CY15B104Q

# 4-Mbit (512 K × 8) Serial (SPI) F-RAM

## Features

- 4-Mbit ferroelectric random access memory (F-RAM) logically organized as 512 K × 8
  - High-endurance 100 trillion ($10^{14}$) read/writes
  - 151-year data retention (See the Data Retention and Endurance table)
  - NoDelay™ writes
  - Advanced high-reliability ferroelectric process
- Very fast serial peripheral interface (SPI)
  - Up to 40-MHz frequency
  - Direct hardware replacement for serial flash and EEPROM
  - Supports SPI mode 0 (0, 0) and mode 3 (1, 1)
- Sophisticated write protection scheme
  - Hardware protection using the Write Protect ($\overline{WP}$) pin
  - Software protection using Write Disable instruction
  - Software block protection for 1/4, 1/2, or entire array
- Device ID
  - Manufacturer ID and Product ID
- Low power consumption
  - 300 µA active current at 1 MHz
  - 100 µA (typ) standby current
  - 3 µA (typ) sleep mode current
- Low-voltage operation: $V_{DD}$ = 2.0 V to 3.6 V
- Industrial temperature: –40 °C to +85 °C
- Packages
  - 8-pin small outline integrated circuit (SOIC) package
  - 8-pin thin dual flat no leads (TDFN) package
- Restriction of hazardous substances (RoHS) compliant

## Functional Description

The CY15B104Q is a 4-Mbit nonvolatile memory employing an advanced ferroelectric process. A ferroelectric random access memory or F-RAM is nonvolatile and performs reads and writes similar to a RAM. It provides reliable data retention for 151 years while eliminating the complexities, overhead, and system-level reliability problems caused by serial flash, EEPROM, and other nonvolatile memories.

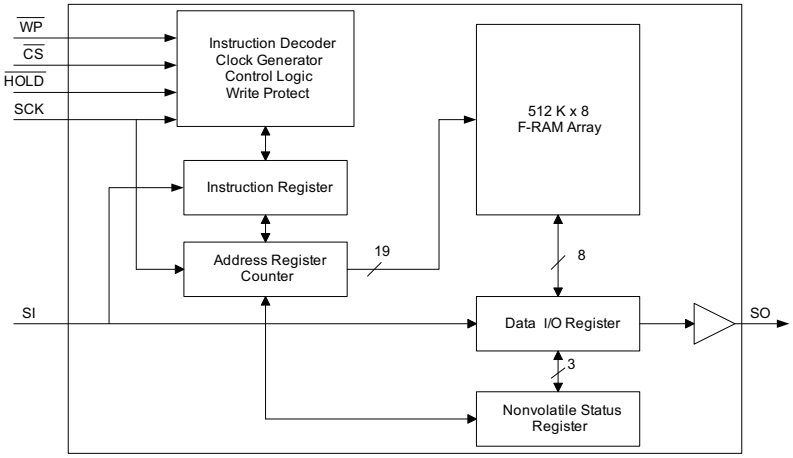
Unlike serial flash and EEPROM, the CY15B104Q performs write operations at bus speed. No write delays are incurred. Data is written to the memory array immediately after each byte is successfully transferred to the device. The next bus cycle can commence without the need for data polling. In addition, the product offers substantial write endurance compared to other nonvolatile memories. The CY15B104Q is capable of supporting $10^{14}$ read/write cycles, or 100 million times more write cycles than EEPROM.

These capabilities make the CY15B104Q ideal for nonvolatile memory applications, requiring frequent or rapid writes. Examples range from data collection, where the number of write cycles may be critical, to demanding industrial controls where the long write time of serial flash or EEPROM can cause data loss.

The CY15B104Q provides substantial benefits to users of serial EEPROM or flash as a hardware drop-in replacement. The CY15B104Q uses the high-speed SPI bus, which enhances the high-speed write capability of F-RAM technology. The device incorporates a read-only Device ID that allows the host to determine the manufacturer, product density, and product revision. The device specifications are guaranteed over an industrial temperature range of –40 °C to +85 °C.

For a complete list of related documentation, click here.

## Logic Block Diagram




深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com
微信扫码咨询客服

## Contents


**Pinouts** ..... **3**
**Pin Definitions** ..... **3**
**Overview** ..... **4**
Memory Architecture ..... 4
Serial Peripheral Interface (SPI) Bus ..... 4
SPI Overview ..... 4
SPI Modes ..... 5
Power Up to First Access ..... 6
Command Structure ..... 6
WREN - Set Write Enable Latch ..... 6
WRDI - Reset Write Enable Latch ..... 6
**Status Register and Write Protection** ..... **7**
Read Status Register (RDSR) ..... 7
Write Status Register (WRSR) ..... 7
**Memory Operation** ..... **8**
Write Operation ..... 8
Read Operation ..... 8
Fast Read Operation ..... 8
HOLD Pin Operation ..... 10
Sleep Mode ..... 10
Device ID ..... 11
Endurance ..... 11
**Maximum Ratings** ..... **12**
**Operating Range** ..... **12**
**DC Electrical Characteristics** ..... **12**
**Data Retention and Endurance** ..... **13**
**Capacitance** ..... **13**
**Thermal Resistance** ..... **13**
**AC Test Conditions** ..... **13**
**AC Switching Characteristics** ..... **14**
**Power Cycle Timing** ..... **16**
**Ordering Information** ..... **17**
Ordering Code Definitions ..... 17
**Package Diagrams** ..... **18**
**Acronyms** ..... **20**
**Document Conventions** ..... **20**
Units of Measure ..... 20
**Document History Page** ..... **21**
**Sales, Solutions, and Legal Information** ..... **22**
Worldwide Sales and Design Support ..... 22
Products ..... 22
PSoC® Solutions ..... 22
Cypress Developer Community ..... 22
Technical Support ..... 22




深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Pinouts

**Figure 1. 8-pin SOIC Pinout**

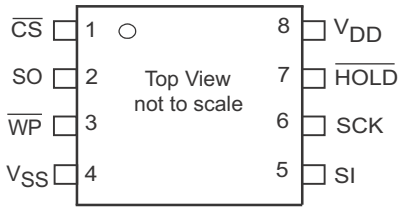
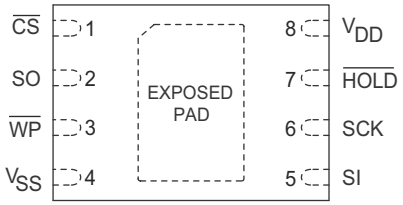



**Figure 2. 8-pin TDFN Pinout**




## Pin Definitions

| Pin Name | I/O Type | Description |
|---|---|---|
| $\overline{CS}$ | Input | **Chip Select**. This active LOW input activates the device. When HIGH, the device enters low-power standby mode, ignores other inputs, and the output is tristated. When LOW, the device internally activates the SCK signal. A falling edge on $\overline{CS}$ must occur before every opcode. |
| SCK | Input | **Serial Clock**. All I/O activity is synchronized to the serial clock. Inputs are latched on the rising edge and outputs occur on the falling edge. Because the device is synchronous, the clock frequency may be any value between 0 and 40 MHz and may be interrupted at any time. |
| SI[1] | Input | **Serial Input**. All data is input to the device on this pin. The pin is sampled on the rising edge of SCK and is ignored at other times. It should always be driven to a valid logic level to meet IDD specifications. |
| SO[1] | Output | **Serial Output**. This is the data output pin. It is driven during a read and remains tristated at all other times including when $\overline{HOLD}$ is LOW. Data transitions are driven on the falling edge of the serial clock. |
| $\overline{WP}$ | Input | **Write Protect**. This Active LOW pin prevents write operation to the Status Register when WPEN is set to '1'. This is critical because other write protection features are controlled through the Status Register. A complete explanation of write protection is provided in Status Register and Write Protection on page 7. This pin must be tied to $V_{DD}$ if not used. |
| $\overline{HOLD}$ | Input | **HOLD Pin**. The $\overline{HOLD}$ pin is used when the host CPU must interrupt a memory operation for another task. When $\overline{HOLD}$ is LOW, the current operation is suspended. The device ignores any transition on SCK or $\overline{CS}$. All transitions on $\overline{HOLD}$ must occur while SCK is LOW. This pin must be tied to $V_{DD}$ if not used. |
| $V_{SS}$ | Power supply | Ground for the device. Must be connected to the ground of the system. |
| $V_{DD}$ | Power supply | Power supply input to the device. |
| EXPOSED PAD | No connect | The EXPOSED PAD on the bottom of 8-pin TDFN package is not connected to the die. The EXPOSED PAD should be left floating. |

**Note**
1. SI may be connected to SO for a single pin data interface.


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Overview

The CY15B104Q is a serial F-RAM memory. The memory array is logically organized as 524,288 × 8 bits and is accessed using an industry-standard serial peripheral interface (SPI) bus. The functional operation of the F-RAM is similar to serial flash and serial EEPROMs. The major difference between the CY15B104Q and a serial flash or EEPROM with the same pinout is the F-RAM's superior write performance, high endurance, and low power consumption.

### Memory Architecture

When accessing the CY15B104Q, the user addresses 512K locations of eight data bits each. These eight data bits are shifted in or out serially. The addresses are accessed using the SPI protocol, which includes a chip select (to permit multiple devices on the bus), an opcode, and a three-byte address. The upper 5 bits of the address range are 'don't care' values. The complete address of 19 bits specifies each byte address uniquely.

Most functions of the CY15B104Q are either controlled by the SPI interface or handled by on-board circuitry. The access time for the memory operation is essentially zero, beyond the time needed for the serial protocol. That is, the memory is read or written at the speed of the SPI bus. Unlike a serial flash or EEPROM, it is not necessary to poll the device for a ready condition because writes occur at bus speed. By the time a new bus transaction can be shifted into the device, a write operation is complete. This is explained in more detail in the interface section.

### Serial Peripheral Interface (SPI) Bus

The CY15B104Q is an SPI slave device and operates at speeds up to 40 MHz. This high-speed serial bus provides high-performance serial communication to an SPI master. Many common microcontrollers have hardware SPI ports allowing a direct interface. It is simple to emulate the port using ordinary port pins for microcontrollers that do not. The CY15B104Q operates in SPI Mode 0 and 3.

### SPI Overview

The SPI is a four-pin interface with Chip Select ($\overline{CS}$), Serial Input (SI), Serial Output (SO), and Serial Clock (SCK) pins.

The SPI is a synchronous serial interface, which uses clock and data pins for memory access and supports multiple devices on the data bus. A device on the SPI bus is activated using the $\overline{CS}$ pin.

The relationship between chip select, clock, and data is dictated by the SPI mode. This device supports SPI modes 0 and 3. In both of these modes, data is clocked into the F-RAM on the rising edge of SCK starting from the first rising edge after $\overline{CS}$ goes active.

The SPI protocol is controlled by opcodes. These opcodes specify the commands from the bus master to the slave device. After $\overline{CS}$ is activated, the first byte transferred from the bus master is the opcode. Following the opcode, any addresses and data are then transferred. The $\overline{CS}$ must go inactive after an operation is complete and before a new opcode can be issued. The commonly used terms in the SPI protocol are as follows:

*SPI Master*

The SPI master device controls the operations on the SPI bus. An SPI bus may have only one master with one or more slave devices. All the slaves share the same SPI bus lines and the master may select any of the slave devices using the $\overline{CS}$ pin. All of the operations must be initiated by the master activating a slave device by pulling the $\overline{CS}$ pin of the slave LOW. The master also generates the SCK and all the data transmission on SI and SO lines are synchronized with this clock.

*SPI Slave*

The SPI slave device is activated by the master through the Chip Select line. A slave device gets the SCK as an input from the SPI master and all the communication is synchronized with this clock. An SPI slave never initiates a communication on the SPI bus and acts only on the instruction from the master.

The CY15B104Q operates as an SPI slave and may share the SPI bus with other SPI slave devices.

*Chip Select ($\overline{CS}$)*

To select any slave device, the master needs to pull down the corresponding $\overline{CS}$ pin. Any instruction can be issued to a slave device only while the $\overline{CS}$ pin is LOW. When the device is not selected, data through the SI pin is ignored and the serial output pin (SO) remains in a high-impedance state.

**Note** A new instruction must begin with the falling edge of $\overline{CS}$. Therefore, only one opcode can be issued for each active Chip Select cycle.

*Serial Clock (SCK)*

The serial clock is generated by the SPI master and the communication is synchronized with this clock after $\overline{CS}$ goes LOW.

The CY15B104Q enables SPI modes 0 and 3 for data communication. In both of these modes, the inputs are latched by the slave device on the rising edge of SCK and outputs are issued on the falling edge. Therefore, the first rising edge of SCK signifies the arrival of the first Most Significant Bit (MSB) of an SPI instruction on the SI pin. Further, all data inputs and outputs are synchronized with SCK.

*Data Transmission (SI/SO)*

The SPI data bus consists of two lines, SI and SO, for serial data communication. SI is also referred to as Master Out Slave In (MOSI) and SO is referred to as Master In Slave Out (MISO). The master issues instructions to the slave through the SI pin, while the slave responds through the SO pin. Multiple slave devices may share the SI and SO lines as described earlier.

The CY15B104Q has two separate pins for SI and SO, which can be connected with the master as shown in Figure 3.



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

For a microcontroller that has no dedicated SPI bus, a general-purpose port may be used. To reduce hardware resources on the controller, it is possible to connect the two data pins (SI, SO) together and tie off (HIGH) the HOLD and WP pins. Figure 4 shows such a configuration, which uses only three pins.

*Most Significant Bit (MSB)*

The SPI protocol requires that the first bit to be transmitted is the Most Significant Bit (MSB). This is valid for both address and data transmission.

The 4-Mbit serial F-RAM requires a 3-byte address for any read or write operation. Because the address is only 19 bits, the first five bits, which are fed in are ignored by the device. Although these five bits are ‘don’t care’, Cypress recommends that these bits be set to 0s to enable seamless transition to higher memory densities.

*Serial Opcode*

After the slave device is selected with $\overline{CS}$ going LOW, the first byte received is treated as the opcode for the intended operation. CY15B104Q uses the standard opcodes for memory accesses.

*Invalid Opcode*

If an invalid opcode is received, the opcode is ignored and the device ignores any additional serial data on the SI pin until the next falling edge of $\overline{CS}$, and the SO pin remains tristated.

*Status Register*

CY15B104Q has an 8-bit Status Register. The bits in the Status Register are used to configure the device. These bits are described in Table 3 on page 7.

**Figure 3. System Configuration with SPI Port**

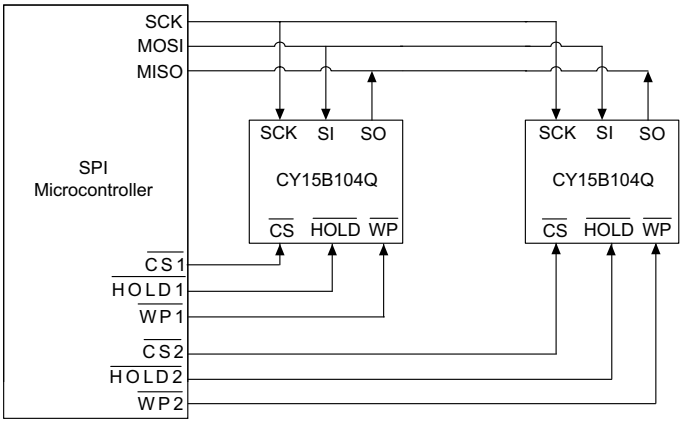
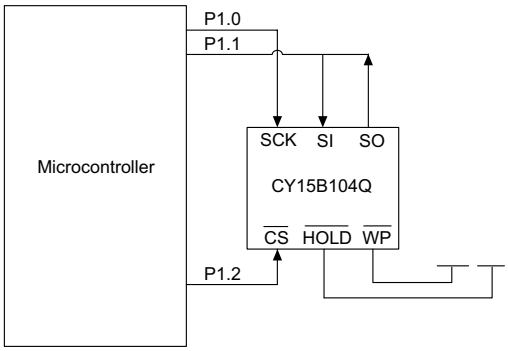



**Figure 4. System Configuration without SPI Port**




## SPI Modes

CY15B104Q may be driven by a microcontroller with its SPI peripheral running in either of the following two modes:

- SPI Mode 0 (CPOL = 0, CPHA = 0)
- SPI Mode 3 (CPOL = 1, CPHA = 1)

For both these modes, the input data is latched in on the rising edge of SCK starting from the first rising edge after $\overline{CS}$ goes active. If the clock starts from a HIGH state (in mode 3), the first rising edge after the clock toggles is considered. The output data is available on the falling edge of SCK.

The two SPI modes are shown in Figure 5 and Figure 6 on page 6. The status of the clock when the bus master is not transferring data is:

- SCK remains at 0 for Mode 0
- SCK remains at 1 for Mode 3

The device detects the SPI mode from the status of the SCK pin when the device is selected by bringing the $\overline{CS}$ pin LOW. If the SCK pin is LOW when the device is selected, SPI Mode 0 is assumed and if the SCK pin is HIGH, it works in SPI Mode 3.


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

**Figure 5. SPI Mode 0**

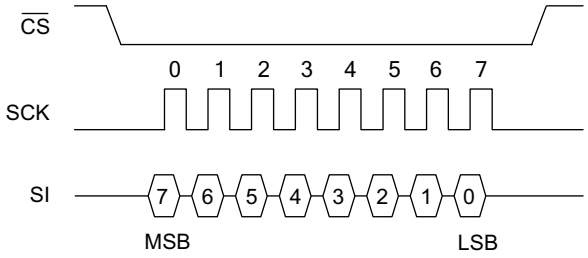
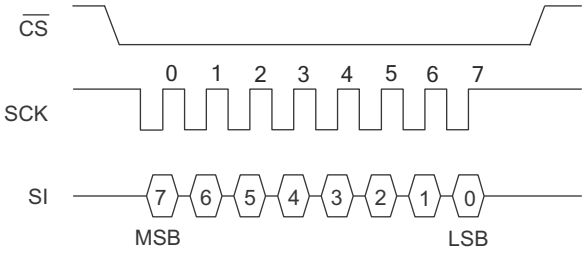



**Figure 6. SPI Mode 3**




## Power Up to First Access

The CY15B104Q is not accessible for a $t_{PU}$ time after power-up. Users must comply with the timing parameter, $t_{PU}$, which is the minimum time from $V_{DD}$ (min) to the first $\overline{CS}$ LOW.

## Command Structure

There are nine commands, called opcodes, that can be issued by the bus master to the CY15B104Q (see Table 1). These opcodes control the functions performed by the memory.

**Table 1. Opcode Commands**

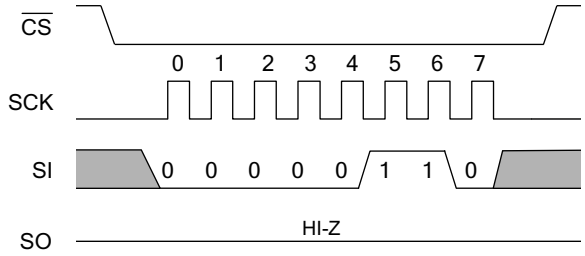
| Name | Description | Opcode |
|---|---|---|
| WREN | Set write enable latch | 0000 0110b |
| WRDI | Reset write enable latch | 0000 0100b |
| RDSR | Read Status Register | 0000 0101b |
| WRSR | Write Status Register | 0000 0001b |
| READ | Read memory data | 0000 0011b |
| FSTRD | Fast read memory data | 0000 1011b |
| WRITE | Write memory data | 0000 0010b |
| SLEEP | Enter sleep mode | 1011 1001b |
| RDID | Read device ID | 1001 1111b |
| Reserved | Reserved | 1100 0011b |
| | | 1100 0010b |
| | | 0101 1010b |
| | | 0101 1011b |

## WREN - Set Write Enable Latch

The CY15B104Q will power up with writes disabled. The WREN command must be issued before any write operation. Sending the WREN opcode allows the user to issue subsequent opcodes for write operations. These include writing the Status Register (WRSR) and writing the memory (WRITE).

Sending the WREN opcode causes the internal Write Enable Latch to be set. A flag bit in the Status Register, called WEL, indicates the state of the latch. WEL = '1' indicates that writes are permitted. Attempting to write the WEL bit in the Status Register has no effect on the state of this bit – only the WREN opcode can set this bit. The WEL bit will be automatically cleared on the rising edge of $\overline{CS}$ following a WRDI, a WRSR, or a WRITE operation. This prevents further writes to the Status Register or the F-RAM array without another WREN command. Figure 7 illustrates the WREN command bus configuration.

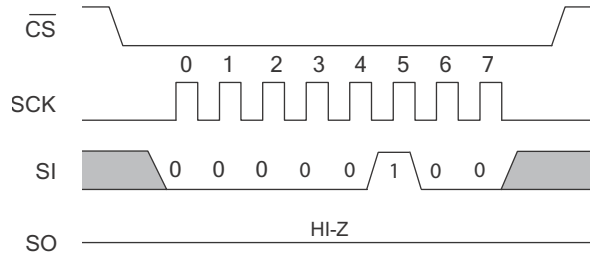
**Figure 7. WREN Bus Configuration**




## WRDI - Reset Write Enable Latch

The WRDI command disables all write activity by clearing the Write Enable Latch. The user can verify that writes are disabled by reading the WEL bit in the Status Register and verifying that WEL is equal to '0'. Figure 8 illustrates the WRDI command bus configuration.

**Figure 8. WRDI Bus Configuration**





深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Status Register and Write Protection

The write protection features of the CY15B104Q are multi-tiered and are enabled through the status register. The Status Register is organized as follows. (The default value shipped from the factory for WEL, BP0, BP1, bits 4–5, WPEN is ‘0’, and for bit 6 is ‘1’.)

**Table 2. Status Register**

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|---|---|---|---|---|---|---|---|
| WPEN (0) | X (1) | X (0) | X (0) | BP1 (0) | BP0 (0) | WEL (0) | X (0) |

**Table 3. Status Register Bit Definition**

| Bit | Definition | Description |
|---|---|---|
| Bit 0 | Don’t care | This bit is non-writable and always returns ‘0’ upon read. |
| Bit 1 (WEL) | Write Enable | WEL indicates if the device is write enabled. This bit defaults to ‘0’ (disabled) on power-up.<br>WEL = '1' --> Write enabled<br>WEL = '0' --> Write disabled |
| Bit 2 (BP0) | Block Protect bit ‘0’ | Used for block protection. For details, see Table 4. |
| Bit 3 (BP1) | Block Protect bit ‘1’ | Used for block protection. For details, see Table 4. |
| Bit 4-5 | Don’t care | These bits are non-writable and always return ‘0’ upon read. |
| Bit 6 | Don’t care | This bit is non-writable and always returns ‘1’ upon read. |
| Bit 7 (WPEN) | Write Protect Enable bit | Used to enable the function of Write Protect Pin ($\overline{WP}$). For details, see Table 5. |

Bits 0 and 4–5 are fixed at ‘0’ and bit 6 is fixed at ‘1’; none of these bits can be modified. Note that bit 0 ("Ready or Write in progress” bit in serial flash and EEPROM) is unnecessary, as the F-RAM writes in real-time and is never busy, so it reads out as a ‘0’. An exception to this is when the device is waking up from sleep mode, which is described in Sleep Mode on page 10. The BP1 and BP0 control the software write-protection features and are nonvolatile bits. The WEL flag indicates the state of the Write Enable Latch. Attempting to directly write the WEL bit in the Status Register has no effect on its state. This bit is internally set and cleared via the WREN and WRDI commands, respectively.

BP1 and BP0 are memory block write protection bits. They specify portions of memory that are write-protected as shown in Table 4.

**Table 4. Block Memory Write Protection**

| BP1 | BP0 | Protected Address Range |
|---|---|---|
| 0 | 0 | None |
| 0 | 1 | 60000h to 7FFFFh (upper 1/4) |
| 1 | 0 | 40000h to 7FFFFh (upper 1/2) |
| 1 | 1 | 00000h to 7FFFFh (all) |

The BP1 and BP0 bits and the Write Enable Latch are the only mechanisms that protect the memory from writes. The remaining write protection features protect inadvertent changes to the block protect bits.

The write protect enable bit (WPEN) in the Status Register controls the effect of the hardware write protect ($\overline{WP}$) pin. When the WPEN bit is set to '0', the status of the $\overline{WP}$ pin is ignored. When the WPEN bit is set to '1', a LOW on the $\overline{WP}$ pin inhibits a write to the Status Register. Thus the Status Register is write-protected only when WPEN = '1' and $\overline{WP}$ = '0'. Table 5 summarizes the write protection conditions.

**Table 5. Write Protection**

| WEL | WPEN | $\overline{WP}$ | Protected Blocks | Unprotected Blocks | Status Register |
|---|---|---|---|---|---|
| 0 | X | X | Protected | Protected | Protected |
| 1 | 0 | X | Protected | Unprotected | Unprotected |
| 1 | 1 | 0 | Protected | Unprotected | Protected |
| 1 | 1 | 1 | Protected | Unprotected | Unprotected |

### Read Status Register (RDSR)

The RDSR command allows the bus master to verify the contents of the Status Register. Reading the status register provides information about the current state of the write-protection features. Following the RDSR opcode, the CY15B104Q will return one byte with the contents of the Status Register.

### Write Status Register (WRSR)

The WRSR command allows the SPI bus master to write into the Status Register and change the write protect configuration by setting the WPEN, BP0 and BP1 bits as required. Before issuing a WRSR command, the $\overline{WP}$ pin must be HIGH or inactive. Note that on the CY15B104Q, $\overline{WP}$ only prevents writing to the Status Register, not the memory array. Before sending the WRSR command, the user must send a WREN command to enable writes. Executing a WRSR command is a write operation and therefore, clears the Write Enable Latch.



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

**Figure 9. RDSR Bus Configuration**

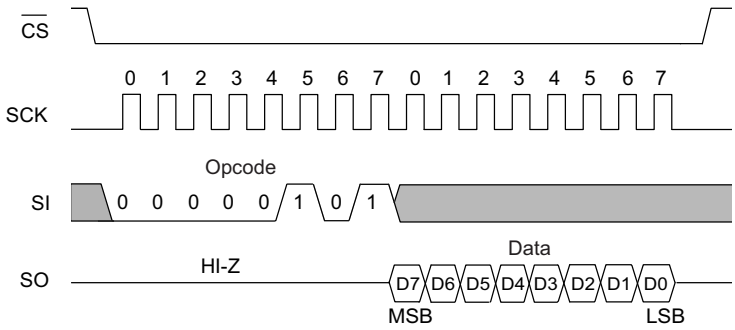
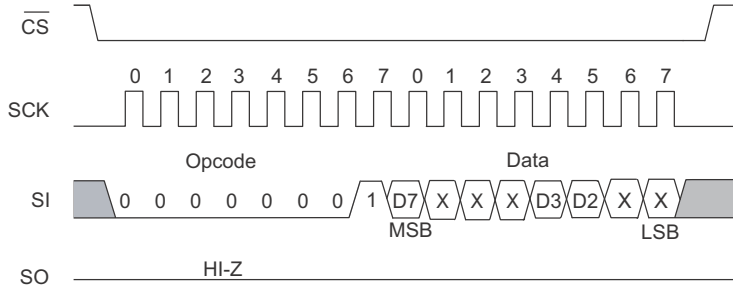



**Figure 10. WRSR Bus Configuration (WREN not shown)**




## Memory Operation

The SPI interface, which is capable of a high clock frequency, highlights the fast write capability of the F-RAM technology. Unlike serial flash and EEPROMs, the CY15B104Q can perform sequential writes at bus speed. No page register is needed and any number of sequential writes may be performed.

### Write Operation

All writes to the memory begin with a WREN opcode with $\overline{CS}$ being asserted and deasserted. The next opcode is WRITE. The WRITE opcode is followed by a three-byte address containing the 19-bit address (A18–A0) of the first data byte to be written into the memory. The upper five bits of the three-byte address are ignored. Subsequent bytes are data bytes, which are written sequentially. Addresses are incremented internally as long as the bus master continues to issue clocks and keeps $\overline{CS}$ LOW. If the last address of 7FFFFh is reached, the counter will roll over to 00000h. Data is written MSB first. The rising edge of $\overline{CS}$ terminates a write operation. A write operation is shown in Figure 11.

**Note** When a burst write reaches a protected block address, the automatic address increment stops and all the subsequent data bytes received for write will be ignored by the device.

EEPROMs use page buffers to increase their write throughput. This compensates for the technology's inherently slow write operations. F-RAM memories do not have page buffers because each byte is written to the F-RAM array immediately after it is clocked in (after the eighth clock). This allows any number of bytes to be written without page buffer delays.

**Note** If the power is lost in the middle of the write operation, only the last completed byte will be written.

### Read Operation

After the falling edge of $\overline{CS}$, the bus master can issue a READ opcode. Following the READ command is a three-byte address containing the 19-bit address (A18–A0) of the first byte of the read operation. The upper five bits of the address are ignored. After the opcode and address are issued, the device drives out the read data on the next eight clocks. The SI input is ignored during read data bytes. Subsequent bytes are data bytes, which are read out sequentially. Addresses are incremented internally as long as the bus master continues to issue clocks and $\overline{CS}$ is LOW. If the last address of 7FFFFh is reached, the counter will roll over to 00000h. Data is read MSB first. The rising edge of $\overline{CS}$ terminates a read operation and tristates the SO pin. A read operation is shown in Figure 12.

### Fast Read Operation

The CY15B104Q supports a FAST READ opcode (0Bh) that is provided for code compatibility with serial flash devices. The FAST READ opcode is followed by a three-byte address containing the 19-bit address (A18–A0) of the first byte of the read operation and then a dummy byte. The dummy byte inserts a read latency of 8-clock cycle. The fast read operation is otherwise the same as an ordinary read operation except that it requires an additional dummy byte. After receiving the opcode, address, and a dummy byte, the CY15B104Q starts driving its SO line with data bytes, with MSB first, and continues transmitting as long as the device is selected and the clock is available. In case of bulk read, the internal address counter is incremented automatically, and after the last address 7FFFFh is reached, the counter rolls over to 00000h. When the device is driving data on its SO line, any transition on its SI line is ignored. The rising edge of $\overline{CS}$ terminates a fast read operation and tristates the SO pin. A Fast Read operation is shown in Figure 13.


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

**Figure 11. Memory Write (WREN not shown) Operation**

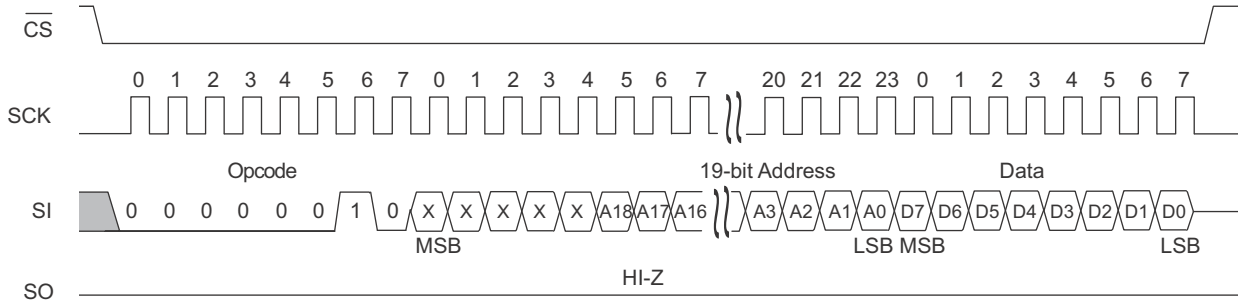



**Figure 12. Memory Read Operation**

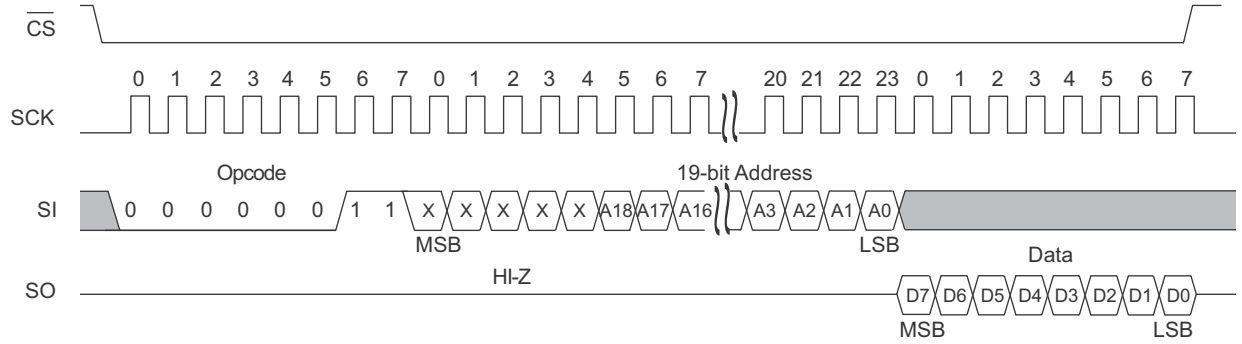
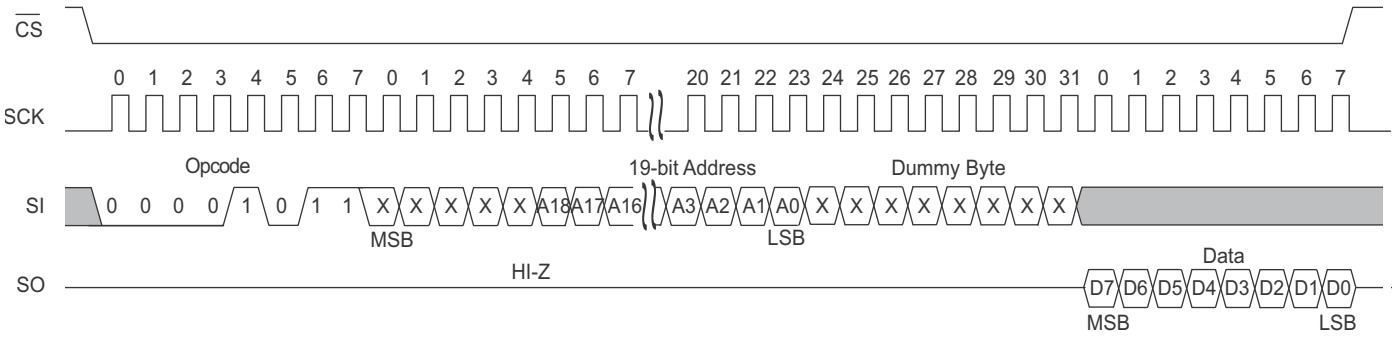



**Figure 13. Fast Read Operation**



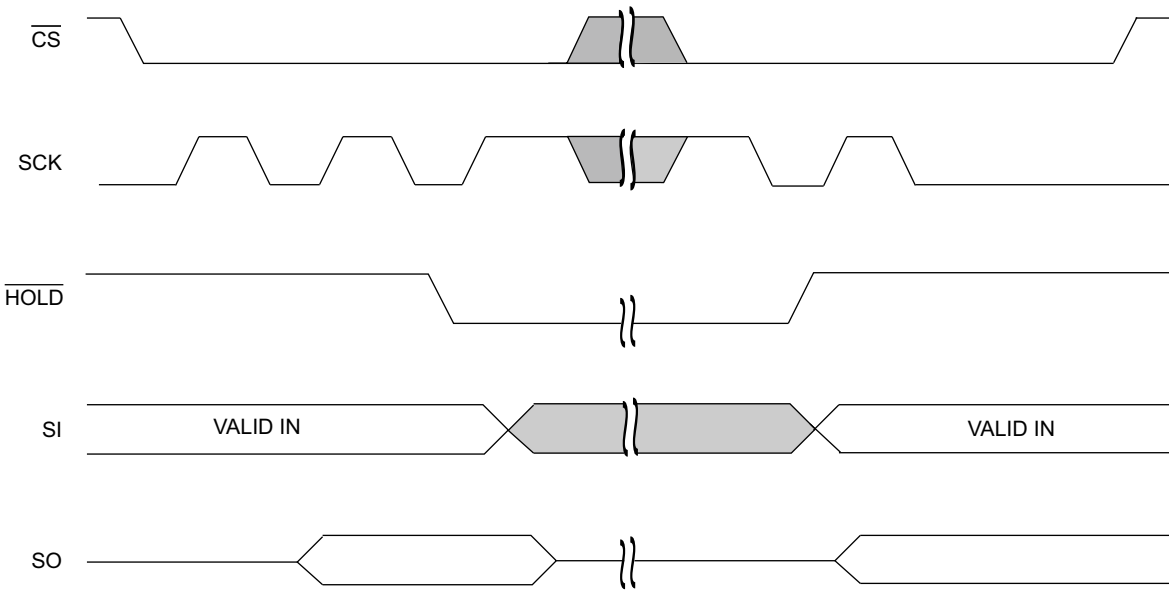


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## HOLD Pin Operation

The HOLD pin can be used to interrupt a serial operation without aborting it. If the bus master pulls the HOLD pin LOW while SCK is LOW, the current operation will pause. Taking the HOLD pin HIGH while SCK is LOW will resume an operation. The transitions of HOLD must occur while SCK is LOW, but the SCK and CS pin can toggle during a hold state.

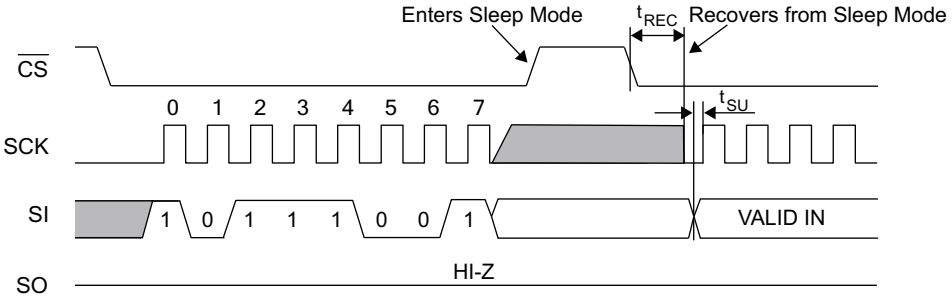
**Figure 14. HOLD Operation[2]**




## Sleep Mode

A low-power sleep mode is implemented on the CY15B104Q device. The device will enter the low-power state when the SLEEP opcode B9h is clocked in and a rising edge of CS is applied. When in sleep mode, the SCK and SI pins are ignored and SO will be HI-Z, but the device continues to monitor the CS pin. On the next falling edge of CS, the device will return to normal operation within $t_{REC}$ time. The SO pin remains in a HI-Z state during the wakeup period. The device does not necessarily respond to an opcode within the wakeup period. To start the wakeup procedure, the controller may send a “dummy” read, for example, and wait the remaining $t_{REC}$ time.

**Figure 15. Sleep Mode Operation**




**Note**
2. Figure 14 shows HOLD operation for input mode and output mode.


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

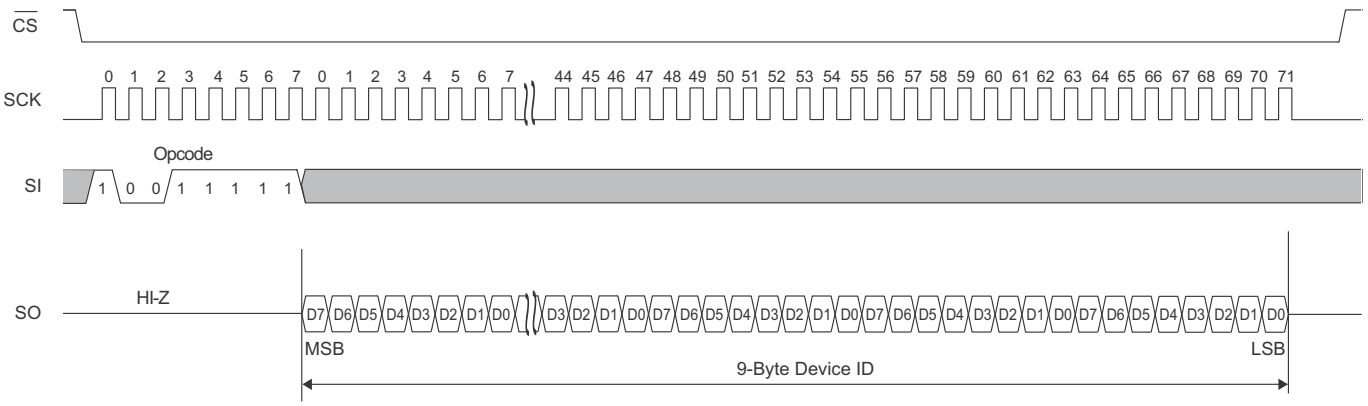
## Device ID

The CY15B104Q device can be interrogated for its manufacturer, product identification, and die revision. The RDID opcode 9Fh allows the user to read the manufacturer ID and product ID, both of which are read-only bytes. The JEDEC-assigned manufacturer ID places the Cypress (Ramtron) identifier in bank 7; therefore, there are six bytes of the continuation code 7Fh followed by the single byte C2h. There are two bytes of product ID, which includes a family code, a density code, a sub code, and the product revision code.

**Table 6. Device ID**

| Device ID (9 bytes) | Device ID Description | | | | | |
|---|---|---|---|---|---|---|
| | 71–16 (56 bits) | 15–13 (3 bits) | 12–8 (5 bits) | 7–6 (2 bits) | 5–3 (3 bits) | 2–0 (3 bits) |
| | Manufacturer ID | Product ID | | | | |
| | | Family | Density | Sub | Rev | Rsvd |
| 7F7F7F7F7F7FC22608h | 01111111011111101111111011111110111101111111101111111111000010 | 001 | 00110 | 00 | 001 | 000 |

**Figure 16. Read Device ID**




## Endurance

The CY15B104Q devices are capable of being accessed at least $10^{14}$ times, reads or writes. An F-RAM memory operates with a read and restore mechanism. Therefore, an endurance cycle is applied on a row basis for each access (read or write) to the memory array. The F-RAM architecture is based on an array of rows and columns of 32K rows of 64-bits each. The entire row is internally accessed once, whether a single byte or all eight bytes are read or written. Each byte in the row is counted only once in an endurance calculation. Table 7 shows endurance calculations for a 64-byte repeating loop, which includes an opcode, a starting address, and a sequential 64-byte data stream. This causes each byte to experience one endurance cycle through the loop. F-RAM read and write endurance is virtually unlimited even at a 40-MHz clock rate.

**Table 7. Time to Reach Endurance Limit for Repeating 64-byte Loop**

| SCK Freq (MHz) | Endurance Cycles/sec | Endurance Cycles/year | Years to Reach Limit |
|---|---|---|---|
| 40 | 73,520 | $2.32 \times 10^{12}$ | 43.1 |
| 10 | 18,380 | $5.79 \times 10^{11}$ | 172.7 |
| 5 | 9,190 | $2.90 \times 10^{11}$ | 345.4 |


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. These user guidelines are not tested.

Storage temperature ..... –55 °C to +125 °C

Maximum accumulated storage time
At 125 °C ambient temperature ..... 1000 h
At 85 °C ambient temperature ..... 10 Years

Ambient temperature
with power applied ..... –55 °C to +125 °C

Supply voltage on $V_{DD}$ relative to $V_{SS}$ .....–1.0 V to +4.5 V

Input voltage ..... –1.0 V to +4.5 V and $V_{IN} < V_{DD} + 1.0$ V

DC voltage applied to outputs
in High-Z state ..... –0.5 V to $V_{DD}$ + 0.5 V

Transient voltage (< 20 ns) on
any pin to ground potential ..... –2.0 V to $V_{DD}$ + 2.0 V

Package power dissipation
capability ($T_A$ = 25 °C) ..... 1.0 W

Surface mount lead soldering
temperature (3 seconds) ..... +260 °C

DC output current (1 output at a time, 1s duration) .... 15 mA

Electrostatic Discharge Voltage
Human Body Model (JEDEC Std JESD22-A114-B) ..... 2 kV

Charged Device Model (JEDEC Std JESD22-C101-A) ..... 500 V

Latch-up current ..... > 140 mA

## Operating Range

| Range | Ambient Temperature ($T_A$) | $V_{DD}$ |
|---|---|---|
| Industrial | –40 °C to +85 °C | 2.0 V to 3.6 V |

## DC Electrical Characteristics

Over the Operating Range

| Parameter | Description | Test Conditions | | Min | Typ[3] | Max | Unit |
|---|---|---|---|---|---|---|---|
| $V_{DD}$ | Power supply | | | 2.0 | 3.3 | 3.6 | V |
| $I_{DD}$ | $V_{DD}$ supply current | SCK toggling between $V_{DD}$ – 0.2 V and $V_{SS}$, other inputs $V_{SS}$ or $V_{DD}$ – 0.2 V. SO = Open | $f_{SCK}$ = 1 MHz | – | 0.13 | 0.30 | mA |
| | | | $f_{SCK}$ = 40 MHz | – | 1.4 | 3 | mA |
| $I_{SB}$ | $V_{DD}$ standby current | $\overline{CS}$ = $V_{DD}$. All other inputs $V_{SS}$ or $V_{DD}$. | $T_A$ = 25 °C | – | 100 | 150 | µA |
| | | | $T_A$ = 85 °C | – | – | 250 | µA |
| $I_{ZZ}$ | Sleep mode current | $\overline{CS}$ = $V_{DD}$. All other inputs $V_{SS}$ or $V_{DD}$. | $T_A$ = 25 °C | – | 3 | 5 | µA |
| | | | $T_A$ = 85 °C | – | – | 8 | µA |
| $I_{LI}$ | Input leakage current | $V_{SS} \le V_{IN} \le V_{DD}$ | | – | – | ±1 | µA |
| $I_{LO}$ | Output leakage current | $V_{SS} \le V_{OUT} \le V_{DD}$ | | – | – | ±1 | µA |
| $V_{IH}$ | Input HIGH voltage | | | 0.7 × $V_{DD}$ | – | $V_{DD}$ + 0.3 | V |
| $V_{IL}$ | Input LOW voltage | | | – 0.3 | – | 0.3 × $V_{DD}$ | V |
| $V_{OH1}$ | Output HIGH voltage | $I_{OH}$ = –1 mA, $V_{DD}$ = 2.7 V. | | 2.4 | – | – | V |
| $V_{OH2}$ | Output HIGH voltage | $I_{OH}$ = –100 µA | | $V_{DD}$ – 0.2 | – | – | V |
| $V_{OL1}$ | Output LOW voltage | $I_{OL}$ = 2 mA, $V_{DD}$ = 2.7 V | | – | – | 0.4 | V |
| $V_{OL2}$ | Output LOW voltage | $I_{OL}$ = 150 µA | | – | – | 0.2 | V |

**Note**
3. Typical values are at 25 °C, $V_{DD}$ = $V_{DD}$ (typ). Not 100% tested.



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Data Retention and Endurance

| Parameter | Description | Test condition | Min | Max | Unit |
|---|---|---|---|---|---|
| $T_{DR}$ | Data retention | $T_A$ = 85 °C | 10 | – | Years |
| | | $T_A$ = 75 °C | 38 | – | |
| | | $T_A$ = 65 °C | 151 | – | |
| $NV_C$ | Endurance | Over operating temperature | $10^{14}$ | – | Cycles |

## Capacitance

| Parameter [4] | Description | Test Conditions | Max | Unit |
|---|---|---|---|---|
| $C_O$ | Output pin capacitance (SO) | $T_A$ = 25 °C, f = 1 MHz, $V_{DD}$ = $V_{DD}$(typ) | 8 | pF |
| $C_I$ | Input pin capacitance | | 6 | pF |

## Thermal Resistance

| Parameter | Description | Test Conditions | 8-pin SOIC | 8-pin TDFN | Unit |
|---|---|---|---|---|---|
| $\Theta_{JA}$ | Thermal resistance (junction to ambient) | Test conditions follow standard test methods and procedures for measuring thermal impedance, per EIA / JESD51. | 114 | 30 | °C/W |
| $\Theta_{JC}$ | Thermal resistance (junction to case) | | 52 | 26 | °C/W |

## AC Test Conditions

Input pulse levels .....10% and 90% of $V_{DD}$
Input rise and fall times .....3 ns
Input and output timing reference levels .....0.5 × $V_{DD}$
Output load capacitance ..... 30 pF

**Note**
4. This parameter is periodically sampled and not 100% tested.


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## AC Switching Characteristics

Over the Operating Range

| Parameters [5] | | Description | $V_{DD}$ = 2.0 V to 3.6 V | | $V_{DD}$ = 2.7 V to 3.6 V | | Unit |
|---|---|---|---|---|---|---|---|
| Cypress Parameter | Alt. Parameter | | Min | Max | Min | Max | |
| $f_{SCK}$ | – | SCK clock frequency | 0 | 25 | 0 | 40 | MHz |
| $t_{CH}$ | – | Clock HIGH time | 18 | – | 11 | – | ns |
| $t_{CL}$ | – | Clock LOW time | 18 | – | 11 | – | ns |
| $t_{CSU}$ | $t_{CSS}$ | Chip select setup | 12 | – | 10 | – | ns |
| $t_{CSH}$ | $t_{CSH}$ | Chip select hold | 12 | – | 10 | – | ns |
| $t_{OD}$ [6, 7] | $t_{HZCS}$ | Output disable time | – | 20 | – | 12 | ns |
| $t_{ODV}$ | $t_{CO}$ | Output data valid time | – | 16 | – | 9 | ns |
| $t_{OH}$ | – | Output hold time | 0 | – | 0 | – | ns |
| $t_D$ | – | Deselect time | 60 | – | 40 | – | ns |
| $t_R$ [7, 8] | – | Data in rise time | – | 50 | – | 50 | ns |
| $t_F$ [7, 8] | – | Data in fall time | – | 50 | – | 50 | ns |
| $t_{SU}$ | $t_{SD}$ | Data setup time | 8 | – | 5 | – | ns |
| $t_H$ | $t_{HD}$ | Data hold time | 8 | – | 5 | – | ns |
| $t_{HS}$ | $t_{SH}$ | $\overline{\text{HOLD}}$ setup time | 12 | – | 10 | – | ns |
| $t_{HH}$ | $t_{HH}$ | $\overline{\text{HOLD}}$ hold time | 12 | – | 10 | – | ns |
| $t_{HZ}$ [6, 7] | $t_{HHZ}$ | $\overline{\text{HOLD}}$ LOW to HI-Z | – | 25 | – | 20 | ns |
| $t_{LZ}$ [7] | $t_{HLZ}$ | $\overline{\text{HOLD}}$ HIGH to data active | – | 25 | – | 20 | ns |

**Notes**

5. Test conditions assume a signal transition time of 3 ns or less, timing reference levels of 0.5 × $V_{DD}$, input pulse levels of 10% to 90% of $V_{DD}$, and output loading of the specified $I_{OL}/I_{OH}$ and 30 pF load capacitance shown in AC Test Conditions on page 13.
6. $t_{OD}$ and $t_{HZ}$ are specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state
7. Characterized but not 100% tested in production.
8. Rise and fall times measured between 10% and 90% of waveform.



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

**Figure 17. Synchronous Data Timing (Mode 0)**

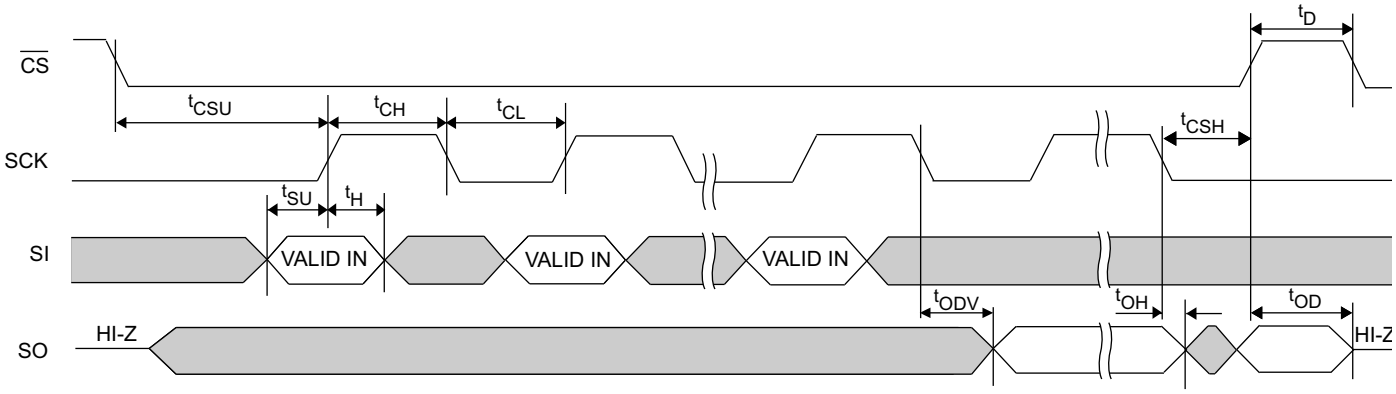
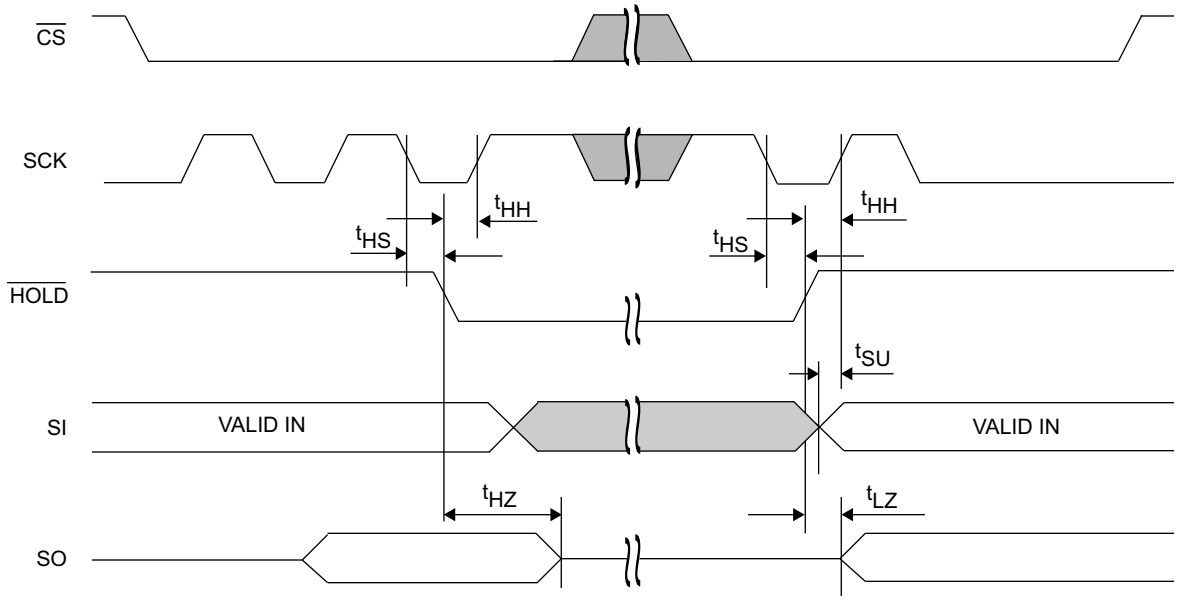



**Figure 18. $\overline{\text{HOLD}}$ Timing**





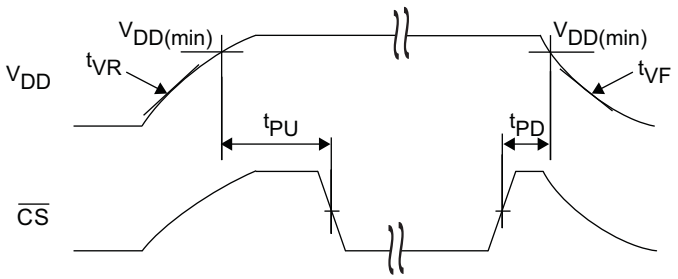
深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Power Cycle Timing

Over the Operating Range

| Parameter | Description | Min | Max | Unit |
|---|---|---|---|---|
| $t_{PU}$ | Power-up $V_{DD}$(min) to first access ($\overline{CS}$ LOW) | 1 | – | ms |
| $t_{PD}$ | Last access ($\overline{CS}$ HIGH) to power-down ($V_{DD}$(min)) | 0 | – | µs |
| $t_{VR}$ [9] | $V_{DD}$ power-up ramp rate | 50 | – | µs/V |
| $t_{VF}$ [9] | $V_{DD}$ power-down ramp rate | 100 | – | µs/V |
| $t_{REC}$ [10] | Recovery time from sleep mode | – | 450 | µs |

**Figure 19. Power Cycle Timing**




**Notes**
9. Slope measured at any point on the $V_{DD}$ waveform.
10. Guaranteed by design. Refer to Figure 15 for sleep mode recovery timing.

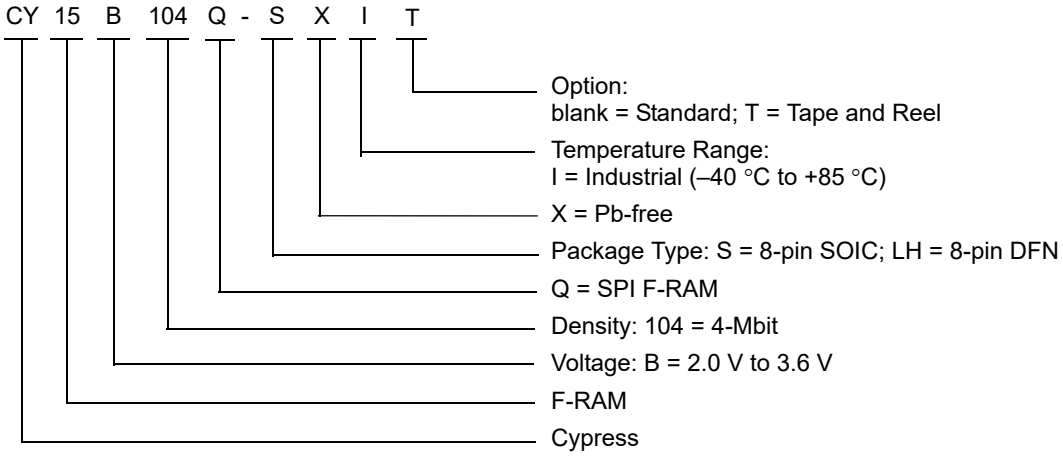

深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Ordering Information

| Ordering Code | Package Diagram | Package Type | Operating Range |
|---|---|---|---|
| CY15B104Q-SXI | 001-85261 | 8-pin SOIC | Industrial |
| CY15B104Q-SXIT | 001-85261 | 8-pin SOIC | |
| CY15B104Q-LHXI | 001-85579 | 8-pin TDFN | |
| CY15B104Q-LHXIT | 001-85579 | 8-pin TDFN | |

All these parts are Pb-free. Contact your local Cypress sales representative for availability of these parts.

### Ordering Code Definitions

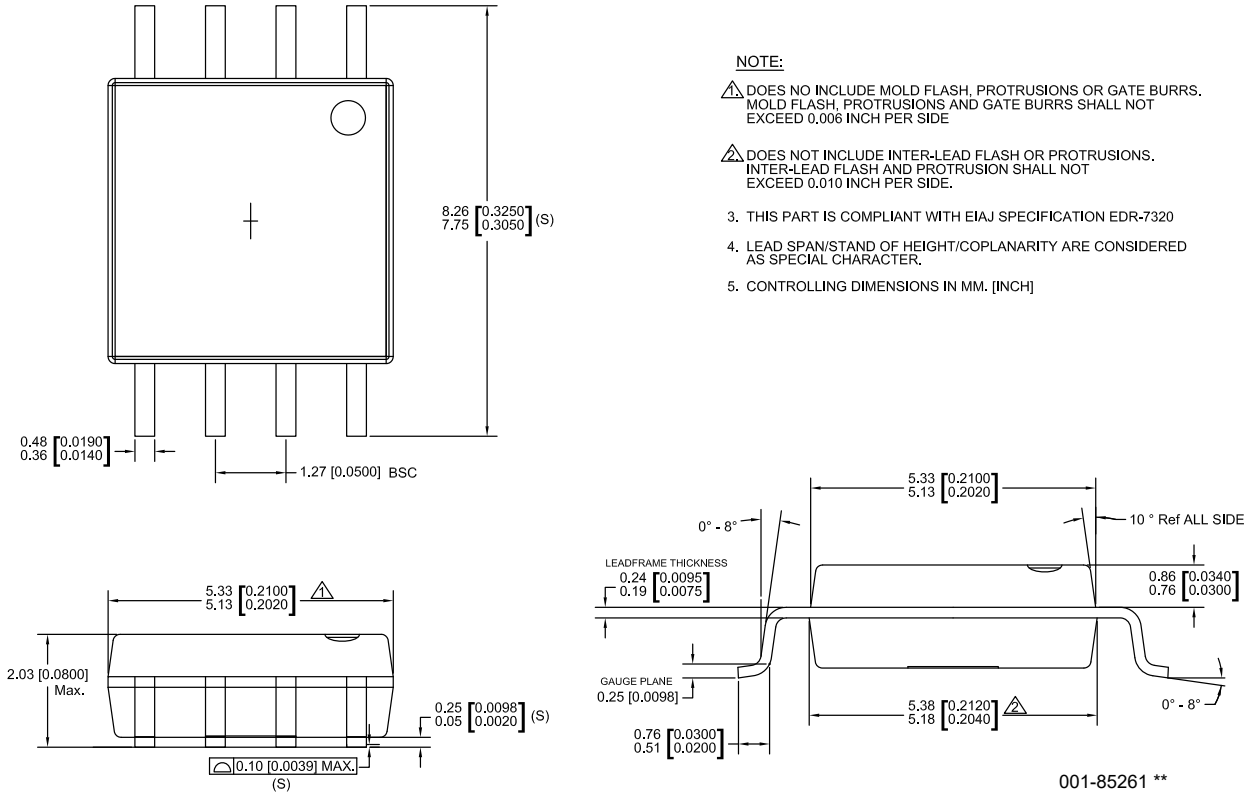




深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Package Diagrams

**Figure 20. 8-pin SOIC (208 Mils) Package Outline, 001-85261**

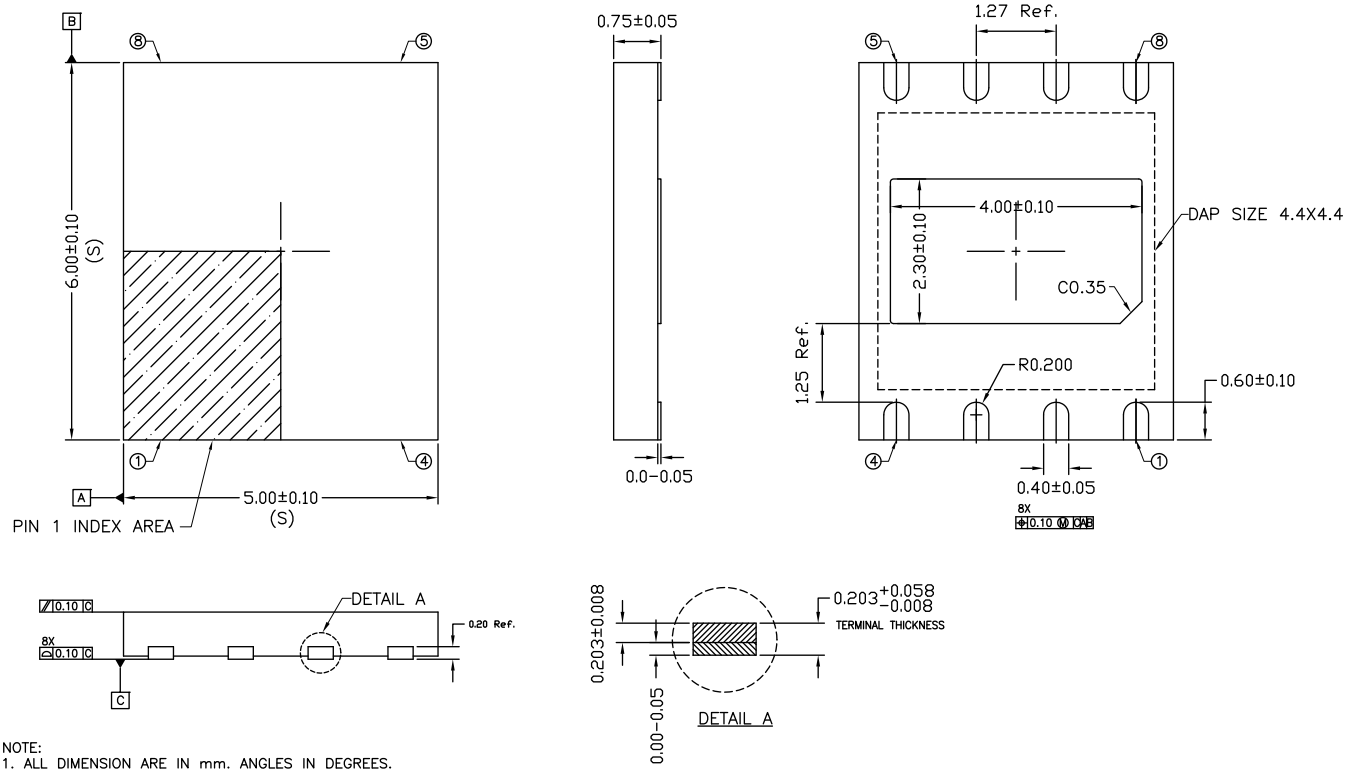




深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Package Diagrams (continued)

**Figure 21. 8-pin DFN (5 mm × 6 mm × 0.75 mm) Package Outline, 001-85579**




NOTE:
1. ALL DIMENSION ARE IN mm. ANGLES IN DEGREES.
2. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS. COPLANARITY SHALL NOT EXCEED 0.08mm.
3. WARPAGE SHALL NOT EXCEED 0.10mm.
4. PACKAGE LENGTH / PACKAGE WIDTH ARE CONSIDERED AS SPECIAL CHARACTERISTICS.(S)
5. REFER TO JEDEC MO-229.
6. FRAME STOCK# FL0106 (Ag Ring Plate), UTL PKG CODE TD56G008A OR TD500X600G008A OR TD500T600G008A OR TD500L600G008A OR TD500U600G008A.
7. L/F STOCK# FR0221 (Ag Ring), UTL PKG CODE TD500E600G008A OR TD500S600G008A OR TD500M600G008A OR TD500D600G008A.

001-85579 *A



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Acronyms

| Acronym | Description |
|---|---|
| CPHA | Clock Phase |
| CPOL | Clock Polarity |
| EEPROM | Electrically Erasable Programmable Read-Only Memory |
| EIA | Electronic Industries Alliance |
| F-RAM | Ferroelectric Random Access Memory |
| I/O | Input/Output |
| JEDEC | Joint Electron Devices Engineering Council |
| JESD | JEDEC standards |
| LSB | Least Significant Bit |
| MSB | Most Significant Bit |
| RoHS | Restriction of Hazardous Substances |
| SPI | Serial Peripheral Interface |
| SOIC | Small Outline Integrated Circuit |
| TDFN | Thin Dual Flat No-lead |

## Document Conventions

### Units of Measure

| Symbol | Unit of Measure |
|---|---|
| °C | degree Celsius |
| Hz | hertz |
| kHz | kilohertz |
| kΩ | kilohm |
| Mbit | megabit |
| MHz | megahertz |
| µA | microampere |
| µF | microfarad |
| µs | microsecond |
| mA | milliampere |
| ms | millisecond |
| ns | nanosecond |
| Ω | ohm |
| % | percent |
| pF | picofarad |
| V | volt |
| W | watt |


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Document History Page

| Document Title: CY15B104Q, 4-Mbit (512 K × 8) Serial (SPI) F-RAM<br>Document Number: 001-94240 | | | | |
|---|---|---|---|---|
| **Rev.** | **ECN No.** | **Orig. of Change** | **Submission Date** | **Description of Change** |
| ** | 4504587 | GVCH | 09/17/2014 | New data sheet. |
| *A | 4569855 | GVCH | 11/18/2014 | Changed status from Summary to Advance.<br>Updated Overview:<br>Updated Command Structure:<br>Updated Table 1:<br>Added reserved opcodes - 0xC3, 0xC2, 0x5A, 0x5B. |
| *B | 4587063 | GVCH | 12/04/2014 | Changed status from Advance to Preliminary. |
| *C | 4878316 | ZSK / PSR | 09/03/2015 | Changed status from Preliminary to Final.<br>Updated Functional Description:<br>Added “For a complete list of related documentation, click here.” at the end.<br>Updated Maximum Ratings:<br>Removed “Maximum junction temperature”.<br>Added “Maximum accumulated storage time”.<br>Added “Ambient temperature with power applied”.<br>Updated to new template.<br>Completing Sunset Review. |
| *D | 5688114 | RUPA | 04/18/2017 | Updated Cypress logo.<br>Updated Copyright information. |
| *E | 5958992 | GVCH | 11/09/2017 | Updated template. |


深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com

## Sales, Solutions, and Legal Information

### Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

### Products

| | |
|---|---|
| ARM® Cortex® Microcontrollers | cypress.com/arm |
| Automotive | cypress.com/automotive |
| Clocks & Buffers | cypress.com/clocks |
| Interface | cypress.com/interface |
| Internet of Things | cypress.com/iot |
| Memory | cypress.com/memory |
| Microcontrollers | cypress.com/mcu |
| PSoC | cypress.com/psoc |
| Power Management ICs | cypress.com/pmic |
| Touch Sensing | cypress.com/touch |
| USB Controllers | cypress.com/usb |
| Wireless Connectivity | cypress.com/wireless |

### PSoC® Solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP | PSoC 6

### Cypress Developer Community

Forums | WICED IOT Forums | Projects | Video | Blogs | Training | Components

### Technical Support

cypress.com/support

© Cypress Semiconductor Corporation, 2014-2017. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.



深圳市满度科技有限公司
Web:www.manduic.com
Tel:150-1290-5940
Email:sales@manduic.com