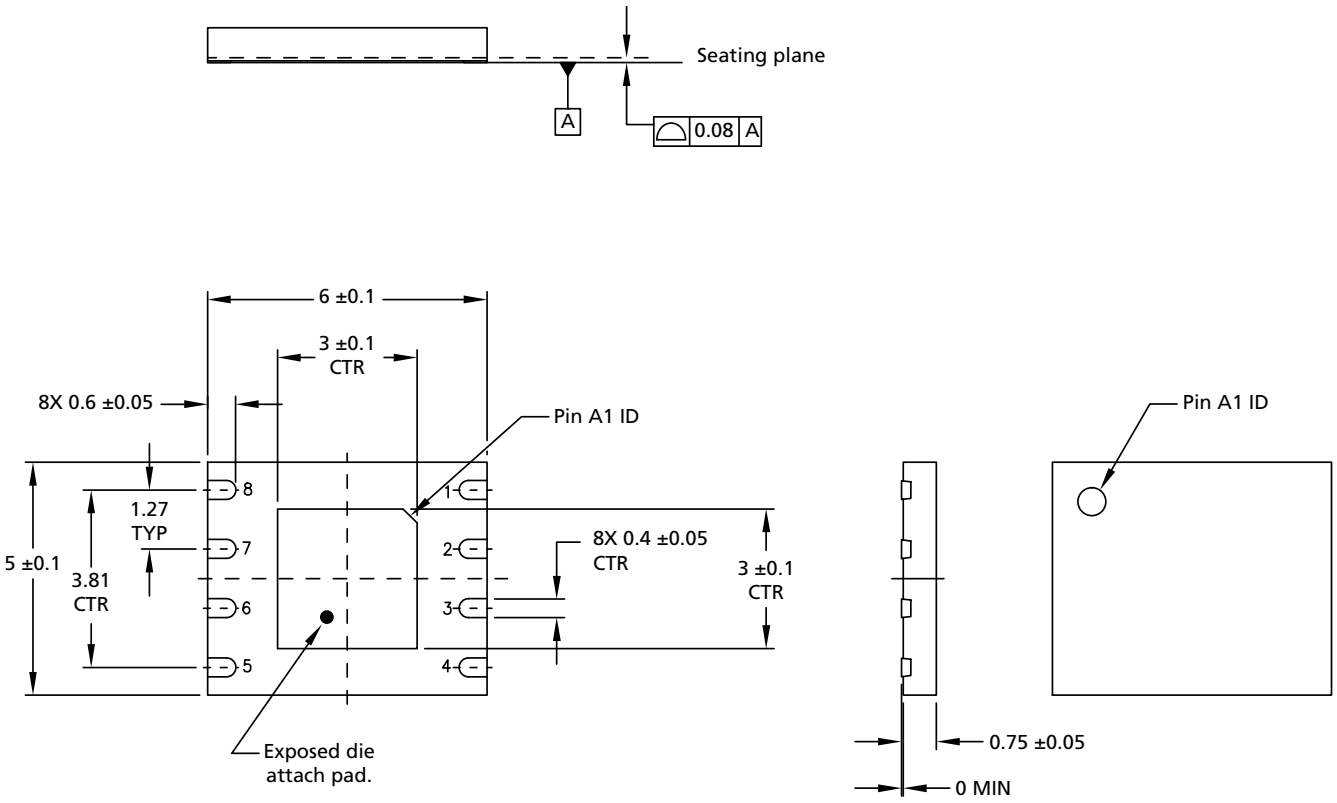
Notes:
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Package Dimensions – Package Code: W7

Figure 12: W-PDFN-8 (MLP8) – 6mm x 5mm



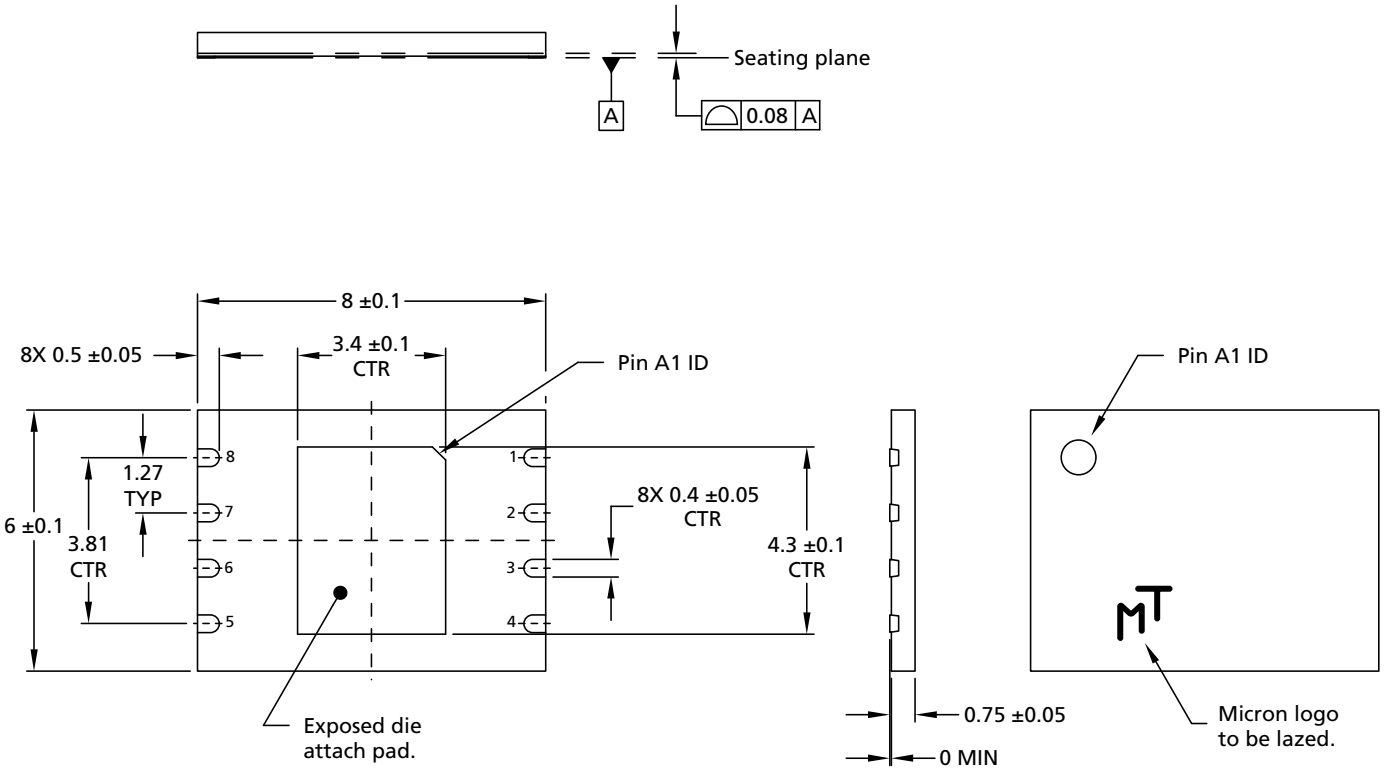
Notes:
1. All dimensions are in millimeters.
2. See Part Number Ordering Information for complete package names and details.

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Package Dimensions – Package Code: W9

Figure 13: W-PDFN-8 (MLP8) – 8mm x 6mm



Notes:
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Memory Map – 128Mb Density

Table 2: Memory Map

Sector	Subsector (32KB)	Subsector (4KB)	Address Range	
			Start	End
255	511	4095	00FF F000h	00FF FFFFh
		⋮	⋮	⋮
		4088	00FF 8000h	00FF 8FFFh
	510	4087	00FF 7000h	00FF 7FFFh
		⋮	⋮	⋮
		4080	00FF 0000h	00FF 0FFFh
⋮	⋮	⋮	⋮	⋮
127	255	2047	007F F000h	007F FFFFh
		⋮	⋮	⋮
		2040	007F 8000h	007F 8FFFh
	254	2039	007F 7000h	007F 7FFFh
		⋮	⋮	⋮
		2032	007F 0000h	007F 0FFFh
⋮	⋮	⋮	⋮	⋮
63	127	1023	003F F000h	003F FFFFh
			⋮	⋮
		1016	003F 8000h	003F 8FFFh
	126	1015	003F 7000h	003F 7FFFh
			⋮	⋮
		1008	003F 0000h	003F 0FFFh
⋮	⋮	⋮	⋮	⋮
0	1	15	0000 F000h	0000 FFFFh
		⋮	⋮	⋮
		8	0000 8000h	0000 8FFFh
	0	7	0000 7000h	0000 7FFFh
		⋮	⋮	⋮
		0	0000 0000h	0000 0FFFh

Note: 1. See Part Number Ordering Information, Sector Size – Part Numbers table for options.

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Status Register

Status register bits can be read from or written to using READ STATUS REGISTER or WRITE STATUS REGISTER commands, respectively. When the status register enable/disable bit (bit 7) is set to 1 and W# is driven LOW, the status register nonvolatile bits become read-only and the WRITE STATUS REGISTER operation will not execute. The only way to exit this hardware-protected mode is to drive W# HIGH.

Table 3: Status Register

Bit	Name	Settings	Description	Notes
7	Status register write enable/disable	0 = Enabled (Default) 1 = Disabled	**Nonvolatile control bit:** Used with W# to enable or disable writing to the status register.	
5	Top/bottom	0 = Top (Default) 1 = Bottom	**Nonvolatile control bit:** Determines whether the protected memory area defined by the block protect bits starts from the top or bottom of the memory array.	
6, 4:2	BP[3:0]	See Protected Area tables	**Nonvolatile control bit:** Defines memory to be software protected against PROGRAM or ERASE operations. When one or more block protect bits is set to 1, a designated memory area is protected from PROGRAM and ERASE operations.	1
1	Write enable latch	0 = Clear (Default) 1 = Set	**Volatile control bit:** The device always powers up with this bit cleared to prevent inadvertent WRITE, PROGRAM, or ERASE operations. To enable these operations, the WRITE ENABLE operation must be executed first to set this bit.	
0	Write in progress	0 = Ready (Default) 1 = Busy	**Volatile status bit:** Indicates if one of the following command cycles is in progress: WRITE STATUS REGISTER WRITE NONVOLATILE CONFIGURATION REGISTER PROGRAM ERASE	2

Notes:
1. The BULK ERASE command is executed only if all bits = 0.
2. Status register bit 0 is the inverse of flag status register bit 7.

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Block Protection Settings

Table 4: Protected Area

Status Register Content					Protected Area
Top/Bottom	BP3	BP2	BP1	BP0	64KB Sectors
0	0	0	0	0	None
0	0	0	0	1	255:255
0	0	0	1	0	255:254
0	0	0	1	1	255:252
0	0	1	0	0	255:248
0	0	1	0	1	255:240
0	0	1	1	0	255:224
0	0	1	1	1	255:192
0	1	0	0	0	255:128
0	1	0	0	1	255:0
0	1	0	1	0	255:0
0	1	0	1	1	255:0
0	1	1	0	0	255:0
0	1	1	0	1	255:0
0	1	1	1	0	255:0
0	1	1	1	1	255:0
1	0	0	0	0	None
1	0	0	0	1	0:0
1	0	0	1	0	1:0
1	0	0	1	1	3:0
1	0	1	0	0	7:0
1	0	1	0	1	15:0
1	0	1	1	0	31:0
1	0	1	1	1	63:0
1	1	0	0	0	127:0
1	1	0	0	1	255:0
1	1	0	1	0	255:0
1	1	0	1	1	255:0
1	1	1	0	0	255:0
1	1	1	0	1	255:0
1	1	1	1	0	255:0
1	1	1	1	1	255:0

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Flag Status Register

Flag status register bits are read by using READ FLAG STATUS REGISTER command. All bits are volatile and are reset to zero on power-up.

Status bits are set and reset automatically by the internal controller. Error bits must be cleared through the CLEAR STATUS REGISTER command.

Table 5: Flag Status Register

Bit	Name	Settings	Description
7	Program or erase controller	0 = Busy 1 = Ready	**Status bit:** Indicates whether one of the following command cycles is in progress: WRITE STATUS REGISTER, WRITE NONVOLATILE CONFIGURATION REGISTER, PROGRAM, or ERASE.
6	Erase suspend	0 = Clear 1 = Suspend	**Status bit:** Indicates whether an ERASE operation has been or is going to be suspended.
5	Erase	0 = Clear 1 = Failure or protection error	**Error bit:** Indicates whether an ERASE operation has succeeded or failed.
4	Program	0 = Clear 1 = Failure or protection error	**Error bit:** Indicates whether a PROGRAM operation has succeeded or failed. It indicates, also, whether a CRC check has succeeded or failed.
3	Reserved	0	Reserved
2	Program suspend	0 = Clear 1 = Suspend	**Status bit:** Indicates whether a PROGRAM operation has been or is going to be suspended.
1	Protection	0 = Clear 1 = Failure or protection error	**Error bit:** Indicates whether an ERASE or PROGRAM operation has attempted to modify the protected array sector, or whether a PROGRAM operation has attempted to access the locked OTP space.
0	Reserved	0	Reserved

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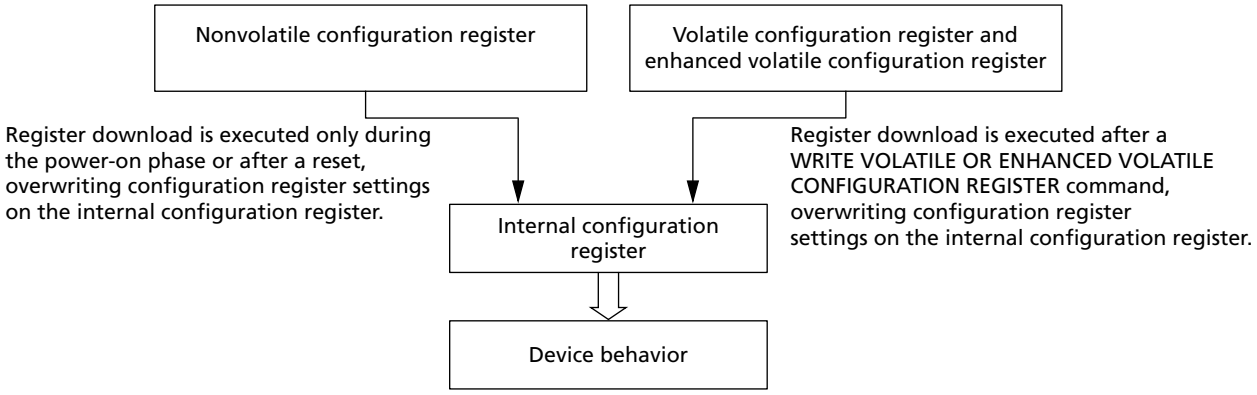
Internal Configuration Register

The memory configuration is set by an internal configuration register that is not directly accessible to users.

The user can change the default configuration at power up by using the WRITE NONVOLATILE CONFIGURATION REGISTER. Information from the nonvolatile configuration register overwrites the internal configuration register during power-on or after a reset.

The user can change the configuration during operation by using the WRITE VOLATILE CONFIGURATION REGISTER or the WRITE ENHANCED VOLATILE CONFIGURATION REGISTER commands. Information from the volatile configuration registers overwrite the internal configuration register immediately after the WRITE command completes.

Figure 14: Internal Configuration Register



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Nonvolatile Configuration Register

This register is read from and written to using the READ NONVOLATILE CONFIGURATION REGISTER and the WRITE NONVOLATILE CONFIGURATION REGISTER commands, respectively. A register download is executed during power-on or after reset, overwriting the internal configuration register settings that determine device behavior.

A WRITE NONVOLATILE CONFIGURATION REGISTER command to a reserved setting is ignored, flag status register bit 1 is set, and the write enable latch bit is cleared.

Table 6: Nonvolatile Configuration Register

Bit	Name	Settings	Description	Notes
15:12	Number of dummy clock cycles	0000 = identical to 1111 0001 = 1 0010 = 2 . . 1101 = 13 1110 = 14 1111 = Default	Sets the number of dummy clock cycles subsequent to all FAST READ commands (See the Command Set Table for default setting values).	1
11:9	XIP mode at power-on reset	000 = XIP: Fast read 001 = XIP: Dual output fast read 010 = XIP: Dual I/O fast read 011 = XIP: Quad output fast read 100 = XIP: Quad I/O fast read 101 = Reserved 110 = Reserved 111 = Disabled (Default)	Enables the device to operate in the selected XIP mode immediately after power-on reset.	
8:6	Output driver strength	000 = Reserved 001 = 90 Ohms 010 = Reserved 011 = 45 Ohms 100 = Reserved 101 = 20 Ohms 110 = Reserved 111 = 30 Ohms (Default)	Optimizes the impedance at V_{CC}/2 output voltage.	
5	Double transfer rate protocol	0 = Enabled 1 = Disabled (Default)	Set DTR protocol as current one. Once enabled, all commands will work in DTR.	
4	Reset/hold	0 = Disabled 1 = Enabled (Default)	Enables or disables HOLD# or RESET# on DQ3.	
3	Quad I/O protocol	0 = Enabled 1 = Disabled (Default)	Enables or disables quad I/O command input (4-4-4 mode).	2
2	Dual I/O protocol	0 = Enabled 1 = Disabled (Default)	Enables or disables dual I/O command input (2-2-2 mode).	2
1	Reserved	1	Reserved	

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Table 6: Nonvolatile Configuration Register (Continued)

Bit	Name	Settings	Description	Notes
0	Reserved	1	Reserved	

Notes:
1. The number of cycles must be set to accord with the clock frequency, which varies by the type of FAST READ command (See Supported Clock Frequencies table). Insufficient dummy clock cycles for the operating frequency causes the memory to read incorrect data.
2. When bits 2 and 3 are both set to 0, the device operates in quad I/O protocol.

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Volatile Configuration Register

This register is read from and written to by the READ VOLATILE CONFIGURATION REGISTER and the WRITE VOLATILE CONFIGURATION REGISTER commands, respectively. A register download is executed after these commands, overwriting the internal configuration register settings that determine device memory behavior.

Table 7: Volatile Configuration Register

Bit	Name	Settings	Description	Notes
7:4	Number of dummy clock cycles	0000 = Identical to 1111 0001 = 1 0010 = 2 ⋮ 1101 = 13 1110 = 14 1111 = Default	Sets the number of dummy clock cycles subsequent to all FAST READ commands. (See the Command Set Table for default setting values.)	1
3	XIP	0 = Enable 1 = Disable (default)	Enables or disables XIP.	
2	Reserved	0	0b = Fixed value.	
1:0	Wrap	00 = 16-byte boundary aligned	16-byte wrap: Output data wraps within an aligned 16-byte boundary starting from the 3-byte address issued after the command code.	2
		01 = 32-byte boundary aligned	32-byte wrap: Output data wraps within an aligned 32-byte boundary starting from the 3-byte address issued after the command code.	
		10 = 64-byte boundary aligned	64-byte wrap: Output data wraps within an aligned 64-byte boundary starting from the 3-byte address issued after the command code.	
		11 = Continuous (default)	Continuously sequences addresses through the entire array.	

Notes:
1. The number of cycles must be set according to and sufficient for the clock frequency, which varies by the type of FAST READ command, as shown in the Supported Clock Frequencies table. An insufficient number of dummy clock cycles for the operating frequency causes the memory to read incorrect data.
2. See the Sequence of Bytes During Wrap table.

Table 8: Sequence of Bytes During Wrap

Starting Address	16-Byte Wrap	32-Byte Wrap	64-Byte Wrap
0	0-1-2- . . . -15-0-1- . .	0-1-2- . . . -31-0-1- . .	0-1-2- . . . -63-0-1- . .
1	1-2- . . . -15-0-1-2- . .	1-2- . . . -31-0-1-2- . .	1-2- . . . -63-0-1-2- . .
....	....	....	....
15	15-0-1-2-3- . . . -15-0-1- . .	15-16-17- . . . -31-0-1- . .	15-16-17- . . . -63-0-1- . .
....	....	....	....
31	–	31-0-1-2-3- . . . -31-0-1- . .	31-32-33- . . . -63-0-1- . .
....	....	....	....
63	–	–	63-0-1- . . . -63-0-1- . .

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Supported Clock Frequencies

Table 9: Clock Frequencies – STR (in MHz)

Notes apply to entire table

Number of Dummy Clock Cycles	FAST READ	DUAL OUTPUT FAST READ	DUAL I/O FAST READ	QUAD OUTPUT FAST READ	QUAD I/O FAST READ
1	94	79	60	44	39
2	112	97	77	61	48
3	129	106	86	78	58
4	133	115	97	97	69
5	133	125	106	106	78
6	133	133	115	115	86
7	133	133	125	125	97
8	133	133	133	133	106
9	133	133	133	133	115
10	133	133	133	133	125
11 : 14	133	133	133	133	133

Notes:
1. Values are guaranteed by characterization and not 100% tested in production.
2. A tuning data pattern (TDP) capability provides applications with data patterns for adjusting the data latching point at the host end when the clock frequency is set higher than 133 MHz in STR mode and higher than 66 MHz in double transfer rate (DTR) mode. For additional details, refer to TN-25-07: Tuning Data Pattern for MT25Q and MT25T Devices.

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Table 10: Clock Frequencies – DTR (in MHz)

Notes apply to entire table

Number of Dummy Clock Cycles	FAST READ	DUAL OUTPUT FAST READ	DUAL I/O FAST READ	QUAD OUTPUT FAST READ	QUAD I/O FAST READ
1	59	45	40	26	20
2	73	59	49	40	30
3	82	68	59	59	39
4	90	76	65	65	49
5	90	83	75	75	58
6	90	90	83	83	68
7	90	90	90	90	78
8	90	90	90	90	85
9	90	90	90	90	90
10 : 14	90	90	90	90	90

Notes:
1. Values are guaranteed by characterization and not 100% tested in production.
2. A tuning data pattern (TDP) capability provides applications with data patterns for adjusting the data latching point at the host end when the clock frequency is set higher than 133 MHz in STR mode and higher than 66 MHz in double transfer rate (DTR) mode. For additional details, refer to TN-25-07: Tuning Data Pattern for MT25Q and MT25T Devices.

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Enhanced Volatile Configuration Register

This register is read from and written to using the READ ENHANCED VOLATILE CONFIGURATION REGISTER and the WRITE ENHANCED VOLATILE CONFIGURATION REGISTER commands, respectively. A register download is executed after these commands, overwriting the internal configuration register settings that determine device memory behavior.

Table 11: Enhanced Volatile Configuration Register

Bit	Name	Settings	Description	Notes
7	Quad I/O protocol	0 = Enabled 1 = Disabled (default)	Enables or disables quad I/O command input (4-4-4 mode).	1
6	Dual I/O protocol	0 = Enabled 1 = Disabled (default)	Enables or disables dual I/O command input (2-2-2 mode).	1
5	Double transfer rate protocol	0 = Enabled 1 = Disabled (Default, single transfer rate)	Set DTR protocol as current one. Once enabled, all commands will work in DTR.	
4	Reset/hold	0 = Disabled 1 = Enabled (default)	Enables or disables HOLD# or RESET# on DQ3. (Available only on specified part numbers.)	
3	Reserved	1		
2:0	Output driver strength	000 = Reserved 001 = 90 ohms 010 = Reserved 011 = 45 ohms 100 = Reserved 101 = 20 ohms 110 = Reserved 111 = 30 ohms (default)	Optimizes the impedance at V_{CC}/2 output voltage.	

Note: 1. When bits 6 and 7 are both set to 0, the device operates in quad I/O protocol. When either bit 6 or 7 is set to 0, the device operates in dual I/O or quad I/O respectively. When a bit is set, the device enters the selected protocol immediately after the WRITE ENHANCED VOLATILE CONFIGURATION REGISTER command. The device returns to the default protocol after the next power-on or reset. Also, the rescue sequence or another WRITE ENHANCED VOLATILE CONFIGURATION REGISTER command will return the device to the default protocol.

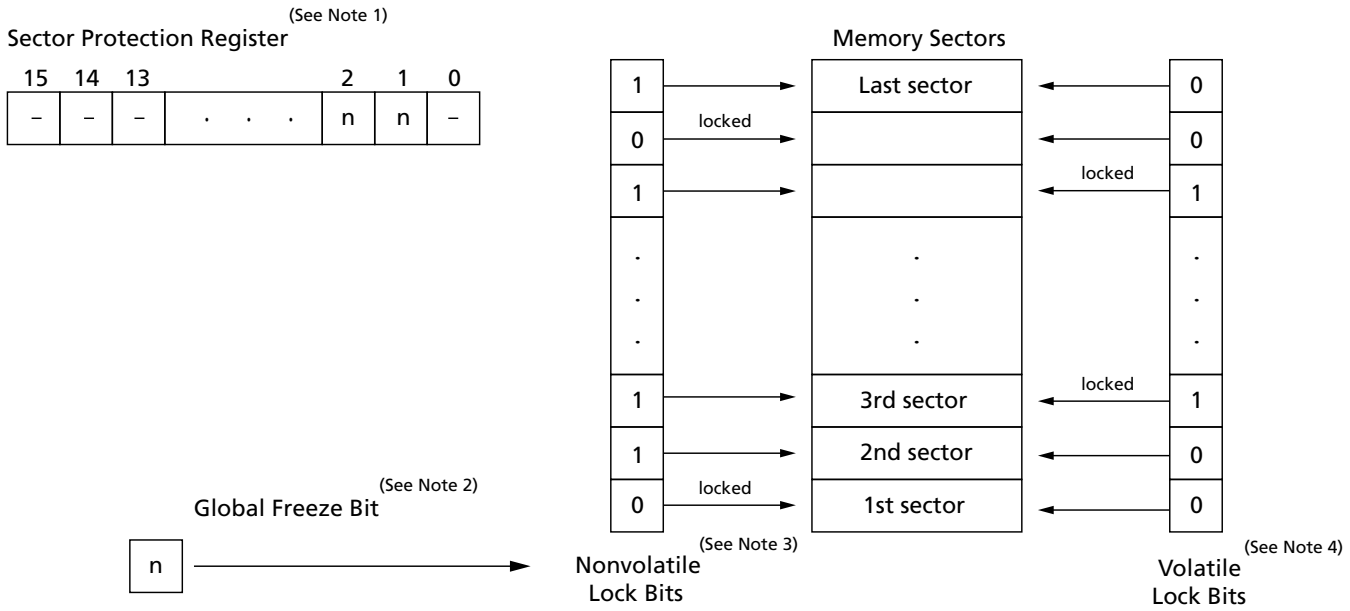
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Security Registers

Security registers enable sector and password protection on multiple levels using non-volatile and volatile register and bit settings (shown below). The applicable register tables follow.

Figure 15: Sector and Password Protection



Notes:
1. **Sector protection register.** This 16-bit nonvolatile register includes two active bits[2:1] to enable sector and password protection.
2. **Global freeze bit.** This volatile bit protects the settings in all nonvolatile lock bits.
3. **Nonvolatile lock bits.** Each nonvolatile bit corresponds to and provides nonvolatile protection for an individual memory sector, which remains locked (protection enabled) until its corresponding bit is cleared to 1.
4. **Volatile lock bits.** Each volatile bit corresponds to and provides volatile protection for an individual memory sector, which is locked temporarily (protection is cleared when the device is reset or powered down).
5. The first and last sectors will have volatile protections at the 4KB subsector level. Each 4KB subsector in these sectors can be individually locked by volatile lock bits setting; nonvolatile protections granularity remain at the sector level.

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Sector Protection Security Register

Table 12: Sector Protection Register

Bits	Name	Settings	Description	Notes
15:3	Reserved	1 = Default	–	
2	Password protection lock	1 = Disabled (default) 0 = Enabled	**Nonvolatile bit:** When set to 1, password protection is disabled. When set to 0, password protection is enabled permanently; the 64-bit password cannot be retrieved or reset.	1, 2
1	Sector protection lock	1 = Enabled, with password protection (default) 0 = Enabled, without password protection	**Nonvolatile bit:** When set to 1, nonvolatile lock bits can be set to lock/unlock their corresponding memory sectors; bit 2 can be set to 0, enabling password protection permanently. When set to 0, nonvolatile lock bits can be set to lock/unlock their corresponding memory sectors; bit 2 must remain set to 1, disabling password protection permanently.	1, 3, 4
0	Reserved	1 = Default	–	

Notes:
1. Bits 2 and 1 are user-configurable, one-time-programmable, and mutually exclusive in that only one of them can be set to 0. It is recommended that one of the bits be set to 0 when first programming the device.
2. The 64-bit password must be programmed and verified before this bit is set to 0 because after it is set, password changes are not allowed, thus providing protection from malicious software. When this bit is set to 0, a 64-bit password is required to reset the global freeze bit from 0 to 1. In addition, if the password is incorrect or lost, the global freeze bit can no longer be set and nonvolatile lock bits cannot be changed. (See the Sector and Password Protection figure and the Global Freeze Bit Definition table).
3. Whether this bit is set to 1 or 0, it enables programming or erasing nonvolatile lock bits (which provide memory sector protection). The password protection bit must be set beforehand because setting this bit will either enable password protection permanently (bit 2 = 0) or disable password protection permanently (bit 1 = 0).
4. By default, all sectors are unlocked when the device is shipped from the factory. Sectors are locked, unlocked, read, or locked down as explained in the Nonvolatile and Volatile Lock Bits table and the Volatile Lock Bit Register Bit Definitions table.

Table 13: Global Freeze Bit

Bits	Name	Settings	Description
7:1	Reserved	0	Bit values are 0
0	Global freeze bit	1 = Disabled (default) 0 = Enabled	**Volatile bit:** When set to 1, all nonvolatile lock bits can be set to enable or disable locking their corresponding memory sectors. When set to 0, nonvolatile lock bits are protected from PROGRAM or ERASE commands. This bit should not be set to 0 until the nonvolatile lock bits are set.

Note:
1. The READ GLOBAL FREEZE BIT command enables reading this bit. When password protection is enabled, this bit is locked upon device power-up or reset. It cannot be changed without the password. After the password is entered, the UNLOCK PASSWORD command resets this bit to 1, enabling programing or erasing the nonvolatile lock bits. After the bits are changed, the WRITE GLOBAL FREEZE BIT command sets this bit to 0, protecting the nonvolatile lock bits from PROGRAM or ERASE operations.

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Nonvolatile and Volatile Sector Lock Bits Security

Table 14: Nonvolatile and Volatile Lock Bits

Bit Details	Nonvolatile Lock Bit	Volatile Lock Bit
Description	Each sector of memory has one corresponding nonvolatile lock bit	Each sector of memory has one corresponding volatile lock bit; this bit is the sector write lock bit described in the Volatile Lock Bit Register table.
Function	When set to 0, locks and protects its corresponding memory sector from PROGRAM or ERASE operations. Because this bit is nonvolatile, the sector remains locked, protection enabled, until the bit is cleared to 1.	When set to 1, locks and protects its corresponding memory sector from PROGRAM or ERASE operations. Because this bit is volatile, protection is temporary. The sector is unlocked, protection disabled, upon device reset or power-down.
Settings	1 = Lock disabled 0 = Lock enabled	0 = Lock disabled 1 = Lock enabled
Enabling protection	The bit is set to 0 by the WRITE NONVOLATILE LOCK BITS command, enabling protection for designated locked sectors. Programming a sector lock bit requires the typical byte programming time.	The bit is set to 1 by the WRITE VOLATILE LOCK BITS command, enabling protection for designated locked sectors.
Disabling protection	All bits are cleared to 1 by the ERASE NONVOLATILE LOCK BITS command, unlocking and disabling protection for all sectors simultaneously. Erasing all sector lock bits requires typical sector erase time.	All bits are set to 0 upon reset or power-down, unlocking and disabling protection for all sectors.
Reading the bit	Bits are read by the READ NONVOLATILE LOCK BITS command.	Bits are read by the READ VOLATILE LOCK BITS command.

Volatile Lock Bit Security Register

One volatile lock bit register is associated with each sector of memory. It enables the sector to be locked, unlocked, or locked-down with the WRITE VOLATILE LOCK BITS command, which executes only when sector lock down (bit 1) is set to 0. Each register can be read with the READ VOLATILE LOCK BITS command. This register is compatible with and provides the same locking capability as the lock register in the Micron N25Q SPI NOR family.

Table 15: Volatile Lock Bit Register

Bit	Name	Settings	Description
7:2	Reserved	0	Bit values are 0.
1	Sector lock down	0 = Lock-down disabled (default) 1 = Lock-down enabled	**Volatile bit:** Device always powers up with this bit set to 0 so that sector lock down and sector write lock bits can be set to 1. When this bit set to 1, neither of the two volatile lock bits can be written to until the next power cycle, hardware, or software reset.
0	Sector write lock	0 = Write lock disabled (default) 1 = Write lock enabled	**Volatile bit:** Device always powers up with this bit set to 0 so that PROGRAM and ERASE operations in this sector can be executed and sector content modified. When this bit is set to 1, PROGRAM and ERASE operations in this sector are not executed.

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Device ID Data

The device ID data shown in the tables here is read by the READ ID and MULTIPLE I/O READ ID operations.

Table 16: Device ID Data

Byte#	Name	Content Value	Assigned By
Manufacturer ID (1 byte total)			
1	Manufacturer ID (1 byte)	20h	JEDEC
Device ID (2 bytes total)			
2	Memory type (1 byte)	BAh = 3V	Manufacturer
		BBh = 1.8V	
3	Memory capacity (1 byte)	22h = 2Gb	
		21h = 1Gb	
		20h = 512Mb	
		19h = 256Mb	
		18h = 128Mb	
		17h = 64Mb	
Unique ID (17 bytes total)			
4	Indicates the number of remaining ID bytes (1 byte)	10h	Factory
5	Extended device ID (1 byte)	See Extended Device ID table	
6	Device configuration information (1 byte)	00h = Standard	
7:20	Customized factory data (14 bytes)	Unique ID code (UID)	

Table 17: Extended Device ID Data, First Byte

Bit 7	Bit 6	Bit 5[1]	Bit 4	Bit 3	Bit 2[2]	Bit 1	Bit 0
Reserved	Device Generation 1 = 2nd generation	1 = Alternate BP scheme 0 = Standard BP scheme	Reserved	HOLD#/RESET#: 0 = HOLD 1 = RESET	Additional HW RESET#: 1 = Available 0 = Not available	Sector size: 00 = Uniform 64KB	

Notes:
1. For alternate BP scheme information, contact the factory.
2. Available for specific part numbers. See Part Number Ordering Information for details.

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Serial Flash Discovery Parameter Data

The serial Flash discovery parameter (SFDP) provides a standard, consistent method to describe serial Flash device functions and features using internal parameter tables. The parameter tables can be interrogated by host system software, enabling adjustments to accommodate divergent features from multiple vendors. The SFDP standard defines a common parameter table that describes important device characteristics and serial access methods used to read the parameter table data.

Micron's SFDP table information aligns with JEDEC-standard JESD216 for serial Flash discoverable parameters. The latest JEDEC standard includes revision 1.6. Beginning week 42 (2014), Micron's MT25Q production parts will include SFDP data that aligns with revision 1.6.

Refer to JEDEC-standard JESD216B for a complete overview of the SFDP table definition.

Data in the SFDP tables is read by the READ SERIAL FLASH DISCOVERY PARAMETER operation.

See Micron TN-25-06: Serial Flash Discovery Parameters for MT25Q Family for serial Flash discovery parameter data.

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Command Definitions

Table 18: Command Set

Notes 1 and 2 apply to the entire table

Command	Code	Command-Address-Data			Address Bytes	Dummy Clock Cycles			Data Bytes	Notes
		Extended -SPI	Dual -SPI	Quad -SPI		Extended -SPI	Dual -SPI	Quad -SPI		
Software RESET Operations										
RESET ENABLE	66h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
RESET MEMORY	99h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
READ ID Operations										
READ ID	9E/9Fh	1-0-1			0	0			1 to 20	–
MULTIPLE I/O READ ID	AFh	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to 20	–
READ SERIAL FLASH DISCOVERY PARAMETER	5Ah	1-1-1	2-2-2	4-4-4	3	8	8	8	1 to ∞	3
READ MEMORY Operations										
READ	03h	1-1-1			3	0	0	0	1 to ∞	–
FAST READ	0Bh	1-1-1	2-2-2	4-4-4	3	8	8	10	1 to ∞	4
DUAL OUTPUT FAST READ	3Bh	1-1-2	2-2-2		3	8	8		1 to ∞	4
DUAL INPUT/OUTPUT FAST READ	BBh	1-2-2	2-2-2		3	8	8		1 to ∞	4
QUAD OUTPUT FAST READ	6Bh	1-1-4		4-4-4	3	8		10	1 to ∞	4
QUAD INPUT/OUTPUT FAST READ	EBh	1-4-4		4-4-4	3	10		10	1 to ∞	4
DTR FAST READ	0Dh	1-1-1	2-2-2	4-4-4	3	6	6	8	1 to ∞	4
DTR DUAL OUTPUT FAST READ	3Dh	1-1-2	2-2-2		3	6	6		1 to ∞	4
DTR DUAL INPUT/OUTPUT FAST READ	BDh	1-2-2	2-2-2		3	6	6		1 to ∞	4
DTR QUAD OUTPUT FAST READ	6Dh	1-1-4		4-4-4	3	6		8	1 to ∞	4
DTR QUAD INPUT/OUTPUT FAST READ	EDh	1-4-4		4-4-4	3	8		8	1 to ∞	4
QUAD INPUT/OUTPUT WORD READ	E7h	1-4-4		4-4-4	3	4		4	1 to ∞	–
WRITE Operations										
WRITE ENABLE	06h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
WRITE DISABLE	04h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
READ REGISTER Operations										
READ STATUS REGISTER	05h	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to ∞	–

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Table 18: Command Set (Continued)

Notes 1 and 2 apply to the entire table

Command	Code	Command-Address-Data			Address Bytes	Dummy Clock Cycles			Data Bytes	Notes
		Extended -SPI	Dual -SPI	Quad -SPI		Extended -SPI	Dual -SPI	Quad -SPI		
READ FLAG STATUS REGISTER	70h	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to ∞	–
READ NONVOLATILE CONFIGURATION REGISTER	B5h	1-0-1	2-0-2	4-0-4	0	0	0	0	2 to ∞	–
READ VOLATILE CONFIGURATION REGISTER	85h	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to ∞	–
READ ENHANCED VOLATILE CONFIGURATION REGISTER	65h	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to ∞	–
READ GENERAL PURPOSE READ REGISTER	96h	1-0-1	2-0-2	4-0-4	0	8	8	8	1 to ∞	5, 6
WRITE REGISTER Operations										
WRITE STATUS REGISTER	01h	1-0-1	2-0-2	4-0-4	0	0	0	0	1	7
WRITE NONVOLATILE CONFIGURATION REGISTER	B1h	1-0-1	2-0-2	4-0-4	0	0	0	0	2	7
WRITE VOLATILE CONFIGURATION REGISTER	81h	1-0-1	2-0-2	4-0-4	0	0	0	0	1	7
WRITE ENHANCED VOLATILE CONFIGURATION REGISTER	61h	1-0-1	2-0-2	4-0-4	0	0	0	0	1	7
CLEAR FLAG STATUS REGISTER Operation										
CLEAR FLAG STATUS REGISTER	50h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
PROGRAM Operations										
PAGE PROGRAM	02h	1-1-1	2-2-2	4-4-4	3	0	0	0	1 to 256	7
DUAL INPUT FAST PROGRAM	A2h	1-1-2	2-2-2		3	0	0		1 to 256	7
EXTENDED DUAL INPUT FAST PROGRAM	D2h	1-2-2	2-2-2		3	0	0		1 to 256	7
QUAD INPUT FAST PROGRAM	32h	1-1-4		4-4-4	3	0		0	1 to 256	7
EXTENDED QUAD INPUT FAST PROGRAM	38h	1-4-4		4-4-4	3	0		0	1 to 256	7
ERASE Operations										
32KB SUBSECTOR ERASE	52h	1-1-0	2-2-0	4-4-0	3	0	0	0	0	7
4KB SUBSECTOR ERASE	20h	1-1-0	2-2-0	4-4-0	3	0	0	0	0	7
SECTOR ERASE	D8h	1-1-0	2-2-0	4-4-0	3	0	0	0	0	7

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Table 18: Command Set (Continued)

Notes 1 and 2 apply to the entire table

Command	Code	Command-Address-Data			Address Bytes	Dummy Clock Cycles			Data Bytes	Notes
		Extended -SPI	Dual -SPI	Quad -SPI		Extended -SPI	Dual -SPI	Quad -SPI		
BULK ERASE	C7h/60h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	7
SUSPEND/RESUME Operations										
PROGRAM/ERASE SUSPEND	75h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
PROGRAM/ERASE RESUME	7Ah	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
ONE-TIME PROGRAMMABLE (OTP) Operations										
READ OTP ARRAY	4Bh	1-1-1	2-2-2	4-4-4	3	8	8	10	1 to 64	4
PROGRAM OTP ARRAY	42h	1-1-1	2-2-2	4-4-4	3	0	0	0	1 to 64	7
QUAD PROTOCOL Operations										
ENTER QUAD INPUT/OUTPUT MODE	35h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
RESET QUAD INPUT/OUTPUT MODE	F5h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
DEEP POWER-DOWN Operations										
ENTER DEEP POWER-DOWN	B9h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
RELEASE FROM DEEP POWER-DOWN	ABh	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
ADVANCED SECTOR PROTECTION Operations										
READ SECTOR PROTECTION	2Dh	1-0-1	2-0-2	4-0-4	0	0	0	0	1 to ∞	–
PROGRAM SECTOR PROTECTION	2Ch	1-0-1	2-0-2	4-0-4	0	0	0	0	2	7
READ VOLATILE LOCK BITS	E8h	1-1-1	2-2-2	4-4-4	3	0	0	0	1 to ∞	8
WRITE VOLATILE LOCK BITS	E5h	1-1-1	2-2-2	4-4-4	3	0	0	0	1	7,9
READ NONVOLATILE LOCK BITS	E2h	1-1-1	2-2-2	4-4-4	4	0	0	0	1 to ∞	–
WRITE NONVOLATILE LOCK BITS	E3h	1-1-0	2-2-0	4-4-0	4	0	0	0	0	7
ERASE NONVOLATILE LOCK BITS	E4h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	7
READ GLOBAL FREEZE BIT	A7h	1-0-1			0	0	0	0	1 to ∞	–
WRITE GLOBAL FREEZE BIT	A6h	1-0-0	2-0-0	4-0-0	0	0	0	0	0	7
READ PASSWORD	27h	1-0-1			0	0	0	0	1 to ∞	–
WRITE PASSWORD	28h	1-0-1	2-0-2	4-0-4	0	0	0	0	8	7
UNLOCK PASSWORD	29h	1-0-1	2-0-2	4-0-4	0	0	0	0	8	–
ADVANCED FUNCTION INTERFACE Operations										

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Table 18: Command Set (Continued)

Notes 1 and 2 apply to the entire table

Command	Code	Command-Address-Data			Address Bytes	Dummy Clock Cycles			Data Bytes	Notes
		Extended -SPI	Dual -SPI	Quad -SPI		Extended -SPI	Dual -SPI	Quad -SPI		
INTERFACE ACTIVATION	9Bh	1-0-0	2-0-0	4-0-0	0	0	0	0	0	–
CYCLIC REDUNDANCY CHECK	9Bh/27h	1-0-1	2-0-2	4-0-4	0	0	0	0	10 or 18	–

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Notes:
1. Micron extended-SPI protocol is the standard SPI protocol with additional commands that extend functionality and enable address or data transmission on multiple DQn lines.
2. The command code is always transmitted on DQn = 1, 2, or 4 lines according to the standard, dual, or quad protocol respectively. However, a command may be able to transmit address and data on multiple DQn lines regardless of protocol. The protocol columns show the number of DQn lines a command uses to transmit command, address, and data information as shown in these examples: command-address-data = 1-1-1, or 1-2-2, or 2-4-4, and so on.
3. The number of dummy cycles for the READ SFDP command is fixed (8 dummy cycles) and is not affected by dummy cycle settings in the nonvolatile configuration register and volatile configuration register. For the max clock frequency achievable refer to Supported Clock Frequencies tables for 8 dummy cycles.
4. The number of dummy clock cycles required when shipped from Micron factories. The user can modify the dummy clock cycle number via the nonvolatile configuration register and the volatile configuration register.
5. The number of dummy cycles for the READ GENERAL PURPOSE READ REGISTER command is fixed (8 dummy cycles) and is not affected by dummy cycle settings in the nonvolatile configuration register and volatile configuration register.
6. The general purpose read register is 64 bytes. After the first 64 bytes, the device outputs 00h and does not wrap.
7. The WRITE ENABLE command must be issued first before this operation can be executed.
8. Formerly referred to as the READ LOCK REGISTER operation.
9. Formerly referred to as the WRITE LOCK REGISTER operation.

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Software RESET Operations

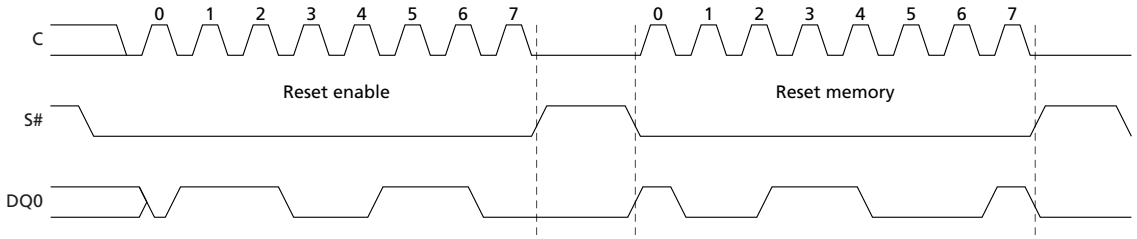
RESET ENABLE and RESET MEMORY Commands

To initiate these commands, S# is driven LOW and the command code is input on DQn. A minimum de-selection time of ^{t}SHSL2 must come between RESET ENABLE and RESET MEMORY or reset is not guaranteed. Then, S# must be driven HIGH for the device to enter power-on reset. A time of ^{t}SHSL3 is required before the device can be re-selected by driving S# LOW.

Table 19: RESET ENABLE and RESET MEMORY Operations

Operation Name	Description/Conditions
RESET ENABLE (66h)	To reset the device, the RESET ENABLE command must be followed by the RESET MEMORY command. When the two commands are executed, the device enters a power-on reset condition. It is recommended to exit XIP mode before executing these two commands. All volatile lock bits, the volatile configuration register, and the enhanced volatile configuration register are reset to the power-on reset default condition according to nonvolatile configuration register settings. If a reset is initiated while a WRITE, PROGRAM, or ERASE operation is in progress or suspended, the operation is aborted and data may be corrupted. Reset is effective after the flag status register bit 7 outputs 1 with at least one byte output. A RESET ENABLE command is not accepted during WRITE STATUS REGISTER and WRITE NONVOLATILE CONFIGURATION REGISTER operations.
RESET MEMORY (99h)	

Figure 16: RESET ENABLE and RESET MEMORY Command



Note: 1. Above timing diagram is showed for extended-SPI protocol case, however these commands are available in all protocols. In DIO-SPI protocol, the instruction bits are transmitted on both DQ0 and DQ1 pins. In QIO-SPI protocol the instruction bits are transmitted on all four data pins. In Extended-DTR-SPI protocol, the instruction bits are transmitted on DQ0 pin in double transfer rate mode. In DIO-DTR-SPI protocol, the instruction bits are transmitted on both DQ0 and DQ1 pins in double transfer rate mode. In QIO-DTR-SPI protocol, the instruction bits are transmitted on all four data pins in double transfer rate mode.

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READ ID Operations

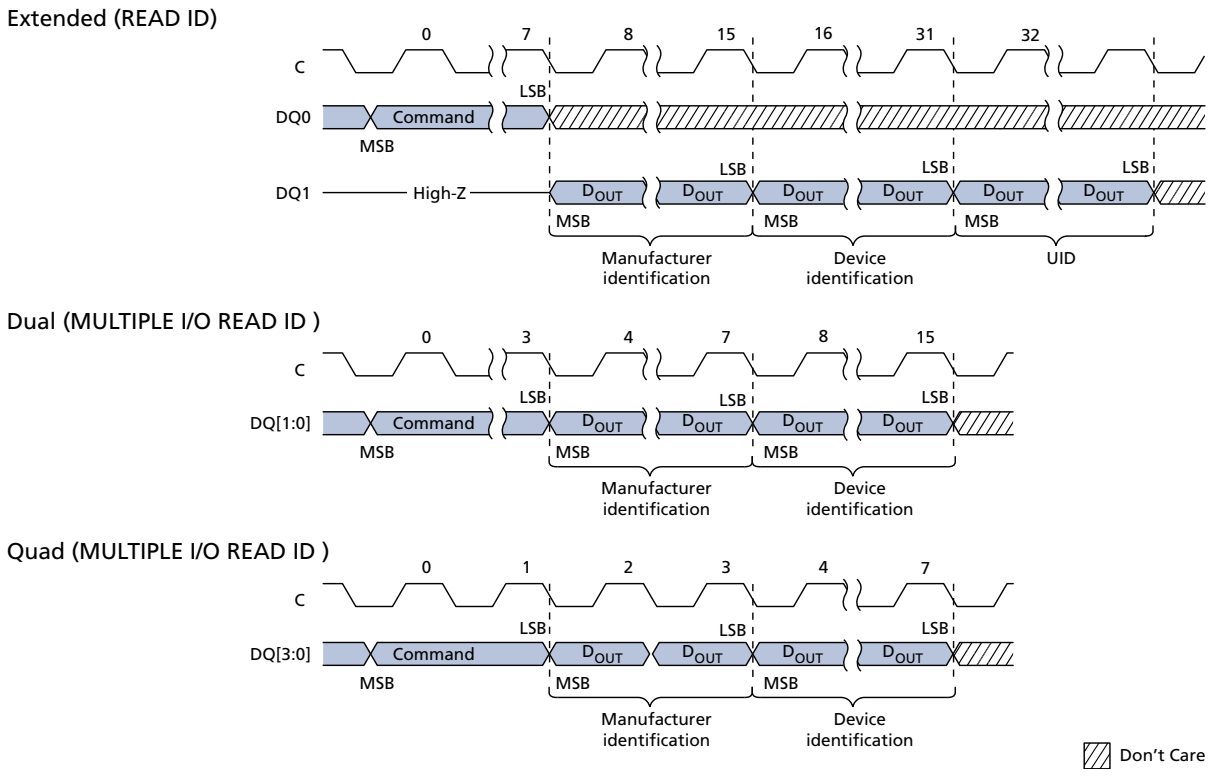
READ ID and MULTIPLE I/O READ ID Commands

To initiate these commands, S# is driven LOW and the command code is input on DQ*n*. When S# is driven HIGH, the device goes to standby. The operation is terminated by driving S# HIGH at any time during data output.

Table 20: READ ID and MULTIPLE I/O READ ID Operations

Operation Name	Description/Conditions
READ ID (9Eh/9Fh)	Outputs information shown in the Device ID Data tables. If an ERASE or PROGRAM cycle is in progress when the command is initiated, the command is not decoded and the command cycle in progress is not affected.
MULTIPLE I/O READ ID (AFh)	

Figure 17: READ ID and MULTIPLE I/O READ ID Commands



Note: 1. S# not shown.

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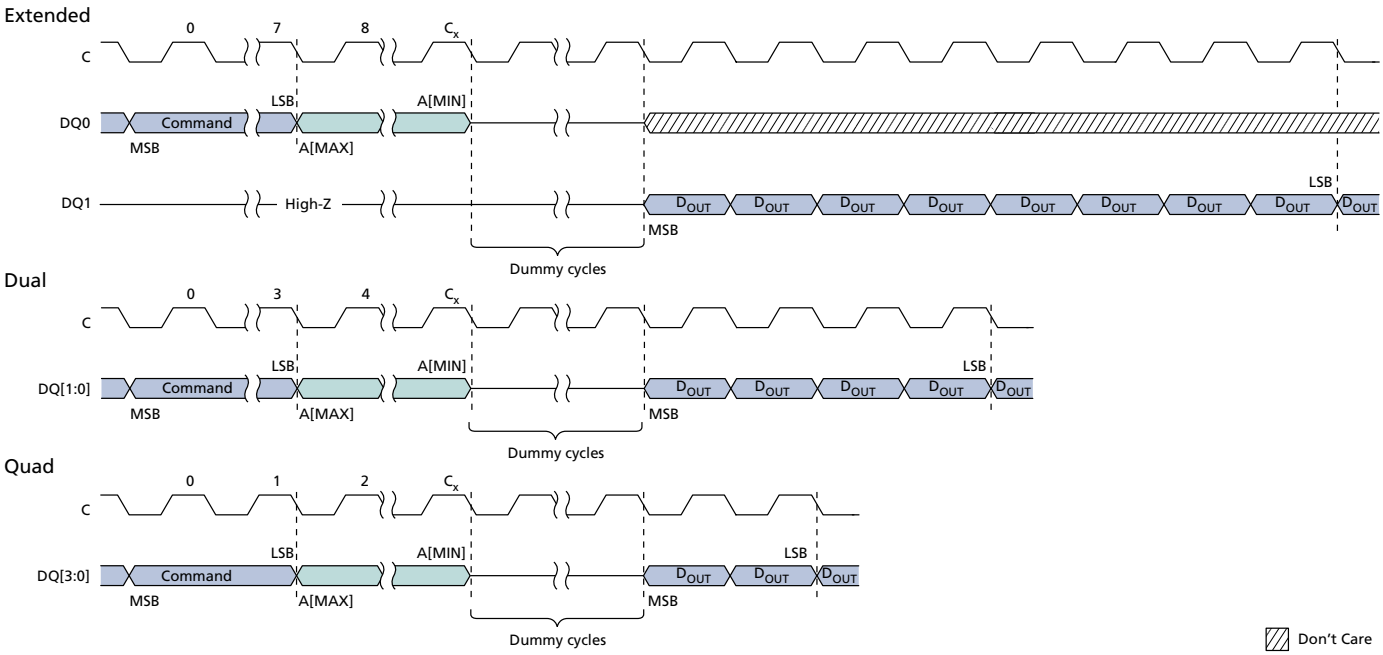
READ SERIAL FLASH DISCOVERY PARAMETER Operation

READ SERIAL FLASH DISCOVERY PARAMETER Command

To execute READ SERIAL FLASH DISCOVERY PARAMETER command, S# is driven LOW. The command code is input on DQ0, followed by three address bytes and eight dummy clock cycles. The device outputs the information starting from the specified address. When the 2048-byte boundary is reached, the data output wraps to address 0 of the serial Flash discovery parameter table. The operation is terminated by driving S# HIGH at any time during data output.

Note: The operation always executes in continuous mode so the read burst wrap setting in the volatile configuration register does not apply.

Figure 18: READ SERIAL FLASH DISCOVERY PARAMETER Command – 5Ah



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1); For dual protocol, C_x = 3 + (A[MAX] + 1)/2; For quad protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

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READ MEMORY Operations

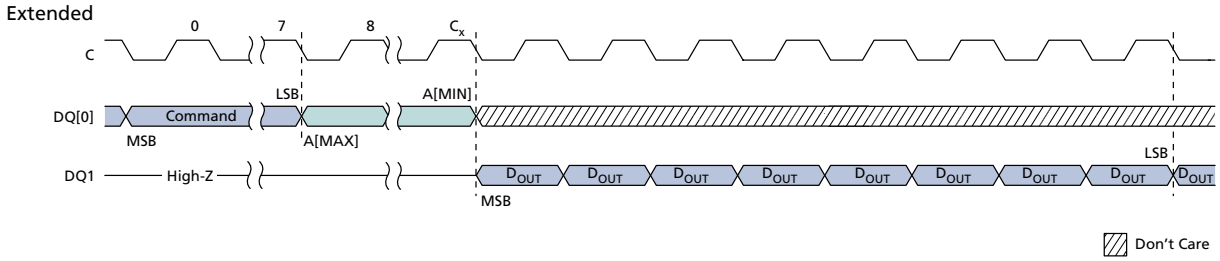
To initiate a command, S# is driven LOW and the command code is input on DQ*n*, followed by input of the address bytes on DQ*n*. The operation is terminated by driving S# HIGH at any time during data output.

Table 21: READ MEMORY Operations

Operation Name	Description/Conditions
READ (03h)	The device supports 3-byte addressing (default), with A[23:0] input during address cycle. After any READ command is executed, the device will output data from the selected address. After the boundary is reached, the device will start reading again from the beginning. Each address bit is latched in during the rising edge of the clock. The addressed byte can be at any location, and the address automatically increments to the next address after each byte of data is shifted out; therefore, a die can be read with a single command. FAST READ can operate at a higher frequency (^{f}C). DTR commands function in DTR protocol regardless of settings in the nonvolatile configuration register or enhanced volatile configuration register; other commands function in DTR protocol only after DTR protocol is enabled by the register settings. E7h is similar to the QUAD I/O FAST READ command except that the lowest address bit (A0) must equal 0 and only four dummy clocks are required prior to the data output. This command is supported in extended-SPI and quad-SPI protocols, but not in the DTR protocol; it is ignored it in dual-SPI protocol.
FAST READ (0Bh)	
DUAL OUTPUT FAST READ (3Bh)	
DUAL INPUT/OUTPUT FAST READ (BBh)	
QUAD OUTPUT FAST READ (6Bh)	
QUAD INPUT/OUTPUT FAST READ (EBh)	
DTR FAST READ (0Dh)	
DTR DUAL OUTPUT FAST READ (3Dh)	
DTR DUAL INPUT/OUTPUT FAST READ (BDh)	
DTR QUAD OUTPUT FAST READ (6Dh)	
DTR QUAD INPUT/OUTPUT FAST READ (EDh)	
QUAD INPUT/OUTPUT WORD READ (E7h)	

READ MEMORY Operations Timings

Figure 19: READ – 03h

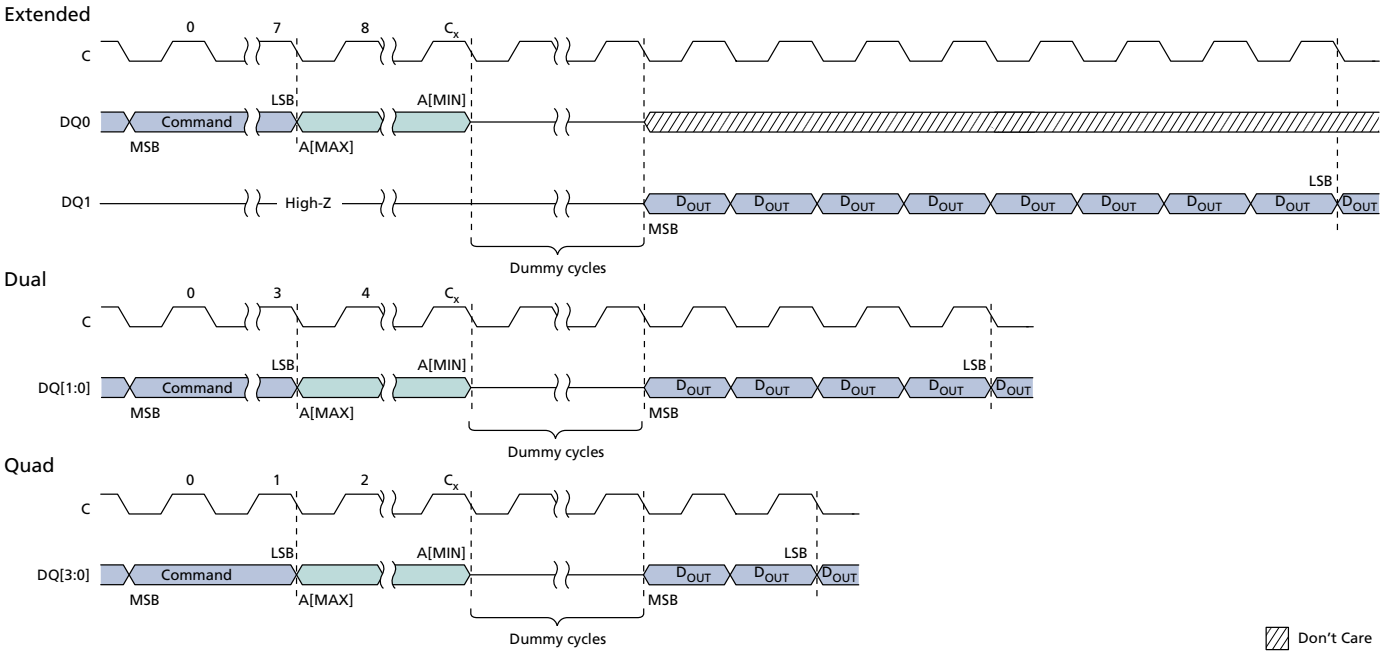


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1).
2. S# not shown.

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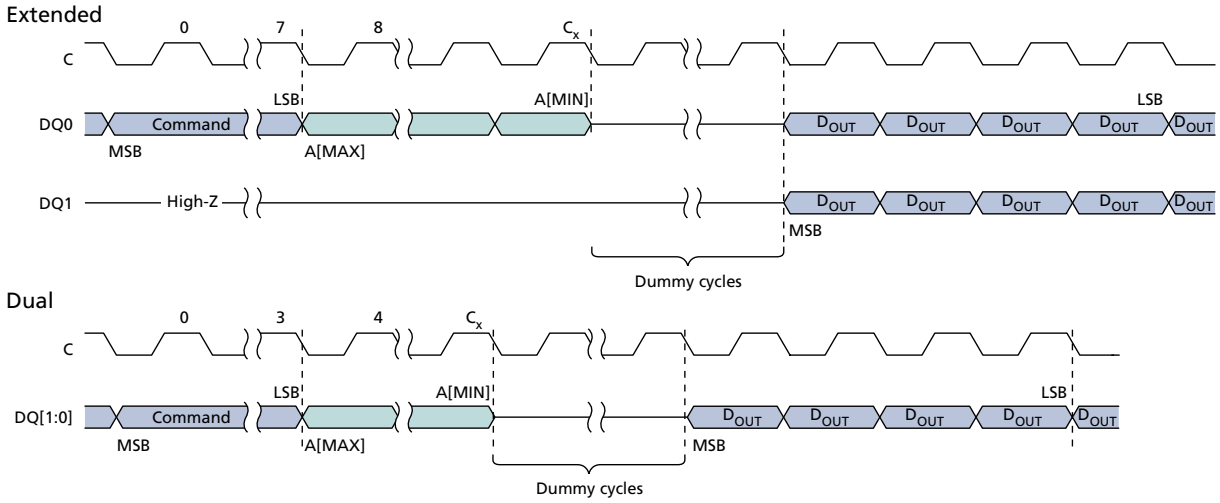
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Figure 20: FAST READ – 0Bh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1); For dual protocol, C_x = 3 + (A[MAX] + 1)/2; For quad protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

Figure 21: DUAL OUTPUT FAST READ – 3Bh

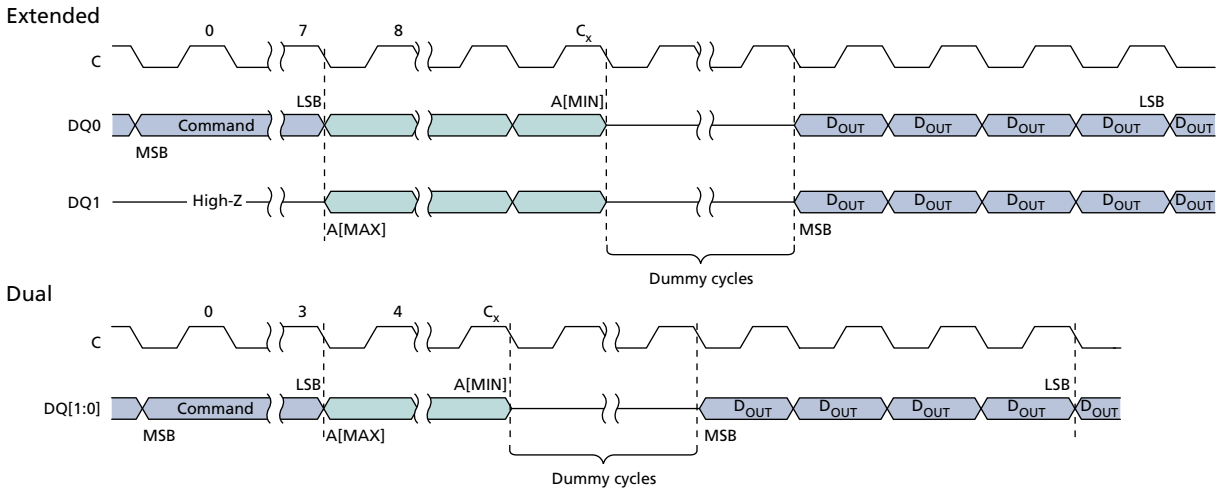


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1); For dual protocol, C_x = 3 + (A[MAX] + 1)/2.
2. S# not shown.

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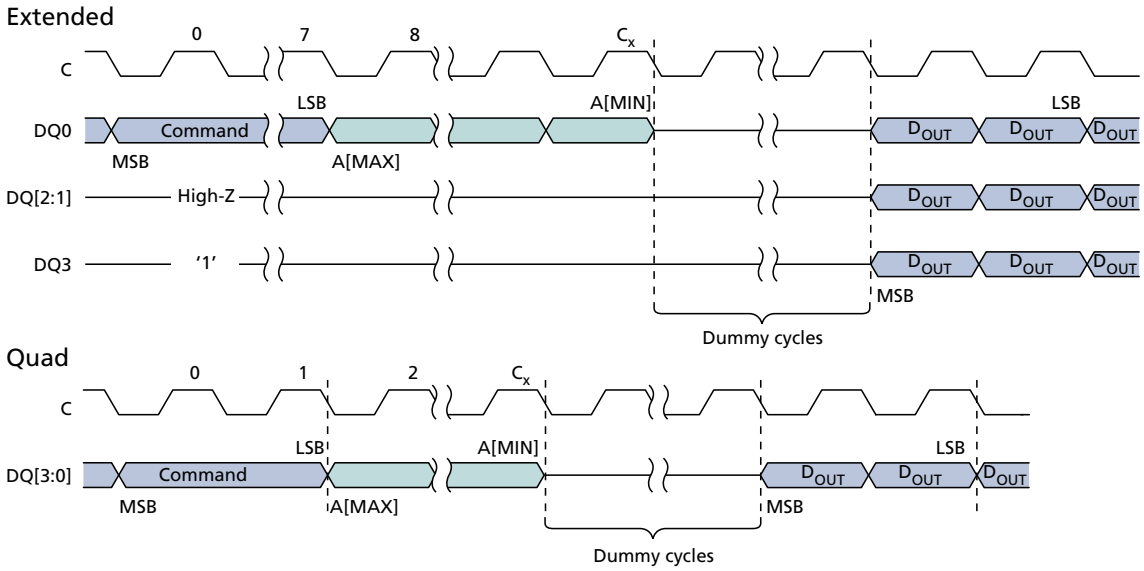
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Figure 22: DUAL INPUT/OUTPUT FAST READ – BBh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/2; For dual protocol, C_x = 3 + (A[MAX] + 1)/2.
2. S# not shown.

Figure 23: QUAD OUTPUT FAST READ – 6Bh

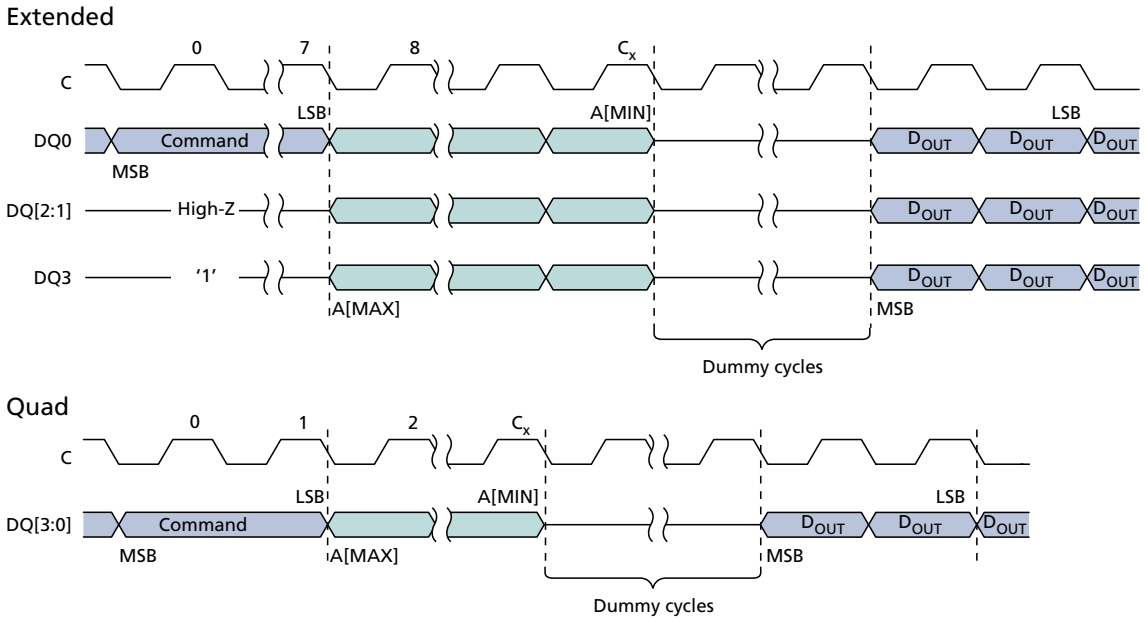


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1); For quad protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

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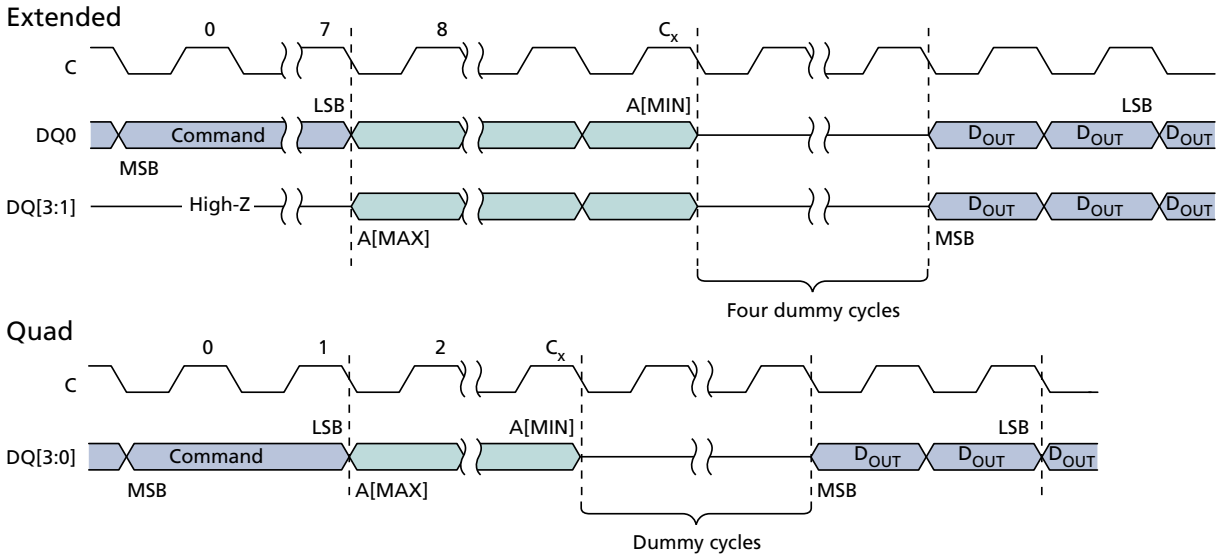
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Figure 24: QUAD INPUT/OUTPUT FAST READ – EBh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/4; For quad protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

Figure 25: QUAD INPUT/OUTPUT WORD READ – E7h

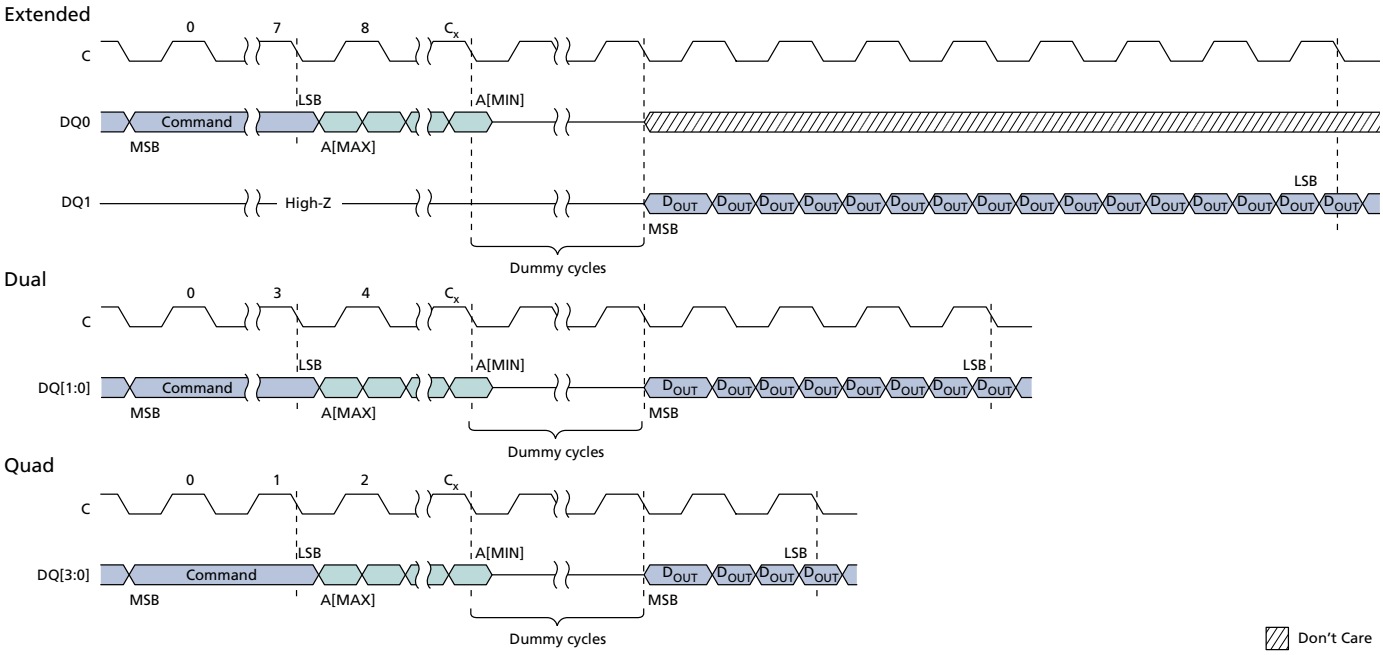


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/4; For quad protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

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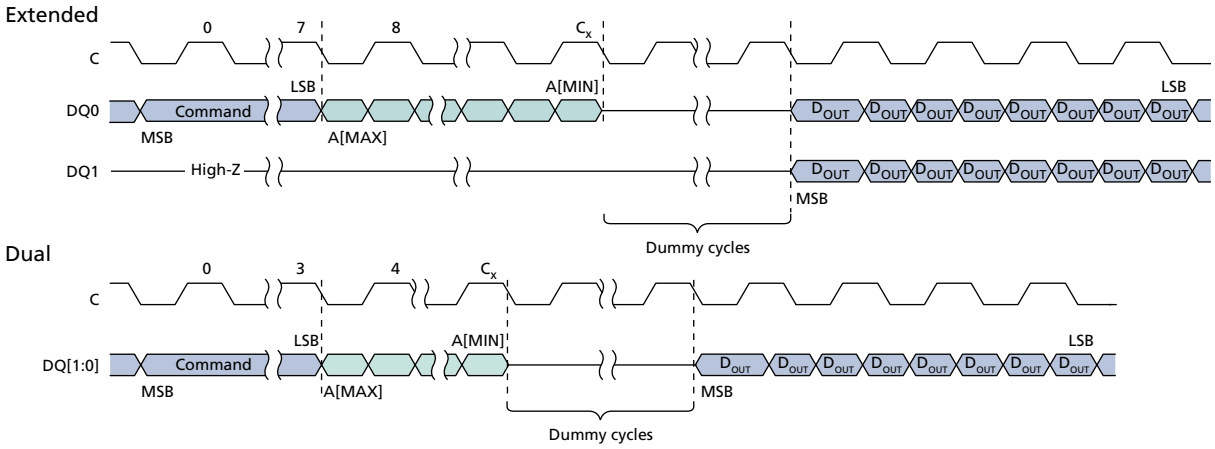
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Figure 26: DTR FAST READ – 0Dh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/2; For dual protocol, C_x = 3 + (A[MAX] + 1)/4; For quad protocol, C_x = 1 + (A[MAX] + 1)/8.
2. S# not shown.

Figure 27: DTR DUAL OUTPUT FAST READ – 3Dh

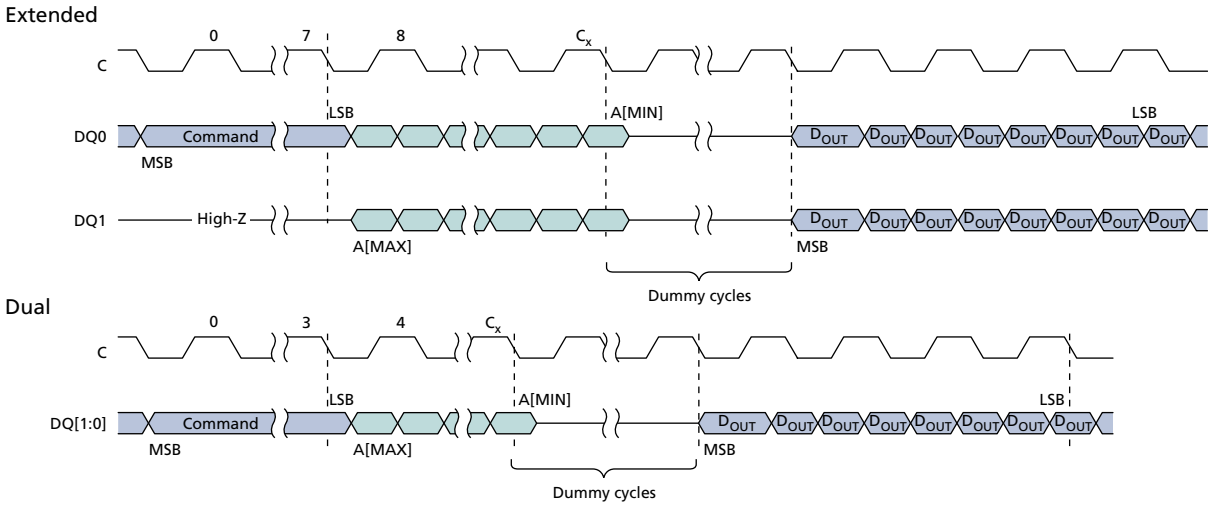


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/2; For dual protocol, C_x = 3 + (A[MAX] + 1)/4.
2. S# not shown.

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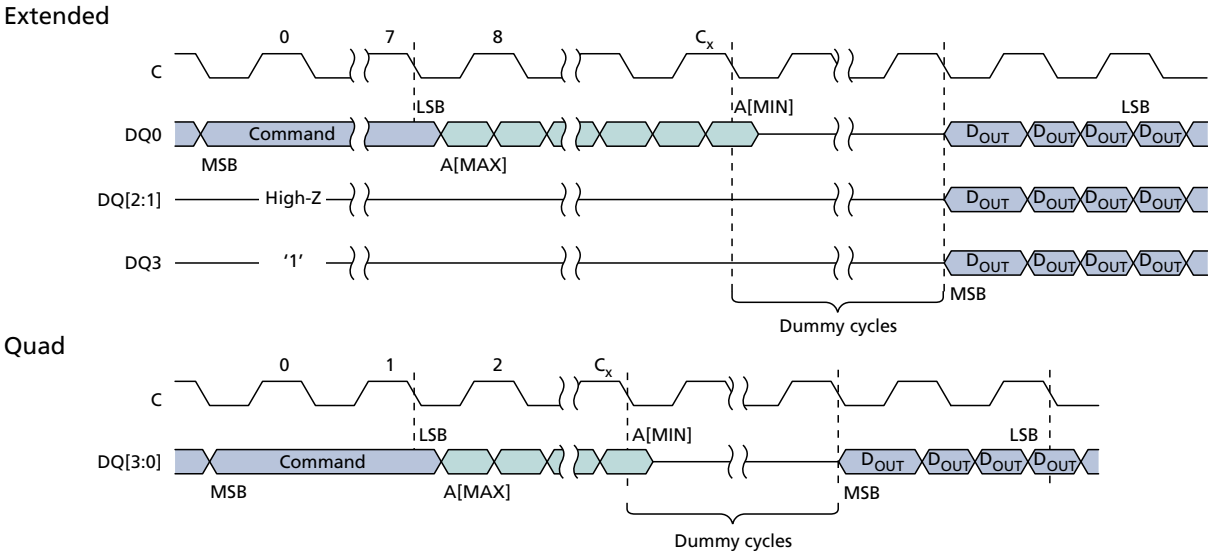
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Figure 28: DTR DUAL INPUT/OUTPUT FAST READ – BDh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/4; For dual protocol, C_x = 3 + (A[MAX] + 1)/8.
2. S# not shown.

Figure 29: DTR QUAD OUTPUT FAST READ – 6Dh

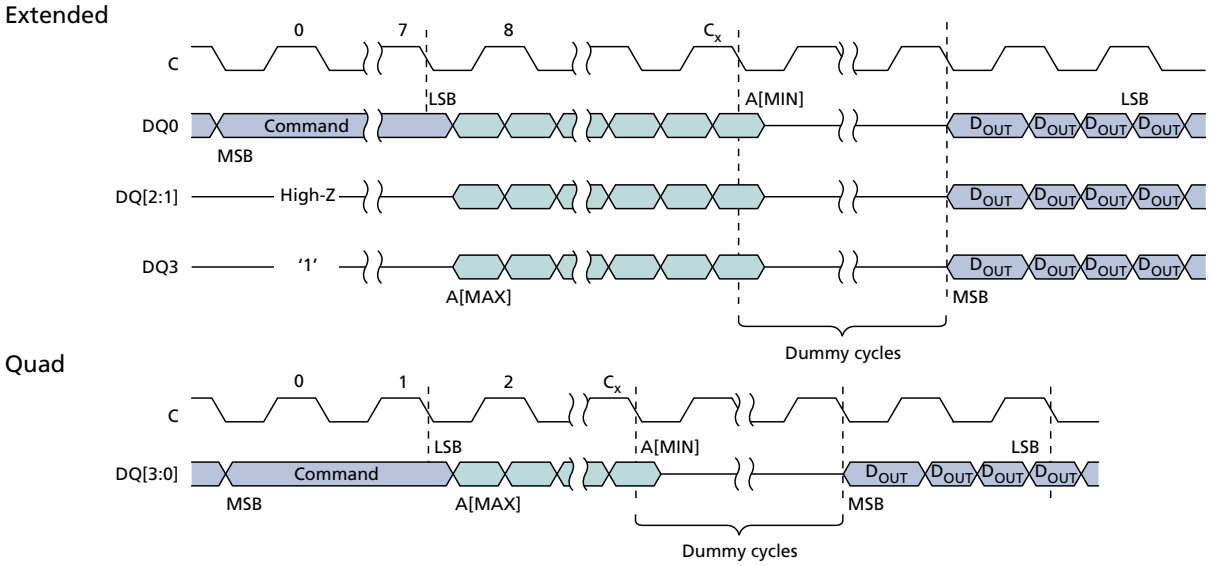


Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/2; For quad protocol, C_x = 1 + (A[MAX] + 1)/8.
2. S# not shown.

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Figure 30: DTR QUAD INPUT/OUTPUT FAST READ – EDh



Notes:
1. For extended protocol, C_x = 7 + (A[MAX] + 1)/8; For quad protocol, C_x = 1 + (A[MAX] + 1)/8.
2. S# not shown.

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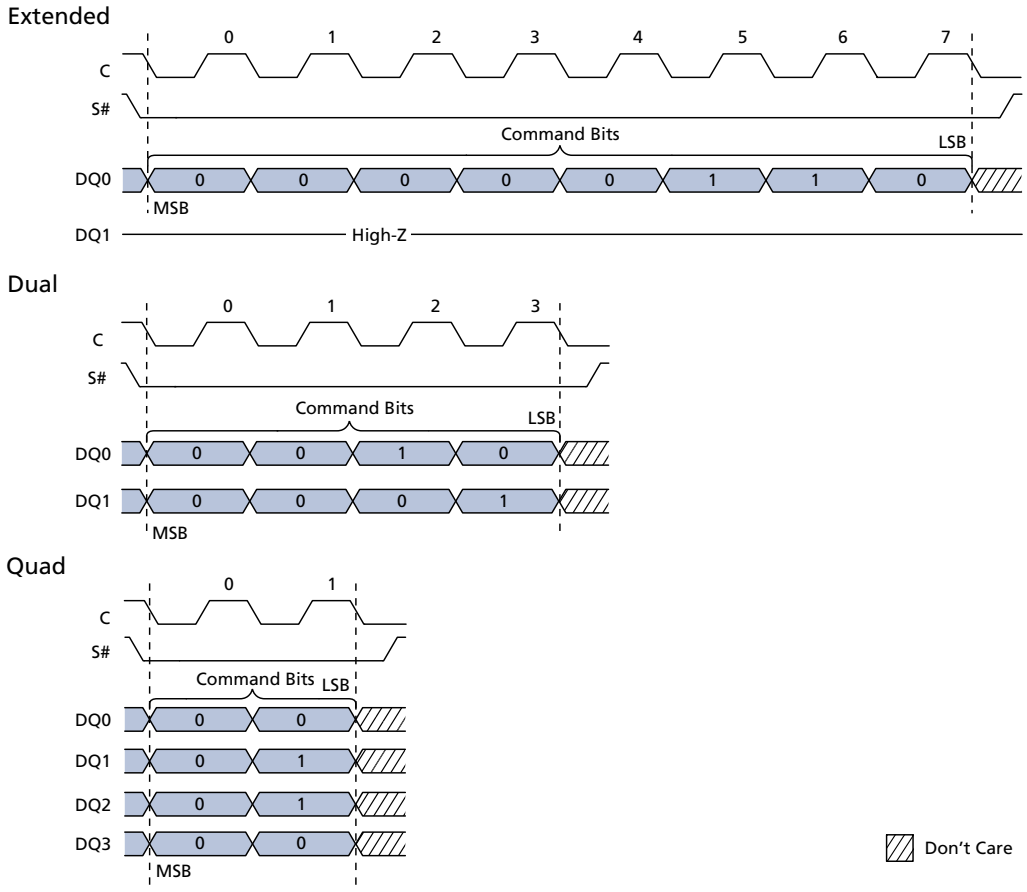
WRITE ENABLE/DISABLE Operations

To initiate a command, S# is driven LOW and held LOW until the eighth bit of the command code has been latched in, after which it must be driven HIGH. For extended-, dual-, and quad-SPI protocols respectively, the command code is input on DQ0, DQ[1:0], and DQ[3:0]. If S# is not driven HIGH after the command code has been latched in, the command is not executed, flag status register error bits are not set, and the write enable latch remains cleared to its default setting of 0, providing protection against errant data modification.

Table 22: WRITE ENABLE/DISABLE Operations

Operation Name	Description/Conditions
WRITE ENABLE (06h)	Sets the write enable latch bit before each PROGRAM, ERASE, and WRITE command.
WRITE DISABLE (04h)	Clears the write enable latch bit. In case of a protection error, WRITE DISABLE will not clear the bit. Instead, a CLEAR FLAG STATUS REGISTER command must be issued to clear both flags.

Figure 31: WRITE ENABLE and WRITE DISABLE Timing



Note: 1. WRITE ENABLE command sequence and code, shown here, is 06h (0000 0110 binary); WRITE DISABLE is identical, but its command code is 04h (0000 0100 binary).

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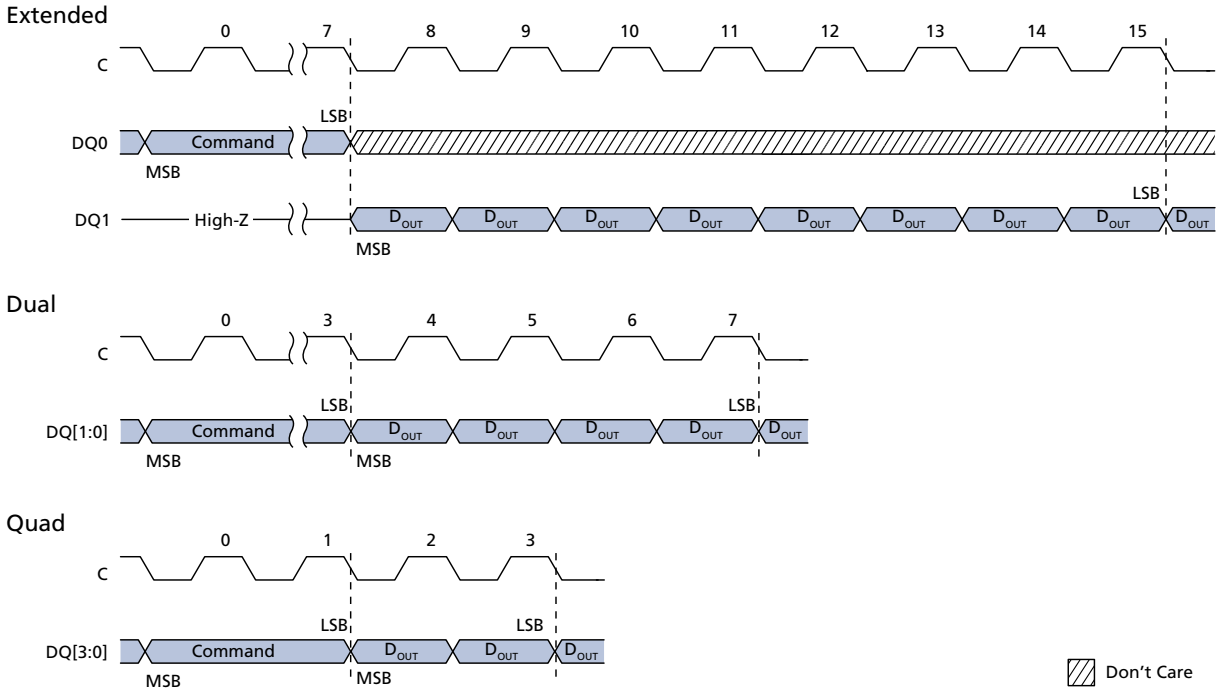
READ REGISTER Operations

To initiate a command, S# is driven LOW. For extended-SPI protocol, input is on DQ0, output on DQ1. For dual-SPI protocol, input/output is on DQ[1:0] and for quad-SPI protocol, input/output is on DQ[3:0]. The operation is terminated by driving S# HIGH at any time during data output.

Table 23: READ REGISTER Operations

Operation Name	Description/Conditions
READ STATUS REGISTER (05h)	Can be read continuously and at any time, including during a PROGRAM, ERASE, or WRITE operation. If one of these operations is in progress, checking the write in progress bit or P/E controller bit is recommended before executing the command.
READ FLAG STATUS REGISTER (70h)	
READ NONVOLATILE CONFIGURATION REGISTER (B5h)	Can be read continuously. After all 16 bits of the register have been read, a 0 is output. All reserved fields output a value of 1. **Note: The operation will have output data starting from the least significant byte.**
READ VOLATILE CONFIGURATION REGISTER (85h)	When the register is read continuously, the same byte is output repeatedly.
READ ENHANCED VOLATILE CONFIGURATION REGISTER (65h)	

Figure 32: READ REGISTER Timing



Notes:
1. Supports all READ REGISTER commands except DYNAMIC PROTECTION BITS READ.
2. A READ NONVOLATILE CONFIGURATION REGISTER operation will output data starting from the least significant byte.
3. S# not shown.

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WRITE REGISTER Operations

Before a WRITE REGISTER command is initiated, the WRITE ENABLE command must be executed to set the write enable latch bit to 1. To initiate a command, S# is driven LOW and held LOW until the eighth bit of the last data byte has been latched in, after which it must be driven HIGH; for the WRITE NONVOLATILE CONFIGURATION REGISTER command, S# is held LOW until the 16th bit of the last data byte has been latched in. For the extended-, dual-, and quad-SPI protocols respectively, input is on DQ0, DQ[1:0], and DQ[3:0], followed by the data bytes. If S# is not driven HIGH, the command is not executed, flag status register error bits are not set, and the write enable latch remains set to 1. The operation is self-timed and its duration is ^{t}W for WRITE STATUS REGISTER and $^{t}NVCR$ for WRITE NONVOLATILE CONFIGURATION REGISTER.

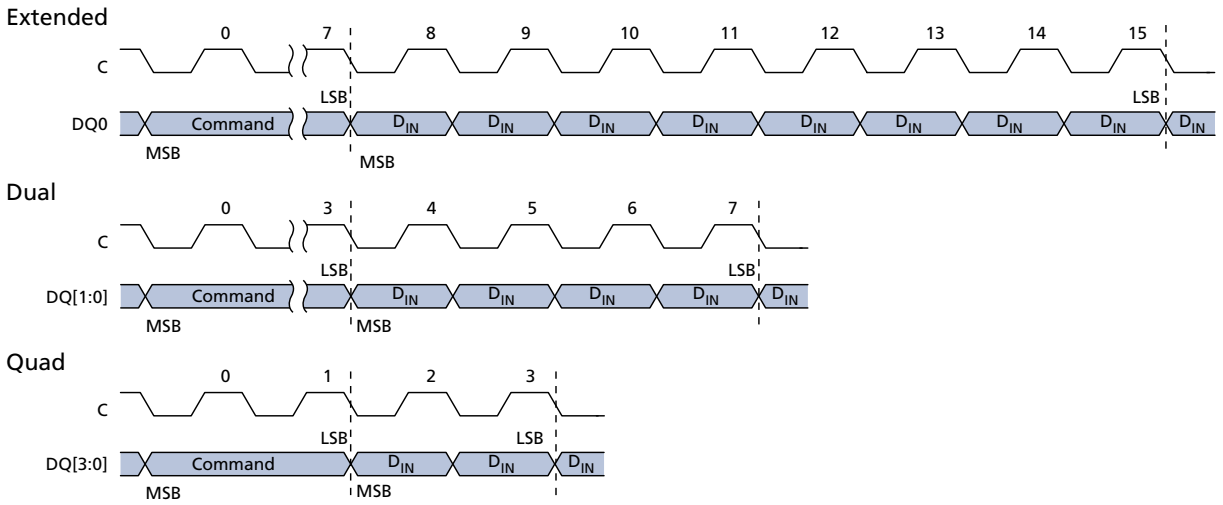
Table 24: WRITE REGISTER Operations

Operation Name	Description/Conditions
WRITE STATUS REGISTER (01h)	The WRITE STATUS REGISTER command writes new values to status register bits 7:2, enabling software data protection. The status register can also be combined with the W# signal to provide hardware data protection. This command has no effect on status register bits 1:0.
WRITE NONVOLATILE CONFIGURATION REGISTER (B1h)	For the WRITE STATUS REGISTER and WRITE NONVOLATILE CONFIGURATION REGISTER commands, when the operation is in progress, the write in progress bit is set to 1. The write enable latch bit is cleared to 0, whether the operation is successful or not. The status register and flag status register can be polled for the operation status. When the operation completes, the write in progress bit is cleared to 0, whether the operation is successful or not. **Note: The WRITE NONVOLATILE CONFIGURATION REGISTER operation must have input data starting from the least significant byte.**
WRITE VOLATILE CONFIGURATION REGISTER (81h)	Because register bits are volatile, change to the bits is immediate. Reserved bits are not affected by this command.
WRITE ENHANCED VOLATILE CONFIGURATION REGISTER (61h)	

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Figure 33: WRITE REGISTER Timing



Notes:
1. Supports all WRITE REGISTER commands except WRITE LOCK REGISTER.
2. Data is two bytes for a WRITE NONVOLATILE CONFIGURATION REGISTER operation, input starting from the least significant byte.
3. S# not shown.

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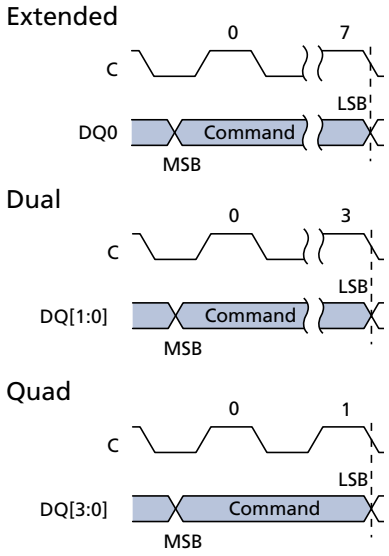
CLEAR FLAG STATUS REGISTER Operation

To initiate a command, S# is driven LOW. For the extended-, dual-, and quad-SPI protocols respectively, input is on DQ0, DQ[1:0], and DQ[3:0]. The operation is terminated by driving S# HIGH at any time.

Table 25: CLEAR FLAG STATUS REGISTER Operation

Operation Name	Description/Conditions
CLEAR FLAG STATUS REGISTER (50h)	Resets the error bits (erase, program, and protection)

Figure 34: CLEAR FLAG STATUS REGISTER Timing



Note: 1. S# not shown.

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PROGRAM Operations

Before a PROGRAM command is initiated, the WRITE ENABLE command must be executed to set the write enable latch bit to 1. To initiate a command, S# is driven LOW and held LOW until the eighth bit of the last data byte has been latched in, after which it must be driven HIGH. If S# is not driven HIGH, the command is not executed, flag status register error bits are not set, and the write enable latch remains set to 1. Each address bit is latched in during the rising edge of the clock. When a command is applied to a protected sector, the command is not executed, the write enable latch bit remains set to 1, and flag status register bits 1 and 4 are set. If the operation times out, the write enable latch bit is reset and the program fail bit is set to 1.

Note: The manner of latching data shown and explained in the timing diagrams ensures that the number of clock pulses is a multiple of one byte before command execution, helping reduce the effects of noisy or undesirable signals and enhancing device data protection.

Table 26: PROGRAM Operations

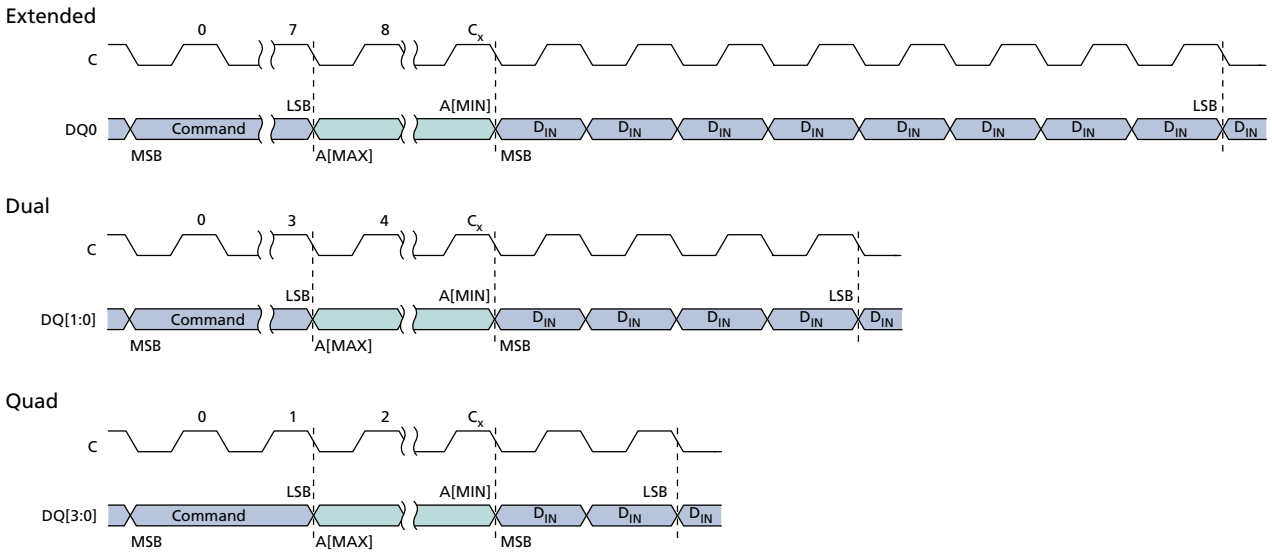
Operation Name	Description/Conditions
PAGE PROGRAM (02h)	A PROGRAM operation changes a bit from 1 to 0. When the operation is in progress, the write in progress bit is set to 1. The write enable latch bit is cleared to 0, whether the operation is successful or not. The status register and flag status register can be polled for the operation status. When the operation completes, the write in progress bit is cleared to 0. An operation can be paused or resumed by the PROGRAM/ERASE SUSPEND or PROGRAM/ERASE RESUME command, respectively. If the bits of the least significant address, which is the starting address, are not all zero, all data transmitted beyond the end of the current page is programmed from the starting address of the same page. If the number of bytes sent to the device exceed the maximum page size, previously latched data is discarded and only the last maximum page-size number of data bytes are guaranteed to be programmed correctly within the same page. If the number of bytes sent to the device is less than the maximum page size, they are correctly programmed at the specified addresses without any effect on the other bytes of the same page.
DUAL INPUT FAST PROGRAM (A2h)	
EXTENDED DUAL INPUT FAST PROGRAM (D2h)	
QUAD INPUT FAST PROGRAM (32h)	
EXTENDED QUAD INPUT FAST PROGRAM (38h)	

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PROGRAM Operations Timings

Figure 35: PAGE PROGRAM Command

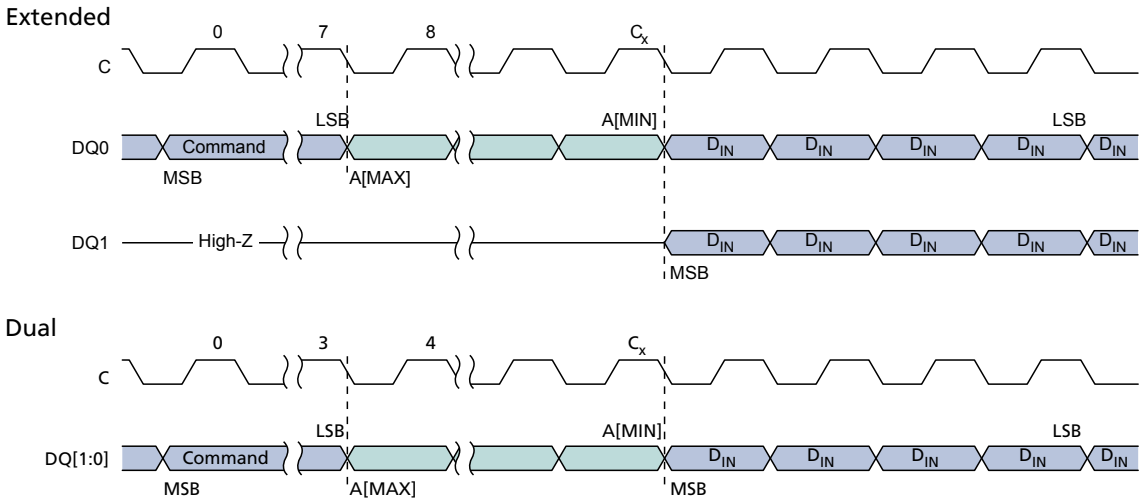


Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2; For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown. The operation is self-timed, and its duration is ^{t}PP.

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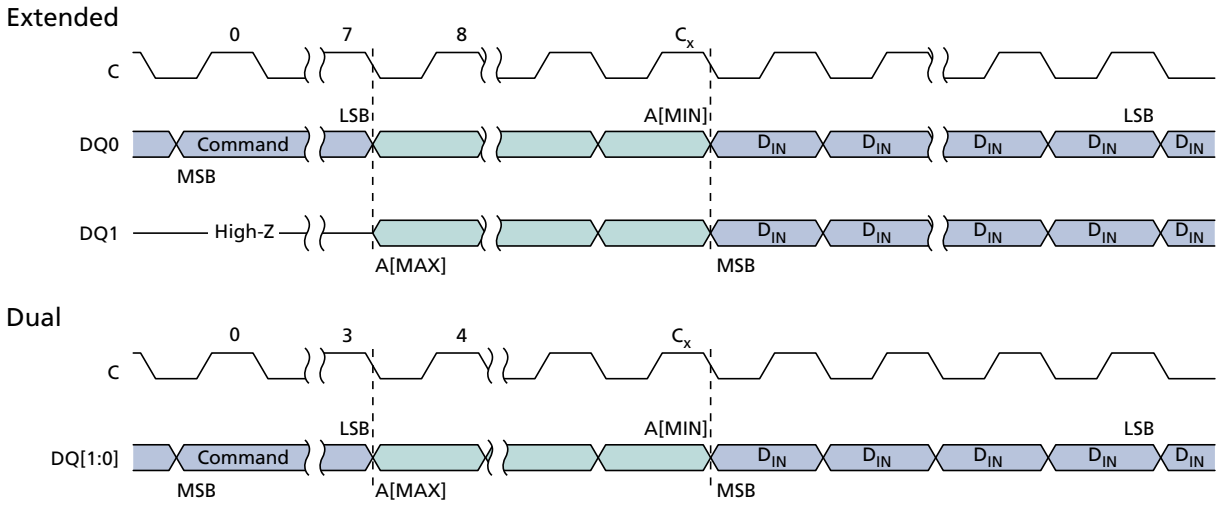
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Figure 36: DUAL INPUT FAST PROGRAM Command



Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2.
2. S# not shown.

Figure 37: EXTENDED DUAL INPUT FAST PROGRAM Command

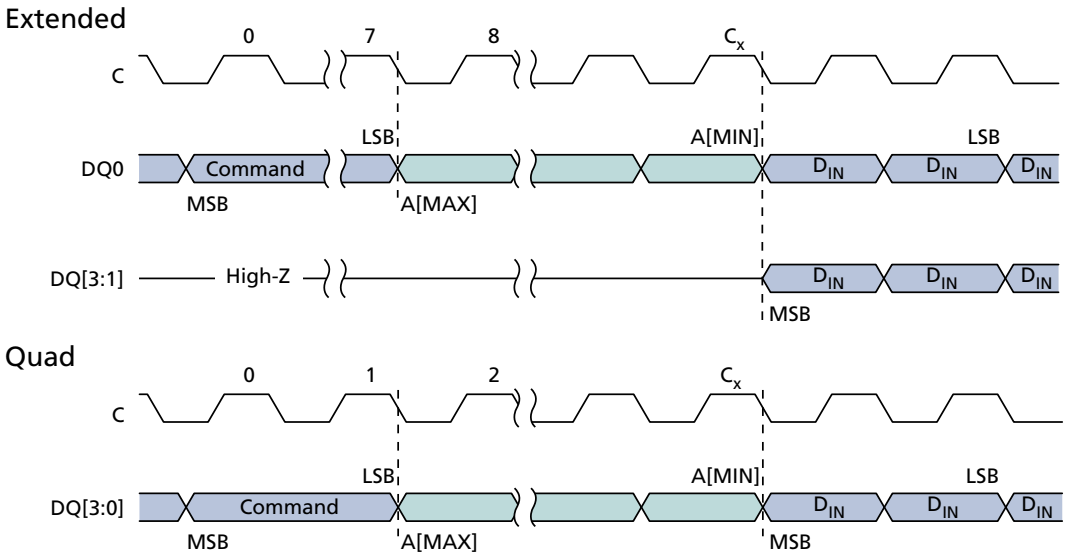


Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1)/2; For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2.
2. S# not shown.

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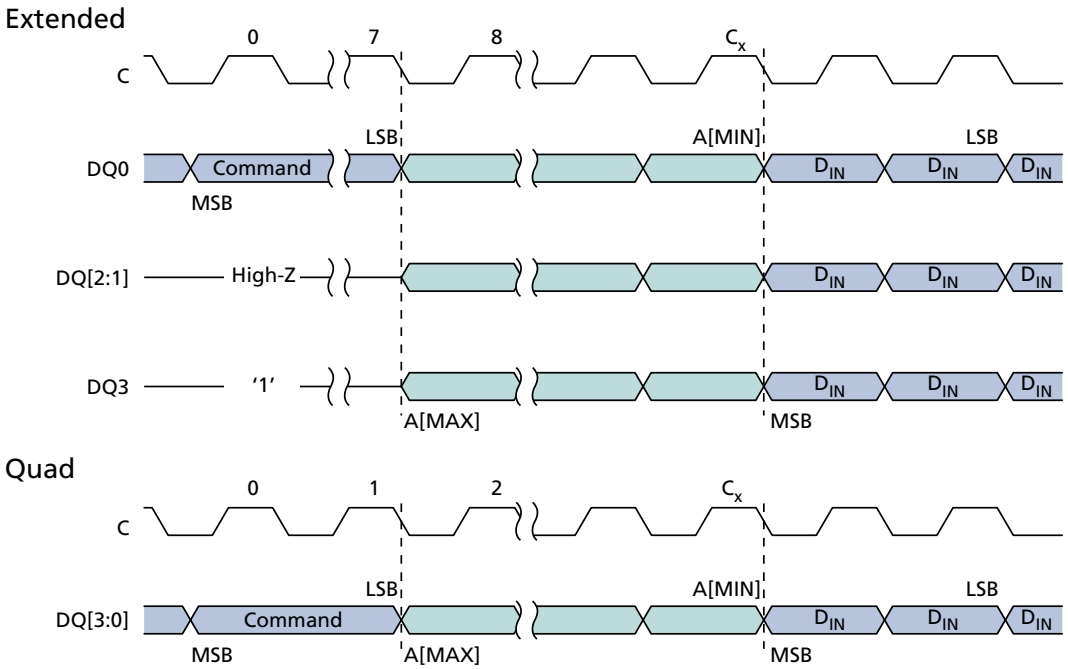
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Figure 38: QUAD INPUT FAST PROGRAM Command



Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

Figure 39: EXTENDED QUAD INPUT FAST PROGRAM Command



Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1)/4; For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

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ERASE Operations

An ERASE operation changes a bit from 0 to 1. Before any ERASE command is initiated, the WRITE ENABLE command must be executed to set the write enable latch bit to 1; if not, the device ignores the command and no error bits are set to indicate operation failure. S# is driven LOW and held LOW until the eighth bit of the last data byte has been latched in, after which it must be driven HIGH. The operations are self-timed, and duration is ^{t}SSE, ^{t}SE, or ^{t}BE according to command.

If S# is not driven HIGH, the command is not executed, flag status register error bits are not set, and the write enable latch remains set to 1. A command applied to a protected subsector is not executed. Instead, the write enable latch bit remains set to 1, and flag status register bits 1 and 5 are set.

When the operation is in progress, the program or erase controller bit of the flag status register is set to 0. In addition, the write in progress bit is set to 1. When the operation completes, the write in progress bit is cleared to 0. The write enable latch bit is cleared to 0, whether the operation is successful or not. If the operation times out, the write enable latch bit is reset and the erase error bit is set to 1.

The status register and flag status register can be polled for the operation status. When the operation completes, these register bits are cleared to 1.

Note: For all ERASE operations, noisy or undesirable signal effects can be reduced and device data protection enhanced by holding S# LOW until the eighth bit of the last data byte has been latched in; this ensures that the number of clock pulses is a multiple of one byte before command execution.

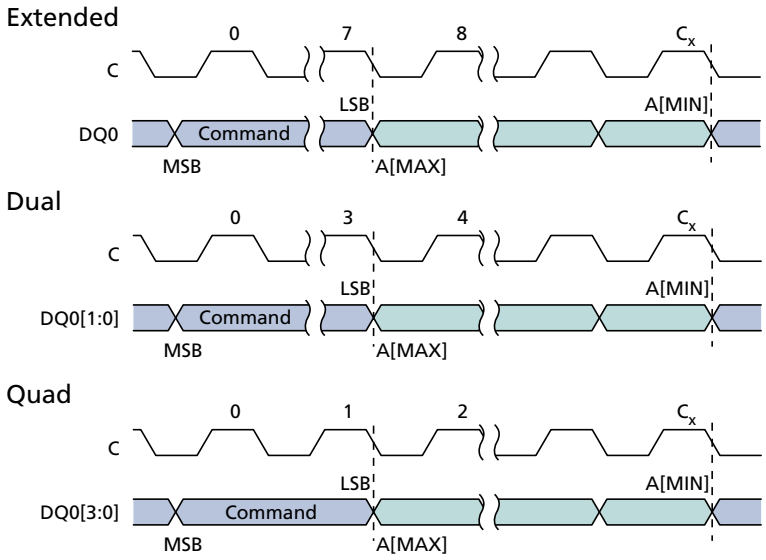
Table 27: ERASE Operations

Operation Name	Description/Conditions
SUBSECTOR ERASE (52h/20h)	Sets the selected subsector or sector bits to FFh. Any address within the subsector is valid for entry. Each address bit is latched in during the rising edge of the clock. The operation can be suspended and resumed by the PROGRAM/ERASE SUSPEND and PROGRAM/ERASE RESUME commands, respectively.
SECTOR ERASE (D8h)	
BULK ERASE (C7h/60h)	Sets the device bits to FFh. The command is not executed if any sector is locked. Instead, the write enable latch bit remains set to 1, and flag status register bits 1 and 5 are set.

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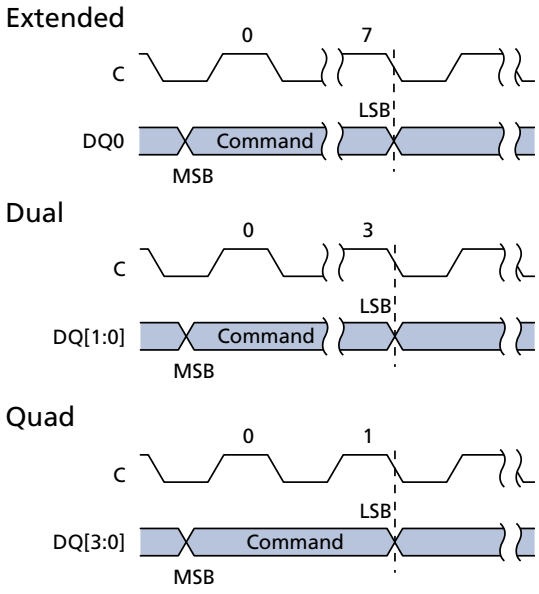
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Figure 40: SUBSECTOR and SECTOR ERASE Timing



Notes:
1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2; For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.
2. S# not shown.

Figure 41: BULK ERASE Timing



Note:
1. S# not shown.

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SUSPEND/RESUME Operations

PROGRAM/ERASE SUSPEND Operations

A PROGRAM/ERASE SUSPEND command enables the memory controller to interrupt and suspend an array PROGRAM or ERASE operation within the program/erase latency. To initiate the command, S# is driven LOW, and the command code is input on DQn. The operation is terminated by the PROGRAM/ERASE RESUME command.

For a PROGRAM SUSPEND, the flag status register bit 2 is set to 1. For an ERASE SUSPEND, the flag status register bit 6 is set to 1.

After an erase/program latency time, the flag status register bit 7 is also set to 1, but the device is considered in suspended state once bit 7 of the flag status register outputs 1 with at least one byte output. In the suspended state, the device is waiting for any operation.

If the time remaining to complete the operation is less than the suspend latency, the device completes the operation and clears the flag status register bits 2 or 6, as applicable. Because the suspend state is volatile, if there is a power cycle, the suspend state information is lost and the flag status register powers up as 80h.

It is possible to nest a PROGRAM/ERASE SUSPEND operation inside a PROGRAM/ERASE SUSPEND operation just once. Issue an ERASE command and suspend it. Then issue a PROGRAM command and suspend it also. With the two operations suspended, the next PROGRAM/ERASE RESUME command resumes the latter operation, and a second PROGRAM/ERASE RESUME command resumes the former (or first) operation.

PROGRAM/ERASE RESUME Operations

A PROGRAM/ERASE RESUME operation terminates the PROGRAM/ERASE RESUME command. To initiate the command, S# is driven LOW, and the command code is input on DQn. The operation is terminated by driving S# HIGH.

Table 28: SUSPEND/RESUME Operations

Operation Name	Description/Conditions
PROGRAM SUSPEND (75h)	A READ operation is possible in any page except the one in a suspended state. Reading from a sector that is in a suspended state will output indeterminate data.
ERASE SUSPEND (75h)	A PROGRAM or READ operation is possible in any sector except the one in a suspended state. Reading from a sector that is in a suspended state will output indeterminate data. During a SUSPEND SUBSECTOR ERASE operation, reading an address in the sector that contains the suspended subsector could output indeterminate data. The device ignores a PROGRAM command to a sector that is in an erase suspend state; it also sets the flag status register bit 4 to 1 (program failure/protection error) and leaves the write enable latch bit unchanged. When the ERASE resumes, it does not check the new lock status of the WRITE VOLATILE LOCK BITS command.

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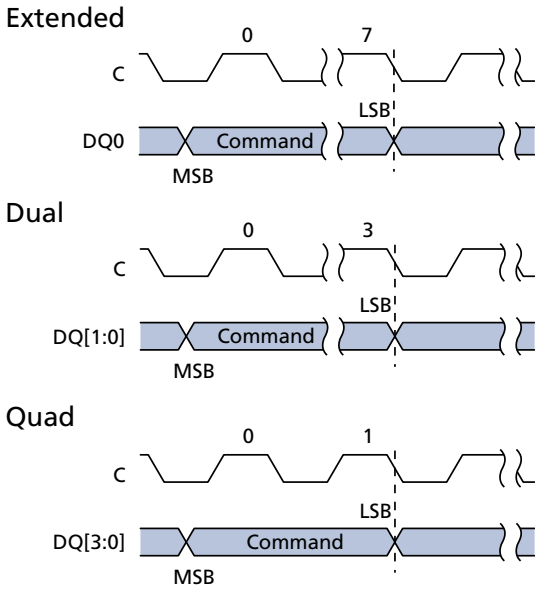
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Table 28: SUSPEND/RESUME Operations (Continued)

Operation Name	Description/Conditions
PROGRAM RESUME (7Ah)	The status register write in progress bit is set to 1 and the flag status register program erase controller bit is set to 0. The command is ignored if the device is not in a suspended state. When the operation is in progress, the program or erase controller bit of the flag status register is set to 0. The flag status register can be polled for the operation status. When the operation completes, that bit is cleared to 1.
ERASE RESUME (7Ah)	

Note: 1. See the Operations Allowed/Disallowed During Device States table.

Figure 42: PROGRAM/ERASE SUSPEND and RESUME Timing



Note: 1. S# not shown.

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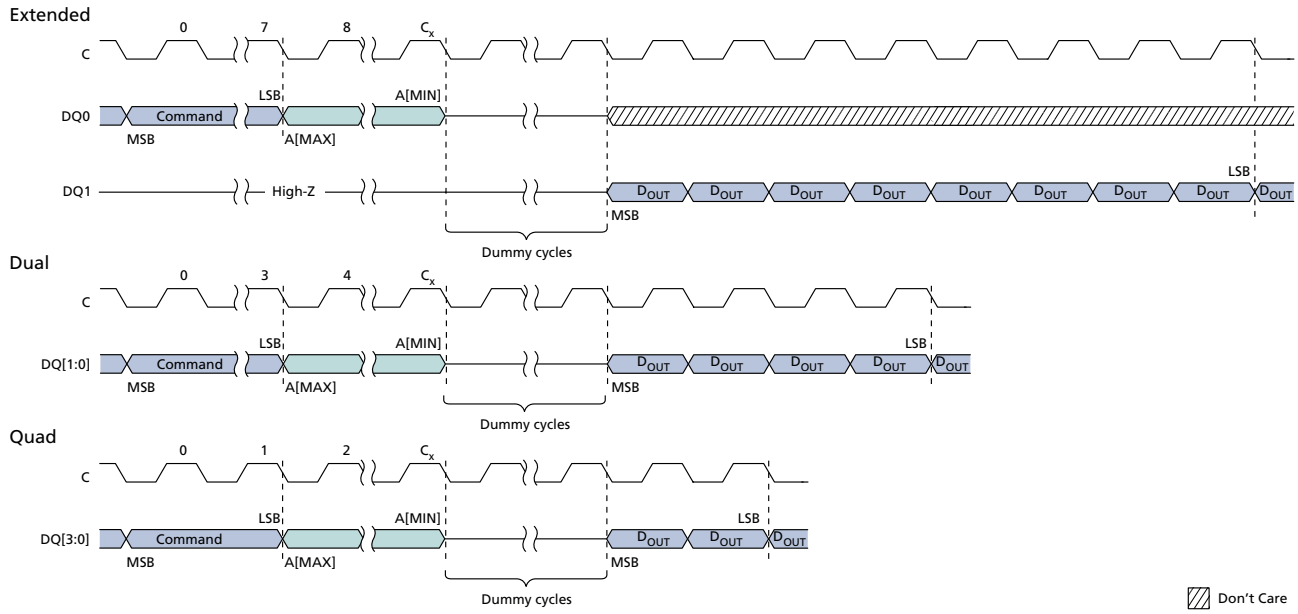
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ONE-TIME PROGRAMMABLE Operations

READ OTP ARRAY Command

To initiate a READ OTP ARRAY command, S# is driven LOW. The command code is input on DQ0, followed by address bytes and dummy clock cycles. Each address bit is latched in during the rising edge of C. Data is shifted out on DQ1, beginning from the specified address and at a maximum frequency of ^{f}C (MAX) on the falling edge of the clock. The address increments automatically to the next address after each byte of data is shifted out. There is no rollover mechanism; therefore, if read continuously, after location 0x40, the device continues to output data at location 0x40. The operation is terminated by driving S# HIGH at any time during data output.

Figure 43: READ OTP ARRAY Command Timing



Note: 1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2; For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.

PROGRAM OTP ARRAY Command

To initiate the PROGRAM OTP ARRAY command, the WRITE ENABLE command must be issued to set the write enable latch bit to 1; otherwise, the PROGRAM OTP ARRAY command is ignored and flag status register bits are not set. S# is driven LOW and held LOW until the eighth bit of the last data byte has been latched in, after which it must be driven HIGH. The command code is input on DQ0, followed by address bytes and at least one data byte. Each address bit is latched in during the rising edge of the clock. When S# is driven HIGH, the operation, which is self-timed, is initiated; its duration is ^{t}POTP. There is no rollover mechanism; therefore, after a maximum of 65 bytes are latched in the subsequent bytes are discarded.

PROGRAM OTP ARRAY programs, at most, 64 bytes to the OTP memory area and one OTP control byte. When the operation is in progress, the write in progress bit is set to 1.

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The write enable latch bit is cleared to 0, whether the operation is successful or not, and the status register and flag status register can be polled for the operation status. When the operation completes, the write in progress bit is cleared to 0.

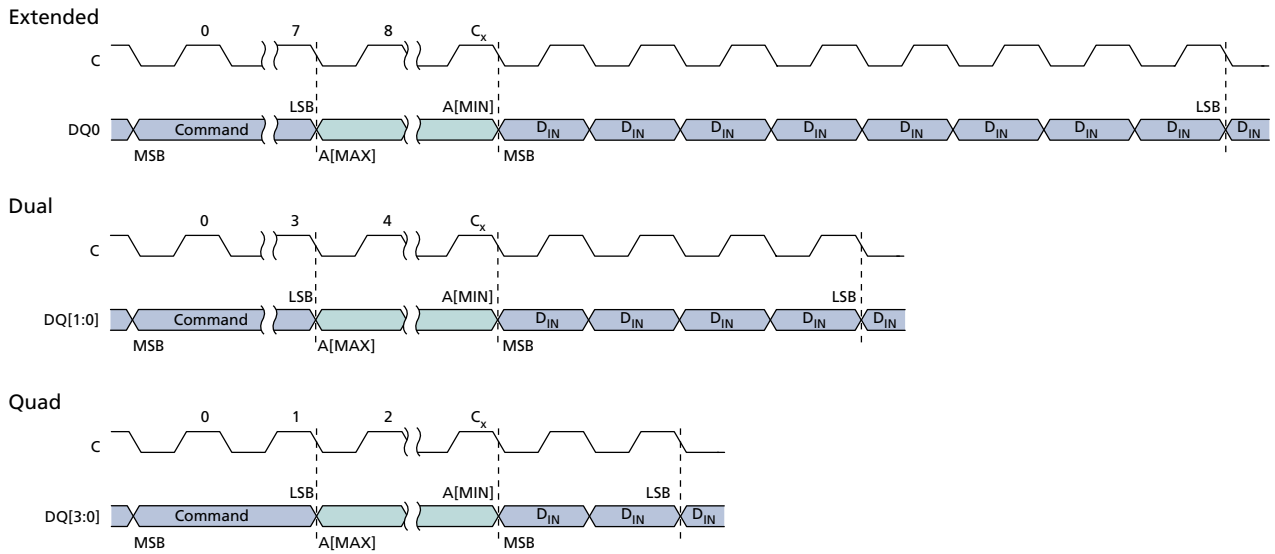
If the operation times out, the write enable latch bit is reset and the program fail bit is set to 1. If S# is not driven HIGH, the command is not executed, flag status register error bits are not set, and the write enable latch remains set to 1. The operation is considered complete once bit 7 of the flag status register outputs 1 with at least one byte output.

The OTP control byte (byte 64) is used to permanently lock the OTP memory array.

Table 29: OTP Control Byte (Byte 64)

Bit	Name	Settings	Description
0	OTP control byte	0 = Locked 1 = Unlocked (default)	Used to permanently lock the 64-byte OTP array. When bit 0 = 1, the 64-byte OTP array can be programmed. When bit 0 = 0, the 64-byte OTP array is read only. Once bit 0 has been programmed to 0, it can no longer be changed to 1. Program OTP array is ignored, the write enable latch bit remains set, and flag status register bits 1 and 4 are set.

Figure 44: PROGRAM OTP Command Timing



Note: 1. For extended-SPI protocol, C_x = 7 + (A[MAX] + 1); For dual-SPI protocol, C_x = 3 + (A[MAX] + 1)/2; For quad-SPI protocol, C_x = 1 + (A[MAX] + 1)/4.

DEEP POWER-DOWN Operations

ENTER DEEP POWER-DOWN Command

To execute ENTER DEEP POWER-DOWN, S# must be driven HIGH after the eighth bit of the command code is latched in, after which, ^{t}DP time must elapse before the supply

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current is reduced to $I_{CC2.}$. Any attempt to execute ENTER DEEP POWER-DOWN during a WRITE operation is rejected without affecting the operation.

In deep power-down mode, no device error bits are set, the WEL state is unchanged, and the device ignores all commands except RELEASE FROM DEEP POWER-DOWN, RESET ENABLE, RESET, hardware reset, and power-loss rescue sequence commands.

RELEASE FROM DEEP POWER-DOWN Command

To execute the RELEASE FROM DEEP POWER-DOWN command, S# is driven LOW, followed by the command code. Sending additional clock cycles on C while S# is driven LOW voids the command.

RELEASE FROM DEEP POWER-DOWN is terminated by driving S# HIGH. The device enters standby mode after S# is driven HIGH followed by a delay of ^{t}RDP. S# must remain HIGH during this time.

Table 30: DEEP POWER-DOWN Operations

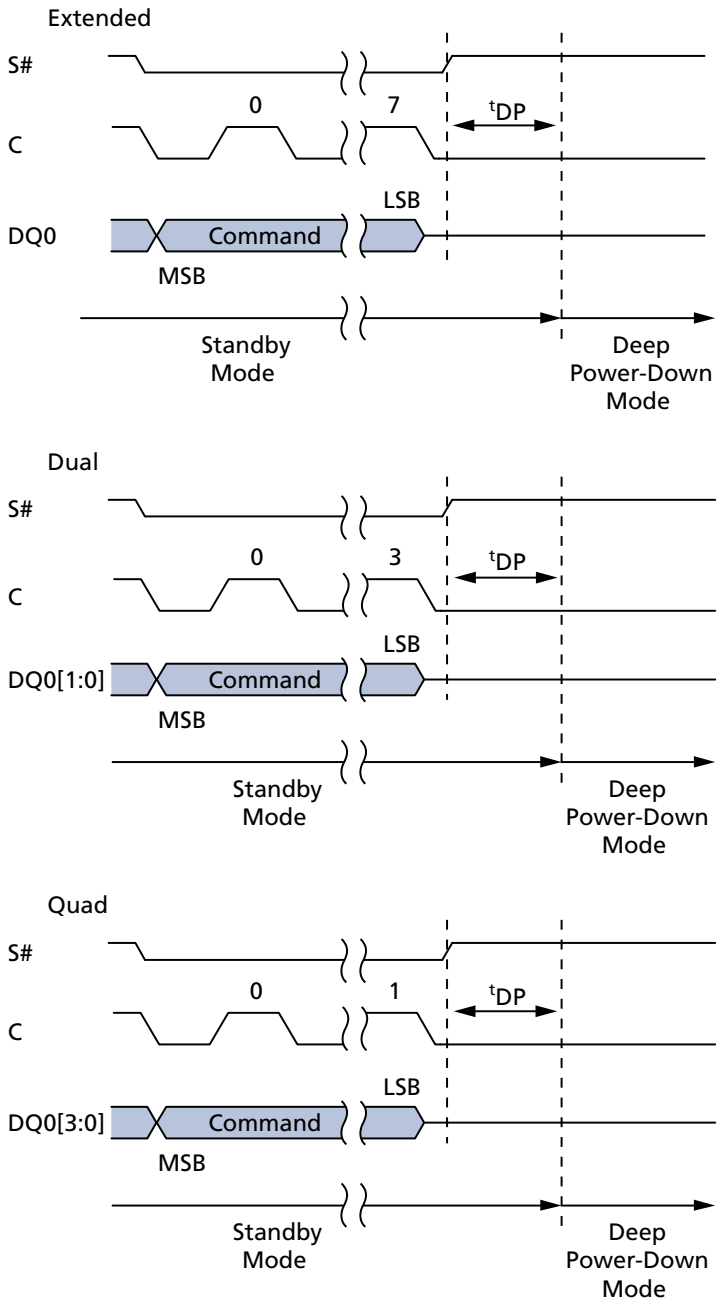
Operation Name	Description/Conditions
ENTER DEEP POWER-DOWN (B9h)	The command is used to place the device in deep power-down mode for the lowest device power consumption, with device current reduced to $I_{CC2.}$ This command can also be used as a software protection mechanism while the device is not in active use.
RELEASE FROM DEEP POWER-DOWN (ABh)	The command is used to exit from deep power-down mode. The device also exits deep power-down mode upon: A power-down, entering standby mode with the next power-up. A hardware or software reset operation, entering standby mode with a recovery time as specified in the AC Reset Specifications.

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DEEP POWER-DOWN Timings

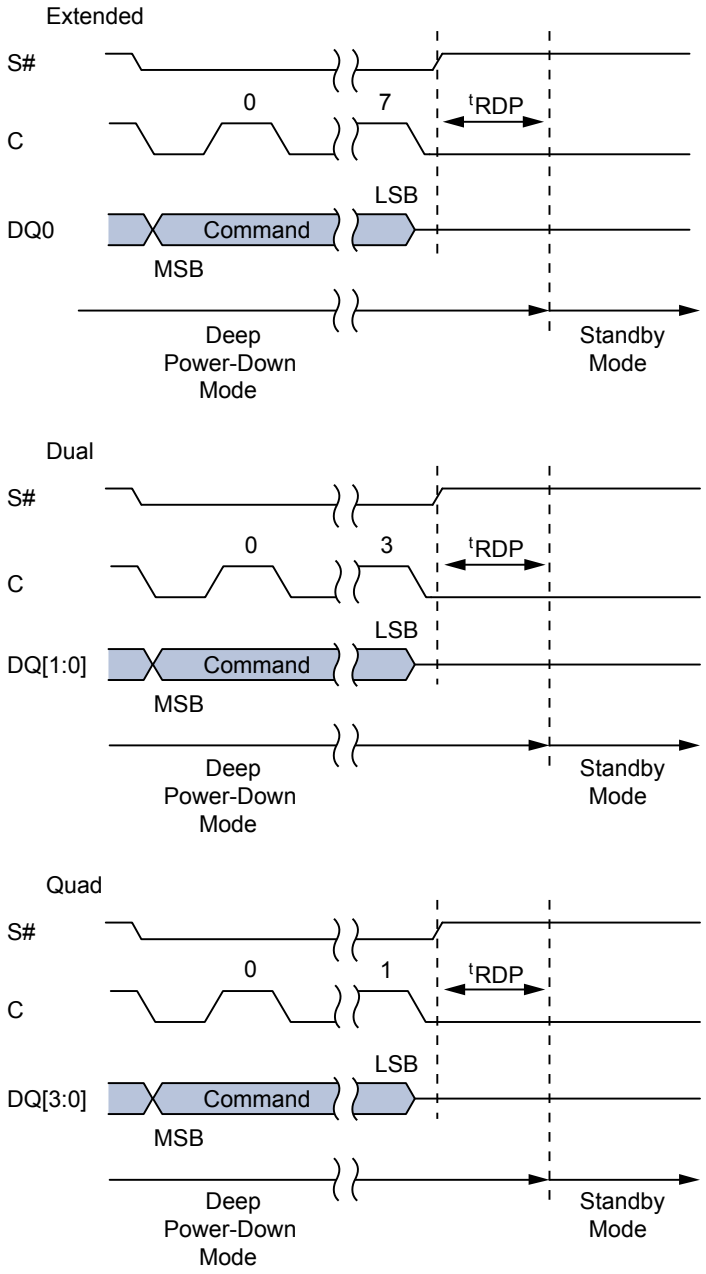
Figure 45: ENTER DEEP POWER-DOWN Timing



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Figure 46: RELEASE FROM DEEP POWER-DOWN Timing



QUAD PROTOCOL Operations

ENTER or RESET QUAD INPUT/OUTPUT MODE Command

To initiate these commands, the WRITE ENABLE command must not be executed. S# must be driven LOW, and the command must be input on DQ*n*.

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Table 31: ENTER and RESET QUAD PROTOCOL Operations

Operation Name	Description/Conditions
ENTER QUAD INPUT/OUTPUT MODE (35h)	The effect of the command is immediate.
RESET QUAD INPUT/OUTPUT MODE (F5h)	

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CYCLIC REDUNDANCY CHECK Operations

A CYCLIC REDUNDANCY CHECK (CRC) operation is a hash function designed to detect accidental changes to raw data and is used commonly in digital networks and storage devices such as hard disk drives. A CRC-enabled device calculates a short, fixed-length binary sequence, known as the CRC code or just CRC, for each block of data. CRC can be a higher performance alternative to reading data directly in order to verify recently programmed data. Or, it can be used to check periodically the data integrity of a large block of data against a stored CRC reference over the life of the product. CRC helps improve test efficiency for programmer or burn-in stress tests. No system hardware changes are required to enable CRC.

The CRC-64 operation follows the ECMA standard. The generating polynomial is:

$$G(x) = x^{64} + x^{62} + x^{57} + x^{55} + x^{54} + x^{53} + x^{52} + x^{47} + x^{46} + x^{45} + x^{40} + x^{39} + x^{38} + x^{37} + x^{35} + x^{33}$$

$$+ x^{32} + x^{31} + x^{29} + x^{27} + x^{24} + x^{23} + x^{22} + x^{21} + x^{19} + x^{17} + x^{13} + x^{12} + x^{10} + x^{9} + x^{7} + x^{4} + x + 1$$

Note: The data stream sequence is from LSB to MSB and the default initial CRC value is all zero.

The device CRC operation generates the CRC result of the entire device or of an address range specified by the operation. Then the CRC result is compared with the expected CRC data provided in the sequence. Finally the device indicates a pass or fail through the bit #4 of FLAG STATUS REGISTER. If the CRC fails, it is possible to take corrective action such as verifying with a normal read mode or by rewriting the array data.

CRC operation supports CRC data read back when CRC check fails; the CRC data generated from the target address range or entire device will be stored in a dedicated register: general purpose read register (GPRR) only when CRC check fails, and it can be read out through the GPRR read sequence with command 96h, least significant byte first. GPRR is reset to default all 0 at the beginning of the CRC operation, and so customer will read all 0 if CRC operation pass.

Note that the GPRR is a volatile register. It is cleared to all 0s on power-up and hardware/software reset. Read GPRR starts from the first location, when clocked continuously, will output 00h after location 64.

The CYCLIC REDUNDANCY CHECK operation command sequences are shown in the tables below, for an entire die or for a selected range.

Table 32: CRC Command Sequence on Entire Device

Command Sequence		Description
Byte#	Data	
1	9Bh	Command code for interface activation
2	27h	Sub-command code for CRC operation
3	FFh	CRC operation option selection (CRC operation on entire device)
4	CRC[7:0]	1st byte of expected CRC value
5–10	CRC[55:8]	2nd to 7th byte of expected CRC value
11	CRC[63:56]	8th byte of expected CRC value
Drive S# HIGH		Operation sequence confirmed; CRC operation starts

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Table 33: CRC Command Sequence on a Range

Command Sequence		Description
Byte#	Data	
1	9Bh	Command code for interface activation
2	27h	Sub-command code for CRC operation
3	FEh	CRC operation option selection (CRC operation on a range)
4	CRC[7:0]	1st byte of expected CRC value
5–10	CRC[55:8]	2nd to 7th byte of expected CRC value
11	CRC[63:56]	8th byte of expected CRC value
12	Start Address [7:0]	Specifies the starting byte address for CRC operation
13–14	Start Address [23:8]	
15	Start Address [31:24]	
16	Stop Address [7:0]	Specifies the ending byte address for CRC operation
17–18	Stop Address [23:8]	
19	Stop Address [31:24]	
Drive S# HIGH		Operation sequence confirmed; CRC operation starts

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State Table

The device can be in only one state at a time. Depending on the state of the device, some operations as shown in the table below are allowed (Yes) and others are not (No). For example, when the device is in the standby state, all operations except SUSPEND are allowed in any sector. For all device states except the erase suspend state, if an operation is allowed or disallowed in one sector, it is allowed or disallowed in all other sectors. In the erase suspend state, a PROGRAM operation is allowed in any sector except the one in which an ERASE operation has been suspended.

Table 34: Operations Allowed/Disallowed During Device States

Operation	Standby State	Program or Erase State	Subsector Erase Suspend or Program Suspend State	Erase Suspend State	Notes
READ (memory)	Yes	No	Yes	Yes	1
READ (status/flag status registers)	Yes	Yes	Yes	Yes	6
PROGRAM	Yes	No	No	Yes/No	2
ERASE (sector/subsector)	Yes	No	No	No	3
WRITE	Yes	No	No	No	4
WRITE	Yes	No	Yes	Yes	5
SUSPEND	No	Yes	No	No	7

Notes:
1. All READ operations except READ STATUS REGISTER and READ FLAG REGISTER. When issued to a sector or subsector that is simultaneously in an erase suspend state, the READ operation is accepted, but the data output is not guaranteed until the erase has completed.
2. All PROGRAM operations except PROGRAM OTP. In the erase suspend state, a PROGRAM operation is allowed in any sector (Yes) except the sector (No) in which an ERASE operation has been suspended.
3. Applies to the SECTOR ERASE or SUBSECTOR ERASE operation.
4. Applies to the following operations: WRITE STATUS REGISTER, WRITE NONVOLATILE CONFIGURATION REGISTER, PROGRAM OTP, and BULK ERASE.
5. Applies to the WRITE VOLATILE CONFIGURATION REGISTER, WRITE ENHANCED VOLATILE CONFIGURATION REGISTER, WRITE ENABLE, WRITE DISABLE, CLEAR FLAG STATUS REGISTER, or WRITE LOCK REGISTER operation.
6. Applies to the READ STATUS REGISTER or READ FLAG STATUS REGISTER operation.
7. Applies to the PROGRAM SUSPEND or ERASE SUSPEND operation.

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XIP Mode

Execute-in-place (XIP) mode allows the memory to be read by sending an address to the device and then receiving the data on one, two, or four pins in parallel, depending on the customer requirements. XIP mode offers maximum flexibility to the application, saves instruction overhead, and reduces random access time.

Activate and Terminate XIP Using Volatile Configuration Register

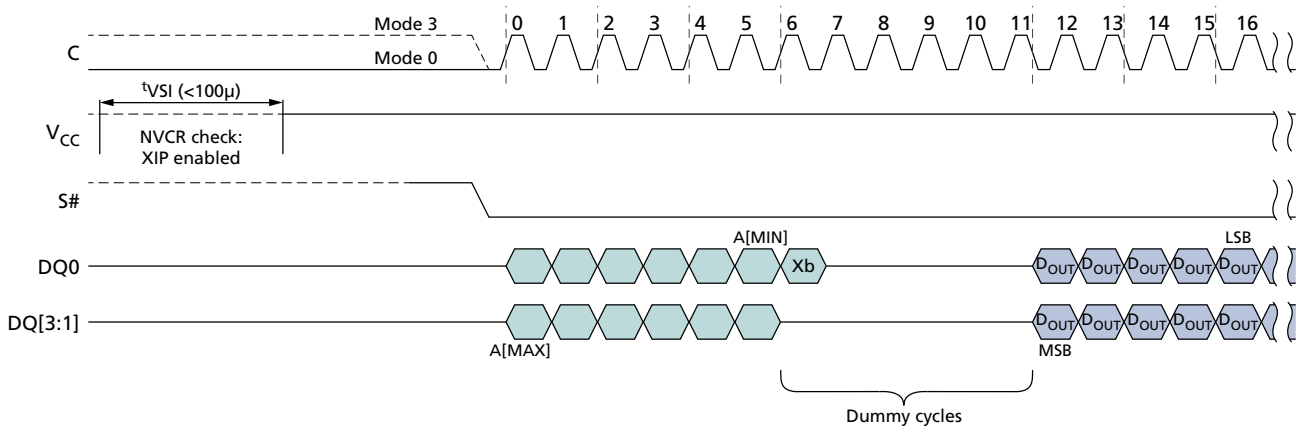
Applications that boot in SPI and must switch to XIP use the volatile configuration register. XIP provides faster memory READ operations by requiring only an address to execute, rather than a command code and an address.

To activate XIP requires two steps. First, enable XIP by setting volatile configuration register bit 3 to 0. Next, drive the XIP confirmation bit to 0 during the next FAST READ operation. XIP is then active. Once in XIP, any command that occurs after S# is toggled requires only address bits to execute; a command code is not necessary, and device operations use the SPI protocol that is enabled. XIP is terminated by driving the XIP confirmation bit to 1. The device automatically resets volatile configuration register bit 3 to 1.

Activate and Terminate XIP Using Nonvolatile Configuration Register

Applications that must boot directly in XIP use the nonvolatile configuration register. To enable a device to power-up in XIP using this register, set nonvolatile configuration register bits [11:9]. Settings vary according to protocol, as explained in the Nonvolatile Configuration Register section. Because the device boots directly in XIP, after the power cycle, no command code is necessary. XIP is terminated by driving the XIP confirmation bit to 1.

Figure 47: XIP Mode Directly After Power-On



Note: 1. Xb is the XIP confirmation bit and should be set as follows: 0 to keep XIP state; 1 to exit XIP mode and return to standard read mode.

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Confirmation Bit Settings Required to Activate or Terminate XIP

The XIP confirmation bit setting activates or terminates XIP after it has been enabled or disabled. This bit is the value on DQ0 during the first dummy clock cycle in the FAST READ operation. In dual I/O XIP mode, the value of DQ1 during the first dummy clock cycle after the addresses is always "Don't Care." In quad I/O XIP mode, the values of DQ3, DQ2, and DQ1 during the first dummy clock cycle after the addresses are always "Don't Care."

Table 35: XIP Confirmation Bit

Bit Value	Description
0	Activates XIP: While this bit is 0, XIP remains activated.
1	Terminates XIP: When this bit is set to 1, XIP is terminated and the device returns to SPI.

Table 36: Effects of Running XIP in Different Protocols

Protocol	Effect
Extended I/O and Dual I/O	In a device with a dedicated part number where RESET# is enabled, a LOW pulse on that pin resets XIP and the device to the state it was in previous to the last power-up, as defined by the nonvolatile configuration register.
Dual I/O	Values of DQ1 during the first dummy clock cycle are "Don't Care."
Quad I/O[1]	Values of DQ[3:1] during the first dummy clock cycle are "Don't Care." In a device with a dedicated part number, it is only possible to reset memory when the device is deselected.

Note: 1. In a device with a dedicated part number where RESET# is enabled, a LOW pulse on that pin resets XIP and the device to the state it was in previous to the last power-up, as defined by the nonvolatile configuration register only when the device is deselected.

Terminating XIP After a Controller and Memory Reset

The system controller and the device can become out of synchronization if, during the life of the application, the system controller is reset without the device being reset. In such a case, the controller can reset the memory to power-on reset if the memory has reset functionality. (Reset is available in devices with a dedicated part number.)

- 7 clock cycles within S# LOW (S# becomes HIGH before 8th clock cycle)
- + 9 clock cycles within S# LOW (S# becomes HIGH before 10th clock cycle)
- + 13 clock cycles within S# LOW (S# becomes HIGH before 14th clock cycle)
- + 17 clock cycles within S# LOW (S# becomes HIGH before 18th clock cycle)
- + 25 clock cycles within S# LOW (S# becomes HIGH before 26th clock cycle)
- + 33 clock cycles within S# LOW (S# becomes HIGH before 34th clock cycle)

These sequences cause the controller to set the XIP confirmation bit to 1, thereby terminating XIP. However, it does not reset the device or interrupt PROGRAM/ERASE operations that may be in progress. After terminating XIP, the controller must execute RESET ENABLE and RESET MEMORY to implement a software reset and reset the device.

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Power-Up and Power-Down

Power-Up and Power-Down Requirements

At power-up and power-down, the device must not be selected; that is, S# must follow the voltage applied on V_{CC} until V_{CC} reaches the correct values: $V_{CC,min}$ at power-up and V_{SS} at power-down.

To provide device protection and prevent data corruption and inadvertent WRITE operations during power-up, a power-on reset circuit is included. The logic inside the device is held to RESET while V_{CC} is less than the power-on reset threshold voltage shown here; all operations are disabled, and the device does not respond to any instruction. During a standard power-up phase, the device ignores all commands except READ STATUS REGISTER and READ FLAG STATUS REGISTER. These operations can be used to check the memory internal state. After power-up, the device is in standby power mode; the write enable latch bit is reset; the write in progress bit is reset; and the dynamic protection register is configured as: (write lock bit, lock down bit) = (0,0).

Normal precautions must be taken for supply line decoupling to stabilize the V_{CC} supply. Each device in a system should have the V_{CC} line decoupled by a suitable capacitor (typically 100nF) close to the package pins. At power-down, when V_{CC} drops from the operating voltage to below the power-on-reset threshold voltage shown here, all operations are disabled and the device does not respond to any command.

When the operation is in progress, the program or erase controller bit of the status register is set to 0. To obtain the operation status, the flag status register must be polled. When the operation completes, the program or erase controller bit is cleared to 1. The cycle is complete after the flag status register outputs the program or erase controller bit to 1.

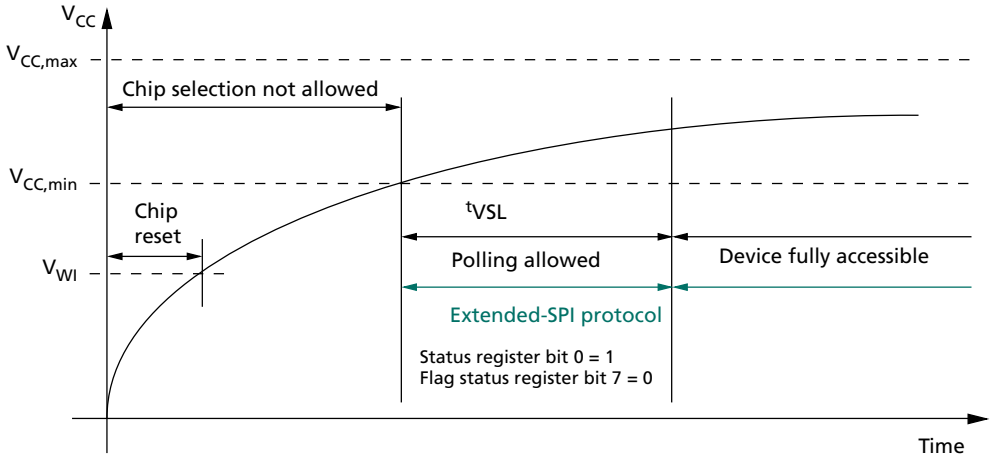
Note: If power-down occurs while a WRITE, PROGRAM, or ERASE cycle is in progress, data corruption may result.

Note: For additional details about how to properly apply and remove the power supply to the device, refer to TN-25-38: Power-Up, Power-Down, and Brownout Considerations on MT25Q, MT25T, and MT35X NOR Flash Memory.

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Figure 48: Power-Up Timing



Notes:
1. ^{t}VSL polling has to be in extended-SPI protocol and STR mode.
2. During ^{t}VSL period, HOLD# is enabled, RESET# disabled, and output strength is in default setting.
3. In a system that uses a fast V_{CC} ramp rate, current design requires a minimum 100µs after V_{CC} reaches ^{t}VWI, and before the polling is allowed, even though $V_{CC,min}$ is achieved.
4. In extended-SPI protocol, 1Gb and 2Gb device must wait 100µs after V_{CC} reaches $V_{CC,min}$ before polling the status register or flag status register.

Table 37: Power-Up Timing and V_{WI} Threshold

Note 1 applies to entire table

Symbol	Parameter	Min	Max	Unit	Notes
^{t}VSL	$V_{CC,min}$ to device fully accessible	–	300	µs	2, 3
V_{WI}	Write inhibit voltage	1.5	2.5	V	2

Notes:
1. When V_{CC} reaches $V_{CC,min}$, to determine whether power-up initialization is complete, the host can poll status register bit 0 or flag status register bit 7 only in extended-SPI protocol because the device will accept commands only on DQ0 and output data only on DQ1. When the device is ready, the host has full access using the protocol configured in the nonvolatile configuration register. If the host cannot poll the status register in x1 SPI mode, it is recommended to wait ^{t}VSL before accessing the device.
2. Parameters listed are characterized only.
3. On the first power-up after an event causing a subsector erase operation interrupt (for example, due to power-loss), the maximum time for ^{t}VSL will be up to 4.5ms in case of 4KB subsector erase interrupt and up to 36ms in case of 32KB subsector erase interrupt; this accounts for erase recovery embedded operation.

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Active, Standby, and Deep Power-Down Modes

When S# is LOW, the device is selected and in active power mode. When S# is HIGH, the device is deselected but could remain in active power mode until ongoing internal operations are completed. Then the device goes into standby power mode and device current consumption drops to I_{CC1}.

Deep power-down mode enbles users to place the device in the lowest power consumption mode, I_{CC2}. The ENTER DEEP POWER-DOWN command is used to put the device in deep power-down mode, and the RELEASE FROM DEEP POWER-DOWN command is used to bring the device out of deep power-down mode. Command details are in the Command Set table and the DEEP POWER-DOWN Operations section of this data sheet.

Power Loss and Interface Rescue

If a power loss occurs during a WRITE NONVOLATILE CONFIGURATION REGISTER command, after the next power-on, the device might begin in an undetermined state (XIP mode or an unnecessary protocol). If this occurs, a power loss recovery sequence must reset the device to a fixed state (extended-SPI protocol without XIP) until the next power-up.

If the controller and memory device get out of synchronization, the controller can follow an interface rescue sequence to reset the memory device interface to power-up to the last reset state (as defined by latest nonvolatile configuration register). This resets only the interface, not the entire memory device, and any ongoing operations are not interrupted.

After each sequence, the issue should be resolved definitively by running the WRITE NONVOLATILE CONFIGURATION REGISTER command again.

Note: The two steps in each sequence must be in the correct order, and ^{t}SHSL2 must be at least 50ns for the duration of each sequence.

The first step for both the power loss recovery and interface rescue sequences is described under "Recovery." The second step in the power loss recovery sequence is under "Power Loss Recovery" and the second step in the interface rescue sequence is under "Interface Rescue."

Recovery

Step one of both the power loss recovery and interface rescue sequences is DQ0 (PAD DATA) and DQ3 (PAD HOLD) equal to 1 for the situations listed here:

- 7 clock cycles within S# LOW (S# becomes HIGH before 8th clock cycle)
- + 9 clock cycles within S# LOW (S# becomes HIGH before 10th clock cycle)
- + 13 clock cycles within S# LOW (S# becomes HIGH before 14th clock cycle)
- + 17 clock cycles within S# LOW (S# becomes HIGH before 18th clock cycle)
- + 25 clock cycles within S# LOW (S# becomes HIGH before 26th clock cycle)
- + 33 clock cycles within S# LOW (S# becomes HIGH before 34th clock cycle)

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Power Loss Recovery

For power loss recovery, the second part of the sequence is exiting from dual- or quad-SPI protocol by using the following FFh sequence: DQ0 and DQ3 equal to 1 for 8 clock cycles within S# LOW; S# becomes HIGH before 9th clock cycle. After this two-part sequence the extended-SPI protocol is active.

Interface Rescue

For interface rescue, the second part of the sequence is for exiting from dual or quad-SPI protocol by using the following FFh sequence: DQ0 and DQ3 equal to 1 for 16 clock cycles within S# LOW; S# becomes HIGH before 17th clock cycle. For DTR protocol, 1 should be driven on both edges of clock for 16 cycles with S# LOW. After this two-part sequence, the extended-SPI protocol is active.

Initial Delivery Status

The device is delivered as follows:

- Memory array erased: all bits are set to 1 (each byte contains FFh)
- Status register contains 00h (all status register bits are 0)
- Nonvolatile configuration register (NVCR) bits all erased (FFFFh)

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Absolute Ratings and Operating Conditions

Stresses greater than those listed may cause permanent damage to the device. This is a stress rating only. Exposure to absolute maximum rating for extended periods may adversely affect reliability. Stressing the device beyond the absolute maximum ratings may cause permanent damage.

Table 38: Absolute Ratings

Symbol	Parameter	Min	Max	Units	Notes
T_{STG}	Storage temperature	–65	150	°C	
T_{LEAD}	Lead temperature during soldering	–	See note 1	°C	
V_{CC}	Supply voltage	–0.6	4.0	V	2
V_{IO}	Input/output voltage with respect to ground	–0.6	V_{CC} + 0.6	V	2
V_{ESD}	Electrostatic discharge voltage (human body model)	–2000	2000	V	2, 3

Notes:
1. Compliant with JEDEC Standard J-STD-020C (for small-body, Sn-Pb or Pb assembly), RoHS, and the European directive on Restrictions on Hazardous Substances (RoHS) 2002/95/EU.
2. All specified voltages are with respect to V_{SS}. During infrequent, nonperiodic transitions, the voltage potential between V_{SS} and the V_{CC} may undershoot to –2.0V for periods less than 20ns, or overshoot to $V_{CC,max}$ + 2.0V for periods less than 20ns.
3. JEDEC Standard JESD22-A114A (C1 = 100pF, R1 = 1500Ω, R2 = 500Ω).

Table 39: Operating Conditions

Symbol	Parameter	Min	Max	Units
V_{CC}	Supply voltage	2.7	3.6	V
T_A	Ambient operating temperature	–40	85	°C
T_A	Ambient operating temperature (automotive)	–40	105	°C

Table 40: Input/Output Capacitance

Note 1 applies to entire table

Symbol	Description	Min	Max	Units
$C_{IN/OUT}$	Input/output capacitance (DQ0/DQ1/DQ2/DQ3)	–	10	pF
C_{IN}	Input capacitance (other pins)	–	6	pF
$C_{IN/S\#}$	Input/Chip select	–	10	pF

Note:
1. Verified in device characterization; not 100% tested. These parameters are not subject to a production test. They are verified by design and characterization. The capacitance is measured according to JEP147 ("PROCEDURE FOR MEASURING INPUT CAPACITANCE USING A VECTOR NETWORK ANALYZER (VNA)") with V_{CC} and V_{SS} applied and all other pins floating (except the pin under test), $V_{BIAS} = V_{CC}/2$, T_A = 25°C, Frequency = 54 MHz.

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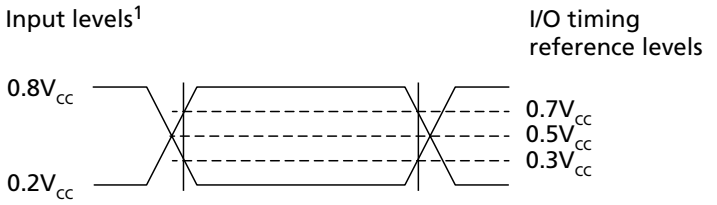
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Table 41: AC Timing Input/Output Conditions

Symbol	Description	Min	Max	Units	Notes
C_L	Load capacitance	–	30	pF	1
–	Input rise and fall times	–	1.5	ns	
	Input pulse voltages	$0.2V_{CC}$ to $0.8V_{CC}$		V	2
	Input timing reference voltages	$0.3V_{CC}$ to $0.7V_{CC}$		V	
	Output timing reference voltages	$V_{CC}/2$		V	

Notes: 1. Output buffers are configurable by user.
2. For quad/dual operations: 0V to V_{CC}.

Figure 49: AC Timing Input/Output Reference Levels



Note: 1. $0.8V_{CC} = V_{CC}$ for dual/quad operations; $0.2V_{CC} = 0V$ for dual/quad operations.

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DC Characteristics and Operating Conditions

Table 42: DC Current Characteristics and Operating Conditions

Notes 1–5 apply to entire table

Parameter	Symbol	Test Conditions	Typ	Max	Unit
Input leakage current	I_{LI}	–	–	±2	µA
Output leakage current	I_{LO}	–	–	±2	µA
Standby current (IT range)	I_{CC1}	S# = V_{CC}, V_{IN} = V_{SS} or V_{CC}	15	50	µA
Standby current (AT range)	I_{CC1}	S# = V_{CC}, V_{IN} = V_{SS} or V_{CC}	30	80	µA
Deep power-down current (IT range)	I_{CC2}	S# = V_{CC}, V_{IN} = V_{SS} or V_{CC}	5	30	µA
Deep power-down current (AT range)	I_{CC2}	S# = V_{CC}, V_{IN} = V_{SS} or V_{CC}	5	50	µA
Operating current (fast-read extended I/O)	I_{CC3}	C = 0.1V_{CC}/0.9V_{CC} at 133 MHz, DQ1 = open	–	16	mA
		C = 0.1V_{CC}/0.9V_{CC} at 54 MHz, DQ1 = open	–	8	mA
Operating current (fast-read dual I/O)		C = 0.1V_{CC}/0.9V_{CC} at 133 MHz, DQ1 = open	–	20	mA
Operating current (fast-read quad I/O)		C = 0.1V_{CC}/0.9V_{CC} at 133 MHz, DQ1 = open	–	22	mA
		C = 0.1V_{CC} / 0.9V_{CC} at 80 MHz DTR, DQ=open	–	28	mA
		C = 0.1V_{CC} / 0.9V_{CC} at 90 MHz DTR, DQ=open	–	31	mA
Operating current (PROGRAM operations)	I_{CC4}	S# = V_{CC}	–	35	mA
Operating current (WRITE operations)	I_{CC5}	S# = V_{CC}	–	35	mA
Operating current (erase)	I_{CC6}	S# = V_{CC}	–	35	mA

Notes:
1. All currents are RMS unless noted. Typical values at typical V_{CC} (3.0/1.8V); V_{IO} = 0V/V_{CC}; T_C = +25°C.
2. Standby current is the average current measured over any time interval 5µs after S de-assertion (and any internal operations are complete).
3. Deep power-down current is the average current measured 5ms over any 5ms time interval, 100µs after the ENTER DEEP POWER-DOWN operation (and any internal operations are complete).
4. All read currents are the average current measured over any 1KB continuous read. No load, checker-board pattern.
5. All program currents are the average current measured over any 256-byte typical data program.

Table 43: DC Voltage Characteristics and Operating Conditions

Note 1 applies to entire table

Parameter	Symbol	Conditions	Min	Max	Unit
Input low voltage	V_{IL}		–0.5	0.3V_{CC}	V

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Table 43: DC Voltage Characteristics and Operating Conditions (Continued)

Note 1 applies to entire table

Parameter	Symbol	Conditions	Min	Max	Unit
Input high voltage	V_{IH}		$0.7V_{CC}$	V_{CC} + 0.4	V
Output low voltage	V_{OL}	I_{OL} = 1.6mA	–	0.4	V
Output high voltage	V_{OH}	I_{OH} = –100µA	V_{CC} - 0.2	–	V

Note: 1. V_{IL} can undershoot to –1.0V for periods <2ns and V_{IH} may overshoot to $V_{CC,max}$ + 1.0V for periods less than 2ns.

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AC Characteristics and Operating Conditions

Table 44: AC Characteristics and Operating Conditions

Parameter	Symbol	Data Transfer Rate	Min	Typ	Max	Unit	Notes
Clock frequency for all commands other than READ (Extended-SPI, DIO-SPI, and QIO-SPI protocol)	^{f}C	STR	DC	–	133	MHz	
		DTR	DC	–	90		
Clock frequency for READ command (03h)	^{f}R	STR	DC	–	54	MHz	
		DTR	DC	–	27		
Clock HIGH time	^{t}CH	STR	3.375	–	–	ns	2
		DTR	5.0	–	–		
Clock LOW time	^{t}CL	STR	3.375	–	–	ns	2
		DTR	5.0	–	–		
Clock rise time (peak-to-peak)	$^{t}CLCH$	STR/DTR	0.1	–	–	V/ns	3, 4
Clock fall time (peak-to-peak)	$^{t}CHCL$	STR/DTR	0.1	–	–	V/ns	3, 4
S# active setup time (relative to clock)	$^{t}SLCH$	STR/DTR	3.375	–	–	ns	
S# not active hold time (relative to clock)	$^{t}CHSL$	STR/DTR	3.375	–	–	ns	
Data in setup time	$^{t}DVCH$	STR	1.75	–	–	ns	
		DTR	1.5	–	–	ns	
	$^{t}DVCL$	DTR only	1.5	–	–	ns	
Data in hold time	$^{t}CHDX$	STR/DTR	2.3	–	–	ns	
	$^{t}CLDX$	DTR only	2.3	–	–	ns	
S# active hold time (relative to clock)	$^{t}CHSH$	STR	3.375	–	–	ns	
		DTR	5.0	–	–		
S# active hold time (relative to clock LOW) Only for writes in DTR	$^{t}CLSH$	DTR only	3.375	–	–	ns	
S# not active setup time (relative to clock)	$^{t}SHCH$	STR	3.375	–	–	ns	
		DTR	5.0	–	–	ns	
S# deselect time after a READ command	$^{t}SHSL1$	STR/DTR	20	–	–	ns	
S# deselect time after a nonREAD command	$^{t}SHSL2$	STR/DTR	50	–	–	ns	5
Output disable time	$^{t}SHQZ$	STR/DTR	–	–	7	ns	3
Clock LOW to output valid under 30pF	$^{t}CLQV$	STR/DTR	–	–	6	ns	
Clock LOW to output valid under 10pF		STR/DTR	–	–	5	ns	
Clock HIGH to output valid under 30pF	$^{t}CHQV$	DTR only	–	–	6	ns	
Clock HIGH to output valid under 10pF		DTR only	–	–	5	ns	
Output hold time	$^{t}CLQX$	STR/DTR	1.5	–	–	ns	
Output hold time	$^{t}CHQX$	DTR only	1.5	–	–	ns	
HOLD setup time (relative to clock)	$^{t}HLCH$	STR/DTR	3.375	–	–	ns	
HOLD hold time (relative to clock)	$^{t}CHHH$	STR/DTR	3.375	–	–	ns	

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Table 44: AC Characteristics and Operating Conditions (Continued)

Parameter	Symbol	Data Transfer Rate	Min	Typ	Max	Unit	Notes
HOLD setup time (relative to clock)	^{t}HHCH	STR/DTR	3.375	–	–	ns	
HOLD hold time (relative to clock)	^{t}CHHL	STR/DTR	3.375	–	–	ns	
HOLD to output Low-Z	^{t}HHQX	STR/DTR	–	–	8	ns	3
HOLD to output High-Z	^{t}HLQZ	STR/DTR	–	–	8	ns	3
CRC check time: main block	^{t}CRC	STR/DTR	–	1.3	–	ms	
CRC check time: full chip (128Mb)	^{t}CRC	STR/DTR	–	0.5	–	s	
Write protect setup time	^{t}WHSL	STR/DTR	20	–	–	ns	6
Write protect hold time	^{t}SHWL	STR/DTR	100	–	–	ns	6
S# HIGH to deep power-down	^{t}DP	STR/DTR	3	–	–	µs	
S# HIGH to standby mode (DPD exit time)	^{t}RDP	STR/DTR	30	–	–	µs	
WRITE STATUS REGISTER cycle time	^{t}W	STR/DTR	–	1.3	8	ms	
WRITE NONVOLATILE CONFIGURATION REGISTER cycle time	^{t}WNVCR	STR/DTR	–	0.2	1	s	
Nonvolatile sector lock time	^{t}PPBP	STR/DTR	–	0.1	2.8	ms	
Program ASP register	^{t}ASPP	STR/DTR	–	0.1	0.5	ms	
Program password	^{t}PASSP	STR/DTR	–	0.2	0.8	ms	
Erase nonvolatile sector lock array	^{t}PPBE	STR/DTR	–	0.2	1	s	
Page program time (256 bytes)	^{t}PP	STR/DTR	–	120	1800	µs	7
Page program time (n bytes)			–	18 + 2.5 x int(n/6)	1800	µs	8
PROGRAM OTP cycle time (64 bytes)	^{t}POTP	STR/DTR	–	0.12	0.8	ms	
Sector erase time	^{t}SE	STR/DTR	–	0.15	1	s	
4KB subsector erase time	^{t}SSE	STR/DTR	–	0.05	0.4	s	
32KB subsector erase time	^{t}SSE	STR/DTR	–	0.1	1	s	
128Mb bulk erase time	^{t}BE	STR/DTR	–	38	114	s	

Notes:
1. Typical values given for T_A = 25 °C.
2. ^{t}CH + ^{t}CL must add up to 1/^{f}C.
3. Value guaranteed by characterization; not 100% tested.
4. Expressed as a slew-rate.
5. nonREAD commands are WRITE, PROGRAM, and ERASE.
6. Only applicable as a constraint for a WRITE STATUS REGISTER command when STATUS REGISTER WRITE is set to 1.
7. Typical value is applied for pattern: 50% "0" and 50% "1."
8. int(n) correspond to the integer part of n. For example, int (12/8) = 1, int (32/8) = 4, int(15.3) = 15.

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AC Reset Specifications

Table 45: AC RESET Conditions

Note 1 applies to entire table

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Reset pulse width	^{t}RLRH[2]		50	–	–	ns
Reset recovery time	^{t}RHSL	Device deselected (S# HIGH) and is in XIP mode	40	–	–	ns
		Device deselected (S# HIGH) and is in standby mode	40	–	–	ns
		Commands are being decoded, any READ operations are in progress or any WRITE operation to volatile registers are in progress	40	–	–	ns
		Any device array PROGRAM/ERASE/SUSPEND/RESUME, PROGRAM OTP, NONVOLATILE SECTOR LOCK, and ERASE NONVOLATILE SECTOR LOCK ARRAY operations are in progress	30	–	–	µs
		While a WRITE STATUS REGISTER operation is in progress	–	^{t}W	–	ms
		While a WRITE NONVOLATILE CONFIGURATION REGISTER operation is in progress	–	^{t}WNVCR	–	ms
		On completion or suspension of a SUBSECTOR ERASE operation	–	^{t}SSE	–	s
		Device in deep power-down mode	–	^{t}RDP	–	ms
		While ADVANCED SECTOR PROTECTION PROGRAM operation is in progress	–	^{t}ASPP	–	ms
		While PASSWORD PROTECTION PROGRAM operation is in progress	–	^{t}PASSP	–	ms
Software reset recovery time	^{t}SHSL3	Device deselected (S# HIGH) and is in standby mode	40	–	–	ns
		Any Flash array PROGRAM/ERASE/SUSPEND/RESUME, PROGRAM OTP, NONVOLATILE SECTOR LOCK, and ERASE NONVOLATILE SECTOR LOCK ARRAY operations are in progress	30	–	–	µs
		While WRITE STATUS REGISTER operation is in progress	–	^{t}W	–	ms
		While a WRITE NONVOLATILE CONFIGURATION REGISTER operation is in progress	–	^{t}WNVCR	–	ms
		On completion or suspension of a SUBSECTOR ERASE operation	–	^{t}SSE	–	s
		Device in deep power-down mode	–	^{t}RDP	–	ms
		While ADVANCED SECTOR PROTECTION PROGRAM operation is in progress	–	^{t}ASPP	–	ms
		While PASSWORD PROTECTION PROGRAM operation is in progress	–	^{t}PASSP	–	ms

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Table 45: AC RESET Conditions (Continued)

Note 1 applies to entire table

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
Chip select high to reset high	^{t}SHRH	Chip must be deselected before reset is de-asserted	10	–	–	ns

Notes: 1. Values are guaranteed by characterization; not 100% tested.
2. The device reset is possible but not guaranteed if ^{t}RLRH < 50ns.

Figure 50: Reset AC Timing During PROGRAM and ERASE Cycle

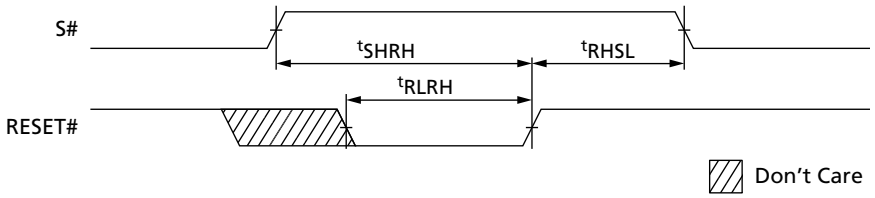


Figure 51: Reset Enable and Reset Memory Timing

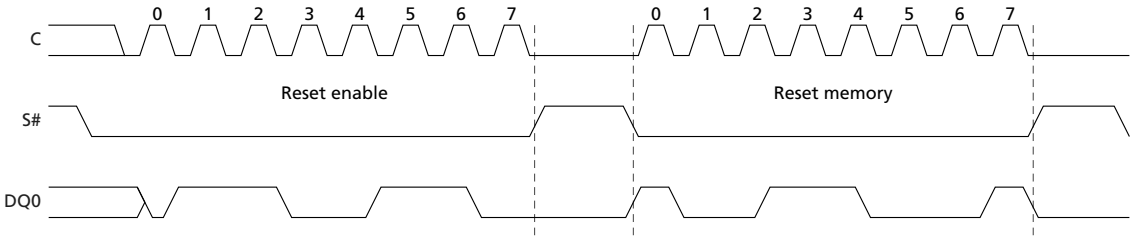
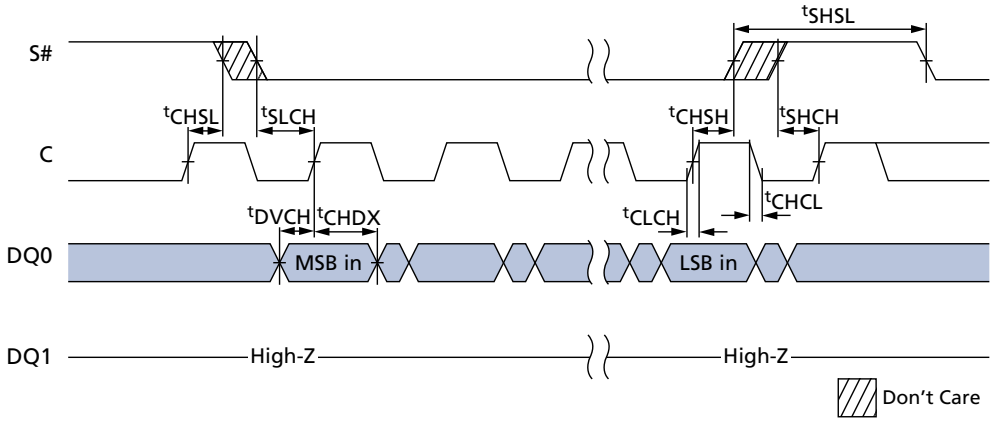


Figure 52: Serial Input Timing STR



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Figure 53: Serial Input Timing DTR

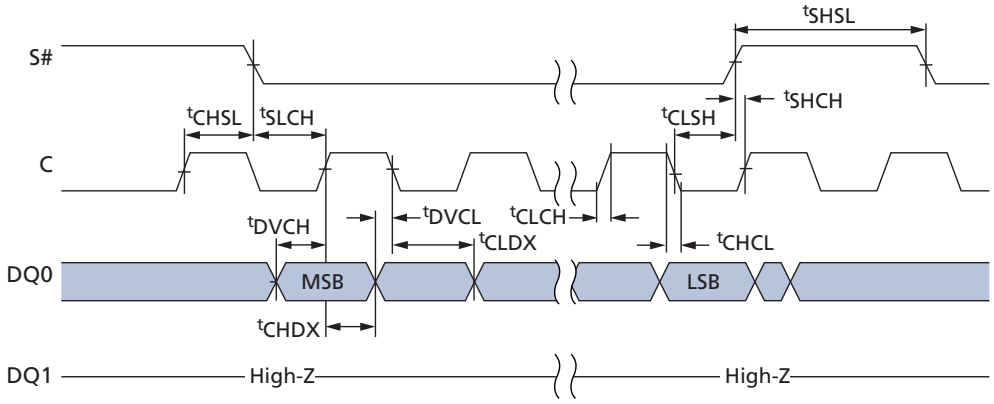


Figure 54: Write Protect Setup and Hold During WRITE STATUS REGISTER Operation (SRWD = 1)

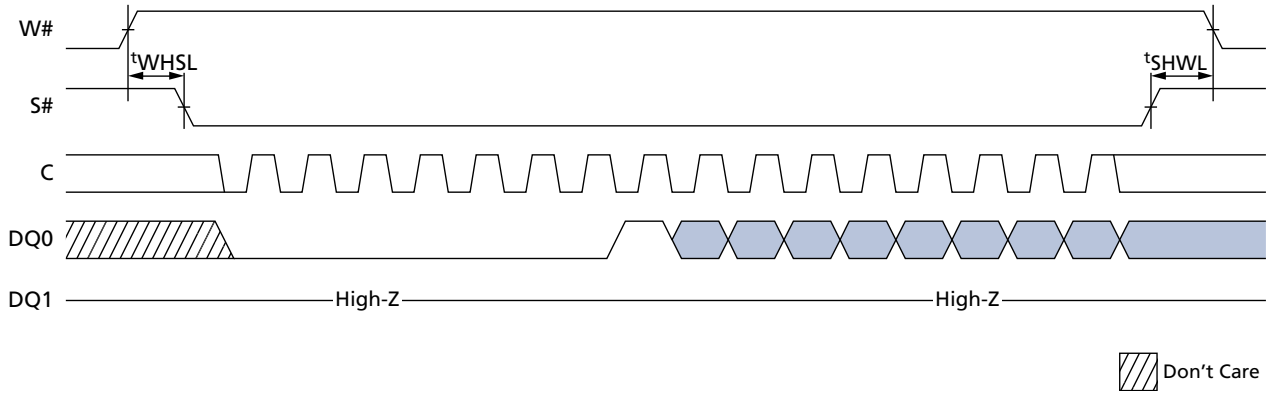
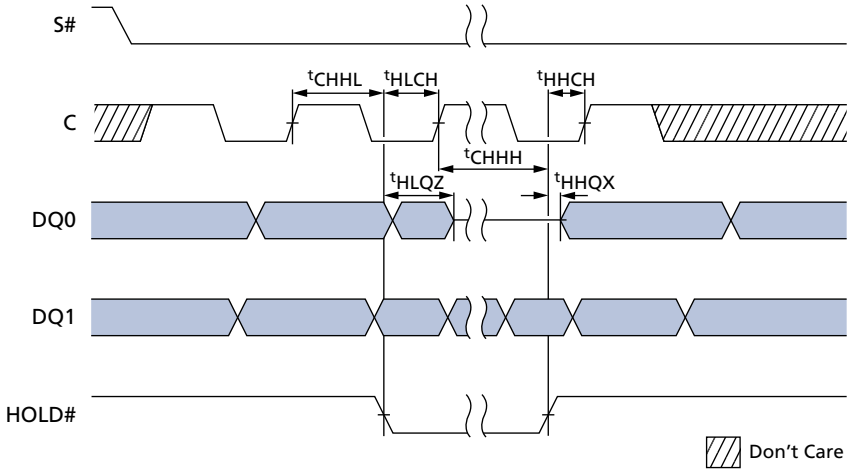


Figure 55: Hold Timing



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Figure 56: Output Timing for STR

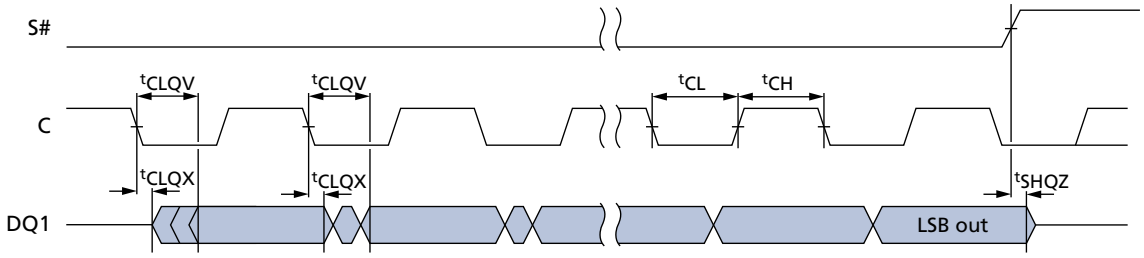
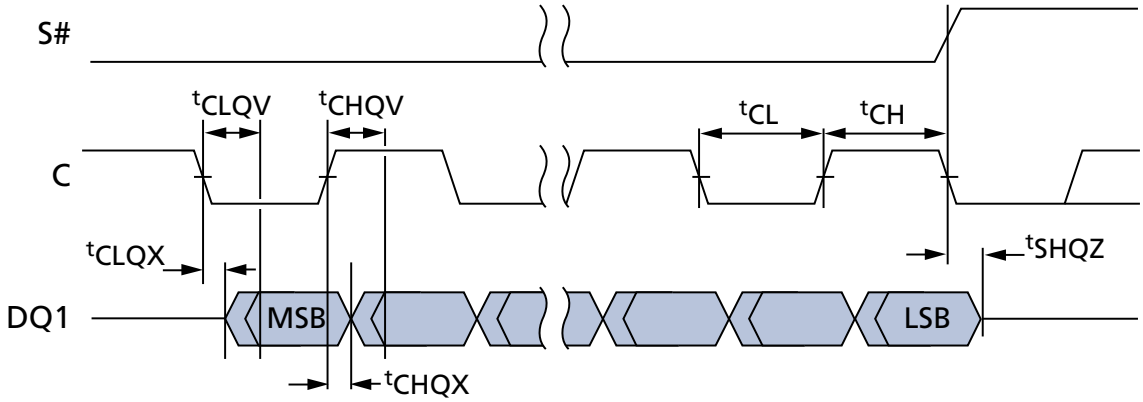


Figure 57: Output Timing for DTR



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Program/Erase Specifications

Table 46: Program/Erase Specifications

Parameter	Condition	Typ	Max	Units	Notes
Erase to suspend	Sector erase or erase resume to erase suspend	150	–	µs	1
Program to suspend	Program resume to program suspend	5	–	µs	1
Subsector erase to suspend	Subsector erase or subsector erase resume to erase suspend	50	–	µs	1
Suspend latency	Program	7	25	µs	2
Suspend latency	Subsector erase	15	30	µs	2
Suspend latency	Erase	15	30	µs	3

Notes:
1. Timing is not internally controlled.
2. Any READ command accepted.
3. Any command except the following are accepted: SECTOR, SUBSECTOR, or BULK ERASE; WRITE STATUS REGISTER; WRITE NONVOLATILE CONFIGURATION REGISTER; and PROGRAM OTP.

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Revision History

Rev. K – 04/19

- Added reference to TN-25-38 in the power-up and power-down chapter

Rev. J – 05/18

- Added Important Notes and Warnings section for further clarification aligning to industry standards
- Added DEEP POWER-DOWN Operations
- Added Active Power, Standby Power, and Deep Power-Down modes
- Adjusted Nonvolatile Configuration Register table
- Added Serial Input Timing DTR figure

Rev. I - 09/16

- Typo correction in root Part Number in cover page
- Updated Part Number Ordering Information

Rev. H - 07/16

- Changed W# description
- Updated MAX DTR frequency to 90 MHz
- Changed Status Register table
- Changed Nonvolatile and Volatile Configuration Register table
- Added Initial delivery status

Rev. G – 06/16

- Added general purpose read register notes to Command Definitions table

Rev. F – 12/15

- Added note for READ REGISTER Operations table and WRITE REGISTER Operations table
- Added code 60h for BULK ERASE Command in Command Set table in Command Definitions section

Rev. E – 10/15

- Typo correction in Output Timing figure in AC Reset Specifications section

Rev. D – 9/15

- Revised wrap table
- Revised supported clock frequencies DTR
- Change bit 3 setting of Enhanced Volatile Configuration Register from 0 to 1
- Revised AC table

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Rev. C – 7/15

- Added reference to serial flash discovery parameter data, which is now contained in a technical note
- Change DTR frequency at 80Mhz
- Revised cover page part number to: MT25QL128ABA.
- Revised signal assignments
- Revised supported clock frequencies with a note to reference TN-25-07: Tuning Data Pattern for MT25Q and MT25T Devices
- Revised serial flash discovery parameter with a note to reference TN-25-06: SFDP for MT25Q Family
- Added ambient temperature for automotive
- Added 80MHz information for $I_{CC}3$ in DC specifications
- Revised minimum clock rise and fall times in AC specifications
- Increase I_{CC4} ,I_{CC5} and I_{CC6} at 35mA
- Increase suspend latency time for erase at 30us
- Change tCLQX and tCHQX at 1.5ns

Rev. B – 7/14

- Added the TBGA 14, DF8N W7, and W9

Rev. A – 01/14

- Initial release

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This data sheet contains minimum and maximum limits specified over the power supply and temperature range set forth herein.
Although considered final, these specifications are subject to change, as further product development and data characterization sometimes occur.

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